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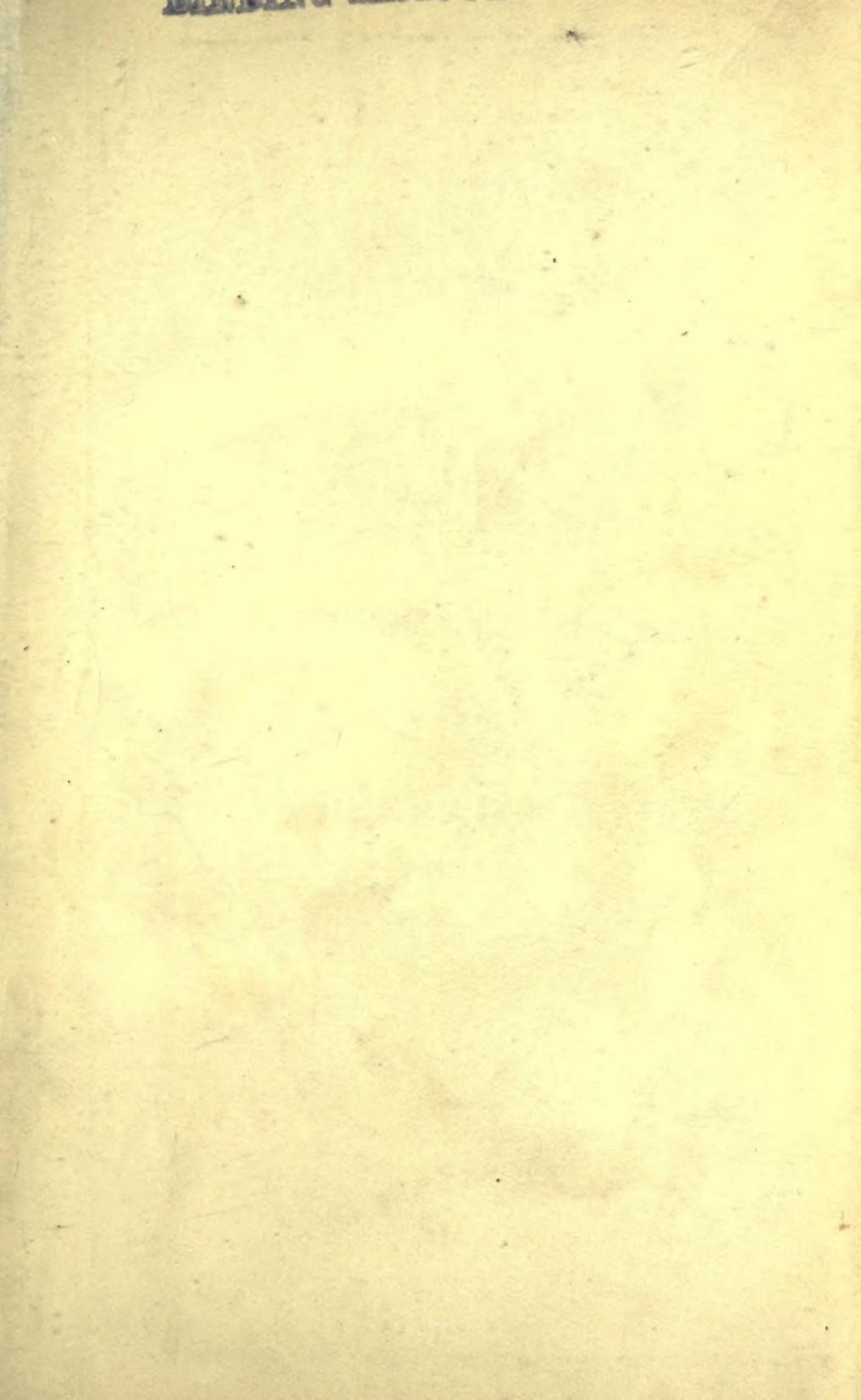


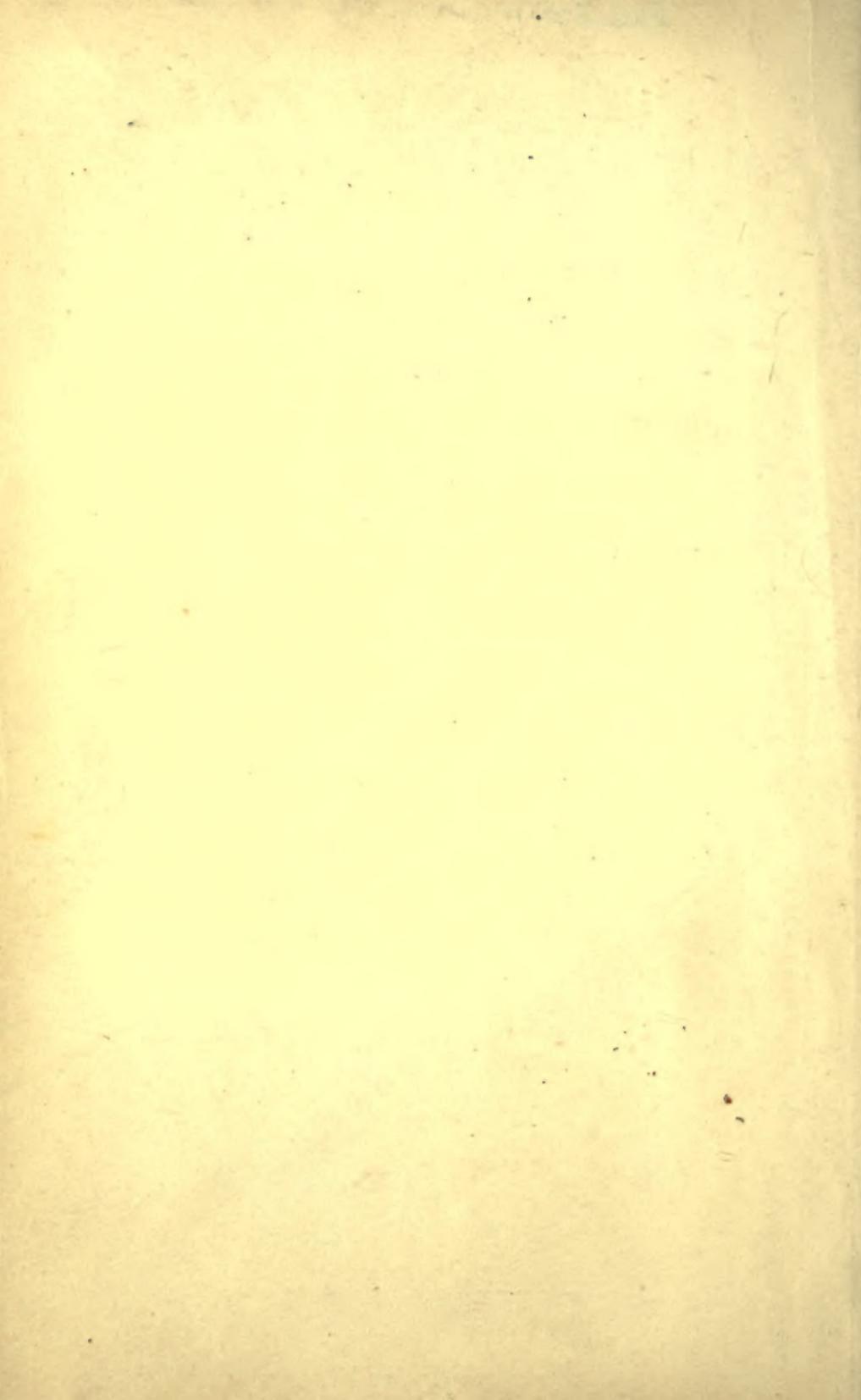


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AN ELEMENTARY TREATISE  
ON  
THE INTEGRAL CALCULUS.

ii

AN ELEMENTARY TREATISE  
ON  
THE DIFFERENTIAL CALCULUS,  
CONTAINING  
THE THEORY OF PLANE CURVES.

BY  
BENJAMIN WILLIAMSON, Sc.D., D.C.L., F.R.S.

*NINTH EDITION.*

---

AN INTRODUCTION TO THE THEORY  
OF  
STRESS AND STRAIN OF ELASTIC SOLIDS.

BY  
BENJAMIN WILLIAMSON, Sc.D., D.C.L., F.R.S.

AN ELEMENTARY TREATISE ON DYNAMICS,  
CONTAINING  
APPLICATIONS TO THERMODYNAMICS.

BY  
BENJAMIN WILLIAMSON, Sc.D., D.C.L., F.R.S.,  
AND  
FRANCIS A. TARLETON, Sc.D., LL.D.

*THIRD EDITION.*

AN ELEMENTARY TREATISE

ON

THE INTEGRAL CALCULUS,

CONTAINING

*APPLICATIONS TO PLANE CURVES  
AND SURFACES,*

AND ALSO

CHAPTERS ON THE CALCULUS OF VARIATIONS,

WITH

NUMEROUS EXAMPLES.

BY

BENJAMIN WILLIAMSON, Sc. D.,  
D. C. L., F. R. S.



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## P R E F A C E.

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THIS Book has been written as a companion volume to my Treatise on the Differential Calculus, and in its construction I have endeavoured to carry out the same general plan on which that book was composed. I have, accordingly, studied simplicity so far as was consistent with rigour of demonstration, and have tried to make the subject as attractive to the beginner as the nature of the Calculus would permit.

I have, as far as possible, confined my attention to the general principles of Integration, and have endeavoured to arrange the successive portions of the subject in the order best suited for the Student.

I have paid considerable attention to the geometrical applications of the Calculus, and have introduced a number of the leading fundamental properties of the more important curves and surfaces, so far as they are connected with the Integral Calculus. This has led me to give many remarkable results, such as Steiner's general theorems on the connexion of pedals and roulettes, Amsler's planimeter, Kempe's theorem, Landen's theorems on the rectification of the hyperbola, Genocchi's theorem on the rectification of the Cartesian oval, and others which have not been usually included in textbooks on the Integral Calculus.

A Chapter has been devoted to the discussion of Integrals of Inertia. For the methods adopted, and a great part of the

details in this Chapter, I am indebted to the kindness of the late Professor Townsend. My friend Professor Crofton has laid me under very deep obligations by contributing a Chapter on Mean Value and Probability. I am glad to be able to lay this Chapter before the Student, as an introduction to this branch of the subject by a Mathematician whose original and admirable Papers, in the *Philosophical Transactions*, 1868-69, and elsewhere, have so largely contributed to the recent extension of this important application of the Integral Calculus.

I have introduced Chapters on the connexion between Line and Surface Integrals; and on the Symbol of Substitution, principally with a view to its employment in the Calculus of Variations I have also devoted two Chapters to an elementary treatment on the application of the Calculus of Variations to Single and Multiple Integrals.

TRINITY COLLEGE, DUBLIN,

*March, 1906.*

# TABLE OF CONTENTS.



## CHAPTER I.

### ELEMENTARY FORMS OF INTEGRATION.

	PAGE
Integration, . . . . .	1
Elementary Integrals, . . . . .	2
Integration by Substitution, . . . . .	5
Integration of $\frac{dx}{a + 2bx + cx^2}$ , . . . . .	8
Euler's expressions for $\sin \theta$ and $\cos \theta$ deduced by Integration, . . . . .	10
Integration of $\frac{dx}{(x - p) \sqrt{a + 2bx + cx^2}}$ , . . . . .	14
"    " $\frac{dx}{(a + 2bx + cx^2)^{\frac{3}{2}}}$ , . . . . .	16
"    " $\frac{d\theta}{\cos \theta}$ and $\frac{d\theta}{\sin \theta}$ , . . . . .	17
"    " $\frac{d\theta}{a + b \cos \theta}$ , . . . . .	19
Different Methods of Integration, . . . . .	20
Formula of Integration by Parts, . . . . .	20
Integration by Rationalization, . . . . .	23
Integration of $\frac{dx}{(A + Cx^2)(a + cx^2)^{\frac{3}{2}}}$ , . . . . .	25
Rationalization by Trigonometrical Transformations, . . . . .	26
Observations on Fundamental Forms, . . . . .	29
Definite Integrals, . . . . .	30
Examples, . . . . .	36

## CHAPTER II.

## INTEGRATION OF RATIONAL FRACTIONS.

	PAGE
Rational Fractions, . . . . .	39
Decomposition into Partial Fractions, . . . . .	42
Case of Real and Unequal Roots, . . . . .	42
Multiple Real Roots, . . . . .	47
Imaginary Roots, . . . . .	49
Multiple Imaginary Roots, . . . . .	53
Integration of $\frac{dx}{(x-a)^m(x-b)^n}$ , . . . . .	56
"    " $\frac{dx}{x^n-1}$ , . . . . .	58
"    " $\frac{x^{m-1}dx}{x^n-1}$ , . . . . .	60
Examples, . . . . .	61

---

## CHAPTER III.

## INTEGRATION BY SUCCESSIVE REDUCTION.

Cases in which $\sin^m \theta \cos^n \theta d\theta$ is immediately integrable, . . . . .	63
Formulæ of Reduction for $\int \sin^m \theta \cos^n \theta d\theta$ , . . . . .	66
Integration of $\tan^n \theta d\theta$ and $\frac{d\theta}{\tan^n \theta}$ , . . . . .	72
Trigonometrical Transformations, . . . . .	73
Binomial Differentials, . . . . .	75
Reduction of $\int e^{mx} x^n dx$ , . . . . .	76
"    " $\int x^m (\log x)^n dx$ , . . . . .	77
"    " $\int x^n \cos ax dx$ , . . . . .	78
"    " $\int e^{ax} \cos^n x dx$ , . . . . .	79
"    " $\int \cos^m x \sin nx dx$ , . . . . .	79
Reduction by Differentiation, . . . . .	80

	PAGE
Reduction of $\int \frac{x^m dx}{(a + cx)^n}$	81
"    " $\int \frac{x^m dx}{(a + 2bx + cx^2)^k}$	82
"    " $\int \frac{x^m dx}{(a + 2bx + cx^2)^n}$	82
"    " $\int \frac{dx}{(a + b \cos x)^n}$	84
Integration of $\frac{f(x)}{\phi(x) \sqrt{a + 2bx + cx^2}} dx$	86
Examples, . . . . .	89

---

## CHAPTER IV.

## INTEGRATION BY RATIONALIZATION.

Integration of Monomials, . . . . .	91
Rationalization of $F(x, \sqrt{a + 2bx + cx^2}) dx$ , . . . . .	92
"    " $\frac{f(x) dx}{\phi(x) \sqrt{a + 2bx + cx^2}}$ , . . . . .	92
General Investigation, . . . . .	97
Case of Recurring Biquadratic, . . . . .	101
Examples, . . . . .	103

---

## CHAPTER V.

## MISCELLANEOUS EXAMPLES OF INTEGRATION.

Integral of $\frac{A \cos x + B \sin x + C}{a \cos x + b \sin x + c} dx$ , . . . . .	104
Differentiation under the sign of Integration, . . . . .	107
Integration under the sign of Integration, . . . . .	109
"    " by Infinite Series, . . . . .	110
Examples, . . . . .	118

## CHAPTER VI.

## DEFINITE INTEGRALS.

	PAGE
Integration regarded as Summation, . . . . .	114
Definite Integrals. Limits of Integration, . . . . .	115
Values of $\int_0^{\frac{\pi}{2}} \sin^n x dx$ and $\int_0^{\frac{\pi}{2}} \cos^n x dx$ , . . . . .	119
., ., $\int_0^{\frac{\pi}{2}} \sin^m x \cos^n x dx$ , when $m$ and $n$ are integers, . . . . .	120
., ., $\int_0^{\infty} e^{-x} x^n dx$ , when $n$ is a positive integer, . . . . .	123
Taylor's Theorem, . . . . .	126
Remainder in Taylor's Theorem expressed as a Definite Integral, . . . . .	127
Bernoulli's Series, . . . . .	128
Exceptional Cases in Definite Integrals, . . . . .	128
Case where $f(x)$ becomes Infinite at either Limit, . . . . .	129
When $f(x)$ becomes Infinite between the Limits, . . . . .	130
Case of Infinite Limits, . . . . .	131
Principal and General Values of a Definite Integral, . . . . .	132
Singular Definite Integrals, . . . . .	134
$\int_0^{\infty} \frac{f(x)}{F(x)} dx$ , . . . . .	135
$\int_0^{\infty} \frac{x^{2m}}{1+x^{2n}} dx$ , where $n > m$ , . . . . .	138
$\int_0^{\infty} \frac{x^{2m}}{1-x^{2n}} dx$ , . . . . .	139
Differentiation of Definite Integrals, . . . . .	143
Integrals deduced by Differentiation, . . . . .	144
Differentiation of a Definite Integral when the Limits vary, . . . . .	147
Integration under the Sign of Integration, . . . . .	148
$\int_0^{\infty} e^{-x^2} dx$ , . . . . .	151

	PAGE
$\int_0^\infty \frac{\cos mx dx}{1+x^2}$	153
$\int_0^\infty \log(\sin \theta) d\theta$	154
Theorem of Frullani,*	155
Value of $\int_0^\infty \frac{\tan^{-1} ax - \tan^{-1} bx}{x} dr$	157
Remainder in Lagrange's Series,	158
Gamma-Functions,	159
Proof of Equation $B(m, n) = \frac{\Gamma(m) \Gamma(n)}{\Gamma(m+n)}$ ,	161
,,    ,, $\Gamma(n) \Gamma(1-n) = \frac{\pi}{\sin n\pi}$ ,	162
Value of $\Gamma\left(\frac{1}{n}\right) \Gamma\left(\frac{2}{n}\right) \Gamma\left(\frac{3}{n}\right) \dots \Gamma\left(\frac{n-1}{n}\right)$ ,	164
Table of Log $\Gamma(p)$ ,	169
Examples,	171

## CHAPTER VII.

## AREAS OF PLANE CURVES.

Areas in Cartesian Coordinates,	176
The Circle,	178
The Ellipse,	179
The Parabola,	180
The Hyperbola,	181
Hyperbolic Sines and Cosines,	182
The Catenary,	183
Form for Area of a Closed Curve,	188
The Cycloid,	189

\* This theorem was communicated by Frullani to Plana in 1821, and published afterwards in *Mem. del Soc. Ital.*, 1828.

	PAGE
Areas in Polar Coordinates, . . . . .	190
Spiral of Archimedes, . . . . .	194
Elliptic Sector—Lambert's Theorem, . . . . .	196
Area of a Pedal Curve, . . . . .	199
Area of Pedal of Ellipse for any Origin, . . . . .	201
Steiner's Theorem on Areas of Pedals, . . . . .	201
,, on Roulettes, . . . . .	203
Theorem of Holditch, . . . . .	206
Theorem of Elliott, . . . . .	209
Kempe's Theorem, . . . . .	210
Areas by Approximation, . . . . .	211
Amsler's Planimeter, . . . . .	214
Examples, . . . . .	218

## CHAPTER VIII.

### LENGTHS OF CURVES.

Rectification in Rectangular Coordinates, . . . . .	222
The Parabola—The Catenary, . . . . .	223
The Semi-cubical Parabola—Evolutes, . . . . .	224
The Ellipse, . . . . .	226
Legendre's Theorem on Rectification, . . . . .	228
Fagnani's Theorem, . . . . .	229
The Hyperbola, . . . . .	231
Landen's Theorem, . . . . .	232
Graves's Theorem, . . . . .	234
Mac Cullagh's Theorem, . . . . .	236
Difference between Infinite Branch and Asymptote for Hyperbola, . . . . .	236
The Limaçon—the Epitrochoid, . . . . .	237
Steiner's Theorem on Rectification of Roulettes, . . . . .	238
Genocchi's Theorem on Oval of Descartes, . . . . .	239
Rectification of Curves of Double Curvature, . . . . .	243
Examples, . . . . .	246

## CHAPTER IX.

## VOLUMES AND SURFACES OF SOLIDS.

	PAGE
The Prism and Cylinder, . . . . .	250
The Pyramid and Cone, . . . . .	251
Surfaces and Volume of Sphere, . . . . .	252
Surfaces of Revolution, . . . . .	254
Paraboloid of Revolution, . . . . .	256
Oblate and Prolate Spheroids, . . . . .	257
Surface of Spheriod, . . . . .	257
Annular Solids, . . . . .	261
Guldin's Theorems, . . . . .	262
Volume of Elliptic Paraboloid, . . . . .	265
Volume of the Ellipsoid, . . . . .	266
Volume by Double Integration, . . . . .	269
Double Integrals, . . . . .	273
Quadrature on the Sphere, . . . . .	276
Quadrature of Surfaces, . . . . .	279
Quadrature of the Paraboloid, . . . . .	280
Quadrature of the Ellipsoid, . . . . .	282
Integration over a Closed Surface, . . . . .	284
Examples, . . . . .	288

## CHAPTER X.

## INTEGRALS OF INERTIA.

Moments and Products of Inertia, . . . . .	291
Moments of Inertia for Parallel Axes, or Planes, . . . . .	292
Radius of Gyration, . . . . .	293
Uniform Rod and Rectangular Lamina, . . . . .	294

	PAGE
Rectangular Parallelepiped, . . . . .	295
Circular Plate and Cylinder, . . . . .	295
Right Cone, . . . . .	296
Elliptic Lamina, . . . . .	296
Sphere, . . . . .	297
Ellipsoid, . . . . .	298
Moments of Inertia for a Lamina, . . . . .	299
Momental Ellipse, . . . . .	300
Products of Inertia for a Lamina, . . . . .	301
Triangular Lamina and Prism, . . . . .	302
Momental Ellipse of a Triangular Lamina, . . . . .	304
Tetrahedron, . . . . .	304
Solid Ring, . . . . .	305
Principal Axes, . . . . .	307
Ellipsoid of Gyration, . . . . .	309
Momental Ellipsoid, . . . . .	309
Equimomental Cone, . . . . .	310
Examples, . . . . .	311

---

## CHAPTER XI.

## MULTIPLE INTEGRALS.

Double Integration, . . . . .	313
Change in Order of Integration, . . . . .	314
Dirichlet's Theorem, . . . . .	316
Transformation of Multiple Integrals, . . . . .	321
Transformation of Element of a Surface, . . . . .	324
General Transformation for $n$ Variables, . . . . .	325
Green's Theorem, . . . . .	326
Application to Spherical Harmonics, . . . . .	332
Laplace's Theorem on Expansion by Spherical Harmonics, . . . . .	338
Examples, . . . . .	342

## CHAPTER XII.

## ON MEAN VALUE AND PROBABILITY.

	PAGE
Mean Values, . . . . .	346
Case of one Independent Variable, . . . . .	347
Case of two or more Independent Variables, . . . . .	350
Probabilities, . . . . .	362
Buffon's Problem, . . . . .	365
Curve of Frequency, . . . . .	369
Errors of Observation, . . . . .	374
Questions of Probability Investigated from Geometrical Considerations, . . . . .	377
Lines drawn at Random, . . . . .	381
Application of Probability to the Determination of Definite Integrals, . . . . .	384
Examples, . . . . .	387

---

## CHAPTER XIII.

## ON FOURIER'S THEOREM.

Fourier's Theorem, . . . . .	392
Examples, . . . . .	399

---

## CHAPTER XIV.

## ON LINE AND SURFACE INTEGRALS.

Integration over a Plane Area, . . . . .	401
Stokes' Theorem, . . . . .	403
Example in Solid Harmonics, . . . . .	405
Lemma on Solid Angles, . . . . .	405
Differential Equations connecting Solid Angles, . . . . .	407
Neumann's Theorem, . . . . .	408
Integrals connected with the Theory of Attraction, . . . . .	409

## CHAPTER XV.

## THE SIGN OF SUBSTITUTION.

	PAGE
Sign of Substitution, . . . . .	413
Differentiation under the Sign of Substitution, . . . . .	414
Differentiation under the Sign of Integration, . . . . .	415
Differentiation for a Double Integral, . . . . .	416
Geometrical Representation, . . . . .	417
Case of a Closed Curvilinear Boundary, . . . . .	419
Transformation of $\iiint \left( \frac{du}{dx} + \frac{dv}{dy} + \frac{dw}{dz} \right) dx dy dz,$ . . . . .	421

---

## CHAPTER XVI.

## CALCULUS OF VARIATIONS.

## SINGLE INTEGRALS.

Definition of Variation $\delta y,$ . . . . .	425
Total Variations, . . . . .	427
Variation of a Definite Integral, . . . . .	428
Case of $V = f(x, y, \dot{y}, \ddot{y}),$ . . . . .	429
Maxima and Minima, . . . . .	430
Case of Geometrical Restrictions, . . . . .	433
$V$ a Function of $y, \dot{y}, \ddot{y}$ solely, . . . . .	434
Case where $V$ contains the Limits, . . . . .	435
Case of Two Dependent Variables, . . . . .	435
Relative Maxima and Minima . . . . .	437
Equations of Condition, . . . . .	438
Case of Arc being the Independent Variable, . . . . .	438
Maxima or Minima of $\int \mu ds,$ . . . . .	438
Lines of Shortest Length, . . . . .	443
The Brachystochrone, . . . . .	445
Minimum Surface of Revolution, . . . . .	449
Properties of the Catenary, . . . . .	452
Isoperimetrical Problem, . . . . .	455
General Transformation, . . . . .	456
Case of Two Dependent Variables, . . . . .	457
Condition of Integrability, . . . . .	458

	PAGE
Method of Differential Calculus, . . . . .	459
Conditions of Integrability for Two Dependent Variables, . . . . .	462
Criterion for Maxima and Minima, . . . . .	463
Application to $V = f(x, y, \dot{y})$ , . . . . .	463
Examples, . . . . .	465

---

## CHAPTER XVII.

## CALCULUS OF VARIATIONS.

## MULTIPLE INTEGRALS.

Variation of a Double Integral where $V$ is of the First Order, . . . . .	468
Case of a Fixed Boundary, . . . . .	469
Terms arising from Variation of Boundary, . . . . .	470
Complete Variation of $U$ , . . . . .	472
Maxima and Minima, . . . . .	472
Reduction of Boundary Relations, . . . . .	473
Surface of Minimum Area, . . . . .	475
Case of $\iint \mu dS$ , . . . . .	476
Relative Maxima and Minima, . . . . .	477
Case where $\Omega$ is reducible to a lower order, . . . . .	478
Variation of a double Integral of a Function of the Second Order, . . . . .	478
Conditions of Maxima and Minima, . . . . .	482
Case when terms of the highest Order in $\Omega$ disappear, . . . . .	483
Terms of the Third Order also disappear, . . . . .	484
General Form of $\Omega$ in this case, . . . . .	485
Variation of a Triple Integral, . . . . .	486
Maxima and Minima, . . . . .	488
Condition of Integrability when $V$ is of the First Order, . . . . .	490
Condition when $V$ is of the Second Order, . . . . .	491
General Transformation, . . . . .	492
Equation for Principal Radii of Curvature, . . . . .	494
Examples, . . . . .	498
NOTE, . . . . .	501
MISCELLANEOUS EXAMPLES, . . . . .	503

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The beginner is recommended to omit the following portions on the *first* reading:—Arts. 46, 49, 50, 72–76, 79–81, 89, 96–125, 132, 140, 142–147, 149, 158–167, 178, 180, 182, 189–193, Chapters x., xi., xii., xiii., xiv., xv., xvi.

6

## ERRATA.

p. 41, Ex. 6, for  $\frac{1}{2} \log \frac{x^2 - 2}{x^2 + 2}$  read  $\frac{1}{2} \log \frac{x - 2}{x + 2}$

,, Ex. 7, under the integral sign for  $x^2 - x - 1$  read  $x^2 + x - 1$

p. 86, line 8 from the bottom, for  $\int_0^{\frac{\pi}{2}}$  read  $\int_0^{\alpha}$

p. 96, Ex. 6, for  $(1 + x^2)^{\frac{1}{2}}$  under the integral sign, read  $(1 + x^2)^{\frac{1}{3}}$

p. 102, Ex. 6, in the Answer substitute  $\sqrt{x}$  for  $x$  in the denominator.

p. 168, Ex. 3, instead of  $\frac{\pi}{2\sqrt{2}}$  read  $\frac{\pi}{4\sqrt{2}}$

p. 222, line 3 from the bottom,

for  $\left\{ \left( \frac{dx}{d\phi} \right)^2 + \left( \frac{dy}{d\phi} \right)^2 \right\}$  read  $\left\{ \left( \frac{dx}{d\phi} \right)^2 + \left( \frac{dy}{d\phi} \right)^2 \right\}^{\frac{1}{2}}$

# INTEGRAL CALCULUS.

---

## CHAPTER I.

### ELEMENTARY FORMS OF INTEGRATION.

**1. Integration.**—The Integral Calculus is the inverse of the Differential. In the more simple case to which this treatise is principally limited, the object of the Integral Calculus is to find a function of a single variable when its differential is known.

Let the differential be represented by  $F(x) dx$ , then the function whose differential is  $F(x) dx$  is called its integral, and is represented by the notation

$$\int F(x) dx.$$

Thus, since in the notation of the Differential Calculus we have

$$df(x) = f'(x) dx,$$

the integral of  $f'(x) dx$  is denoted by  $f(x)$ ; i.e.

$$\int f'(x) dx = f(x).$$

Moreover, as  $f(x)$  and  $f(x) + C$  (where  $C$  is any arbitrary quantity that does not vary with  $x$ ) have the same differential, it follows, that to find the general form of the integral of  $f'(x) dx$  it is necessary to add an arbitrary constant to  $f(x)$ ; hence we obtain, as the general expression for the integral in question,

$$\int f'(x) dx = f(x) + C. \quad (1)$$

In the subsequent integrals the constant  $C$  will be omitted, as it can always be supplied when necessary. In the applications of the Integral Calculus the value of the constant is determined in each case by the data of the problem, as will be more fully explained subsequently.

The process of finding the *primitive function* or the *integral* of any given differential is called *integration*.

The expression  $F(x) dx$  under the sign of integration is called an *element* of the integral; it is also, in the limit, the increment of the primitive function when  $x$  is changed into  $x + dx$  (Diff. Calc., Art. 7); accordingly, the process of integration may be regarded as the finding the *sum*\* of an infinite number of such elements.

We shall postpone the consideration of Integration from this point of view, and shall commence with the treatment of Integration regarded as being the inverse of Differentiation.

**2. Elementary Integrals.**—A very slight acquaintance with the Differential Calculus will at once suggest the integrals of many differentials. We commence with the simplest cases, *an arbitrary constant being in all cases understood*.

On referring to the elementary forms of differentiation established in Chapter I. Diff. Calc. we may write down at once the following integrals:—

$$\int x^m dx = \frac{x^{m+1}}{m+1}. \quad \int \frac{dx}{x^m} = \frac{-1}{(m-1)x^{m-1}}. \quad (a)$$

$$\int \frac{dx}{x} = \log (x). \quad (b)$$

$$\int \sin mx dx = -\frac{\cos mx}{m}, \quad \int \cos mx dx = \frac{\sin mx}{m}. \quad (c)$$

$$\int \frac{dx}{\cos^2 x} = \tan x, \quad \int \frac{dx}{\sin^2 x} = -\cot x. \quad (d)$$

\* It was in this aspect that the process of integration was treated by Leibnitz, the symbol of integration  $\int$  being regarded as the initial letter of the word *sum*, in the same way as the symbol of differentiation  $d$  is the initial letter in the word *difference*.

$$\int \frac{dx}{\sqrt{a^2 - x^2}} = \sin^{-1} \frac{x}{a}. \quad (e)$$

$$\int \frac{dx}{a^2 + x^2} = \frac{1}{a} \tan^{-1} \frac{x}{a}. \quad (f)$$

$$\int e^x dx = e^x, \quad \int a^x dx = \frac{a^x}{\log a}. \quad (g)$$

These, together with two or three additional forms which shall be afterwards supplied, are called the *fundamental*\* or *elementary* integrals, to which all other forms,† that admit of integration in a finite number of terms, are ultimately reducible.

Many integrals are immediately reducible to one or other of these forms: a few simple examples are given for exercise.

## EXAMPLES.

$$1. \int \frac{dx}{x^2}. \quad \text{Ans. } -\frac{1}{x}.$$

$$2. \int \frac{dx}{\sqrt{x}}. \quad \text{,, } 2\sqrt{x}.$$

$$3. \int \tan x dx. \quad \text{,, } -\log(\cos x).$$

$$4. \int \frac{x^{n-1} dx}{a + bx^n}. \quad \text{,, } \frac{1}{nb} \log(a + bx^n).$$

$$5. \int \frac{xdx}{\sqrt{1 - x^2}}. \quad \text{,, } -\sqrt{1 - x^2}.$$

$$6. \int \frac{dx}{a + bx^2}. \quad \text{,, } \frac{1}{\sqrt{ab}} \tan^{-1} \left( x \sqrt{\frac{b}{a}} \right).$$

$$7. \int \frac{\sin \theta d\theta}{\cos^2 \theta}. \quad \text{,, } \sec \theta.$$

$$8. \int e^{ax} dx. \quad \text{,, } \frac{1}{a} e^{ax}.$$

\* The fundamental integrals are denoted in this chapter by the letters  $a, b, c$ , &c.; the other formulae by numerals 1, 2, 3, &c.

† Integrable forms are here understood those contained in the elementary portion of the Integral Calculus as involving the ordinary transcendental functions, and excluding what are styled Elliptic and Hyper-Elliptic functions.

$$9. \int \frac{dx}{x^3}. \quad \text{Ans. } -\frac{3}{x^2}.$$

$$10. \int \frac{dx}{x^{\frac{n-1}{n}}}. \quad \text{,, } nx^{\frac{1}{n}}.$$

$$11. \int \frac{dx}{x-a}. \quad \text{,, } \log(x-a).$$

3. **Integral of a Sum.**—It follows immediately from Art. 12, Diff. Calc., that the integral of the sum of any number of differentials is the sum of the integrals of each taken separately. For example—

$$\int (Ax^m + Bx^n + Cx^r + \&c.) dx = A \int x^m dx + B \int x^n dx + C \int x^r dx + \&c.$$

$$= \frac{Ax^{m+1}}{m+1} + \frac{Bx^{n+1}}{n+1} + \frac{Cx^{r+1}}{r+1} + \&c. \quad (2)$$

Hence we can write down immediately the integral of any function which is reducible to a finite number of terms consisting of powers of  $x$  multiplied by constant coefficients.

Again, to find the integrals of  $\cos^2 x dx$  and  $\sin^2 x dx$ ; here

$$\int \cos^2 x dx = \int \frac{1 + \cos 2x}{2} dx = \frac{x}{2} + \frac{\sin 2x}{4}, \quad (3)$$

$$\int \sin^2 x dx = \int \frac{1 - \cos 2x}{2} dx = \frac{x}{2} - \frac{\sin 2x}{4}. \quad (4)$$

A few examples are added for practice.

#### EXAMPLES.

$$1. \int \frac{(1 - x^2)^2 dx}{x}. \quad \text{Ans. } \log x - x^2 + \frac{x^4}{4}.$$

$$2. \int \frac{(x-2) dx}{x\sqrt{x}}. \quad \text{,, } 2\sqrt{x} + \frac{4}{\sqrt{x}}.$$

$$3. \int \tan^2 x dx = \int (\sec^2 x - 1) dx. \quad \text{,, } \tan x - x.$$

$$4. \int \cos mx \cos nx dx.$$

$$Ans. \frac{\sin(m+n)x}{2(m+n)} + \frac{\sin(m-n)x}{2(m-n)}.$$

$$5. \int \sin mx \sin nx dx.$$

$$", \frac{\sin(m-n)x}{2(m-n)} - \frac{\sin(m+n)x}{2(m+n)}.$$

$$6. \int \sqrt{\frac{a+x}{a-x}} dx.$$

$$", a \sin^{-1} \frac{x}{a} - \sqrt{a^2 - x^2}.$$

Multiply the numerator and denominator by  $\sqrt{a+x}$ .

$$7. \int x \sqrt{x+a} dx.$$

$$Ans. \frac{2}{5} (x+a)^{\frac{5}{2}} - \frac{2}{3} a (x+a)^{\frac{3}{2}}.$$

$$8. \frac{dx}{\sqrt{x+a} + \sqrt{x}}.$$

$$", \frac{2}{3a} \left( (x+a)^{\frac{3}{2}} - x^{\frac{3}{2}} \right).$$

Multiply the numerator and denominator by the complementary surd

$$\sqrt{x+a} - \sqrt{x}.$$

$$9. \int \frac{a+bx}{a'+b'x} dx.$$

$$Ans. \frac{bx}{b'} + \frac{ab' - ba'}{b'^2} \log(a' + b'x).$$

Here

$$\frac{a+bx}{a'+b'x} = \frac{b}{b'} + \frac{ab' - ba'}{b'(a' + b'x)}.$$

4. **Integration by Substitution.**—The integration of many expressions is immediately reducible to the elementary forms in Art. 2, by the substitution of a new variable.

For example, to integrate  $(a+bx)^n dx$ , we substitute  $z$  for  $a+bx$ ; then  $dz = bdx$ , and

$$\int (a+bx)^n dx = \int \frac{z^n dz}{b} = \frac{z^{n+1}}{(n+1)b} = \frac{(a+bx)^{n+1}}{(n+1)b}.$$

Again, to find

$$\int \frac{x^n dx}{(a+bx)^n},$$

we substitute  $z$  for  $a+bx$ , as before, when the integral becomes

$$\frac{1}{b^3} \int \frac{(z-a)^2 dz}{z^n},$$

$$or \quad -\frac{1}{b^3} \left\{ \frac{1}{(n-3)z^{n-3}} - \frac{2a}{(n-2)z^{n-2}} + \frac{a^2}{(n-1)z^{n-1}} \right\}.$$

On replacing  $z$  by  $a + bx$  the required integral can be expressed in terms of  $x$ .

The more general integral

$$\int \frac{x^m dx}{(a + bx)^n},$$

where  $m$  is any positive integer, by a like substitution becomes

$$\frac{1}{b^{m+1}} \int \frac{(z - a)^m dz}{z^n}.$$

Expanding by the binomial theorem and integrating each term separately the required integral can be immediately obtained.

Again, to find

$$\int \frac{dx}{x^m (a + bx)^n},$$

we substitute  $z$  for  $\frac{a}{x} + b$ , and it becomes

$$-\frac{1}{a^{m+n-1}} \int \frac{(z - b)^{m+n-2} dz}{z^n},$$

which is integrable, as before, whenever  $m + n$  is a positive integer greater than unity.

Thus, for example, we have

$$\int \frac{dx}{x(a + bx)} = \frac{1}{a} \log \left( \frac{x}{a + bx} \right).$$

It may be observed that all fractional expressions in which the numerator is the differential of the denominator can be immediately integrated.

For we obviously have, from (b),

$$\int \frac{f'(x) dx}{f(x)} = \log f(x). \quad (5)$$

EXAMPLES.

1.  $\int \frac{\sin x dx}{a + b \cos x}.$  ✓  $\text{Ans.} - \frac{\log(a + b \cos x)}{b}.$
2.  $\int \frac{x^3 dx}{\sqrt{a^8 - x^8}}.$  „  $\frac{1}{4} \sin^{-1} \left( \frac{x}{a} \right)^4.$
3.  $\int \log x \frac{dx}{x}.$  „  $\frac{1}{2} (\log x)^2.$
4.  $\int \frac{dx}{x \log x}.$  „  $\log(\log x).$
- ✓ 5.  $\int \frac{x^2 dx}{(a + bx)^3}.$  „  $\frac{\log(a + bx)}{b^3} + \frac{3a^2 + 4abx}{2b^3(a + bx)^2}.$
6.  $\int \frac{dx}{x^2(a + bx)^2}.$  „  $\frac{2b}{a^3} \log \frac{a + bx}{x} - \frac{a + 2bx}{a^2 x (a + bx)}.$
- ✓ 7.  $\int \frac{x dx}{(a + bx)^{\frac{3}{2}}}.$  „  $\frac{2(a + bx)^{\frac{1}{2}}}{3b^2} - \frac{2a(a + bx)^{\frac{1}{2}}}{b^2}.$
- ✓ 8.  $\int \frac{x dx}{(a + bx)^{\frac{5}{2}}}.$  „  $\frac{3(a + bx)^{\frac{3}{2}}}{5b^2} - \frac{3a(a + bx)^{\frac{3}{2}}}{2b^2}.$
9.  $\int \frac{dx}{x\sqrt{2ax - a^2}}.$  „  $\frac{2}{a} \tan^{-1} \sqrt{\frac{2x - a}{a}}.$

Assume  $2ax - a^2 = z^2$ , then  $adx = zdz$ , and the transformed integral is

$$\int \frac{2dz}{a^2 + z^2}.$$

5. Integration of  $\frac{dx}{x^2 - a^2}.$

Since  $\frac{1}{x^2 - a^2} = \frac{1}{2a} \left\{ \frac{1}{x - a} - \frac{1}{x + a} \right\},$

we get  $\int \frac{dx}{x^2 - a^2} = \frac{1}{2a} \log \frac{x - a}{x + a}. \quad (h)$

This is to be regarded as another fundamental formula additional to those contained in Art. 2.

*Integration of*  $\frac{dx}{a + 2bx + cx^2}$ .

In like manner, since

$$\frac{1}{(x - a)(x - \beta)} = \frac{1}{a - \beta} \left\{ \frac{1}{x - a} - \frac{1}{x - \beta} \right\},$$

we have  $\int \frac{dx}{(x - a)(x - \beta)} = \frac{1}{a - \beta} \log \frac{x - a}{x - \beta}$ . (6)

### EXAMPLES.

1.  $\int \frac{dx}{x^2 - 9}$ . *Ans.*  $\frac{1}{6} \log \frac{x - 3}{x + 3}$ .

2.  $\int \frac{dx}{(x + 2)(x - 3)}$ . "  $\frac{1}{5} \log \frac{x - 3}{x + 2}$ .

3.  $\int \frac{dx}{x^2 + 9x + 20}$ . "  $\log \frac{x + 4}{x + 5}$ .

4.  $\int \frac{dx}{x^2 - 3}$ . "  $\frac{1}{2\sqrt{3}} \log \frac{x - \sqrt{3}}{x + \sqrt{3}}$ .

6. **Integration of**  $\frac{dx}{a + 2bx + cx^2}$ .

This may be written in the form

$$\frac{cdx}{(cx + b)^2 + ac - b^2};$$

or, substituting  $z$  for  $cx + b$ ,

$$\frac{dz}{z^2 + ac - b^2}.$$

This is of the form (f) or (h) according as  $ac - b^2$  is positive or negative.

Hence, if  $ac > b^2$  we have

$$\int \frac{dx}{a + 2bx + cx^2} = \frac{1}{\sqrt{ac - b^2}} \tan^{-1} \frac{cx + b}{\sqrt{ac - b^2}}. \quad (7)$$

$$\text{Integration of } \frac{(p+qx)dx}{a+2bx+cx^2}.$$

9

If  $ac < b^2$ ,

$$\int \frac{dx}{a+2bx+cx^2} = \frac{1}{2\sqrt{b^2-ac}} \log \frac{cx+b-\sqrt{b^2-ac}}{cx+b+\sqrt{b^2-ac}}. \quad (8)$$

This latter form can be also immediately obtained from (6).

In the particular case when  $ac = b^2$ , the value of the integral is

$$\frac{-1}{cx+b}.$$

7. **Integration of**  $\frac{(p+qx)dx}{a+2bx+cx^2}$ .

This can at once be written in the form

$$\frac{q}{c} \frac{(b+cx)dx}{a+2bx+cx^2} + \frac{pc-qb}{c} \frac{dx}{a+2bx+cx^2}.$$

The integral of the first term is evidently

$$\frac{q}{2c} \log (a+2bx+cx^2),$$

while the integral of the second is obtained by the preceding Article.

For example, let it be proposed to integrate

$$\frac{(x \cos \theta - 1)dx}{x^2 - 2x \cos \theta + 1}.$$

The expression becomes in this case

$$\frac{\cos \theta (x - \cos \theta)dx}{x^2 - 2x \cos \theta + 1} - \frac{\sin^2 \theta dx}{(x - \cos \theta)^2 + \sin^2 \theta};$$

hence

$$\begin{aligned} \int \frac{(x \cos \theta - 1)dx}{x^2 - 2x \cos \theta + 1} &= \frac{\cos \theta}{2} \log (x^2 - 2x \cos \theta + 1) \\ &\quad - \sin \theta \tan^{-1} \frac{x - \cos \theta}{\sin \theta}. \end{aligned} \quad (9)$$

When the roots of  $a + 2bx + cx^2$  are real, it will be found simpler to integrate the expression by its decomposition into partial fractions. A general discussion of this method will be given in the next chapter.

## EXAMPLES.

1. 
$$\int \frac{dx}{1+x+x^2}.$$

Ans. 
$$\frac{2}{\sqrt{3}} \tan^{-1} \left( \frac{2x+1}{\sqrt{3}} \right).$$

2. 
$$\int \frac{dx}{1+x-x^2}.$$

" 
$$\frac{1}{\sqrt{5}} \log \left( \frac{2x-1+\sqrt{5}}{2x-1-\sqrt{5}} \right).$$

3. 
$$\int \frac{dx}{x^2+x-12}.$$

" 
$$\frac{1}{7} \log \left( \frac{x-3}{x+4} \right).$$

4. 
$$\int \frac{dx}{x^2+4x+5}.$$

" 
$$\tan^{-1}(x+2).$$

5. 
$$\int \frac{dx}{5x^2+4x+8}.$$

" 
$$\frac{1}{6} \tan^{-1} \frac{5x+2}{6}.$$

6. 
$$\int \frac{x^2 dx}{1-x^6}.$$

" 
$$\frac{1}{6} \log \left( \frac{1+x^3}{1-x^3} \right).$$

7. 
$$\int \frac{x^8 dx}{x^8-x^4-6}.$$

" 
$$\frac{1}{20} \log \left( \frac{x^4-3}{x^4+2} \right).$$

8. 
$$\int \frac{dx}{1-2x+2x^2}.$$

" 
$$\tan^{-1}(2x-1).$$

8. **Exponential Value for  $\sin \theta$  and  $\cos \theta$ .**—By comparing the fundamental formulæ (f) and (h) the well-known exponential forms for  $\sin \theta$  and  $\cos \theta$  can be immediately deduced, as follows:

Substitute  $z\sqrt{-1}$  for  $x$  in both sides of the equation

$$\int \frac{dx}{1-x^2} = \frac{1}{2} \log \left( \frac{1+x}{1-x} \right) + \text{const.};$$

and we get

$$\int \frac{dz}{1+z^2} = \frac{1}{2\sqrt{-1}} \log \left( \frac{1+z\sqrt{-1}}{1-z\sqrt{-1}} \right) + \text{const.};$$

$$\text{or, by (f), } \tan^{-1} z = \frac{1}{2\sqrt{-1}} \log \left( \frac{1 + z\sqrt{-1}}{1 - z\sqrt{-1}} \right) + \text{const.}$$

Now, let  $z = \tan \theta$ , and this becomes.

$$\theta = \frac{1}{2\sqrt{-1}} \log \left( \frac{1 + \sqrt{-1} \tan \theta}{1 - \sqrt{-1} \tan \theta} \right) + \text{const.}$$

When  $\theta = 0$ , this reduces to  $0 = \text{const.}$

$$\text{Hence } e^{i\theta\sqrt{-1}} = \frac{\cos \theta + \sqrt{-1} \sin \theta}{\cos \theta - \sqrt{-1} \sin \theta} = (\cos \theta + \sqrt{-1} \sin \theta)^2,$$

$$\text{or } e^{i\theta\sqrt{-1}} = \cos \theta + \sqrt{-1} \sin \theta,$$

$$e^{-i\theta\sqrt{-1}} = \cos \theta - \sqrt{-1} \sin \theta.$$

### 9. Integration of

$$\frac{dx}{\sqrt{x^2 \pm a^2}}.$$

Assume\*

$$\sqrt{x^2 \pm a^2} = z - x,$$

then we get

$$\pm a^2 = z^2 - 2xz,$$

if logarithmically

$$\text{hence } (z - x) dz = z dx, \text{ or } \frac{dx}{z - x} = \frac{dz}{z};$$

$$\therefore \int \frac{dx}{\sqrt{x^2 \pm a^2}} = \int \frac{dz}{z} = \log z = \log (x + \sqrt{x^2 \pm a^2}). \quad (i)$$

This is to be regarded as another fundamental form.

By aid of this and of form (e) it is evident that all expressions of the shape

$$\frac{dx}{\sqrt{a + 2bx + cx^2}}$$

\* The student will better understand the propriety of this assumption after reading a subsequent chapter, in which a general transformation, of which the above is a particular case, will be given.

can be immediately integrated;  $a, b, c$ , being any constants, positive or negative.

The preceding integration evidently depends on formula (i), or (e), according as the coefficient of  $x^2$  is positive or negative.

Thus, we have

$$\int \frac{dx}{\sqrt{a + 2bx + cx^2}} = \frac{1}{\sqrt{c}} \log \left( cx + b + \sqrt{c(a + 2bx + cx^2)} \right), \quad (10)$$

$$\int \frac{dx}{\sqrt{a + 2bx - cx^2}} = \frac{1}{\sqrt{c}} \sin^{-1} \left( \frac{cx - b}{\sqrt{ac + b^2}} \right), \quad (11)$$

$c$  being regarded as positive in both integrals.

When the factors in the quadratic  $a + 2bx + cx^2$  are real, and given, the preceding integral can be exhibited in a simpler form by the method of the two next Articles.

10. Integration of  $\frac{dx}{\sqrt{(x - a)(x - \beta)}}$ .

Assume  $x - a = z^2$ , then  $dx = 2zdz$ ;

$$\therefore \frac{dx}{\sqrt{x - a}} = 2dz;$$

hence  $\frac{dx}{\sqrt{(x - a)(x - \beta)}} = \frac{2dz}{\sqrt{z^2 + a - \beta}};$

$$\begin{aligned} \therefore \int \frac{dx}{\sqrt{(x - a)(x - \beta)}} &= 2 \int \frac{dz}{\sqrt{z^2 + a - \beta}} \\ &= 2 \log (z + \sqrt{z^2 + a - \beta}), \text{ by (i),} \end{aligned}$$

or  $\int \frac{dx}{\sqrt{(x - a)(x - \beta)}} = 2 \log (\sqrt{x - a} + \sqrt{x - \beta}). \quad (12)$

11. **Integration of**  $\frac{dx}{\sqrt{(x-a)(\beta-x)}}$ .

As before, assume  $x-a = z^2$ , and we get

$$\frac{dx}{\sqrt{(x-a)(\beta-x)}} = \frac{2dz}{\sqrt{\beta-a-z^2}}.$$

Hence, by (e),

$$\int \frac{dx}{\sqrt{(x-a)(\beta-x)}} = 2 \sin^{-1} \sqrt{\frac{x-a}{\beta-a}}. \quad (13)$$

Otherwise, thus :

assume  $x = a \cos^2 \theta + \beta \sin^2 \theta$ ,

then  $\beta - x = (\beta - a) \cos^2 \theta$ ,  $x - a = (\beta - a) \sin^2 \theta$ ,

and  $dx = 2(\beta - a) \sin \theta \cos \theta d\theta$ ;

hence  $\frac{dx}{\sqrt{(x-a)(\beta-x)}} = 2d\theta$ ;

$$\therefore \int \frac{dx}{\sqrt{(x-a)(\beta-x)}} = 2\theta = 2 \sin^{-1} \sqrt{\frac{x-a}{\beta-a}}.$$

12. Again, as in Art. 7, the expression

$$\frac{(p+qx)dx}{\sqrt{a+2bx+cx^2}}$$

can be transformed into

$$\frac{q}{c} \frac{(b+cx)dx}{\sqrt{a+2bx+cx^2}} + \frac{pc-qb}{c} \frac{dx}{\sqrt{a+2bx+cx^2}},$$

and is, accordingly, immediately integrable by aid of the preceding formulæ.

## EXAMPLES.

1.  $\int \frac{dx}{\sqrt{x^2 - ax}}.$  *Ans.*  $2 \log(\sqrt{x} + \sqrt{x-a}).$

2.  $\int \frac{dx}{\sqrt{ax - x^2}}.$  "  $2 \sin^{-1} \sqrt{\frac{x}{a}}.$

3.  $\int \frac{dx}{\sqrt{3x - x^2 - 2}}.$  "  $2 \sin^{-1} \sqrt{x-1}.$

4.  $\int \frac{dx}{\sqrt{1+x+x^2}}.$  "  $\log(2x+1+2\sqrt{1+x+x^2}).$

5.  $\int \frac{\sqrt{x+a}}{\sqrt{x+b}} dx = \sqrt{(x+a)(x+b)} + (a-b) \log(\sqrt{x+a} + \sqrt{x+b}).$

Multiply the numerator and denominator by  $\sqrt{x+a}.$

6.  $\int \frac{dx}{\sqrt{1-x-x^2}}.$  *Ans.*  $\sin^{-1} \frac{2x+1}{\sqrt{5}}.$

7.  $\int \frac{dx}{\sqrt{(a+bx)(a'-bx')}}.$  "  $\frac{2}{\sqrt{bb'}} \sin^{-1} \sqrt{\frac{b'(a+bx)}{ab'+ba'}}.$

8. Show, as in Art. 8, by comparing the fundamental formulæ (e) and (i), that

$$\cos \theta + \sqrt{-1} \sin \theta = e^{\theta\sqrt{-1}}.$$

13. **Integration of**  $\frac{dx}{(x-p)\sqrt{a+2bx+cx^2}}.$

Let  $x-p = \frac{1}{z}$ , then

$$\frac{dx}{x-p} = -\frac{dz}{z} \text{ and } x = \frac{1+pz}{z}.$$

$$\begin{aligned} \therefore \int \frac{dx}{(x-p)\sqrt{a+2bx+cx^2}} &= \int \frac{-dz}{\sqrt{az^2 + 2bz(1+pz) + c(1+pz)^2}} \\ &= - \int \frac{dz}{\sqrt{a'z^2 + 2b'z + c'z^2}}; \end{aligned}$$

where  $a' = c, b' = b + cp, c' = a + 2bp + cp^2.$

The integral consequently is reducible to (10), or (11), according as  $c'$  is positive or negative.

EXAMPLES.

1.  $\int \frac{dx}{x\sqrt{x^2 - a^2}}$ .

Ans.  $\frac{1}{a} \cos^{-1} \left( \frac{a}{x} \right)$ .

2.  $\int \frac{dx}{x\sqrt{x^2 + 1}}$ .

„  $\log \left( \frac{\sqrt{1+x^2} - 1}{x} \right)$ .

3.  $\int \frac{dx}{(1+x)\sqrt{1-x^2}}$ .

„  $-\sqrt{\frac{1-x}{1+x}}$ .

4.  $\int \frac{dx}{x\sqrt{a+2bx+cx^2}}$ . Ans.  $\frac{1}{\sqrt{a}} \log \left( \frac{x}{a+bx+\sqrt{a\sqrt{a+2bx+cx^2}}} \right)$ .

5.  $\int \frac{dx}{x\sqrt{cx^2+2bx-a}}$ .

Ans.  $\frac{1}{\sqrt{a}} \sin^{-1} \left( \frac{bx-a}{x\sqrt{ac+b^2}} \right)$ .

6.  $\int \frac{dx}{(1+x)\sqrt{1+2x-x^2}}$ .

„  $\frac{1}{\sqrt{2}} \sin^{-1} \left( \frac{x\sqrt{2}}{1+x} \right)$ .

7.  $\int \frac{dx}{(1+x)\sqrt{1+x-x^2}}$ .

„  $\sin^{-1} \left( \frac{1+3x}{(1+x)\sqrt{5}} \right)$ .

14. The transformation adopted in the last Article is one of frequent application in Integration. It is, accordingly, worthy of the student's notice that when we change  $x$  into  $\frac{1}{z}$  we have  $\frac{dx}{x} = -\frac{dz}{z}$ ; and, in general, if  $x^n = \frac{1}{z}$ ,  $\frac{dx}{x} = -\frac{dz}{nz}$ .

These results follow immediately from *logarithmic* differentiation, and often furnish a clue as to when an Integration is facilitated by such a transformation.

For example, let us take the integral

$$\int \frac{dx}{x(a+bx^n)}.$$

Here, the substitution of  $\frac{1}{z}$  for  $x^n$  gives

$$-\frac{1}{n} \int \frac{dz}{az+b}.$$

The value of which is obviously

$$-\frac{1}{na} \log (ax + b), \text{ or } \frac{1}{na} \log \left( \frac{x^n}{a + bx^n} \right).$$

Again, to integrate

$$\frac{dx}{x \sqrt{ax^n + b}},$$

assume  $x^n = \frac{1}{z^2}$ , and the transformed integral is

$$-\frac{2}{n} \int \frac{dz}{\sqrt{a + bz^2}}.$$

This is found by (e) or (i) according as  $b$  is positive or negative.

**15. Integration of**  $\frac{dx}{(a + cx^2)^{\frac{1}{2}}}.$

Let  $x = \frac{1}{z}$  and the expression becomes

$$-\frac{z/dz}{(az^2 + c)^{\frac{1}{2}}};$$

the integral of this is evidently

$$\frac{1}{a(az^2 + c)^{\frac{1}{2}}}, \text{ or } \frac{x}{a(a + cx^2)^{\frac{1}{2}}}.$$

Hence  $\int \frac{dx}{(a + cx^2)^{\frac{1}{2}}} = \frac{x}{a(a + cx^2)^{\frac{1}{2}}}.$  (14)

**16. To find the integral of**

$$\frac{dx}{(a + 2bx + cx^2)^{\frac{1}{2}}}.$$

This can be written in the form

$$\frac{c^{\frac{3}{2}} dx}{\{ac - b^2 + (cx + b)^2\}^{\frac{1}{2}}},$$

which is reduced to the preceding on making  $cx + b = z.$

Hence, we get

$$\int \frac{dx}{(a + 2bx + cx^2)^{\frac{1}{2}}} = \frac{b + cx}{(ac - b^2)(a + 2bx + cx^2)^{\frac{1}{2}}}. \quad (15)$$

Again, if we substitute  $\frac{1}{z}$  for  $x$ ,

$$\frac{xdx}{(a + 2bx + cx^2)^{\frac{1}{2}}} \text{ becomes } \frac{-dz}{(az^2 + 2bz + c)^{\frac{1}{2}}},$$

and, accordingly, we have

$$\int \frac{xdx}{(a + 2bx + cx^2)^{\frac{1}{2}}} = - \frac{a + bx}{(ac - b^2)(a + 2bx + cx^2)^{\frac{1}{2}}}.$$

Combining these two results, we get

$$\int \frac{(p + qx) dx}{(a + 2bx + cx^2)^{\frac{1}{2}}} = \frac{bp - aq + (cp - bq)x}{(ac - b^2)(a + 2bx + cx^2)^{\frac{1}{2}}}. \quad (16)$$

### 17. Integration of $\frac{d\theta}{\sin \theta}$ and $\frac{d\theta}{\cos \theta}$ .

It will be shown in a subsequent chapter that the integration of a numerous class of expressions is reducible either to that of  $\frac{d\theta}{\sin \theta}$ , or of  $\frac{d\theta}{\cos \theta}$ : we accordingly propose to investigate their values here. For this purpose we shall first find the integral of  $\frac{d\theta}{\sin \theta \cos \theta}$ .

$$\text{Here } \frac{d\theta}{\sin \theta \cos \theta} = \frac{\frac{d\theta}{\cos^2 \theta}}{\frac{\tan \theta}{\cos \theta}} = \frac{d(\tan \theta)}{\tan \theta};$$

$$\text{consequently } \int \frac{d\theta}{\sin \theta \cos \theta} = \log(\tan \theta). \quad (17)$$

Next, to find the integral of

$$\frac{d\theta}{\sin \theta}.$$

This can be written in the form

$$\frac{d\theta}{2 \sin \frac{\theta}{2} \cos \frac{\theta}{2}},$$

and, by the preceding, we have

$$\int \frac{d\theta}{\sin \theta} = \log \left( \tan \frac{\theta}{2} \right). \quad (18)$$

Again, to determine the integral of  $\frac{d\theta}{\cos \theta}$  we substitute  $\frac{\pi}{2} - \phi$  for  $\theta$ , and the expression becomes  $\frac{-d\phi}{\sin \phi}$  : the integral of this, by (18), is

$$-\log \left( \tan \frac{\phi}{2} \right), \text{ or } \log \left( \cot \frac{\phi}{2} \right), \text{ or } \log \left\{ \cot \left( \frac{\pi}{4} - \frac{\theta}{2} \right) \right\}.$$

Accordingly, we have

$$\int \frac{d\theta}{\cos \theta} = \log \left\{ \cot \left( \frac{\pi}{4} - \frac{\theta}{2} \right) \right\} = \log \left\{ \tan \left( \frac{\pi}{4} + \frac{\theta}{2} \right) \right\}. \quad (19)$$

This integral can also be easily obtained otherwise, as follows :—

$$\int \frac{d\theta}{\cos \theta} = \int \frac{\cos \theta d\theta}{\cos^2 \theta} = \int \frac{d(\sin \theta)}{\cos^2 \theta}.$$

Let  $\sin \theta = x$ , and the integral becomes

$$\int \frac{dx}{1 - x^2} = \frac{1}{2} \log \left( \frac{1+x}{1-x} \right) = \frac{1}{2} \log \left( \frac{1+\sin \theta}{1-\sin \theta} \right).$$

The student will find no difficulty in identifying this result with that contained in (19).

18. Integration of  $\frac{d\theta}{a + b \cos \theta}$ .

This can be immediately written in the form

$$\frac{d\theta}{(a + b) \cos^2 \frac{\theta}{2} + (a - b) \sin^2 \frac{\theta}{2}}$$

$$\sec^2 \frac{\theta}{2} d\theta$$

or  $\frac{\sec^2 \frac{\theta}{2} d\theta}{a + b + (a - b) \tan^2 \frac{\theta}{2}}$ :

on substituting  $z$  for  $\tan \frac{\theta}{2}$  this becomes

$$\frac{2dz}{a + b + (a - b)z^2}$$

Consequently, by Ex. 6, Art. 2, we get

(1) when  $a > b$ ,

$$\int \frac{d\theta}{a + b \cos \theta} = \frac{2}{\sqrt{a^2 - b^2}} \tan^{-1} \left\{ \sqrt{\frac{a - b}{a + b}} \tan \frac{\theta}{2} \right\}. \quad (20)$$

(2) when  $a < b$ , by formula (h),

$$\int \frac{d\theta}{a + b \cos \theta} = \frac{1}{\sqrt{b^2 - a^2}} \log \left\{ \frac{\sqrt{b + a} + \sqrt{b - a} \tan \frac{\theta}{2}}{\sqrt{b + a} - \sqrt{b - a} \tan \frac{\theta}{2}} \right\}. \quad (21)$$

If we assume  $a = b \cos a$ , we deduce immediately from the latter integral

$$\int \frac{d\theta}{\cos a + \cos \theta} = \frac{1}{\sin a} \log \left\{ \frac{\cos \frac{a - \theta}{2}}{\cos \frac{a + \theta}{2}} \right\}.$$

The integral in (20) can be transformed into

$$\int \frac{d\theta}{a + b \cos \theta} = \frac{1}{\sqrt{a^2 - b^2}} \cos^{-1} \left\{ \frac{b + a \cos \theta}{a + b \cos \theta} \right\}.$$

In a subsequent chapter a more general class of integrals which depend on the preceding will be discussed.

19. **Methods of Integration.**—The reduction of the integration of functions to one or other of the fundamental formulæ is usually effected by one of the following methods:—

- 1 (1). Transformation by the introduction of a new variable.
- (2). Integration by parts.
- (3). Integration by rationalization.
- (4). Successive reduction.
- (5). Decomposition into partial fractions.

Two or more of these methods can often be combined with advantage. It may also be observed that these different methods are not essentially distinct: thus the method of rationalization is a case of the first method, as it is always effected by the substitution of a new variable.

We proceed to illustrate these processes by a few elementary examples, reserving their fuller treatment for subsequent consideration.

20. **Integration by Transformation.**—Examples of this method have been already given in Arts. 4, 10, &c. One or two more cases are here added.

Ex. 1. To find the integral of  $\sin^2 x \cos^3 x \, dx$ .

Let  $\sin x = y$ , and the transformed integral is

$$\int y^2 (1 - y^2) \, dy = \int y^2 \, dy - \int y^4 \, dy = \frac{y^3}{3} - \frac{y^5}{5} = \frac{\sin^3 x}{3} - \frac{\sin^5 x}{5}.$$

Ex. 2. 
$$\int \frac{e^x \, dx}{1 + e^{2x}}.$$

Let  $e^x = y$ , and we get

$$\int \frac{dy}{1 + y^2} = \tan^{-1} y = \tan^{-1}(e^x).$$

21. **Integration by Parts.**—We have seen in Art. 13, Diff. Calc., that

hence we get

$$d(uv) = u \, dv + v \, du;$$

or

$$uv = \int u \, dv + \int v \, du,$$

$$\int u \, dv = uv - \int v \, du$$

(22)

Consequently the integration of an expression of the form  $udv$  can always be made to depend on that of the expression  $rdu$ .

The advantage of this method will be best exhibited by applying it to a few elementary cases.

Ex. 1. 
$$\int \sin^{-1} x \, dx = x \sin^{-1} x - \int \frac{x \, dx}{\sqrt{1-x^2}} \quad \left( \text{u.d. } \int \frac{du}{\sqrt{1-u^2}} \right)$$

$$= x \sin^{-1} x + \sqrt{1-x^2}.$$

Ex. 2. 
$$\int x \log x \, dx.$$

Let  $u = \log x, v = \frac{x^2}{2}$ , and we get

$$\int x \log x \, dx = \frac{x^2 \log x}{2} - \frac{1}{2} \int x^2 \frac{dx}{x} = \frac{x^2}{2} \left( \log x - \frac{1}{2} \right).$$

Ex. 3. 
$$\int e^{ax} x \, dx.$$

Let  $x = u, \frac{e^{ax}}{a} = v$ , then

$$\int x e^{ax} \, dx = \frac{x e^{ax}}{a} - \int \frac{e^{ax}}{a} \, dx = \frac{e^{ax}}{a} \left( x - \frac{1}{a} \right).$$

Ex. 4. 
$$\int e^{ax} \sin mx \, dx.$$

Let  $\sin mx = u, \frac{e^{ax}}{a} = v$ , then

$$\int e^{ax} \sin mx \, dx = \frac{e^{ax} \sin mx}{a} - \frac{m}{a} \int e^{ax} \cos mx \, dx.$$

Similarly,  $\int e^{ax} \cos mx \, dx = \frac{e^{ax} \cos mx}{a} + \frac{m}{a} \int e^{ax} \sin mx \, dx.$

Substituting, and solving for  $\int e^{ax} \sin mx dx$ , we obtain

$$\int e^{ax} \sin mx dx = \frac{e^{ax} (a \sin mx - m \cos mx)}{a^2 + m^2}. \quad (23)$$

In like manner we get

$$\int e^{ax} \cos mx dx = \frac{e^{ax} (a \cos mx + m \sin mx)}{a^2 + m^2}. \quad (24)$$

Ex. 5.

$$\int \sqrt{a^2 + x^2} dx.$$

Let

$$\sqrt{a^2 + x^2} = u, \text{ then}$$

$$\int \sqrt{a^2 + x^2} dx = x \sqrt{a^2 + x^2} - \int \frac{x^2 dx}{\sqrt{a^2 + x^2}};$$

$$\text{also } \int \sqrt{a^2 + x^2} dx = a^2 \int \frac{dx}{\sqrt{a^2 + x^2}} + \int \frac{x^2 dx}{\sqrt{a^2 + x^2}}.$$

Hence, by addition, and dividing by 2,

$$\int \sqrt{a^2 + x^2} dx = \frac{x \sqrt{a^2 + x^2}}{2} + \frac{a^2}{2} \log (x + \sqrt{a^2 + x^2}). \quad (25)$$

Ex. 6.  $\int \log (x + \sqrt{x^2 \pm a^2}) dx.$

Here  $\int \log (x + \sqrt{x^2 \pm a^2}) dx = x \log (x + \sqrt{x^2 \pm a^2})$ .

$$- \int \frac{x dx}{\sqrt{x^2 \pm a^2}}$$

$$= x \log (x + \sqrt{x^2 \pm a^2}) - \sqrt{x^2 \pm a^2}. \quad (26)$$

## EXAMPLES.

1.  $\int x^n \log x \, dx.$

Ans.  $\frac{x^{n+1}}{n+1} \left( \log x - \frac{1}{n+1} \right).$

2.  $\int \tan^{-1} x \, dx.$

,,  $x \tan^{-1} x - \frac{1}{2} \log(1+x^2).$

3.  $\int x \tan^2 x \, dx.$

,,  $x \tan x + \log(\cos x) - \frac{x^2}{2}.$

4.  $\int \frac{\sin^{-1} x \, dx}{(1-x^2)^{\frac{3}{2}}}.$

,,  $\frac{x \sin^{-1} x}{\sqrt{1-x^2}} + \frac{1}{2} \log(1-x^2).$

Let  $x = \sin y$ , and the integral becomes

$$\int dy \frac{y}{\cos^2 y} = \int y \, d(\tan y) = y \tan y + \log(\cos y).$$

5.  $\int e^x x^2 \, dx.$  X

,,  $e^x(x^2 - 2x + 2).$

**22. Integration by Rationalization.**—By a proper assumption of a new variable we can, in many cases, change an irrational expression into a rational one, and thus integrate it. An instance of this method has been given in Art. 9.

The simplest case is where the quantity under the radical sign is of the form  $a + bx$ : such expressions admit of being easily integrated.

For example, let the expression be of the form

$$\frac{x^n \, dx}{(a+bx)^{\frac{1}{2}}},$$

where  $n$  is a positive integer. Suppose  $a+bx = z^2$ , then

$$dx = \frac{2z \, dz}{b}, \text{ and } x = \frac{z^2 - a}{b}:$$

making these substitutions, the expression becomes

$$\frac{2(z^2 - a)^n \, dz}{b^{n+1}}.$$

Expanding by the Binomial Theorem and integrating the terms separately, the required integral can be immediately found. It is also evident that the expression  $\frac{x^n dx}{(a + bx)^{\frac{p}{q}}}$  can be integrated by a similar substitution.

23. **Integration of**  $\frac{x^{2m+1} dx}{(a + cx^2)^{\frac{1}{2}}}$ ,

where  $m$  is a positive integer.

Let  $a + cx^2 = z^2$ ; then  $x dx = \frac{z dz}{c}$ ,  $x^2 = \frac{z^2 - a}{c}$ ; and the transformed expression is

$$\frac{(z^2 - a)^m dz}{c^{m+1}}.$$

This can be integrated as before. It can be easily seen that the expression  $\frac{x^{2m+1} dx}{(a + cx^2)^{\frac{1}{2}}}$  is immediately integrable by the same substitution.

A considerable number of integrals will be found to be reducible to this form: a few examples are given for illustration.

#### EXAMPLES.

1.  $\int \frac{x^3 dx}{\sqrt{1 - x^2}}.$  *Ans.*  $\frac{(1 - x^2)^{\frac{3}{2}}}{3} - (1 - x^2)^{\frac{1}{2}}.$

2.  $\int \frac{x^5 dx}{\sqrt{1 + x^2}}.$  "  $\frac{z^5}{5} - \frac{2z^3}{3} + z$ ; where  $z = \sqrt{1 + x^2}.$

3.  $\int \frac{x^3 dx}{(a + cx^2)^{\frac{5}{2}}}.$  "  $\frac{-(2a + 3cx^2)}{3c^2(a + cx^2)^{\frac{3}{2}}}.$

24. It is easily seen that the more general expression

$$\frac{f(x^2) x dx}{\sqrt{a^2 + cx^2}},$$

where  $f(x^2)$  is a rational algebraic function, can be rationalized by the same transformation.

Again, if we make  $x = \frac{1}{z}$  the expression

$$\frac{dx}{x^n(a + cx^2)^{\frac{1}{2}}}$$

transforms into

$$\frac{z^{n-1} dz}{(az^3 + c)^{\frac{1}{2}}};$$

and is reducible to the preceding form when  $n$  is an *even positive* integer.

Hence, in this case, the expression can be easily integrated by the substitution  $(a + cx^2)^{\frac{1}{2}} = xy$ .

It will be subsequently seen that the integrals discussed in this and the preceding Articles are cases of a more general form, which is integrable by a similar transformation.

#### EXAMPLES.

1.  $\int \frac{dx}{x^4(x^2 - 1)^{\frac{1}{2}}}$ .

Ans.  $\frac{\sqrt{x^2 - 1}}{3x^3} (2x^2 + 1)$ .

2.  $\int \frac{dx}{x^6(1 + x^2)^{\frac{1}{2}}}$ .

"  $- \frac{(x^2 + 1)^{\frac{1}{2}}}{15x} \left\{ 8 - \frac{4}{x^2} + \frac{3}{x^4} \right\}$ .

#### 25. Integration of $\frac{dx}{(A + Cx^2)(a + cx^2)^{\frac{1}{2}}}$ .

As in the preceding Article, let  $(a + cx^2)^{\frac{1}{2}} = xz$ , or  $a + cx^2 = x^2 z^2$ : then, if we differentiate and divide by  $2x$ , we shall have

$$c dx = z^2 dx + xz dz, \text{ or } \frac{dx}{xz} = \frac{dz}{c - z^2},$$

$$\therefore \frac{dx}{(a + cx^2)^{\frac{1}{2}}} = \frac{dz}{c - z^2}; \quad (27)$$

and the transformed expression evidently is

$$\frac{dz}{(Ac - Ca) - Az^2}.$$

This is reducible to the fundamental formula (h), or (f), according as  $\frac{Ac - Ca}{A}$  is positive or negative.

Hence, (1) if  $\frac{Ac - Ca}{A} > 0$ , the integral is easily seen to be

$$\frac{1}{2\sqrt{A(Ac - Ca)}} \log \left( \frac{\sqrt{A(a + cx^2)} + x\sqrt{Ac - Ca}}{\sqrt{A(a + cx^2)} - x\sqrt{Ac - Ca}} \right). \quad (28)$$

(2). If  $\frac{Ac - Ca}{A} < 0$ , the value of the integral is

$$\frac{1}{\sqrt{A(Ca - Ac)}} \tan^{-1} \frac{x\sqrt{Ca - Ac}}{\sqrt{A(a + cx^2)}}. \quad (29)$$

### EXAMPLES.

$$1. \int \frac{dx}{(1+x^2)(1-x^2)^{\frac{1}{2}}}. \quad \text{Ans. } \frac{1}{\sqrt{2}} \tan^{-1} \left( \frac{x\sqrt{2}}{\sqrt{1-x^2}} \right).$$

$$2. \int \frac{dx}{(3+4x^2)(4-3x^2)^{\frac{1}{2}}}. \quad " \quad \frac{1}{5\sqrt{3}} \tan^{-1} \left( \frac{5x}{\sqrt{12-9x^2}} \right).$$

$$3. \int \frac{dx}{(4-3x^2)(3+4x^2)^{\frac{1}{2}}}. \quad " \quad \frac{1}{20} \log \frac{2\sqrt{3+4x^2} + 5x}{2\sqrt{3+4x^2} - 5x}.$$

**26. Rationalization by Trigonometrical Transformation.**—It can be easily seen, as in Art. 6, that the irrational expression  $\sqrt{a + 2bx + cx^2}$  can be always transformed into one or other of the following shapes:

$$(1) (a^2 - z^2)^{\frac{1}{2}}, \quad (2) (a^2 + z^2)^{\frac{1}{2}}, \quad (3) (z^2 - a^2)^{\frac{1}{2}};$$

neglecting a constant multiplier in each case.

Accordingly, any algebraic expression in  $x$  which contains one, and but one, surd of a quadratic form, is capable of being rationalized by a trigonometrical transformation: the first of the forms, by making  $z = a \sin \theta$ ; the second, by  $z = a \tan \theta$ ; and the third, by  $z = a \sec \theta$ .

For, (1) when  $z = a \sin \theta$ , we have  $(a^2 - z^2)^{\frac{1}{2}} = a \cos \theta$ , and  $dz = a \cos \theta d\theta$ .

(2). When  $z = a \tan \theta, \dots (a^2 + z^2)^{\frac{1}{2}} = a \sec \theta$ , and  $dz = \frac{a d\theta}{\cos^2 \theta}$ .

(3). When  $z = a \sec \theta, \dots (z^2 - a^2)^{\frac{1}{2}} = a \tan \theta$ , and  $dz = a \tan \theta \sec \theta d\theta$ .

A number of integrations can be performed by aid of one or other of these transformations. In a subsequent place this class of transformations will be again considered. For the present we shall merely illustrate the method by a few examples.

### EXAMPLES.

1.  $\int \frac{dx}{x^2(1+x^2)^{\frac{1}{2}}}$ .

Let  $x = \tan \theta$ , and the integral becomes

$$\int \frac{\cos \theta d\theta}{\sin^2 \theta} = \int \frac{d(\sin \theta)}{\sin^2 \theta} = -\frac{1}{\sin \theta} = -\frac{\sqrt{1+x^2}}{x}.$$

2.  $\int \frac{dx}{(a^2 - x^2)^{\frac{1}{2}}}$ .

Let  $x = a \sin \theta$ , and we get

$$\frac{1}{a^2} \int \frac{d\theta}{\cos^2 \theta} = \frac{\tan \theta}{a^2} = \frac{x}{a^2 \sqrt{a^2 - x^2}}.$$

This has been integrated by another transformation in Art. 15.

3.  $\int \frac{dx}{x^3(x^2 - 1)^{\frac{1}{2}}}$ .

Let  $x = \sec \theta$ , and the integral becomes

$$\int \cos^2 \theta d\theta; \text{ or, by (3) Art. 3, } \frac{\sin \theta \cos \theta}{2} + \frac{\theta}{2};$$

accordingly, the value of the integral in question is

$$\frac{\sqrt{x^2 - 1}}{2x^2} + \frac{1}{2} \sec^{-1} x.$$

4.

$$\int \frac{e^a \tan^{-1} x \, dx}{(1+x^2)^{\frac{3}{2}}}.$$

Let  $x = \tan \theta$ , and we get

$$\int \cos \theta e^{a\theta} d\theta; \text{ or by (23), } \frac{e^{a\theta} (a \cos \theta + \sin \theta)}{1+a^2}.$$

Hence

$$\int \frac{dx e^{a \tan^{-1} x}}{(1+x^2)^{\frac{3}{2}}} = \frac{(a+x) e^{a \tan^{-1} x}}{(1+a^2)(1+x^2)^{\frac{1}{2}}}.$$

$$5. \quad \int dx \sin^{-1} \left( \frac{x}{a+x} \right)^{\frac{1}{2}}.$$

Let  $\frac{x}{a+x} = \sin^2 \theta$ , or  $x = a \tan^2 \theta$ , and the integral becomes

$$a \int \theta d(\tan^2 \theta), \text{ or } a \int \theta d(\sec^2 \theta): \text{ (since } \sec^2 \theta = 1 + \tan^2 \theta\text{).}$$

Integrating by parts, we have

$$\int \theta d(\sec^2 \theta) = \theta \sec^2 \theta - \int \sec^2 \theta d\theta = \theta \sec^2 \theta - \tan \theta:$$

hence the value of the proposed integral is

$$(a+x) \tan^{-1} \left( \frac{x}{a} \right)^{\frac{1}{2}} - (ax).$$

It may be observed that the fundamental formulæ (e) and (f) can be at once obtained by aid of the transformations of this Article.

**27. Remarks on Integration.**—The student must not, however, take for granted that whenever one or other of the preceding transformations is applicable, it furnishes the simplest method of integration. We have, in Arts. 9 and 13, already met with integrals of the class here discussed, and have treated them by other substitutions: all that can be stated is, that the method given in the preceding Article will often be found the most simple and useful. The most suitable transformation in each case can only be arrived at after considerable practice and familiarity with the results introduced by such transformations.

By employing different methods we often obtain integrals of the same expression which appear at first sight not to agree. On examination, however, it will always be found that they only differ by some constant; otherwise, they could not have the same differential.

**28. Higher Transcendental Functions.**—Whenever the expression under the radical sign contains powers of  $x$  beyond the second, the integral cannot, unless in exceptional cases, be reduced to any of the fundamental formulæ; and consequently cannot be represented in finite terms of  $x$ , or of the ordinary transcendental functions: i. e. logarithmic, exponential, trigonometrical, or circular functions. Accordingly, the investigation of such integrals necessitates the introduction of higher classes of transcendental functions.

Thus the integration of irrational functions of  $x$ , in which the expression under the square root is of the third or fourth degree in  $x$ , depends on a higher class of transcendental functions called Elliptic Functions.

**29.** The method of integration by successive reduction is reserved for a subsequent place. The integration of rational fractions by the method of decomposition into partial fractions will be considered in the next chapter.

**30. Observations on Fundamental Forms.**—From what has been already stated, the sign of integration ( $\int$ ) may be regarded in the light of a question: i. e. the meaning of the expression  $\int F(x) dx$  is the same as asking what function of  $x$  has  $F(x)$  for its first derived. *The answer to this question can only be derived from our previous knowledge of the differential coefficients of the different classes of functions, as obtained by the aid of the Differential Calculus.* The number of fundamental formulæ of integration must therefore, ultimately, be the same as the number of independent kinds of functions in Algebra and Trigonometry. These may be briefly classed as follows:—

- (1). Ordinary powers and roots, such as  $x^m$ ,  $x^{\frac{p}{q}}$ , &c.
- (2). Exponentials,  $a^x$ , &c., and their inverse functions; viz., Logarithms.
- (3). Trigonometric functions,  $\sin x$ ,  $\tan x$ , &c., and their inverse functions;  $\sin^{-1}x$ ,  $\tan^{-1}x$ , &c.

This classification may assist the student towards understanding why an expression, in order to be capable of integration in a finite form, in terms of  $x$  and the ordinary transcendental functions, must be reducible by transformation to one or other of the fundamental formulæ given in

this chapter. He will also soon find that the classes of integrals which are so reducible are very limited, and that the large majority of expressions can only be integrated by the aid of infinite series.

The student must not expect to understand at once the *reason* for each transformation which he finds given: as he, however, gains familiarity with the subject he will find that most of the elementary integrations which can be performed group themselves under a few heads; and that the proper transformations are in general simple, not numerous, and usually not difficult to arrive at. He must often be prepared to abandon the transformations which seemed at first sight the most suitable: such failures are not, however, to be considered as waste of time, for it is by the application of such processes only that the student is enabled gradually to arrive at the general principles according to which integrals may be classified.

Many expressions will be found to admit of integration in two or more different ways. Such modes of arriving at the same results mutually throw light on each other, and will be found an instructive exercise for the beginner.

**31. Definite Integrals.**—We now proceed to a brief consideration of the *process of integration regarded as a summation*, reserving a more complete discussion for a subsequent chapter.

If we suppose any magnitude,  $u$ , to vary continuously by successive increments, commencing with a value  $a$ , and terminating with a value  $\beta$ , its total increment is obviously represented by  $\beta - a$ . But this total increment is equal to the sum of its partial increments; and this holds, however small we consider each increment to be.

This result is denoted in the case of finite increments by the equation

$$\sum_a^\beta (\Delta u) = \beta - a;$$

and in the case of infinitely small increments, by

$$\int_a^\beta du = \beta - a; \quad (30)$$

in which  $\beta$  and  $a$  are called the *limits of integration* : the former being the *superior* and the latter the *inferior* limit.

Now, suppose  $u$  to be a function of another variable,  $x$ , represented by the equation

$$u = f(x) :$$

then, if when  $x = a$ ,  $u$  becomes  $a$ , and when  $x = b$ ,  $u$  becomes  $\beta$ , we have

$$a = f(a), \quad \beta = f(b).$$

Moreover, in the limit, we have

$$du = f'(x) dx,$$

neglecting\* infinitely small quantities of the second order (See Diff. Calc., Art. 7).

Hence, formula (30) becomes

$$\int_a^b f'(x) dx = f(b) - f(a); \quad (31)$$

in which  $b$  and  $a$  are styled the *superior* and the *inferior* limits of  $x$ , respectively.

It should be observed that the expression  $\int_a^b f'(x) dx$ , represents here the *limit* of the sum denoted by  $\sum_a^b (f'(x) \Delta x)$ , when  $\Delta x$  is regarded as evanescent:

In the preceding we assume that each element  $f'(x) dx$  is infinitely small for all values of  $x$  between the limits of integration  $a$  and  $b$ ; and also that the limits,  $a$  and  $b$ , are both finite.

A general investigation of these exceptional cases will be found in a subsequent chapter: meanwhile it may be stated, reserving these exceptions, that whenever  $f(x)$ , i.e. the integral of  $f'(x) dx$ , can be found, the value of the definite integral  $\int_b^a f'(x) dx$  is obtained by substituting each limit separately

\* In a subsequent chapter on Definite Integrals a rigorous demonstration will be found of the property here assumed, namely that the sum of these quantities of the second order becomes evanescent in the limit, and consequently may be neglected. Compare also Art. 39, *Diff. Calc.*

instead of  $x$  in  $f(x)$ , and subtracting the value for the lower limit from that for the upper.

A few easy examples are added for illustration.

### EXAMPLES.

1.  $\int_0^1 x^n dx.$  *Ans.*  $\frac{1}{n+1}.$

2.  $\int_0^{\frac{\pi}{2}} \sin \theta d\theta.$  " 1.

3.  $\int_0^a \frac{dx}{a^2 + x^2}.$  "  $\frac{\pi}{4a}.$

4.  $\int_0^{\frac{\pi}{2}} \sin^2 x dx.$  "  $\frac{\pi}{4}.$

5.  $\int_0^{\frac{\pi}{4}} \sin^2 x dx.$  "  $\frac{\pi}{8} - \frac{1}{4}.$

6.  $\int_0^{\frac{\pi}{2}} \sin^2 x dx.$  "  $\frac{\pi}{2}.$

7.  $\int_1^4 \frac{dx}{x^{\frac{3}{2}}}.$  " 1.

8.  $\int_0^1 \frac{dx}{1+x+x^2}.$  "  $\frac{1}{3\sqrt{3}}.$

9.  $\int_0^{\frac{\pi}{2}} \cos^5 x dx.$  "  $\frac{2}{3} - \frac{4}{5}.$

10.  $\int_2^3 \frac{x dx}{1+x^2}.$  "  $\frac{1}{2} \log 2.$

11.  $\int_a^b \frac{dx}{a\sqrt{x-a}(\beta-x)}.$  "  $\pi.$

See Art. II.

12.  $\int_0^{\frac{\pi}{2}} x \sin x dx.$  " 1.

13.  $\int_0^{\pi} \frac{dx}{a+b \cos x}, \text{ where } a > b.$  "  $\frac{\pi}{\sqrt{a^2 - b^2}}$

14.  $\int_0^{\pi} \frac{dx}{1-2a \cos x+a^2}.$  "  $\frac{\pi}{1-a^2}.$

**32. Change of Limits.**—It should be observed that it is not necessary that the increment  $dx$  should be regarded as positive, for we may regard  $x$  as decreasing by successive stages, as well as increasing.

Accordingly we have

$$\int_b^a f'(x) dx = f(a) - f(b) = - \int_a^b f'(x) dx. \quad (32)$$

That is, the interchange of the limits is equivalent to a change of sign of the definite integral.

Also, it is obvious that

$$\int_a^c \phi(x) dx = \int_b^c \phi(x) dx + \int_a^b \phi(x) dx;$$

and so on.

Again, if we assume  $x$  to be any function of a new variable  $z$ , so that  $\phi(x)dx$  becomes  $\psi(z)dz$ , we obviously have

$$\int_{x_0}^X \phi(x) dx = \int_{z_0}^Z \psi(z) dz, \quad (33)$$

where  $Z$  and  $z_0$  are the values which  $z$  assumes when  $X$  and  $x_0$  are substituted for  $x$ , respectively.

For example, if  $x = a \tan z$ , the expression  $\frac{dx}{(a^2 + x^2)^{\frac{1}{2}}}$  becomes  $\frac{\cos z dz}{a^2}$ ; and if the limits of  $x$  be 0 and  $a$ , those of  $z$  are 0 and  $\frac{\pi}{4}$ . Consequently

$$\int_0^a \frac{dx}{(a^2 + x^2)^{\frac{1}{2}}} = \frac{1}{a^2} \int_0^{\frac{\pi}{4}} \cos z dz = \frac{1}{a^2 \sqrt{2}}.$$

Also, if we substitute  $a - z$  for  $x$ , we have

$$\int_0^a \phi(x) dx = - \int_a^0 \phi(a - z) dz = \int_0^a \phi(a - z) dz.$$

Since neither  $x$  nor  $z$  occurs in the result, this equation may evidently be written in the form

$$\int_0^a \phi(x) dx = \int_0^a \phi(a-x) dx. \quad (34)$$

For example, let  $\phi(x) = \sin^n x$ , then  $\phi\left(\frac{\pi}{2} - x\right) = \cos^n x$ , and we have

$$\int_0^{\frac{\pi}{2}} \sin^n x dx = \int_0^{\frac{\pi}{2}} \cos^n x dx.$$

And, in general, for any function,

$$\int_0^{\frac{\pi}{2}} f(\sin x) dx = \int_0^{\frac{\pi}{2}} f(\cos x) dx. \quad (35)$$

33. **Values of**  $\int_0^{\pi} \sin mx \sin nx dx$ , **and**  $\int_0^{\pi} \cos mx \cos nx dx$ .

Since

$$2 \sin mx \sin nx = \cos(m-n)x - \cos(m+n)x,$$

and

$$2 \cos mx \cos nx = \cos(m-n)x + \cos(m+n)x,$$

we have

$$\int \sin mx \sin nx dx = \frac{\sin(m-n)x}{2(m-n)} - \frac{\sin(m+n)x}{2(m+n)},$$

$$\text{and } \int \cos mx \cos nx dx = \frac{\sin(m-n)x}{2(m-n)} + \frac{\sin(m+n)x}{2(m+n)}.$$

Hence, when  $m$  and  $n$  are unequal integers, we have

$$\int_0^{\pi} \sin mx \sin nx dx = 0, \text{ and } \int_0^{\pi} \cos mx \cos nx dx = 0. \quad (36)$$

When  $m = n$ , we have

$$\int \sin^2 nx dx = \int \frac{1 - \cos 2nx}{2} dx = \frac{x}{2} - \frac{\sin 2nx}{4n},$$

$$\therefore \int_0^{\pi} \sin^2 nx dx = \frac{\pi}{2}, \text{ when } n \text{ is an integer.}$$

In like manner, with the same condition, we have

$$\int_0^\pi \cos^2 nx dx = \frac{\pi}{2}. \quad (37)$$

Again, to find the value of

$$\int_a^\beta \sqrt{(x-a)(\beta-x)} dx.$$

Assume, as in Art. 11,  $x = a \cos^2 \theta + \beta \sin^2 \theta$ ; then, when  $\theta = 0$ , we have  $x = a$ ; and when  $\theta = \frac{\pi}{2}$ ,  $x = \beta$ .

Hence, as in the article referred to, we have

$$\int_a^\beta \sqrt{(x-a)(\beta-x)} dx = 2(\beta-a)^2 \int_0^{\frac{\pi}{2}} \sin^2 \theta \cos^2 \theta d\theta.$$

$$\begin{aligned} \text{Also } 2 \int_0^{\frac{\pi}{2}} \sin^2 \theta \cos^2 \theta d\theta &= \frac{1}{2} \int_0^{\frac{\pi}{2}} \sin^2 2\theta d\theta \\ &= \frac{1}{4} \int_0^{\pi} \sin^2 \phi d\phi = \frac{\pi}{8}; \end{aligned}$$

$$\therefore \int_a^\beta \sqrt{(x-a)(\beta-x)} dx = \frac{\pi}{8} (\beta-a)^2. \quad (38)$$

## EXAMPLES.

1. 
$$\int \frac{(1 + \cos x) dx}{(x + \sin x)^3}$$

Ans.  $-\frac{1}{2} \frac{1}{(x + \sin x)^2}.$

2. 
$$\int x \sin x dx.$$

,,  $\sin x - x \cos x.$

3. 
$$\int \frac{1-x}{1+x} dx.$$

,,  $2 \log(1+x) - x.$

4. 
$$\int (a + bx^n)^m x^{n-1} dx.$$

,,  $\frac{(a + bx^n)^{m+1}}{n(m+1)b}.$

5. 
$$\int \frac{x^2 dx}{(a^3 + x^3)^{\frac{1}{3}}}.$$

,,  $-\frac{2}{3} \frac{1}{(a^3 + x^3)^{\frac{1}{3}}}.$

6. 
$$\int \frac{dx}{(1+x^2) \tan^{-1} x}.$$

,,  $\log(\tan^{-1} x).$

7. 
$$\int \frac{dx}{\sqrt{5+4x-x^2}}.$$

,,  $2 \sin^{-1} \sqrt{\frac{x+1}{6}}.$

8. 
$$\int \frac{x^2 dx}{x^6 + x^3 - 2}.$$

,,  $\frac{1}{9} \log \left( \frac{x^3 - 1}{x^3 + 2} \right).$

9. 
$$\int \frac{dx}{a^2 \cos^2 x + b^2 \sin^2 x}.$$

,,  $\frac{1}{ab} \tan^{-1} \left( \frac{b}{a} \tan x \right).$

10. 
$$\int \frac{\tan x dx}{a + b \tan^2 x}.$$

,,  $\frac{1}{2(b-a)} \log(a \cos^2 x + b \sin^2 x).$

11. 
$$\int \frac{\cos(\log x) dx}{x}.$$

,,  $\sin(\log x).$

12. Show that the integral of  $\frac{dx}{x}$  can be obtained from that of  $x^m dx$ .

Write the integral of  $x^m dx$  in the form  $\frac{x^{m+1} - a^{m+1}}{m+1}$ ; and, by the method of

indeterminate forms, Ex. 5, Ch. iv. Diff. Calc., it can easily be seen that the true value of the fraction when  $m+1=0$  is  $\log\left(\frac{x}{a}\right)$ , or  $\log x$ , omitting the arbitrary constant.

13.  $\int e^{ax} \sin mx \cos nx dx.$

This is immediately reducible to the integral given in formula (23).

14. 
$$\int \frac{dx}{5+4 \sin x}.$$

Ans.  $\frac{2}{3} \tan^{-1} \left( \frac{4+5 \tan \frac{x}{2}}{3} \right).$

$$15. \int \frac{xe^{a \tan^{-1} x} dx}{(1+x^2)^{\frac{3}{2}}}.$$

$$Ans. \frac{e^{a \tan^{-1} x} (ax - 1)}{(1+a^2)(1+x^2)^{\frac{1}{2}}}.$$

$$16. \int x(a+x)^{\frac{1}{2}} dx.$$

$$", \frac{3(a+x)^{\frac{3}{2}}(4x-3a)}{4 \cdot 7}.$$

$$17. \int \frac{x^3 dx}{(a+bx^2)^{\frac{3}{2}}}.$$

$$", \frac{2a+bx^2}{b^2(a+bx^2)^{\frac{1}{2}}}.$$

$$\text{Let } a+bx^2 = z^2.$$

$$18. \int \frac{(p+q \cos x) dx}{a+b \cos x}.$$

This is equivalent to

$$\int \frac{q dx}{b} + \frac{pb-qa}{b} \int \frac{dx}{a+b \cos x},$$

and accordingly can be integrated by Art. 18.

$$19. \int \frac{xe^x dx}{(1+x)^2}.$$

$$Ans. \frac{e^x}{1+x}.$$

$$20. \int \frac{x dx}{1+x^4}.$$

$$", \frac{1}{2} \tan^{-1}(x^2).$$

$$21. \int \frac{x^2 dx}{(a+bx^2)^{\frac{3}{2}}}.$$

$$", \frac{x^3}{3a(a+bx^2)^{\frac{3}{2}}}.$$

$$22. \int \frac{dx}{x \sqrt{x^3+1}}.$$

$$", \frac{1}{3} \log \left( \frac{\sqrt{1+x^3} - 1}{\sqrt{1+x^3} + 1} \right).$$

$$\text{Let } x^3 + 1 = z^2.$$

$$23. \int \frac{dx}{x \sqrt{x^n+1}}.$$

$$", \frac{1}{n} \log \left( \frac{\sqrt{1+x^n} - 1}{\sqrt{1+x^n} + 1} \right).$$

$$24. \text{Integrate } \frac{d\theta}{a+b \cos \theta}$$

$$\text{by aid of the assumption } x = \frac{b+a \cos \theta}{a+b \cos \theta}.$$

The expression transforms into

$$\frac{dx}{\sqrt{(a^2-b^2)(1-x^2)}};$$

accordingly, when  $a > b$ , its integral is  $\frac{1}{\sqrt{a^2-b^2}} \sin^{-1} x$ ; and when  $a < b$ , it is

$$\frac{1}{\sqrt{b^2-a^2}} \log(x + \sqrt{x^2-1}), \text{ &c.}$$

25. Deduce Gregory's expansion for  $\tan^{-1} x$  from formula (f).  
When  $x < 1$ , we have

$$\frac{1}{1+x^2} = 1 - x^2 + x^4 - x^6 + \text{&c.};$$

$$\therefore \tan^{-1} x = \int \frac{dx}{1+x^2} = x - \frac{x^3}{3} + \frac{x^5}{5} - \frac{x^7}{7} + \text{&c.}$$

No constant is added since  $\tan^{-1} x$  vanishes with  $x$ .

26. Deduce in a similar manner the expansions of  $\log(1+x)$ , and  $\sin^{-1} x$ .

27. Find the integral of  $\frac{d\theta}{a+b\cos\theta+c\sin\theta}$ .

This can be reduced to the form in Art. 18, by assuming  $\frac{b}{c} = \cot a$ , &c.

28.  $\int \frac{dx}{(a+bx)\sqrt{1+x^2}}$ .

$$\text{Ans. } \frac{1}{\sqrt{a^2+b^2}} \log \left\{ \frac{a+bx}{b-ax+\sqrt{(a^2+b^2)(1+x^2)}} \right\}.$$

This can be integrated either by the method of Art. 13 or by that of Art. 23

29.  $\int \frac{dx}{x\sqrt{x^n-1}}$ . Ans.  $\frac{2}{n} \sec^{-1} \left( x^{\frac{n}{2}} \right)$ .

30.  $\int_0^{\frac{\pi}{4}} \frac{\sin x \, dx}{\cos x}$ . "  $\frac{1}{2} \log 2$ .

31.  $\int_0^{\frac{\pi}{4}} \frac{dx}{\cos x}$ . "  $\log(1+\sqrt{2})$

32.  $\int_0^{\frac{\pi}{2}} \frac{dx}{(4+3x^2)^{\frac{3}{2}}}$ . "  $\frac{1}{8}$ .

33.  $\int_0^a \sqrt{a^2-x^2} \, dx$ . "  $\frac{\pi a^2}{4}$ .

34.  $\int_0^{2a} x \operatorname{versin}^{-1} \left( \frac{x}{a} \right) dx$ . "  $\frac{5\pi a^2}{4}$ .

35.  $\int_0^{\frac{\pi}{2}} \frac{dx}{4+5\sin x}$ . "  $\frac{1}{3} \log 2$ .

36.  $\int_0^{\frac{\pi}{2}} \frac{dx}{5+4\sin x}$ . "  $\frac{2}{3} \tan^{-1} \left( \frac{1}{3} \right)$ .

## CHAPTER II.

## INTEGRATION OF RATIONAL FRACTIONS.

34. **Rational Fractions.**—A fraction whose numerator and denominator are both rational and algebraic functions of a variable is called a rational fraction.

Let the expression in question be of the form

$$\frac{ax^m + bx^{m-1} + cx^{m-2} + \&c.}{a'x^n + b'x^{n-1} + c'x^{n-2} + \&c.},$$

in which  $m$  and  $n$  are positive integers, and  $a, b, \dots, a', b', \dots$  are constants.

In the first place, if the degree of the numerator be greater than, or equal to, that of the denominator, by division we can obtain a quotient, together with a new fraction in which the numerator is of a lower degree than the denominator: the former part can be immediately integrated by Art. 3. The integration of the latter part in general comes under the method of Partial Fractions.

35. **Elementary Applications.**—Before proceeding to the general process of integration of rational fractions, we propose to consider a few elementary examples, which will lead up to, and indicate in what the general method really consists.

We commence with the form already considered in Art. 7; in which, denoting by  $a_1$  and  $a_2$  the roots of the denominator, the expression to be integrated may be represented by

$$\frac{(p + qx)dx}{(x - a_1)(x - a_2)}.$$

Assume

$$\frac{p + qx}{(x - a_1)(x - a_2)} = \frac{A_1}{x - a_1} + \frac{A_2}{x - a_2}.$$

Multiplying by  $(x - a_1)(x - a_2)$  we get

$$p + qx = - (A_1 a_2 + A_2 a_1) + (A_1 + A_2) x.$$

Hence, we get for the determination of  $A_1$  and  $A_2$  the equations

$$p = - A_1 a_2 - A_2 a_1, \quad q = A_1 + A_2;$$

whence we obtain

$$A_1 = \frac{p + qa_1}{a_1 - a_2}, \quad A_2 = - \frac{p + qa_2}{a_1 - a_2}.$$

Consequently

$$\begin{aligned} \int \frac{(p + qx) dx}{(x - a_1)(x - a_2)} &= \frac{p + qa_1}{a_1 - a_2} \int \frac{dx}{x - a_1} - \frac{p + qa_2}{a_1 - a_2} \int \frac{dx}{x - a_2} \\ &= \frac{1}{a_1 - a_2} \left\{ (p + qa_1) \log(x - a_1) - (p + qa_2) \log(x - a_2) \right\}. \end{aligned}$$

In like manner

$$\frac{p + qx^2}{(x^2 - a_1)(x^2 - a_2)} = \frac{A_1}{x^2 - a_1} + \frac{A_2}{x^2 - a_2},$$

where  $A_1$  and  $A_2$  have the same values as above; hence

$$\int \frac{(p + qx^2) dx}{(x^2 - a_1)(x^2 - a_2)} = \frac{p + qa_1}{a_1 - a_2} \int \frac{dx}{x^2 - a_1} - \frac{p + qa_2}{a_1 - a_2} \int \frac{dx}{x^2 - a_2}.$$

But each of the latter integrals is of one or other of the fundamental forms (*f*) and (*h*) of Chapter I.; hence the proposed expression can be always integrated.

Again, let it be proposed to integrate an expression of the form

$$\frac{(p + qx + rx^2) dx}{(x - a_1)(x - a_2)(x - a_3)}.$$

We assume

$$\frac{p + qx + rx^2}{(x - a_1)(x - a_2)(x - a_3)} = \frac{A_1}{x - a_1} + \frac{A_2}{x - a_2} + \frac{A_3}{x - a_3};$$

then clearing from fractions, and identifying both sides by equating the coefficients of  $x^2$ , of  $x$ , and the part independent of  $x$ , at both sides, we obtain three equations of the first degree in  $A_1, A_2, A_3$ , which can be readily solved by ordinary algebra ; thus determining the values of  $A_1, A_2, A_3$  in terms of the given constants.

By this means we get

$$\int \frac{(p + qx + rx^2) dx}{(x - a_1)(x - a_2)(x - a_3)} = A_1 \int \frac{dx}{x - a_1} + A_2 \int \frac{dx}{x - a_2} + A_3 \int \frac{dx}{x - a_3}$$

$$= A_1 \log(x - a_1) + A_2 \log(x - a_2) + A_3 \log(x - a_3).$$

We shall illustrate these results by a few simple examples.

### EXAMPLES.

1.  $\int \frac{(x - 1) dx}{(x - 3)(x + 2)}.$  *Ans.*  $\frac{2}{5} \log(x - 3) + \frac{3}{5} \log(x + 2).$

2.  $\int \frac{x dx}{x^2 + 2x - 3}.$  "  $\frac{3}{4} \log(x + 3) + \frac{1}{4} \log(x - 1).$

3.  $\int \frac{dx}{x^4 - 1}.$  "  $\frac{1}{4} \log \frac{x - 1}{x + 1} - \frac{1}{2} \tan^{-1} x.$

4.  $\int \frac{dx}{x^4 + 5x^2 + 4}.$  "  $\frac{1}{3} \tan^{-1} x - \frac{1}{6} \tan^{-1} \frac{x}{2}.$

5.  $\int \frac{x dx}{x^4 - 1}.$  "  $\frac{1}{4} \log \frac{x^2 - 1}{x^2 + 1}.$

6.  $\int \frac{(3x^2 - 2) dx}{x^4 - 3x^2 - 4}.$  "  $\frac{1}{2} \log \left( \frac{x^2 - 2}{x^2 + 2} \right) + \tan^{-1} x.$

7.  $\int \frac{(x^2 + x - 1) dx}{x^3 + x^2 - 6x}.$  "  $\frac{1}{6} \log x + \frac{1}{2} \log(x - 2) + \frac{1}{3} \log(x + 3).$

Here the denominator is equal to  $x(x - 2)(x + 3)$ ; and we have

$$\frac{x^2 + x - 1}{x(x - 2)(x + 3)} = \frac{A_1}{x} + \frac{A_2}{x - 2} + \frac{A_3}{x + 3};$$

hence  $x^2 + x - 1 = A_1(x^2 + x - 6) + A_2x(x + 3) + A_3x(x - 2)$ ;

∴ the equations for determining  $A_1$ ,  $A_2$  and  $A_3$  are

$$A_1 + A_2 + A_3 = 1, \quad A_1 + 3A_2 - 2A_3 = 1, \quad 6A_1 = 1,$$

whence we get

$$A_1 = \frac{1}{6}, \quad A_2 = \frac{1}{2}, \quad A_3 = \frac{1}{3}.$$

8. 
$$\int \frac{(2x^3 + 2x^2 + 4x + 1) dx}{x^2 + x + 1}.$$
 *Ans.*  $x^2 + \log(x^2 + x + 1).$

We now proceed to the consideration of the general method, and, as it is based on the decomposition of partial fractions, we begin with the latter process.

**36. Partial Fractions.**—The method of decomposition of a fraction into its partial fractions is usually given in treatises on Algebra; as, however, the process is intimately connected with the integration of a large class of expressions, a short space is devoted to its consideration here.

For brevity, we shall denote the fraction under consideration by  $\frac{f(x)}{\phi(x)}$ .

Let  $a_1, a_2, a_3, \dots, a_n$  denote the roots of  $\phi(x)$ ; then

$$\phi(x) = (x - a_1)(x - a_2)(x - a_3) \dots (x - a_n). \quad (1)$$

There are four cases to be considered, according as we have roots, (1) real and unequal; (2) real and equal; (3) imaginary and unequal; (4) imaginary and equal.

We proceed to discuss each class separately

**37. Real and Unequal Roots.**—In this case we may assume

$$\frac{f(x)}{\phi(x)} = \frac{A_1}{x - a_1} + \frac{A_2}{x - a_2} + \frac{A_3}{x - a_3} + \dots + \frac{A_n}{x - a_n}, \quad (2)$$

where  $A_1, A_2, \dots, A_n$  are independent of  $x$ . For, if the equation be cleared from fractions by multiplying by  $\phi(x)$ , on equating the coefficients of like powers of  $x$  on both sides we obtain  $n$  equations for the determination of the  $n$  constants  $A_1, A_2, \dots, A_n$ .

Moreover, since these equations contain  $A_1, A_2, \&c.$ , only in the first degree, they can always be solved : however, since the equations are often too complicated for ready solution, the following method is usually more expeditious :—

The question (2), when cleared from fractions, gives

$$f(x) = A_1(x - a_2)(x - a_3) \dots (x - a_n) + A_2(x - a_1)(x - a_3) \dots (x - a_n) \\ + \&c. + A_n(x - a_1)(x - a_2) \dots (x - a_{n-1});$$

and since, by hypothesis, both sides of this equation are identical for all values of  $x$ , we may substitute  $a_1$  for  $x$  throughout ; this gives

$$f(a_1) = A_1(a_1 - a_2)(a_1 - a_3) \dots (a_1 - a_n),$$

$$\text{or } A_1 = \frac{f(a_1)}{\phi'(a_1)}.$$

In like manner, we have

$$A_2 = \frac{f(a_2)}{\phi'(a_2)}, \quad A_3 = \frac{f(a_3)}{\phi'(a_3)}, \dots \quad A_n = \frac{f(a_n)}{\phi'(a_n)}. \quad (3)$$

Hence, when all the roots are unequal, we have

$$\frac{f(x)}{\phi(x)} = \frac{f(a_1)}{\phi'(a_1)} \frac{1}{x - a_1} + \frac{f(a_2)}{\phi'(a_2)} \frac{1}{x - a_2} + \&c. + \frac{f(a_n)}{\phi'(a_n)} \frac{1}{x - a_n}. \quad (4)$$

Accordingly, in this case

$$\int \frac{f(x)}{\phi(x)} dx = \frac{f(a_1)}{\phi'(a_1)} \log(x - a_1) + \frac{f(a_2)}{\phi'(a_2)} \log(x - a_2) + \&c. \\ + \frac{f(a_n)}{\phi'(a_n)} \log(x - a_n). \quad (5)$$

The preceding investigation shows that to any root ( $a$ ), which is *not a multiple root*, corresponds a single term in the integral, viz.

$$\frac{f(a)}{\phi'(a)} \log(x - a);$$

one which can always be found, whether the remaining roots are known or not; and whether they are real or imaginary.

**38. Case where Numerator is of higher Degree than Denominator.**—It should also be observed that even when the degree of  $x$  in the numerator is greater than, or equal to, that in the denominator, the partial fraction corresponding to any root ( $a$ ) in the denominator is still of the form found above.

For let

$$\frac{f(x)}{\phi(x)} = Q + \frac{R}{\phi(x)},$$

where  $Q$  and  $R$  denote the quotient and remainder, and let  $\frac{A}{x-a}$  be the partial fraction of  $\frac{R}{\phi(x)}$  corresponding to a single root  $a$ ; then, by multiplying by  $\phi(x)$  and substituting  $a$  instead of  $x$ , it is easily seen, as before, that we get

$$A = \frac{f(a)}{\phi'(a)}.$$

For, example, let it be proposed to integrate the expression

$$\frac{x^5 dx}{x^3 - 2x^2 - 5x + 6}.$$

Here the factors of the denominator are easily seen to be

$$x - 1, \quad x + 2, \text{ and } x - 3;$$

accordingly, we may assume

$$\frac{x^5}{x^3 - 2x^2 - 5x + 6} = x^2 + ax + \beta + \frac{A}{x-1} + \frac{B}{x+2} + \frac{C}{x-3}.$$

To find  $a$  and  $\beta$ , we equate the coefficients of  $x^4$  and  $x^3$  to zero, after clearing from fractions: this gives, immediately,  $a = 2$ , and  $\beta = 9$ .

Again, since  $\phi(x) = x^3 - 2x^2 - 5x + 6$ , we have

$$\phi'(x) = 3x^2 - 4x - 5.$$

Accordingly, substituting 1, - 2, and 3, successively for  $x$  in the fraction

$$\frac{x^5}{3x^3 - 4x - 5},$$

we get

$$A = -\frac{1}{6}, \quad B = -\frac{32}{15}, \quad C = \frac{243}{10};$$

and hence

$$\begin{aligned} \frac{x^5}{x^3 - 2x^2 - 5x + 6} &= x^2 + 2x + 9 - \frac{1}{6(x-1)} - \frac{32}{15(x+2)} + \frac{243}{10(x-3)}; \\ \therefore \int \frac{x^5 dx}{x^3 - 2x^2 - 5x + 6} &= \frac{x^3}{3} + x^2 + 9x - \frac{\log(x-1)}{6} \\ &\quad - \frac{32}{15} \log(x+2) + \frac{243}{10} \log(x-3). \end{aligned}$$

**39. Case of Even Powers.**—If the numerator and denominator contain  $x$  in even powers only, the process can generally be simplified; for, on substituting  $z$  for  $x^2$ , the fraction becomes of the form

$$\frac{f(z)}{\phi(z)}.$$

Accordingly, whenever the roots of  $\phi(z)$  are *real and unequal*, the fraction can be decomposed into partial fractions, and to any root ( $a$ ) corresponds a fraction of the form

$$\frac{f(a)}{\phi'(a)} \frac{1}{z-a}.$$

The corresponding term in the integral of

$$\frac{f(x^2)}{\phi(x^2)} dx$$

is obviously represented by

$$\frac{f(a)}{\phi'(a)} \int \frac{dx}{x^2 - a}.$$

This is of the form  $(f)$  or  $(h)$ , according as  $a$  is a positive or negative root.

The case of imaginary roots in  $\phi(z)$  will be considered in a subsequent part of the chapter.

It may be observed that the integrals treated of in Art. 5 are simple cases of the method of partial fractions discussed in this Article.

### EXAMPLES.

1. 
$$\int \frac{(2x+3)dx}{x^3+x^2-2x}.$$

Here the factors of the denominator evidently are  $x$ ,  $x-1$ , and  $x+2$ ; we accordingly assume

$$\frac{2x+3}{x^3+x^2-2x} = \frac{A}{x} + \frac{B}{x-1} + \frac{C}{x+2}.$$

Again, as  $\phi(x) = x^3+x^2-2x$ , we have  $\phi'(x) = 3x^2+2x-2$ ;

$$\therefore \frac{f(x)}{\phi'(x)} = \frac{2x+3}{3x^2+2x-2}.$$

Hence, by (3) we have

$$A = -\frac{3}{2}, \quad B = \frac{5}{3}, \quad C = -\frac{1}{6};$$

consequently

$$\int \frac{(2x+3)dx}{x^3+x^2-2x} = -\frac{3}{2} \log x + \frac{5}{3} \log(x-1) - \frac{1}{6} \log(x+2).$$

2. 
$$\int \frac{dx}{(x^3+a^3)(x^2+b^2)}.$$

Here

$$\frac{1}{(x^3+a^3)(x^2+b^2)} = \frac{1}{a^2-b^2} \left( \frac{1}{x^3+b^3} - \frac{1}{x^3+a^3} \right);$$

hence the value of the required integral is

$$\frac{1}{(a^2-b^2)} \left\{ \frac{1}{b} \tan^{-1} \left( \frac{x}{b} \right) - \frac{1}{a} \tan^{-1} \left( \frac{x}{a} \right) \right\}.$$

3. 
$$\int \frac{x dx}{(x^2+a)(x^2+b)}.$$

Substitute  $z$  for  $x^2$  and the transformed integral is

$$\int \frac{1}{2} \frac{dz}{(z+a)(z+b)}.$$

Consequently the value of the required integral is

$$\frac{1}{2(a-b)} \log \left( \frac{x^2+b}{x^2+a} \right).$$

4.  $\int \frac{(3x^3-1)dx}{x^2-3x+2}.$  *Ans.*  $3x + 11 \log(x-2) - 2 \log(x-1).$

5.  $\int \frac{(x^2-3)dx}{x^3-7x+6}.$  "  $\frac{1}{2} \log(x-1) + \frac{1}{5} \log(x-2) + \frac{3}{10} \log(x+3).$

6.  $\int \frac{(2x+1)dx}{x(x+1)(x+2)}.$  "  $\frac{1}{2} \log x + \log(x+1) - \frac{3}{2} \log(x+2).$

7.  $\int \frac{x^2dx}{x^4-x^2-12}.$  "  $\frac{\sqrt{3}}{7} \tan^{-1} \left( \frac{x}{\sqrt{3}} \right) + \frac{1}{7} \log \left( \frac{x-2}{x+2} \right).$

8.  $\int \frac{dx(a'+b'x^n)}{x^{n+1}(a+bx^n)}.$

Let  $x^n = \frac{1}{s}.$

40. **Multiple Real Roots.**—Suppose  $\phi(x)$  has  $r$  roots each equal to  $a$ , then the fraction can be written in the shape

$$\frac{f(x)}{(x-a)^r \psi(x)}.$$

In this case we may assume

$$\frac{f(x)}{(x-a)^r \psi(x)} = \frac{M_1}{(x-a)^r} + \frac{M_2}{(x-a)^{r-1}} + \dots + \frac{M_r}{x-a} + \frac{P}{\psi(x)},$$

where the last term arises from the remaining roots.

For, when the expression is cleared from fractions, it is readily seen that, on equating the coefficients of like powers at both sides, we have as many equations as there are unknown quantities, and accordingly the assumption is a legitimate one.

In order to determine the coefficients,  $M_1, M_2, \&c. \dots M_r$ , clear from fractions, and we get

$$f(x) = M_1\psi(x) + M_2(x-a)\psi(x) + M_3(x-a)^2\psi(x) + \&c. \dots \quad (6)$$

This gives, when  $a$  is substituted for  $x$ ,

$$f(a) = M_1\psi(a), \text{ or } M_1 = \frac{f(a)}{\psi(a)}. \quad (7)$$

Next, differentiate with respect to  $x$ , and substitute  $a$  instead of  $x$  in the resulting equation, and we get

$$f'(a) = M_1\psi'(a) + M_2\psi(a); \quad (8)$$

which determines  $M_2$ .

By a second differentiation,  $M_3$  can be determined; and so on.

It can be readily seen, that the series of equations thus arrived at may be written as follows—

$$\begin{aligned} f(a) &= M_1\psi(a), \\ f'(a) &= M_1\psi'(a) + 1 \cdot M_2\psi(a), \\ f''(a) &= M_1\psi''(a) + 2 \cdot M_2\psi'(a) + 1 \cdot 2 \cdot M_3\psi(a), \\ f'''(a) &= M_1\psi'''(a) + 3 \cdot M_2\psi''(a) + 2 \cdot 3 \cdot M_3\psi'(a) + 1 \cdot 2 \cdot 3 \cdot M_4\psi(a), \\ f^{(iv)}(a) &= M_1\psi^{(iv)}(a) + 4 \cdot M_2\psi'''(a) + 3 \cdot 4 \cdot M_3\psi''(a) + 2 \cdot 3 \cdot 4 \cdot M_4\psi(a) \\ &\quad + 1 \cdot 2 \cdot 3 \cdot 4 \cdot M_5\psi(a), \end{aligned}$$

in which the law of formation is obvious, and the coefficients can be obtained in succession.

The corresponding part of the integral of

$$\frac{f(x) dx}{(x-a)^r \psi(x)}$$

evidently is

$$M_r \log(x-a) - \frac{M_{r-1}}{x-a} - \frac{1}{2} \frac{M_{r-2}}{(x-a)^2} - \dots - \frac{M_1}{(r-1)(x-a)^{r-1}}. \quad (9)$$

If  $\phi(x)$  have a second set of multiple roots, the corresponding terms in the integral can be obtained in like manner.

41. **Imaginary Roots.**—The results arrived at in Art. 37 apply to the case of imaginary, as well as to real roots; however, as the corresponding partial fractions appear in this case under an imaginary form, it is desirable to show that conjugate imaginaries give rise to groups in which the coefficients are all real.

Suppose  $a + b\sqrt{-1}$  and  $a - b\sqrt{-1}$  to be a pair of conjugate roots in the equation  $\phi(x) = 0$ ; then the corresponding quadratic factor is

$$(x - a)^2 + b^2; \text{ which may be written in the form } x^2 + px + q.$$

We accordingly assume

$$\phi(x) = (x^2 + px + q)\psi(x),$$

and hence

$$\frac{f(x)}{\phi(x)} = \frac{Lx + M}{x^2 + px + q} + \frac{P}{Q};$$

where  $\frac{P}{Q}$  represents the portion arising from the remaining roots, and  $\frac{Lx + M}{x^2 + px + q}$  is the part arising from the roots  $a \pm b\sqrt{-1}$ .

Multiplying by  $\phi(x)$  we get

$$f(x) = (Lx + M)\psi(x) + (x^2 + px + q)\frac{P}{Q}\psi(x). \quad (10)$$

If in this,  $-(px + q)$  be substituted for  $x^2$ , the last term disappears; and by repeating the same substitution in the equation

$$f(x) = \psi(x)(Lx + M),$$

it ultimately reduces to a simple equation in  $x$ : on identifying both sides of this equation, we can determine the values of  $L$  and  $M$ .

42. In many cases we can determine the coefficients  $L$ ,  $M$  more expeditiously, either by equating coefficients directly, or else by determining the other partial fractions first, and subtracting their sum from the given fraction.

It will also be found that the determination of many

integrals of this class can be much simplified by a transformation to a new variable, or by some other suitable expedient.

Some elementary examples are added for the purpose of illustration.

### EXAMPLES.

1.

$$\int \frac{x dx}{(1+x)(1+x^2)}.$$

Assume

$$\frac{x}{(1+x)(1+x^2)} = \frac{A}{1+x} + \frac{Lx+M}{1+x^2};$$

clearing from fractions, this becomes

$$x = A(1+x^2) + (Lx+M)(1+x).$$

Equate the coefficients, and we get

$$L+A=0, \quad L+M=1, \quad A+M=0.$$

Hence

$$L = \frac{1}{2}, \quad M = \frac{1}{2}, \quad A = -\frac{1}{2};$$

and accordingly

$$\frac{x}{(1+x)(1+x^2)} = -\frac{1}{2} \frac{1}{1+x} + \frac{1}{2} \frac{1+x}{1+x^2};$$

$$\therefore \int \frac{x dx}{(1+x)(1+x^2)} = \frac{1}{4} \log \left| \frac{1+x^2}{(1+x)^4} \right| + \frac{1}{2} \tan^{-1} x.$$

2.

$$\int \frac{dx}{1+x^3}.$$

Let

$$\frac{1}{1+x^3} = \frac{A}{1+x} + \frac{Lx+M}{1-x+x^2};$$

consequently,  $A = \frac{1}{3}$ , by formula (3). Substituting and clearing from fractions we have

$$3 = 1 - x + x^2 + 3(Lx+M)(1+x);$$

hence, dividing by  $1+x$ , we have,

$$2 - x = 3(Lx+M).$$

Consequently

$$\int \frac{dx}{1+x^3} = \frac{1}{3} \int \frac{dx}{1+x} + \frac{1}{3} \int \frac{(2-x)dx}{1-x+x^2}$$

$$= \frac{1}{3} \log(1+x) - \frac{1}{6} \log(1-x+x^2) + \frac{1}{\sqrt{3}} \tan^{-1} \left( \frac{2x-1}{\sqrt{3}} \right).$$

$$3. \quad \int \frac{dx}{1-x^3}. \quad \text{Ans. } \frac{1}{6} \log \left( \frac{1+x+x^2}{1-2x+x^2} \right) + \frac{1}{\sqrt{3}} \tan^{-1} \left( \frac{2x+1}{\sqrt{3}} \right).$$

This can be got from the last by changing the sign of  $x$ .

$$4. \quad \int \frac{dx}{1-x^6}.$$

In this case we have

$$\frac{1}{1-x^6} = \frac{1}{2} \left( \frac{1}{1-x^3} + \frac{1}{1+x^3} \right).$$

$$5. \quad \int \frac{x^7 dx}{x^{12}-1}. \quad \text{Ans. } \frac{1}{24} \log \left\{ \frac{(x^4-1)^2}{x^8+x^4+1} \right\} + \frac{1}{4\sqrt{3}} \tan^{-1} \left\{ \frac{2x^4+1}{\sqrt{3}} \right\}.$$

Let  $x^4 = z$ , and the integral becomes

$$\frac{1}{4} \int \frac{z dz}{z^3-1}.$$

$$6. \quad \int \frac{x^2 dx}{(x-1)^2(x^2+1)}.$$

Assume

$$\frac{x^2}{(x-1)^2(x^2+1)} = \frac{A}{(x-1)^2} + \frac{B}{x-1} + \frac{Lx+M}{1+x^2}.$$

To find  $L$  and  $M$ , clear from fractions, and by Art. 41 the values of  $L$  and  $M$  are found by making  $x^2 = -1$  in the following equation :

$$x^2 = (Lx+M)(x-1)^2.$$

This gives immediately  $L = -\frac{1}{2}$ ,  $M = 0$ .

Again, by Art. 40, we get immediately  $A = \frac{1}{2}$ .

To find  $B$ , make  $x = 0$  in both sides of our identity, and we get

$$0 = A - B + M; \quad \therefore B = A = \frac{1}{2}.$$

[4a]

Finally

$$\frac{x^2}{(x-1)^2(x^2+1)} = \frac{1}{2} \frac{1}{(x-1)^2} + \frac{1}{2} \frac{1}{x-1} - \frac{1}{2} \frac{x}{1+x^2};$$

$$\therefore \int \frac{x^2 dx}{(x-1)^2(x^2+1)} = -\frac{1}{2} \frac{1}{x-1} + \frac{1}{2} \log(x-1) - \frac{1}{4} \log(x^2+1).$$

7.  $\int \frac{dx}{x^8 + x^7 - x^4 - x^3}.$

Here the denominator is easily seen to be  $x^3(x-1)(x+1)^2(x^2+1)$ , and the expression becomes

$$\int \frac{dx}{x^3(x-1)(x+1)^2(x^2+1)}.$$

Assume  $x = \frac{1}{z}$ , and the transformed expression is evidently

$$\int \frac{z^6 dz}{(z-1)(z+1)^2(z^2+1)}.$$

The quotient is easily seen to be  $z-1$ ; and, by the method of Art. 38, we may assume

$$\frac{z^6}{(z-1)(z+1)^2(z^2+1)} = z-1 + \frac{A}{z-1} + \frac{B}{(z+1)^2} + \frac{C}{z+1} + \frac{Lz+M}{z^2+1}.$$

Hence (Arts. 37, 40), we have

$$A = \frac{1}{8}; \quad B = -\frac{1}{4}.$$

Next,  $L$  and  $M$  are found by making  $z^2 = -1$ , in the equation

$$z^6 = (Lz+M)(z-1)(z+1)^2;$$

$$\therefore 1 = 2(Lz+M)(z+1) = 2 \{ Lz^2 + (L+M)z + M \},$$

which gives

$$L+M=0, \quad L-M=-\frac{1}{2};$$

$$\therefore M = \frac{1}{4}, \quad L = -\frac{1}{4}.$$

In order to find the remaining coefficient  $C$ , we make  $z=0$ , when we get

$$0 = -1 - A + B + C + M; \quad \therefore C = \frac{9}{8}.$$

hence we have

$$\frac{z^6}{(z-1)(z+1)^2(z^2+1)} = z-1 + \frac{1}{8(z-1)} - \frac{1}{4(z+1)^2} + \frac{9}{8(z+1)} - \frac{z^2-1}{4(z^2+1)};$$

$$\begin{aligned} \therefore \int \frac{z^6 dz}{(z-1)(z+1)^2(z^2+1)} &= \frac{z^2}{2} - z + \frac{1}{8} \log(z-1) + \frac{1}{4(z+1)} \\ &+ \frac{9}{8} \log(z+1) - \frac{1}{8} \log(z^2+1) + \frac{1}{4} \tan^{-1} z. \end{aligned}$$

Hence

$$\int \frac{dx}{x^8+x^7-x^4-x^3} = \frac{1}{2x^4} - \frac{1}{x} + \frac{x}{4(x+1)} + \frac{1}{8} \log \frac{1-x^2}{1+x^2} + \log \frac{x+1}{x} + \frac{1}{4} \tan^{-1} \frac{1}{x}$$

$$8. \quad \int \frac{(3x+1) dx}{(x-1)^2(x+3)}. \quad \text{Ans. } \frac{1}{2} \log \frac{x-1}{x+3} - \frac{1}{x-1}.$$

**43. Multiple Imaginary Roots.**—To complete the discussion of the decomposition of the fraction  $\frac{f(x)}{\phi(x)}$ , suppose the denominator  $\phi(x)$  to contain  $r$  pairs of equal and imaginary roots, i. e. let the denominator contain a factor of the form  $\{(x-a)^2+b^2\}^r$ ; and suppose  $\phi(x) = \{(x-a)^2+b^2\}^r \phi_1(x)$

In this case we assume

$$\begin{aligned} \frac{f(x)}{\{(x-a)^2+b^2\}^r \phi_1(x)} &= \frac{L_1 x + M_1}{\{(x-a)^2+b^2\}^r} + \frac{L_2 x + M_2}{\{(x-a)^2+b^2\}^{r-1}} \\ &+ \dots + \frac{L_r x + M_r}{(x-a)^2+b^2} + \frac{P}{\phi_1(x)}; \end{aligned}$$

the remaining partial fractions being obtained from the other roots.

There is no difficulty in seeing that we shall still have as many equations as unknown quantities,  $L_1, M_1, L_2, M_2, \dots$  when the coefficients of like powers of  $x$  are equated on both sides.

To determine  $L_1, M_1, L_2, \dots$ ; let the factor  $(x-a)^2+b^2$  be represented by  $X$ , and multiply up by  $X^r$ , when we get

$$\frac{f(x)}{\phi_1(x)} = L_1 x + M_1 + (L_2 x + M_2) X + \dots + (L_r x + M_r) X^{r-1} + \frac{P X^r}{\phi_1(x)}. \quad (11)$$

The coefficients  $L_1$  and  $M_1$  are determined as in Art. 41. To find  $L_2$  and  $M_2$ ; differentiate with respect to  $x$ , and substitute  $a + b\sqrt{-1}$  for  $x$  in the result, when it becomes

$$\frac{d}{dx} \left[ \frac{f(x)}{\phi_1(x)} \right]_0 = L_1 + 2(x_0 - a)(L_2 x_0 + M_2),$$

where  $x_0 = a + b\sqrt{-1}$ .

Hence, equating real and imaginary parts, we get two equations for the determination of  $L_2$  and  $M_2$ . By a second differentiation,  $L_3$  and  $M_3$  can be determined, and so on.

It is unnecessary to go into further detail, as sufficient has been stated to show that the decomposition into partial fractions is possible in all cases, when the roots of  $\phi(x) = 0$  are known.

The practical application is often simplified by transformation to a new variable.

44. The preceding investigation shows that the integration of rational fractions is in all cases reducible to that of one or more fractions of the following forms:

$$\frac{dx}{x-a}, \quad \frac{dx}{(x-a)^r}, \quad \frac{(A+B)dx}{(x-a)^2 + b^2}, \quad \frac{(Lx+M)dx}{\{(x-a)^2 + b^2\}^r}.$$

The methods of integrating the first three forms have been given already. We proceed to show the mode of dealing with the last.

45. In the first place it can be divided into two others,

$$\frac{L(x-a)dx}{\{(x-a)^2 + b^2\}^r} + \frac{(La+M)dx}{\{(x-a)^2 + b^2\}^{r-1}}.$$

The integral of the first part is evidently

$$\frac{-L}{2(r-1)\{(x-a)^2 + b^2\}^{r-1}}.$$

To determine the integral of the other part, we substitute  $z$  for  $x-a$ , and, omitting the constant coefficient, it becomes

$$\int \frac{dz}{(z^2 + b^2)^r}.$$

Again

$$\int \frac{dz}{(z^2 + b^2)^r} = \frac{1}{b^2} \int \frac{(z^2 + b^2 - z^2) dz}{(z^2 + b^2)^r} = \frac{1}{b^2} \int \frac{dz}{(z^2 + b^2)^{r-1}} - \frac{1}{b^2} \int \frac{z^2 dz}{(z^2 + b^2)^r}.$$

But we get by integration by parts

$$\begin{aligned} \int \frac{z^2 dz}{(z^2 + b^2)^r} &= \int z \cdot \frac{z dz}{(z^2 + b^2)^r} = -\frac{1}{2(r-1)} \int z d \left( \frac{1}{(z^2 + b^2)^{r-1}} \right) \\ &= -\frac{z}{2(r-1)(z^2 + b^2)^{r-1}} + \frac{1}{2(r-1)} \int \frac{dz}{(z^2 + b^2)^{r-1}}. \end{aligned}$$

Substituting in the preceding, we obtain

$$\int \frac{dz}{(z^2 + b^2)^r} = \frac{2r-3}{2(r-1)b^2} \int \frac{dz}{(z^2 + b^2)^{r-1}} + \frac{z}{2(r-1)b^2(z^2 + b^2)^{r-1}}, \quad (12)$$

This formula reduces the integral to another of the same shape, in which the exponent  $r$  is replaced by  $r-1$ . By successive repetitions of this formula the integral can be re-

duced to depend on that of  $\frac{dz}{(z^2 + b^2)}$ .

The preceding is a case of the method of integration by *successive reduction*, referred to in Art. 19. Other examples of this method will be found in the next Chapter.

The preceding integral can often be found more expeditiously by the following transformation:—Substitute  $b \tan \theta$  for  $z$ , and the expression  $\frac{dz}{(z^2 + b^2)^r}$  becomes, obviously,

$$\frac{1}{b^{2r-1}} \int \cos^{2r-2} \theta d\theta.$$

The discussion of this class of integrals will be found in the next Chapter.

46. We shall next return to the integration of  $\frac{f(x^2)dx}{\phi(x^2)}$ , which has been already considered in Art. 39 in the case

where the roots of  $\phi(z)$  are real. To a pair of imaginary roots,  $a \pm b\sqrt{-1}$ , corresponds a partial fraction of the form

$$\frac{(Ax^2 + B)dx}{(x^2 - a^2 + b^2)}, \quad \text{or} \quad \frac{(Ax^2 + B)dx}{x^4 - 2ax^2 + c^2},$$

where  $c^2 = a^2 + b^2$ .

In order to integrate this, we assume  $a = c \cos 2\phi$ , when the fraction becomes

$$\frac{(Ax^2 + B)dx}{x^4 - 2x^2c \cos 2\phi + c^2}.$$

The quadratic factors of the denominator are easily seen to be

$$x^2 - 2x\sqrt{c} \cos \phi + c, \text{ and } x^2 + 2x\sqrt{c} \cos \phi + c.$$

Accordingly we assume

$$\frac{Ax^2 + B}{x^4 - 2x^2c \cos 2\phi + c^2} = \frac{Lx + M}{x^2 - 2x\sqrt{c} \cos \phi + c} + \frac{L'x + M'}{x^2 + 2x\sqrt{c} \cos \phi + c};$$

hence it can be seen without difficulty that

$$L = -L' = \frac{Ac - B}{4c^2 \cos \phi}, \quad M = M' = \frac{B}{2c},$$

and after a few easy transformations, we find

$$\begin{aligned} \int \frac{(Ax^2 + B)dx}{x^4 - 2x^2c \cos 2\phi + c^2} &= \frac{Ac - B}{8 \cos \phi c^3} \log \left( \frac{x^2 - 2x\sqrt{c} \cos \phi + c}{x^2 + 2x\sqrt{c} \cos \phi + c} \right) \\ &+ \frac{Ac + B}{4 \sin \phi c^3} \tan^{-1} \left( \underbrace{\frac{2x\sqrt{c} \sin \phi}{c - x^2}} \right). \end{aligned}$$

47. **Integration of**  $\frac{dx}{(x - a)^m (x - b)^n}$ .

This expression can be easily transformed into a shape

which is immediately integrable, by the following substitution :—

Assume  $x-a = (x-b)z$ ; then

$$x = \frac{a-bz}{1-z}; \quad \therefore x-a = \frac{(a-b)z}{1-z}, \quad x-b = \frac{a-b}{1-z}, \quad dx = \frac{(a-b)dz}{(1-z)^2};$$

and the expression transforms into

$$\frac{(1-z)^{m+n-2} dz}{(a-b)^{m+n-1} z^m}.$$

Expand the numerator by the Binomial Theorem, and the integral can be immediately obtained. (Compare Art. 4.)

For example, take the integral

$$\frac{dx}{(x-a)^2 (x-b)^3}.$$

Here the transformed expression is

$$\int \frac{(1-z)^3 dz}{(a-b)^4 z^2},$$

or

$$\frac{1}{(a-b)^4} \int \left( \frac{1}{z^2} - \frac{3}{z} + 3 - z \right) dz = \frac{-1}{(a-b)^4} \left\{ \frac{z^2}{2} - 3z + 3 \log z + \frac{1}{z} \right\}.$$

Substituting  $\frac{x-a}{x-b}$  for  $z$ , the integral can be expressed in terms of  $x$ .

48. **Integration of**  $\frac{x^{2m+1} dx}{(a+cx^2)^n}$ .

where  $m$  and  $n$  are integers.

Let  $a+cx^2 = z$ , and the expression becomes

$$\frac{(z-a)^m dz}{2c^{m+1} z^n};$$

a form which is immediately integrable by aid of the Binomial Theorem.

It is evident that the expression is made integrable by the same transformation when  $n$  is either a fractional or a negative index.

It may be also observed that the more general expression  $\frac{f(x^2) x dx}{(a + cx^2)^n}$  can be integrated by the same transformation, where  $f(x^2)$  denotes an integral algebraic function of  $x^2$ .

### EXAMPLES.

1.  $\int \frac{x^5 dx}{(a^2 - x^2)^2}.$  *Ans.*  $\frac{a^4}{2(a^2 - x^2)} + \frac{x^2}{2} + a^2 \log(a^2 - x^2).$

2.  $\int \frac{x^3 dx}{(a + cx^2)^4}.$  "  $-\frac{1}{4c^2(a + cx^2)^2} + \frac{a}{6c^2(a + cx^2)^3}.$

3.  $\int \frac{x^5 dx}{(1 + x^2)^3}.$  "  $\frac{1}{x^2 + 1} - \frac{1}{4(x^2 + 1)^2} + \frac{1}{2} \log(x^2 + 1).$

### 49. Integration of $\frac{dx}{x^n - 1},$

where  $n$  is a positive integer.

Suppose  $a$  an imaginary root of  $x^n - 1 = 0$ , then it is evident that  $a^{-1}$  is the conjugate root: also, by (3), the partial fraction corresponding to the root  $a$  is

$$\frac{1}{na^{n-1}(x - a)}, \quad \text{or} \quad \frac{a}{n(x - a)}.$$

If to this the fraction arising from the root  $a^{-1}$  be added, we get

$$\frac{1}{n} \left\{ \frac{a}{x - a} + \frac{a^{-1}}{x - a^{-1}} \right\}, \quad \text{or} \quad \frac{1}{n} \left\{ \frac{x(a + a^{-1}) - 2}{x^2 - (a + a^{-1})x + 1} \right\}.$$

But, by the theory of equations,  $a$  is of the form

$$\cos \frac{2k\pi}{n} + \sqrt{-1} \sin \frac{2k\pi}{n},$$

where  $k$  is any integer;

$$\therefore a + a^{-1} = 2 \cos \frac{2k\pi}{n}.$$

Hence, if  $\theta$  be substituted for  $\frac{2k\pi}{n}$ , the preceding fraction becomes

$$\frac{2}{n} \cdot \frac{x \cos \theta - 1}{x^2 - 2x \cos \theta + 1}.$$

The integral of this, by Art. 7, is

$$\frac{\cos \theta}{n} \log (1 - 2x \cos \theta + x^2) - \frac{2 \sin \theta}{n} \tan^{-1} \left( \frac{x - \cos \theta}{\sin \theta} \right).$$

There are two cases to be considered, according as  $n$  is even or odd.

(1). Let  $n = 2r$ : in this case the equation  $x^{2r} - 1 = 0$  has two real roots, viz.,  $+1$  and  $-1$ ; and it is easily seen that

$$\begin{aligned} \int \frac{dx}{x^{2r} - 1} &= \frac{1}{2r} \log \frac{x - 1}{x + 1} + \frac{1}{2r} \Sigma \cos \frac{k\pi}{r} \log \left( 1 - 2x \cos \frac{k\pi}{r} + x^2 \right) \\ &\quad - \frac{1}{r} \Sigma \sin \frac{k\pi}{r} \tan^{-1} \left( \frac{x - \cos \frac{k\pi}{r}}{\sin \frac{k\pi}{r}} \right), \end{aligned} \quad (13)$$

where the summation represented by  $\Sigma$  extends to all integer values of  $k$  from  $1$  to  $r - 1$ .

(2). Let  $n = 2r + 1$ , we obtain

$$\begin{aligned} \int \frac{dx}{x^{2r+1} - 1} &= \frac{\log(x - 1)}{2r + 1} + \frac{1}{2r + 1} \Sigma \cos \frac{2k\pi}{2r + 1} \log \left( 1 - 2x \cos \frac{2k\pi}{2r + 1} + x^2 \right) \\ &\quad - \frac{2}{2r + 1} \Sigma \sin \frac{2k\pi}{2r + 1} \tan^{-1} \left( \frac{x - \cos \frac{2k\pi}{2r + 1}}{\sin \frac{2k\pi}{2r + 1}} \right), \end{aligned} \quad (14)$$

where the summation represented by  $\Sigma$  extends to all integer values of  $k$  from 1 up to  $r$ .

50. **Integration of  $\frac{x^{m-1}dx}{x^n - 1}$ , where  $m$  is less than  $n + 1$ .**

As before, let  $a$  be a root, and the corresponding partial fraction is  $\frac{a^{m-1}}{na^{n-1}(x-a)}$  or  $\frac{a^m}{n(x-a)}$ ; hence the partial fraction arising from the conjugate roots,  $a$  and  $a^{-1}$ , is

$$\begin{aligned} \frac{1}{n} \left( \frac{a^m}{x-a} + \frac{a^{-m}}{x-a^{-1}} \right) &= \frac{1}{n} \cdot \frac{x(a^m + a^{-m}) - (a^{m-1} + a^{-(m-1)})}{x^2 - (a + a^{-1})x + 1} \\ &= \frac{2}{n} \frac{x \cos m\theta - \cos(m-1)\theta}{x^2 - 2x \cos \theta + 1}, \end{aligned}$$

where  $\theta$  is of the same form as before.

The corresponding term in the proposed integral is easily seen, by Art. 7, to be

$$\frac{1}{n} \left\{ \cos m\theta \log(x^2 - 2x \cos \theta + 1) - 2 \sin m\theta \tan^{-1} \frac{x - \cos \theta}{\sin \theta} \right\}. \quad (15)$$

By giving to  $k$  all values from 1 to  $\frac{n}{2} - 1$ , when  $n$  is even, and from 1 to  $\frac{n-1}{2}$  when  $n$  is odd, the integral required can be written down as in the preceding Article.

## EXAMPLES.

1.  $\int \frac{dx}{x^2 + 6x + 8}$ . *Ans.*  $\frac{1}{2} \log \left( \frac{x+2}{x+4} \right)$ .

2.  $\int \frac{3xdx}{x^2 - x - 2}$ . "  $2 \log(x-2) + \log(x+1)$ .

3.  $\int \frac{(A + Bx^2)dx}{x(a + bx^2)}$ . "  $\frac{A}{a} \log x + \frac{Ba - Ab}{2ab} \log(a + bx^2)$ .

4.  $\int \frac{x^2dx}{x^4 + x^2 - 2}$ . "  $\frac{1}{6} \log \frac{x-1}{x+1} + \frac{\sqrt{-2}}{3} \tan^{-1} \left( \frac{x}{\sqrt{-2}} \right)$ .

5.  $\int \frac{dx}{x^4 + 1}$ . "  $\frac{1}{4\sqrt{-2}} \log \frac{x^2 + x\sqrt{-2} + 1}{x^2 - x\sqrt{-2} + 1} + \frac{1}{2\sqrt{-2}} \tan^{-1} \left( \frac{x\sqrt{-2}}{1 - x^2} \right)$ .

6.  $\int \frac{(2x-5)dx}{(x+3)(x+1)^2}$ . "  $\frac{7}{2(x+1)} + \frac{11}{4} \log \left( \frac{x+1}{x+3} \right)$ .

7.  $\int \frac{dx}{x(a+bx^2)^2}$ . "  $\frac{1}{2a(a+bx^2)} + \frac{1}{2a^2} \log \left( \frac{x^2}{a+bx^2} \right)$ .

8.  $\int \frac{dx}{x(a+bx^n)^3}$ . "  $\frac{1}{na^2} \log \left( \frac{x^n}{a+bx^n} \right) + \frac{1}{na(a+bx^n)}$ .

9.  $\int \frac{dx}{x(a+bx^n)^r}$ .

Let  $a + bx^n = x^n z$ , and the transformed expression is  $-\frac{(z-b)^{r-1} dz}{nar z^r}$ .

10.  $\int \frac{x dx}{x^3 + x^2 + x + 1}$ . *Ans.*  $\frac{1}{4} \log(x^2 + 1) - \frac{1}{2} \log(x+1) + \frac{1}{2} \tan^{-1} x$ .

11.  $\int \frac{dx}{x^4 + 4x^3 + 5x^2 + 4x + 4}$ . "  $\frac{3}{25} \log \frac{(x+2)^3}{x^2 + 1} + \frac{3}{25} \tan^{-1} x - \frac{1}{5(x+2)}$ .

12. Apply the method of Art. 47 to the integration of  $\frac{dx}{(1-x^2)^n}$ .

The transformed expression is  $-\frac{(1+z)^{2n-2} dz}{z^{2n-1} z^n}$ .

13.  $\int \frac{x^2 dx}{(1-x^2)^3}$ . *Ans.*  $\frac{1}{8} \frac{x(1+x^2)}{(1-x^2)^2} - \frac{1}{16} \log \frac{1+x}{1-x}$ .

14. Prove that

$$\int \frac{dx}{x^n(1-x)^m} \text{ transforms into } - \int \frac{(1+x)^{m+n-2} dx}{x^m},$$

if we make  $x = \frac{1}{1+z}$ .

$$15. \int \frac{dx}{\sin x(a+b \cos x)}. \quad \text{Ans. } \frac{1}{a+b} \log \sin \frac{x}{2} - \frac{1}{a-b} \log \cos \frac{x}{2} \\ + \frac{b}{a^2-b^2} \log (a+b \cos x).$$

Multiply by  $\sin x$ , substitute  $u$  for  $\cos x$ , and the integral becomes

$$\int \frac{-du}{(1-u^2)(a+bu)}.$$

$$16. \int \frac{dx}{3 \sin x + \sin 2x}. \quad \text{Ans. } \frac{1}{5} \log \sin \frac{x}{2} - \log \cos \frac{x}{2} + \frac{2}{5} \log (3 + 2 \cos x).$$

$$17. \int \frac{(1-x^2) dx}{x(1+x^2+x^4)}. \quad \text{,} \quad \frac{\sqrt{3}}{2} \tan^{-1} \left( \frac{x+x^2}{x^2\sqrt{3}} \right) - \frac{1}{4} \log \left( \frac{x^4+x^2+1}{x^4} \right).$$

Let  $x^2 = \frac{1}{z}$ , &c.

18. Prove that

$$\int \frac{dx}{1+x^{2n}} = -\frac{1}{2n} \sum \cos \frac{(2k-1)\pi}{2n} \log \left( 1 - 2x \cos \frac{(2k-1)\pi}{2n} + x^2 \right) \\ + \frac{1}{n} \sum \sin \frac{(2k-1)\pi}{2n} \tan^{-1} \left\{ \frac{x - \cos \frac{(2k-1)\pi}{2n}}{\sin \frac{(2k-1)\pi}{2n}} \right\};$$

where  $k$  extends through all integer values from 1 to  $n$ , inclusive.

$$19. \int \frac{dx}{1+x^{2n+1}} = \frac{\log(1+x)}{2n+1} - \frac{1}{2n+1} \sum \cos \frac{(2k-1)\pi}{2n+1} \log \left( 1 - 2x \cos \frac{(2k-1)\pi}{2n+1} + x^2 \right) \\ + \frac{2}{2n+1} \sum \sin \frac{(2k-1)\pi}{2n+1} \tan^{-1} \left\{ \frac{x - \cos \frac{(2k-1)\pi}{2n+1}}{\sin \frac{(2k-1)\pi}{2n+1}} \right\},$$

where  $k$  assumes all integer values from 1 to  $n$  inclusive.

## CHAPTER III.

## INTEGRATION BY SUCCESSIVE REDUCTION.

51. **Cases in which  $\sin^m \theta \cos^n \theta d\theta$  is immediately Integrable.**—We shall commence this Chapter\* with the discussion of the integral

$$\int \sin^m \theta \cos^n \theta d\theta;$$

to which form it will be seen that a number of other expressions are readily reducible.

In the first place it is easily seen that whenever either  $m$  or  $n$  is an odd positive integer the expression  $\sin^m \theta \cos^n \theta d\theta$  can be immediately integrated.

For, if  $n = 2r + 1$ , the integral becomes

$$\int \sin^m \theta \cos^{2r+1} \theta d\theta, \text{ or, } \int \sin^m \theta (\cos^2 \theta)^r d(\sin \theta).$$

If we assume  $x = \sin \theta$ , the integral transforms into

$$\int x^m (1 - x^2)^r dx; \quad (1)$$

and as, by hypothesis,  $r$  is a positive integer,  $(1 - x^2)^r$  can be expanded by the Binomial Theorem in a finite number of terms, each of which can be integrated separately. In like manner, if the index of  $\sin \theta$  be an odd integer, we assume  $x = \cos \theta$ , &c.

A few examples are added for the purpose of making the student familiar with this principle.

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\* It may be observed that a large number of the integrals discussed in this Chapter do not require the method of Successive Reduction: however, since other integrals of the same form require this method, it was not considered advisable to separate the discussion into distinct Chapters.

## EXAMPLES.

$$1. \int \sin^3 \theta d\theta. \quad \text{Ans. } \frac{\cos^3 \theta}{3} - \cos \theta.$$

$$2. \int \cos^5 \theta d\theta. \quad \text{,} \quad \sin \theta - \frac{2}{3} \sin^3 \theta + \frac{\sin^5 \theta}{5}.$$

$$3. \int \sin^3 \theta \cos^7 \theta d\theta. \quad \text{,} \quad \frac{\cos^{10} \theta}{10} - \frac{\cos^8 \theta}{8}.$$

$$4. \int \frac{\sin^5 \theta d\theta}{\cos^2 \theta}. \quad \text{,} \quad \frac{1}{\cos \theta} + 2 \cos \theta - \frac{\cos^3 \theta}{3}.$$

$$5. \int \sqrt{\sin \theta} \cos^3 \theta d\theta. \quad \text{,} \quad \frac{2 \sin^{\frac{3}{2}} \theta}{3} - \frac{2 \sin^{\frac{1}{2}} \theta}{7}.$$

$$6. \int \frac{\sin^3 \theta d\theta}{\sqrt{\cos \theta}}. \quad \text{,} \quad \frac{2 \cos^{\frac{3}{2}} \theta}{5} - 2 \cos^{\frac{1}{2}} \theta.$$

$$7. \int \frac{\cos^3 \theta d\theta}{\sin^{\frac{3}{2}} \theta}. \quad \text{,} \quad 3 \sin^{\frac{1}{2}} \theta - \frac{3}{7} \sin^{\frac{3}{2}} \theta.$$

52. Again, whenever  $m + n$  is an even negative integer the expression  $\sin^m \theta \cos^n \theta d\theta$  can be readily integrated.

For if we assume  $x = \tan \theta$ , we have

$$\cos \theta = \frac{1}{\sqrt{1+x^2}}, \quad \sin \theta = \frac{x}{\sqrt{1+x^2}}, \quad \text{and} \quad d\theta = \frac{dx}{1+x^2},$$

and the expression transforms into

$$\frac{x^m dx}{(1+x^2)^{\frac{m+n}{2}+1}}.$$

Hence, if  $m + n = -2r$ , this becomes

$$x^m (1+x^2)^{r-1} dx,$$

a form which is immediately integrable.

Take, for example,  $\int \frac{\sin^2 \theta d\theta}{\cos^6 \theta}$ .

Let  $x = \tan \theta$ , and we get

$$\int x^2 (1 + x^2) dx, \text{ or } \frac{\tan^3 \theta}{3} + \frac{\tan^5 \theta}{5}.$$

Next, to find

$$\int \frac{d\theta}{\sin \theta \cos^5 \theta}.$$

Making the same substitution, we obtain

$$\int \frac{(1 + x^2)^2 dx}{x}.$$

Hence, the value of the proposed integral is

$$\frac{\tan^4 \theta}{4} + \tan^2 \theta + \log (\tan \theta).$$

Again, to find  $\int \frac{d\theta}{\sin^2 \theta \cos^3 \theta}$ .

Here the transformed expression is  $\frac{(1 + x^2) dx}{x^3}$ , and accordingly the value of the proposed integral is

$$\frac{2}{3} \tan^2 \theta - \frac{2}{\tan^2 \theta}.$$

In many cases it is more convenient to assume  $x = \cot \theta$ .

For example, to find  $\int \frac{d\theta}{\sin^4 \theta}$ .

Since  $d(\cot \theta) = -\frac{d\theta}{\sin^2 \theta}$ , if  $\cot \theta = x$ , the transformed integral is

$$-\int (1 + x^2) dx, \text{ or } -\cot \theta - \frac{\cot^3 \theta}{3}.$$

The following examples are added for illustration:—

## EXAMPLES.

1.  $\int \frac{\sin^3 \theta d\theta}{\cos^5 \theta}.$  *Ans.*  $\frac{\tan^4 \theta}{4}.$

2.  $\int \frac{d\theta}{\cos^6 \theta}.$  "  $\tan \theta + \frac{2 \tan^3 \theta}{3} + \frac{\tan^5 \theta}{5}.$

3.  $\int \frac{d\theta}{\sin \theta \cos^3 \theta}$  "  $\frac{\tan^3 \theta}{2} + \log (\tan \theta).$

4.  $\int \frac{\sin^4 \theta d\theta}{\cos^5 \theta}.$  "  $\frac{2}{3} \tan^3 \theta.$

5.  $\int \frac{d\theta}{\sin^4 \theta \cos^4 \theta}.$  "  $-8 \cot 2\theta - \frac{8}{3} \cot^3 2\theta.$

6.  $\int \frac{d\theta}{\sin^4 \theta \cos^3 \theta}.$  "  $2 \tan^4 \theta \left( 1 + \frac{\tan^2 \theta}{5} \right).$

When neither of the preceding methods is applicable, the integration of the expression  $\sin^m \theta \cos^n \theta d\theta$  can be obtained only by aid of successive reduction.

We proceed to establish the formulæ of reduction suitable to this case.

**53. Formulæ of Reduction for  $\sin^m \theta \cos^n \theta d\theta.$**

$$\int \sin^m \theta \cos^n \theta d\theta = \int \cos^{n-1} \theta \sin^m \theta d(\sin \theta) :$$

consequently, if we assume

$$u = \cos^{n-1} \theta, \quad v = \frac{\sin^{m+1} \theta}{m+1},$$

d

the formula for integration by parts (Art. 21) gives

$$\int \sin^m \theta \cos^n \theta d\theta = \frac{\cos^{n-1} \theta \sin^{m+1} \theta}{m+1} + \frac{n-1}{m+1} \int \sin^{m+2} \theta \cos^{n-2} \theta d\theta. \quad (2)$$

In like manner, if the integral be written in the form

$$-\int \sin^{m-1} \theta \cos^n \theta d(\cos \theta),$$

we obtain

$$\int \sin^m \theta \cos^n \theta d\theta = \frac{m-1}{n+1} \int \sin^{m-2} \theta \cos^{n+2} \theta d\theta - \frac{\sin^{m-1} \theta \cos^{n+1} \theta}{n+1}. \quad (3)$$

It may be observed that this latter formula can be derived from (2) by substituting  $\frac{\pi}{2} - \phi$  for  $\theta$ , and interchanging the letters  $m$  and  $n$  in it.

**54. Case of one Positive and one Negative Index.** — The results in (2) and (3) hold whether  $m$  or  $n$  be positive or negative; accordingly, let one of them be negative ( $n$  suppose), and on changing  $n$  into  $-n$ , formula (3) becomes

$$\int \frac{\sin^m \theta}{\cos^n \theta} d\theta = \frac{\sin^{m-1} \theta}{(n-1) \cos^{n-1} \theta} - \frac{m-1}{n-1} \int \frac{\sin^{m-2} \theta}{\cos^{n-2} \theta} d\theta, \quad (A)$$

in which  $m$  and  $n$  are supposed to have positive\* signs.

By this formula the integral of  $\frac{\sin^m \theta}{\cos^n \theta} d\theta$  is made to depend on another in which the indices of  $\sin \theta$  and  $\cos \theta$  are each diminished by two. The same method is applicable to the new integral, and so on.

If  $m$  be an odd integer, the expression is integrable immediately by Art. 51. If  $m$  be even, and  $n$  even and greater than  $m$ , the method of Art. 52 is applicable; if  $m = n$ , the expression becomes  $\int \tan^m \theta d\theta$ , which will be treated subsequently; if  $n < m$ , the integral reduces to that of  $\sin^{m-n} \theta d\theta$ .

Again, if  $n$  be odd, and  $> m$ , the integral reduces to  $\int \frac{d\theta}{\cos^{n-m} \theta}$ ;

\* The formulæ of reduction employed in practice are indicated by the capital letters  $A$ ,  $B$ , &c.; and in them the indices  $m$  and  $n$  are supposed to have always positive signs. By this means the formulæ will be more easily apprehended and applied by the student.

and if  $n < m$ , it reduces to  $\int \frac{\sin^{m-n+1} \theta \, d\theta}{\cos \theta}$ . The mode of finding these latter integrals will be considered subsequently.

Again, if the index of  $\sin \theta$  be negative, we get, by changing the sign of  $m$  in (2),

$$\int \frac{\cos^n \theta}{\sin^m \theta} \, d\theta = - \frac{\cos^{n-1} \theta}{(m-1) \sin^{m-1} \theta} - \frac{n-1}{m-1} \int \frac{\cos^{n-2} \theta}{\sin^{m-2} \theta} \, d\theta. \quad (B,$$

We shall next consider the case where the indices are both positive.

55. **Indices both Positive.**—If  $\sin^m \theta (1 - \cos^2 \theta)$  be written instead of  $\sin^{m+2} \theta$  in formula (2), it becomes

$$\begin{aligned} \int \sin^m \theta \cos^n \theta \, d\theta &= \frac{\cos^{n-1} \theta \sin^{m+1} \theta}{m+1} \\ &+ \frac{n-1}{m+1} \int \sin^m \theta (\cos^{n-2} \theta - \cos^n \theta) \, d\theta = \frac{\cos^{n-1} \theta \sin^{m+1} \theta}{m+1} \\ &+ \frac{n-1}{m+1} \int \sin^m \theta \cos^{n-2} \theta \, d\theta - \frac{n-1}{m+1} \int \sin^m \theta \cos^n \theta \, d\theta: \end{aligned}$$

hence, transposing the latter integral to the other side, and dividing by  $\frac{m+n}{m+1}$ , we get

$$\int \sin^m \theta \cos^n \theta \, d\theta = \frac{\cos^{n-1} \theta \sin^{m+1} \theta}{m+n} + \frac{n-1}{m+n} \int \sin^m \theta \cos^{n-2} \theta \, d\theta. \quad (C)$$

In like manner, from (3), we get

$$\int \sin^m \theta \cos^n \theta \, d\theta = \frac{m-1}{m+n} \int \sin^{m-2} \theta \cos^n \theta \, d\theta - \frac{\sin^{m-1} \theta \cos^{n+1} \theta}{m+n}. \quad (D)$$

By aid of these formulæ the integral of  $\sin^m \theta \cos^n \theta \, d\theta$  is made to depend on another in which the index of either  $\sin \theta$ , or of  $\cos \theta$ , is reduced by two. By successive application of these formulæ the complete integral can always be found when the indices are integers.

**56. Formulae of Reduction for  $\sin^n \theta d\theta$  and  $\cos^n \theta d\theta$ .** These integrals are evidently cases of the general formulæ (C) and (D); however, they are so frequently employed that we give the formulæ of reduction separately in their case,

$$\int \cos^n \theta d\theta = \frac{\sin \theta \cos^{n-1} \theta}{n} + \frac{n-1}{n} \int \cos^{n-2} \theta d\theta. \quad (4)$$

$$\int \sin^n \theta d\theta = -\frac{\cos \theta \sin^{n-1} \theta}{n} + \frac{n-1}{n} \int \sin^{n-2} \theta d\theta. \quad (5)$$

The former gives, when  $n$  is even,

$$\begin{aligned} \int \cos^n \theta d\theta &= \frac{\sin \theta}{n} \left( \cos^{n-1} \theta + \frac{n-1}{n-2} \cos^{n-3} \theta \right. \\ &+ \left. \frac{(n-1)(n-3)}{(n-2)(n-4)} \cos^{n-5} \theta + \text{&c.} \right) \\ &+ \frac{(n-1)(n-3)(n-5) \dots 1}{n(n-2)(n-4) \dots 2} \theta. \end{aligned} \quad (6)$$

A similar expression is readily obtained for the latter integral.

#### EXAMPLES.

$$1. \quad \int \sin^4 \theta d\theta. \quad \text{Ans.} -\frac{\sin \theta \cos \theta}{4} \left( \sin^2 \theta + \frac{3}{2} \right) + \frac{3}{8} \theta.$$

$$2. \quad \int \cos^2 \theta \sin^4 \theta d\theta. \quad \text{,} \quad \frac{\sin \theta \cos \theta}{2} \left( \frac{\sin^4 \theta}{3} - \frac{\sin^2 \theta}{12} - \frac{1}{8} \right) + \frac{\theta}{16}.$$

$$3. \quad \int \cos^6 \theta d\theta. \quad \text{,} \quad \frac{\sin \theta \cos^3 \theta}{6} \left( \cos^2 \theta + \frac{5}{4} \right) + \frac{5}{16} \left( \sin \theta \cos \theta + \theta \right).$$

**57. Indices both Negative.**—It remains to consider the case where the indices of  $\sin \theta$  and  $\cos \theta$  are both negative.

Writing  $-m$  and  $-n$  instead of  $m$  and  $n$ , in formula (C), it becomes

$$\int \frac{d\theta}{\sin^m \theta \cos^n \theta} = \frac{-1}{(m+n) \cos^{n+1} \theta \sin^{m-1} \theta} + \frac{n+1}{m+n} \int \frac{d\theta}{\sin^m \theta \cos^{n+2} \theta};$$

or, transposing and multiplying by  $\frac{m+n}{n+1}$ ,

$$\int \frac{d\theta}{\sin^m \theta \cos^{n+2} \theta} = \frac{1}{(n+1) \cos^{n+1} \theta \sin^{m-1} \theta} + \frac{m+n}{n+1} \int \frac{d\theta}{\sin^m \theta \cos^n \theta}.$$

Again, if we substitute  $n$  for  $n+2$  in this, it becomes

$$\begin{aligned} \int \frac{d\theta}{\sin^m \theta \cos^n \theta} &= \frac{1}{(n-1) \cos^{n-1} \theta \sin^{m-1} \theta} \\ &+ \frac{m+n-2}{n-1} \int \frac{d\theta}{\sin^m \theta \cos^{n-2} \theta}. \end{aligned} \quad (E)$$

Making a like transformation\* in formula (D), it becomes

$$\begin{aligned} \int \frac{d\theta}{\sin^m \theta \cos^n \theta} &= \frac{1}{(m-1) \sin^{m-1} \theta \cos^{n-1} \theta} \\ &+ \frac{m+n-2}{m-1} \int \frac{d\theta}{\sin^{m-2} \theta \cos^n \theta}. \end{aligned} \quad (F)$$

In each of these, one of the indices is reduced by two degrees, and consequently, by successive applications of the formulæ, the integrals are reducible ultimately to those of one or other of the forms  $\frac{d\theta}{\cos \theta}$  or  $\frac{d\theta}{\sin \theta}$ : these have been already integrated in Art. 17.

The formulæ of reduction for  $\frac{d\theta}{\sin^n \theta}$  and  $\frac{d\theta}{\cos^n \theta}$  are so important that they are added independently, as follows:—

\* It may be observed that formulæ (B), (D), and (F) can be immediately obtained from (A), (C), and (E), by interchanging the letters  $m$  and  $n$ , and substituting  $\frac{\pi}{2} - \phi$  instead of  $\theta$ . For, in this case,  $\sin \theta$ ,  $\cos \theta$ , and  $d\theta$ , transform into  $\cos \phi$ ,  $\sin \phi$ , and  $-d\phi$ , respectively.

$$\int \frac{d\theta}{\cos^n \theta} = \frac{\sin \theta}{(n-1) \cos^{n-1} \theta} + \frac{n-2}{n-1} \int \frac{d\theta}{\cos^{n-2} \theta}. \quad (7)$$

$$\int \frac{d\theta}{\sin^n \theta} = \frac{-\cos \theta}{(n-1) \sin^{n-1} \theta} + \frac{n-2}{n-1} \int \frac{d\theta}{\sin^{n-2} \theta}. \quad (8)$$

It may be here observed that, since  $\sin^2 \theta + \cos^2 \theta = 1$ , we have immediately

$$\int \frac{d\theta}{\sin^m \theta \cos^n \theta} = \int \frac{d\theta}{\sin^{m-2} \theta \cos^n \theta} + \int \frac{d\theta}{\sin^m \theta \cos^{n-2} \theta}; \quad (9)$$

and a similar process is applicable to the latter integrals. This method is often useful in elementary cases.

### EXAMPLES.

$$1. \quad \int \frac{d\theta}{\sin \theta \cos^2 \theta} = \int \frac{\sin \theta d\theta}{\cos^2 \theta} + \int \frac{d\theta}{\sin \theta} = \frac{1}{\cos \theta} + \log \tan \frac{\theta}{2}.$$

$$2. \quad \int \frac{d\theta}{\sin \theta \cos^4 \theta} = \int \frac{\sin \theta d\theta}{\cos^4 \theta} + \int \frac{d\theta}{\sin \theta \cos^2 \theta},$$

and is accordingly immediately integrated by the last.

$$3. \quad \int \frac{d\theta}{\sin^3 \theta}. \quad \text{Ans.} - \frac{\cos \theta}{2 \sin^2 \theta} + \frac{1}{2} \log \tan \frac{\theta}{2}.$$

$$4. \quad \int \frac{d\theta}{\sin^3 \theta \cos^2 \theta}. \quad ", \quad \frac{1}{\cos \theta} - \frac{\cos \theta}{2 \sin^2 \theta} + \frac{3}{2} \log \tan \frac{\theta}{2}.$$

**58. Application of Method of Differentiation.**—The formulæ of reduction given in the preceding Articles can also be readily arrived at by direct differentiation.

Thus, for example, we have

$$\frac{d}{d\theta} \left( \frac{\sin^m \theta}{\cos^n \theta} \right) = \frac{m \sin^{m-1} \theta}{\cos^{n-1} \theta} + \frac{n \sin^{m+1} \theta}{\cos^{n+1} \theta};$$

and, consequently,

$$\int \frac{\sin^{m+1} \theta}{\cos^{n+1} \theta} d\theta = \frac{1}{n} \frac{\sin^m \theta}{\cos^n \theta} - \frac{m}{n} \int \frac{\sin^{m-1} \theta}{\cos^{n-1} \theta} d\theta.$$

This result is easily identified with formula (A).

Again,

$$\frac{d}{d\theta} (\sin^m \theta \cos^n \theta) = m \sin^{m-1} \theta \cos^{n+1} \theta - n \sin^{m+1} \theta \cos^{n-1} \theta.$$

If we substitute for  $\cos^{n+1} \theta$  its equivalent  $\cos^{n-1} \theta (1 - \sin^2 \theta)$ , we get

$$\frac{d}{d\theta} (\sin^m \theta \cos^n \theta) = m \sin^{m-1} \theta \cos^{n-1} \theta - (m+n) \sin^{m+1} \theta \cos^{n-1} \theta;$$

hence we get

$$\int \sin^{m+1} \theta \cos^{n-1} \theta d\theta = - \frac{\sin^m \theta \cos^n \theta}{m+n} + \frac{m}{m+n} \int \sin^{m-1} \theta \cos^{n-1} \theta d\theta,$$

a result easily identified with (D).

The other formulæ of reduction can be readily obtained in like manner.

### 59. Integration of $\tan^n \theta d\theta$ and $\frac{d\theta}{\tan^n \theta}$ .

These integrals may be regarded as cases of the preceding : they can, however, be arrived at in a simpler manner, as follows :—

Since  $\tan^2 \theta = \sec^2 \theta - 1$ , we have

$$\begin{aligned} \int \tan^n \theta d\theta &= \int \tan^{n-2} \theta (\sec^2 \theta - 1) d\theta = \int \tan^{n-2} \theta d(\tan \theta) \\ &\quad - \int \tan^{n-2} \theta d\theta = \frac{\tan^{n-1} \theta}{n-1} - \int \tan^{n-2} \theta d\theta. \quad (10) \end{aligned}$$

By aid of this formula we have, at once,

$$\int \tan^n \theta d\theta = \frac{\tan^{n-1} \theta}{n-1} - \frac{\tan^{n-3} \theta}{n-3} + \frac{\tan^{n-5} \theta}{n-5} - \&c. \quad (11)$$

- (1.) If  $n = 2r + 1$ , the last term is easily seen to be  $(-1)^{r+1} \log(\cos \theta)$ .
- (2.) If  $n = 2r$ , the two last terms may be represented by  $(-1)^{r+1} (\tan \theta - \theta)$ .

In a similar manner we have

$$\int \frac{d\theta}{\tan^n \theta} = \int \frac{\sec^2 \theta \, d\theta}{\tan^n \theta} - \int \frac{d\theta}{\tan^{n-2} \theta} = \frac{-1}{(n-1) \tan^{n-1} \theta} - \int \frac{d\theta}{\tan^{n-2} \theta}. \quad (12)$$

### EXAMPLES.

1.  $\int \tan^4 \theta \, d\theta.$

Ans.  $\frac{\tan^3 \theta}{3} - \tan \theta + \theta.$

2.  $\int \frac{d\theta}{\tan^3 \theta}.$

"  $= \frac{1}{2 \tan^2 \theta} - \log(\sin \theta).$

3.  $\int \frac{d\theta}{\tan^5 \theta}.$

"  $= \frac{-1}{4 \tan^4 \theta} + \frac{1}{2 \tan^2 \theta} + \log(\sin \theta).$

4.  $\int \cot^4 \theta \, d\theta.$

"  $= \frac{\cot^3 \theta}{3} + \cot \theta + \theta.$

**60. Trigonometrical Transformations.**—Many elementary integrations are immediately reducible to one or other of the preceding formulæ of reduction by aid of the transformations given in Art. 26. For example, if we assume  $x = a \tan \theta$ , the expression  $\frac{x^m \, dx}{(a^2 + x^2)^{\frac{m}{2}}}$  transforms into  $\sin^m \theta \cos^{n-m-2} \theta \, d\theta$  (neglecting a constant multiplier).

In like manner, the substitution of  $a \sin \theta$  for  $x$  transforms the expression  $\frac{x^m \, dx}{(a^2 - x^2)^{\frac{m}{2}}}$  into  $\frac{a^{m-n+1} \sin^m \theta \, d\theta}{\cos^{n-1} \theta}$ : and, if  $x = a \sec \theta$ , the expression  $\frac{x^m \, dx}{(x^2 - a^2)^{\frac{m}{2}}}$  transforms into  $\frac{\cos^{n-m-2} \theta \, d\theta}{\sin^{n-1} \theta}$  (neglecting the constant multiplier).

A similar transformation may be applied in other cases. For example, to find the integral of  $\frac{x^n \, dx}{(2ax - x^2)^{\frac{1}{2}}}$ ;

let  $x = 2a \sin^2 \theta$ , then  $dx = 4a \sin \theta \cos \theta \, d\theta$ ,

and the transformed integral is

$$2^{n+1} a^n \int \sin^{2n} \theta \, d\theta :$$

accordingly the formula of reduction is the same as that in (5);

## EXAMPLES.

1.  $\int \frac{x^4 dx}{(1-x^2)^{\frac{1}{2}}}.$   $Ans. \frac{1}{2} + \frac{3}{4} \sin^{-1} x - \frac{x\sqrt{1-x^2}}{8} (3+2x^2).$
2.  $\int \frac{dx}{x^3 \sqrt{1-x^2}}.$   $," \frac{1}{2} \log \frac{1-\sqrt{1-x^2}}{x} - \frac{\sqrt{1-x^2}}{2x^3}.$
3.  $\int \frac{dx}{(a^2+x^2)^{\frac{3}{2}}}.$   $," \frac{x}{a^4(a^2+x^2)^{\frac{1}{2}}} - \frac{x^3}{3a^4(a^2+x^2)^{\frac{3}{2}}}.$
4.  $\int \frac{x^4 dx}{(a^2+x^2)^2}.$   $," \frac{-x^3}{2(a^2+x^2)} + \frac{3}{2} \left( x - a \tan^{-1} \frac{x}{a} \right).$
5.  $\int \frac{x^2 dx}{(2ax-x^2)^{\frac{1}{2}}}.$   $," - (2ax-x^2)^{\frac{1}{2}} \left( \frac{x}{2} + \frac{3a}{2} \right) + 3a^2 \sin^{-1} \sqrt{\frac{x}{2a}}.$

The integrals considered in this Article admit also of a more direct treatment. We shall commence with the following:—

61. **Cases in which  $\frac{x^m dx}{(a+cx^2)^{\frac{n}{2}}}$  is immediately integrable.**

We have seen, in Art. 48, that the proposed expression is integrable immediately when  $m$  is an *odd positive integer*.

Again, when  $m$  is an even integer, if we assume  $a+cx^2 = x^2 z^2$ , the transformed expression is

$$-\frac{(z^2 - c)^{\frac{n-m-3}{2}} dz}{a^{\frac{n-m-1}{2}} z^{n-1}}.$$

This is immediately integrable when  $n-m-1$  is even and positive, i.e. when  $m$  is either an *even negative integer, or an even positive integer, less than  $n-1$* .

For example,  $\frac{dx}{(a+cx^2)^{\frac{n}{2}}}$  becomes  $-\frac{(z^2 - c)^{\frac{n-3}{2}} dz}{a^{\frac{n-1}{2}} z^{n-1}}$ , and

accordingly is always integrable by this transformation, since  $n$  is an odd integer, by hypothesis.

## EXAMPLES.

1.  $\int \frac{dx}{(a + cx^2)^{\frac{3}{2}}}.$

Ans.  $\frac{x}{a^{\frac{1}{2}}(a + cx^2)^{\frac{1}{2}}} \left\{ 1 - \frac{cx^2}{3(a + cx^2)} \right\}.$

2.  $\int \frac{x^2 dx}{(a + cx^2)^{\frac{5}{2}}}.$

"  $\frac{x^3}{a^2(a + cx^2)^{\frac{3}{2}}} \left\{ \frac{1}{3} - \frac{cx^2}{5(a + cx^2)} \right\}.$

3.  $\int \frac{x^3 dx}{(a^2 + x^2)^{\frac{5}{2}}}.$

"  $\frac{-(2a^2 + 3x^2)}{3(a^2 + x^2)^{\frac{3}{2}}}.$

4.  $\int \frac{dx}{x^4(a + cx^2)^{\frac{3}{2}}}.$

The differentials considered in this Article are cases of a more general class called binomial differentials.

62. **Binomial Differentials.**—Expressions of the form

$x^m(a + bx^n)^p dx,$

in which  $m, n, p$  denote any numbers, positive, negative, or fractional, are called Binomial Differentials.

Such expressions can be immediately integrated in two cases, which we proceed to determine by transformations analogous to those adopted in the preceding Article:—

(1). Let  $a + bx^n = z$ ; then  $x = \left(\frac{z - a}{b}\right)^{\frac{1}{n}}$ ,

and  $dx = \frac{1}{nb} \left(\frac{z - a}{b}\right)^{\frac{1}{n}-1} dz;$

hence  $x^m(a + bx^n)^p dx = \frac{(z - a)^{\frac{m+1}{n}-1}}{n b^{\frac{m+1}{n}}} z^p dz.$

Consequently, whenever  $\frac{m+1}{n}$  is a positive integer, the transformed expression is immediately integrable after expansion by the Binomial Theorem.

(2). Again, if we substitute  $\frac{1}{y}$  for  $x$ , the differential becomes

$$-y^{-np-m-2}(ay^n + b)^p dy.$$

This is immediately integrable, as in the preceding case, whenever  $\frac{-(np+m+1)}{n}$  is a positive integer; i. e. when  $\frac{m+1}{n} + p$  is a negative integer. In this latter case the integration is effected by the substitution of  $z$  for  $ax^{-n} + b$ .

### EXAMPLES.

1.	$\int \frac{x^6 dx}{(1+x^3)^{\frac{1}{3}}}.$	<i>Ans.</i> $\frac{2(1+x^3)^{\frac{1}{3}}(x^3-2)}{9}.$
2.	$\int \frac{dx}{(1+x^3)^{\frac{1}{3}}}.$	" $\frac{x}{(1+x^3)^{\frac{1}{3}}}.$
3.	$\int \frac{dx}{x^2(1+x^4)^{\frac{1}{2}}}.$	" $-\frac{(1+x^4)^{\frac{1}{2}}}{x}.$
4.	$\int \frac{dx}{x^3(1+x^2)^{\frac{3}{2}}}.$	" $\frac{2x^{\frac{1}{2}}}{(1+x^2)^{\frac{1}{2}}}.$

When neither of the preceding processes is applicable, the expression, if  $p$  be a fractional index, is, in general, incapable of integration in a finite number of terms. Before proceeding with this investigation we shall discuss a few simple forms of integration by reduction, involving transcendental functions.

63. **Reduction of**  $\int e^{mx} x^n dx,$

where  $n$  is an integer.

Integrating by parts, we have

$$\int x^n e^{mx} dx = \frac{x^n e^{mx}}{m} - \frac{n}{m} \int x^{n-1} e^{mx} dx. \quad (13)$$

By successive applications of this formula the integral is made to depend on  $\int e^{mx} dx$ , i. e. on  $\frac{e^{mx}}{m}$ .

Again, to find  $\int \frac{e^{mx}}{x^n} dx$ .

Assuming  $u = e^{mx}$ ,  $v = \frac{-1}{(n-1)x^{n-1}}$ , and integrating by parts, we have

$$\int \frac{e^{mx} dx}{x^n} = \frac{-e^{mx}}{(n-1)x^{n-1}} + \frac{m}{n-1} \int \frac{e^{mx} dx}{x^{n-1}}. \quad (14)$$

By means of this the integral is reduced to depend on

$$\int \frac{e^{mx} dx}{x}.$$

The value of this integral cannot be obtained in a finite form; it however may be exhibited in the shape of an infinite series; for, expanding  $e^{mx}$  and integrating each term separately, we have

$$\int \frac{e^{mx} dx}{x} = \log x + \frac{mx}{1} + \frac{m^2 x^2}{1 \cdot 2^2} + \frac{m^3 x^3}{1 \cdot 2 \cdot 3^2} + \text{&c.} \quad (15)$$

The integral of  $a^x x^n dx$  is immediately reducible to the preceding, since  $a^x = e^{x \log a}$ . Consequently, by the substitution of  $\log a$  for  $m$  in (13) and (14), we obtain the formulæ of reduction for

$$\int a^x x^n dx \text{ and } \int \frac{a^x}{x^n} dx.$$

In like manner we have immediately

$$\int e^{-x} x^n dx = -e^{-x} x^n + n \int e^{-x} x^{n-1} dx. \quad (16)$$

#### 64. Reduction of $\int x^m (\log x)^n dx$ .

Let  $y = \log x$ , and the integral reduces to that discussed in the last Article.

The formula of reduction is

$$\int x^m (\log x)^n dx = \frac{x^{m+1} (\log x)^n}{m+1} - \frac{n}{m+1} \int x^m (\log x)^{n-1} dx. \quad (17)$$

## EXAMPLES.

1.  $\int x^3 e^{ax} dx.$

Ans.  $\frac{e^{ax}}{a} \left\{ x^3 - \frac{3}{a} x^2 + \frac{3 \cdot 2}{a^2} x - \frac{3 \cdot 2 \cdot 1}{a^3} \right\}.$

2.  $\int x^3 (\log x)^2 dx.$

, ,  $\frac{x^4}{4} \left\{ (\log x)^2 - \frac{\log x}{2} + \frac{1}{8} \right\}.$

3.  $\int \frac{e^x dx}{x^4}.$

, ,  $-\frac{e^x}{3} \left\{ \frac{1}{x^3} + \frac{1}{2x^2} + \frac{1}{2x} \right\} + \frac{1}{3 \cdot 2 \cdot 1} \int \frac{e^x dx}{x}.$

65. Reduction of  $\int x^n \cos ax dx.$ 

Here  $\int x^n \cos ax dx = \frac{x^n \sin ax}{a} - \frac{n}{a} \int x^{n-1} \sin ax dx;$

again

$$\int x^{n-1} \sin ax dx = -\frac{x^{n-1} \cos ax}{a} + \frac{n-1}{a} \int x^{n-2} \cos ax dx,$$

hence

$$\int x^n \cos ax dx = \frac{x^{n-1} (ax \sin ax + n \cos ax)}{a^2} - \frac{n(n-1)}{a^3} \int x^{n-2} \cos ax dx.$$

The formula of reduction for  $x^n \sin ax dx$  can be obtained in like manner.Again, if we substitute  $y$  for  $\sin^{-1} x$ , the integral

$$\int (\sin^{-1} x)^n dx$$

transforms into

$$\int y^n \cos y dy,$$

and accordingly its value can be found by the preceding formula.

## EXAMPLES.

1.  $\int x^3 \cos x dx.$  Ans.  $x^3 \sin x + 3x^2 \cos x - 3 \cdot 2 \cdot x \sin x - 3 \cdot 2 \cdot 1 \cdot \cos x.$

2.  $\int x^4 \sin x dx.$

Ans.  $-x^4 \cos x + 4x^3 \sin x + 4 \cdot 3 \cdot x^2 \cos x - 4 \cdot 3 \cdot 2 \cdot x \sin x - 4 \cdot 3 \cdot 2 \cdot 1 \cdot \cos x$

66. **Reduction of  $\int e^{ax} \cos^n x dx$ .**

Integrating by parts, we get

$$\int e^{ax} \cos^n x dx = \frac{\cos^n x e^{ax}}{a} + \frac{n}{a} \int e^{ax} \cos^{n-1} x \sin x dx.$$

Again,

$$\int e^{ax} \cos^{n-1} x \sin x dx$$

$$\begin{aligned} &= \frac{e^{ax} \cos^{n-1} x \sin x}{a} - \frac{1}{a} \int e^{ax} \{ \cos^n x - (n-1) \cos^{n-2} x \sin^2 x \} dx \\ &= \frac{e^{ax} \cos^{n-1} x \sin x}{a} + \frac{(n-1)}{a} \int e^{ax} \cos^{n-2} x dx - \frac{n}{a} \int e^{ax} \cos^n x dx : \end{aligned}$$

substituting, and solving for  $\int e^{ax} \cos^n x dx$ , we get

$$\begin{aligned} \int e^{ax} \cos^n x dx &= \frac{e^{ax} \cos^{n-1} x (a \cos x + n \sin x)}{a^2 + n^2} \\ &+ \frac{n(n-1)}{a^2 + n^2} \int e^{ax} \cos^{n-2} x dx. \end{aligned} \quad (18)$$

The form of reduction for  $e^{ax} \sin^n x dx$  can be obtained in like manner.67. **Reduction of  $\int \cos^m x \sin nx dx$ .**

Integrating by parts, we get

$$\int \cos^m x \sin nx dx = - \frac{\cos^m x \cos nx}{n} - \frac{m}{n} \int \cos^{m-1} x \cos nx \sin x dx :$$

replacing  $\cos nx \sin x$  by  $\sin nx \cos x - \sin(n-1)x$ , after one or two simple transformations we get

$$\begin{aligned} \int \cos^m x \sin nx dx &= - \frac{\cos^m x \cos nx}{m+n} \\ &+ \frac{m}{m+n} \int \cos^{m-1} x \sin(n-1)x dx. \end{aligned} \quad (19)$$

The mode of reduction for  $\cos^m x \cos nx dx$ ,  $\sin^m x \cos nx dx$ , and  $\sin^m x \sin nx dx$  can be easily found in like manner.

## EXAMPLES.

$$1. \int e^{ax} \sin^2 x dx. \quad \text{Ans. } \frac{e^{ax} \sin x}{4 + a^2} (a \sin x - 2 \cos x) + \frac{2e^{ax}}{a(4 + a^2)}.$$

$$2. \int \cos^2 x \sin 4x dx. \quad \text{,} \quad -\frac{\cos^2 x \cos 4x}{6} - \frac{\cos x \cdot \cos 3x}{12} - \frac{\cos 2x}{24}.$$

$$3. \int e^{-x} \cos^2 x dx. \quad \text{,} \quad -\frac{e^{-x}}{5} (\cos^2 x - \sin 2x + 2).$$

68. **Reduction by Differentiation.**—We shall now return to the discussion of the integrals already considered in Arts. 60 and 61; and commence with the reduction of the expression  $\frac{x^m dx}{(a + cx^2)^{\frac{1}{2}}}$ . This, as well as other formulæ of reduction of the same type, is best investigated by the aid of a previous differentiation.

Thus we have

$$\begin{aligned} \frac{d}{dx} \left\{ x^{m-1} (a + cx^2)^{\frac{1}{2}} \right\} &= (m - 1) x^{m-2} (a + cx^2)^{\frac{1}{2}} + \frac{cx^m}{(a + cx^2)^{\frac{1}{2}}} \\ &= \frac{(m - 1) x^{m-2} (a + cx^2) + cx^m}{(a + cx^2)^{\frac{1}{2}}} \\ &= \frac{(m - 1) ax^{m-2}}{(a + cx^2)^{\frac{1}{2}}} + \frac{mcx^m}{(a + cx^2)^{\frac{1}{2}}}; \end{aligned}$$

hence, transposing and integrating, we obtain

$$\int \frac{x^m dx}{(a + cx^2)^{\frac{1}{2}}} = \frac{x^{m-1} (a + cx^2)^{\frac{1}{2}}}{mc} - \frac{(m - 1) a}{mc} \int \frac{x^{m-2} dx}{(a + cx^2)^{\frac{1}{2}}}. \quad (20)$$

By this formula the integral is reduced to one or more dimensions; and by repetition of the same process the expression can be always integrated when  $m$  is a positive integer.

The formula (20) evidently holds whether  $m$  be positive

or negative; accordingly, if we change  $m$  into  $-(m - 2)$ , we obtain, after transposing and dividing,

$$\int \frac{dx}{x^m (a + cx^2)^{\frac{1}{2}}} = - \frac{(a + cx^2)^{\frac{1}{2}}}{(m - 1) ax^{m-1}} - \frac{(m - 2) c}{(m - 1) a} \int \frac{dx}{x^{m-2} (a + cx^2)^{\frac{1}{2}}}. \quad (21)$$

### 69. More generally, we have

$$\begin{aligned} \frac{d}{dx} \{x^{m-1} (a + cx^2)^n\} &= (m - 1) x^{m-2} (a + cx^2)^n + 2ncx^m (a + cx^2)^{n-1} \\ &= (a + cx^2)^{n-1} \{(m - 1) ax^{m-2} + (m + 2n - 1) cx^m\}. \end{aligned}$$

Hence

$$\begin{aligned} \int x^m (a + cx^2)^{n-1} dx &= \frac{x^{m-1} (a + cx^2)^n}{(m + 2n - 1) c} \\ &\quad - \frac{(m - 1) a}{(m + 2n - 1) c} \int x^{m-2} (a + cx^2)^{n-1} dx. \quad (22) \end{aligned}$$

Consequently, when  $m$  is positive the integral can be reduced to one lower by two degrees. If  $m$  be negative, the formula can be transformed as in the preceding Article, and the integration reduced two degrees.

We next proceed to consider the case where  $n$  is negative.

### 70. Reduction of $\int \frac{x^m dx}{(a + cx^2)^n},$

$m$  and  $n$  being both positive.

$$\text{Here } \int \frac{x^m dx}{(a + cx^2)^n} = \int x^{m-1} \frac{x dx}{(a + cx^2)^n}.$$

$$\text{Let } x^{m-1} = u, \text{ and } \int \frac{x dx}{(a + cx^2)^n} = v,$$

$$\text{or } \frac{-1}{2(n - 1)c(a + cx^2)^{n-1}} = v,$$

and we get

$$\int \frac{x^m dx}{(a + cx^2)^n} = \frac{-x^{m-1}}{2(n - 1)c(a + cx^2)^{n-1}} + \frac{m - 1}{2(n - 1)c} \int \frac{x^{m-2} dx}{(a + cx^2)^{n-1}}. \quad (23)$$

By successive applications of this form the integral admits of being reduced to another of a simpler shape. We are not able, however, to find the complete integral by this formula, unless when  $n$  is either an integer, or is of the form  $\frac{r}{2}$ , where  $r$  is an integer.

71. **Reduction of**  $\int \frac{x^m dx}{(a + 2bx + cx^2)^{\frac{1}{2}}}.$

By differentiation, we have

$$\begin{aligned} \frac{d}{dx} \{x^{m-1}(a + 2bx + cx^2)^{\frac{1}{2}}\} &= (m-1)x^{m-2}(a + 2bx + cx^2)^{\frac{1}{2}} \\ &+ \frac{x^{m-1}(b + cx)}{(a + 2bx + cx^2)^{\frac{1}{2}}} = \frac{(m-1)ax^{m-2} + (2m-1)bx^{m-1} + mcx^m}{(a + 2bx + cx^2)^{\frac{1}{2}}}; \end{aligned}$$

hence 
$$\int \frac{x^m dx}{(a + 2bx + cx^2)^{\frac{1}{2}}} = \frac{x^{m-1}(a + 2bx + cx^2)^{\frac{1}{2}}}{mc}$$

$$- \frac{(2m-1)b}{mc} \int \frac{x^{m-1} dx}{(a + 2bx + cx^2)^{\frac{1}{2}}} - \frac{(m-1)a}{mc} \int \frac{x^{m-2} dx}{(a + 2bx + cx^2)^{\frac{1}{2}}}. \quad (24)$$

This furnishes the formula of reduction for this case: by successive applications of it the integral depends ultimately on those of

$$\frac{x dx}{(a + 2bx + cx^2)^{\frac{1}{2}}} \text{ and } \frac{dx}{(a + 2bx + cx^2)^{\frac{1}{2}}}.$$

These have been determined already in Arts. 9 and 12.

Again, the integral of  $\frac{dx}{x^m(a + 2bx + cx^2)^{\frac{1}{2}}}$  can be reduced to the preceding form by making  $x = \frac{1}{z}$ .

## 72. The more general integral

$$\int \frac{x^m dx}{(a + 2bx + cx^2)^n}$$

admits of being treated in like manner.

Reduction of  $\int \frac{x^m dx}{(a + 2bx + cx^2)^n}$ .

83

For if  $a + 2bx + cx^2$  be represented by  $T$ , we have, by differentiation,

$$\begin{aligned} \frac{d}{dx} \left( \frac{x^{m-1}}{T^{n-1}} \right) &= \frac{(m-1)x^{m-2}}{T^{n-1}} - \frac{2(n-1)x^{m-1}(b+cx)}{T^n} \\ &= \frac{(m-1)x^{m-2}(a+2bx+cx^2) - 2(n-1)x^{m-1}(b+cx)}{T^n} \\ &= \frac{(m-1)ax^{m-2}}{T^n} + \frac{2b(m-n)x^{m-1}}{T^n} - \frac{(2n-m-1)cx^m}{T^n}. \end{aligned}$$

Hence, we get the formula of reduction

$$\begin{aligned} \int \frac{x^m dx}{T^n} &= \frac{-x^{m-1}}{(2n-m-1)c T^{n-1}} + \frac{2(m-n)b}{(2n-m-1)c} \int \frac{x^{m-1} dx}{T^n} \\ &\quad + \frac{(m-1)a}{(2n-m-1)c} \int \frac{x^{m-2} dx}{T^n}. \quad (25) \end{aligned}$$

By aid of this, the integral of  $\frac{x^m dx}{T^n}$ , when  $m$  is a positive integer, is made to depend on those of  $\frac{x dx}{T^n}$  and  $\frac{dx}{T^n}$ . Again, it is easily seen that the integral of  $\frac{x dx}{T^n}$  is reduced to that of  $\frac{dx}{T^n}$ , for

$$\begin{aligned} \int \frac{x dx}{T^n} &= \frac{1}{c} \int \frac{(b+cx)dx}{T^n} - \frac{b}{c} \int \frac{dx}{T^n} \\ &= \frac{-1}{2(n-1)c T^{n-1}} - \frac{b}{c} \int \frac{dx}{T^n}. \quad (26) \\ &\quad [6 a] \end{aligned}$$

73. **Reduction of**  $\int \frac{dx}{(a + 2bx + cx^2)^n}$ .

In order to reduce  $\int \frac{dx}{T^n}$ , we have

$$\begin{aligned}\frac{d}{dx} \left( \frac{b+cx}{T^n} \right) &= \frac{c}{T^n} - \frac{2n(b+cx)^2}{T^{n+1}} \\ &= \frac{c}{T^n} + \frac{2n(ac-b^2)}{T^{n+1}} - \frac{2nc}{T^n} = \frac{2n(ac-b^2)}{T^{n+1}} - \frac{(2n-1)c}{T^n}.\end{aligned}$$

Hence  $\int \frac{dx}{T^{n+1}} = \frac{b+cx}{2n(ac-b^2)T^n} + \frac{(2n-1)c}{2n(ac-b^2)} \int \frac{dx}{T^n}$ . (27)

By aid of this formula of reduction the integral of  $\frac{dx}{T^n}$  can be found whenever  $n$  is an integer, or when it is of the form  $\frac{r}{2}$  ( $r$  being an integer).

74. **Reduction of**  $\int \frac{dx}{(a + b \cos x)^n} = \int \frac{du}{U^n}$

when  $n$  is a positive integer.

Let  $U = a + b \cos x$ , then  $\frac{dU}{dx} = -b \sin x$ ,  $\cos x = \frac{U-a}{b}$ .

Again, by differentiation, we have

$$\begin{aligned}\frac{d}{dx} \left\{ \frac{\sin x}{U^{n-1}} \right\} &= \frac{\cos x}{U^{n-1}} + \frac{(n-1)b \sin^2 x}{U^n} \\ &= \frac{\cos x}{U^{n-1}} + \frac{(n-1)b}{U^n} - \frac{(n-1)b \cos^2 x}{U^n};\end{aligned}$$

substitute  $\frac{U-a}{b}$  for  $\cos x$  in the numerators of these fractions, and we get

$$\begin{aligned}\frac{d}{dx} \left\{ \frac{\sin x}{U^{n-1}} \right\} &= \frac{1}{bU^{n-2}} - \frac{a}{bU^{n-1}} + \frac{(n-1)b}{U^n} - \frac{n-1}{bU^{n-2}} + \frac{2(n-1)a}{bU^{n-1}} \\ &\quad - \frac{(n-1)a^2}{bU^n} = -\frac{(n-2)}{bU^{n-2}} + \frac{(2n-3)a}{bU^{n-1}} - \frac{(n-1)(a^2-b^2)}{bU^n}.\end{aligned}$$

Hence, transposing and integrating, we get

$$\begin{aligned} \int \frac{dx}{U^n} &= \frac{-b \sin x}{(n-1)(a^2 - b^2) U^{n-1}} + \frac{(2n-3)a}{(n-1)(a^2 - b^2)} \int \frac{dx}{U^{n-1}} \\ &\quad - \frac{n-2}{(n-1)(a^2 - b^2)} \int \frac{dx}{U^{n-2}}. \end{aligned} \quad (28)$$

By this formula the proposed integral can be reduced to depend on

$$\int \frac{dx}{a + b \cos x},$$

the value of which has been found in Art. 18.

75. The integral considered in the last Article can also be found by aid of a transformation, whenever  $a$  is greater than  $b$ , as follows:—

$$\begin{aligned} \frac{dx}{(a + b \cos x)^n} &= \frac{dx}{\left\{ (a+b) \cos^2 \frac{x}{2} + (a-b) \sin^2 \frac{x}{2} \right\}^n} \\ &= \frac{dx}{\left( A \cos^2 \frac{x}{2} + B \sin^2 \frac{x}{2} \right)^n} = \frac{\left( 1 + \tan^2 \frac{x}{2} \right)^n dx}{\left( A + B \tan^2 \frac{x}{2} \right)^n} \end{aligned}$$

(where  $A = a + b$ ,  $B = a - b$ ).

Next, assume  $\tan \frac{x}{2} = \sqrt{\frac{A}{B}} \tan \phi$ , then

$$\left( 1 + \tan^2 \frac{x}{2} \right) dx = 2 \sqrt{\frac{A}{B}} (1 + \tan^2 \phi) d\phi :$$

and we get

$$\begin{aligned} \frac{\left(1 + \tan^2 \frac{x}{2}\right)^n dx}{\left(A + B \tan^2 \frac{x}{2}\right)^n} &= 2 \sqrt{\frac{A}{B}} \frac{\left(1 + \frac{A}{B} \tan^2 \phi\right)^{n-1} d\phi}{A^n \sec^{2n-2} \phi} \\ &= \frac{2(B \cos^2 \phi + A \sin^2 \phi)^{n-1} d\phi}{(AB)^{n-1}}. \end{aligned}$$

Hence, replacing  $A$  and  $B$  by  $a + b$  and  $a - b$ , we get

$$\int \frac{dx}{(a + b \cos x)^n} = 2 \int \frac{(a - b \cos 2\phi)^{n-1} d\phi}{(a^2 - b^2)^{n-1}}. \quad (29)$$

When  $n$  is a positive integer, the integral at the right-hand side can be found by expanding  $(a - b \cos 2\phi)^{n-1}$ , and integrating each term separately by formula (4).

Again, if in (29) we make  $b = a \cos a$ , and  $2\phi = y$ , we obtain

$$\int \frac{dx}{(1 + \cos a \cos x)^n} = \frac{1}{\sin^{2n-1} a} \int (1 - \cos a \cos y)^{n-1} dy, \quad (30)$$

where  $\tan \frac{y}{2} = \tan \frac{a}{2} \tan \frac{x}{2}$ .

Hence, if we take 0 and  $\frac{\pi}{2}$  as limits for  $x$ , we have

$$\int_0^{\frac{\pi}{2}} \frac{dx}{(1 + \cos a \cos x)^n} = \frac{1}{\sin^{2n-1} a} \int_0^{\frac{\pi}{2}} (1 - \cos a \cos y)^{n-1} dy. \quad \text{See 21.1.1 for a.}$$

**76. Integration of**  $\frac{f(x) dx}{\phi(x) \sqrt{a + 2bx + cx^2}}$ .

We shall conclude this Chapter with the discussion of the above form, where  $f(x)$  and  $\phi(x)$  are supposed rational algebraic functions of  $x$ .

If  $f(x)$  be of higher dimensions than  $\phi(x)$ , the fraction may be written in the form

$$\frac{f(x)}{\phi(x)} = Q + \frac{R}{\phi(x)}.$$

Again, since  $Q$  is of the form  $p + qx + rx^2 + \&c.$ , the integration of  $\frac{Q dx}{\sqrt{a + 2bx + cx^2}}$  can be found by the method of Art. 71.

The fraction  $\frac{R}{\phi(x)}$  can be decomposed by the method of partial fractions (Chap. II.). To any root  $a$ , which is not a multiple root, corresponds a term of the form  $\frac{A}{x - a}$ , and the corresponding term in the expression under discussion is

$$\frac{A dx}{(x - a) \sqrt{a + 2bx + cx^2}}.$$

The method of integration of this has been given in Art. 13.

Next, to a multiple root correspond terms of the form

$$\frac{B dx}{(x - a)^r \sqrt{a + 2bx + cx^2}}.$$

This is reducible to the form of Art. 71 on making  $x - a = \frac{1}{z}$ . Again, to a pair of imaginary roots corresponds an expression of the form

$$\frac{(lx + m) dx}{\{(x - a)^2 + \beta^2\} \sqrt{a + 2bx + cx^2}}.$$

If  $z$  be substituted for  $x - a$ , the transformed expression may be written

$$\frac{(Lz + M) dz}{(z^2 + \beta^2) \sqrt{A + 2Bz + Cz^2}},$$

where  $L, M, A, B, C$ , are constants.

To integrate this form; assume\*  $z = \beta \tan(\theta + \gamma)$ , where

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\* For this simple method of determining the integral in question I am indebted to Mr. Cathcart.

$\theta$  is a new variable, and  $\gamma$  an arbitrary constant, and the transformed expression is

$$\frac{\{L\beta \sin(\theta + \gamma) + M \cos(\theta + \gamma)\}d\theta}{\beta \sqrt{A \cos^2(\theta + \gamma) + 2B\beta \cos(\theta + \gamma) \sin(\theta + \gamma) + C\beta^2 \sin^2(\theta + \gamma)}}.$$

Again, the expression under the square root is easily transformed into

$$\begin{aligned} & \frac{1}{2} \{A + C\beta^2 + (A - C\beta^2) \cos 2(\theta + \gamma) + 2B\beta \sin 2(\theta + \gamma)\} \\ &= \frac{1}{2} \left[ A + C\beta^2 + \cos 2\theta \{ (A - C\beta^2) \cos 2\gamma + 2B\beta \sin 2\gamma \} \right. \\ & \quad \left. + \sin 2\theta \{ 2B\beta \cos 2\gamma - (A - C\beta^2) \sin 2\gamma \} \right]. \end{aligned}$$

Moreover, since  $\gamma$  is perfectly arbitrary, it may be assumed so as to satisfy the equation

$$2B\beta \cos 2\gamma - (A - C\beta^2) \sin 2\gamma = 0, \text{ or } \tan 2\gamma = \frac{2B\beta}{A - C\beta^2}:$$

and consequently the proposed expression is reducible to the form

$$\frac{(L' \cos \theta + M' \sin \theta) d\theta}{\sqrt{P + Q \cos 2\theta}}$$

(in which  $L'$ ,  $M'$ ,  $P$  and  $Q$  are constants), or

$$\frac{L'd(\sin \theta)}{\sqrt{P + Q - 2Q \sin^2 \theta}} - \frac{M'd(\cos \theta)}{\sqrt{P - Q + 2Q \cos^2 \theta}},$$

each of which is immediately integrable.

## EXAMPLES.

1. 
$$\int \cos^3 \theta \sin 2\theta d\theta. \quad Ans. -\frac{2}{5} \cos^5 \theta.$$

2. 
$$\int \sin^2 \theta \cos^3 \theta d\theta. \quad , \quad \frac{\sin^3 \theta}{3} - \frac{\sin^5 \theta}{5}.$$

3. 
$$\int \sin^5 \theta \cos^5 \theta d\theta. \quad , \quad -\frac{1}{64} \left\{ \cos 2\theta - \frac{2}{3} \cos^3 2\theta + \frac{1}{5} \cos^5 2\theta \right\}.$$

4. 
$$\int \frac{\cos^4 \theta d\theta}{\sin \theta}. \quad , \quad \frac{\cos^3 \theta}{3} + \cos \theta + \log \left( \tan \frac{\theta}{2} \right).$$

5. 
$$\int \frac{\cos^4 \theta d\theta}{\sin^3 \theta}. \quad , \quad \left( \cos^3 \theta - \frac{3}{2} \cos \theta \right) \frac{1}{\sin^2 \theta} - \frac{3}{2} \log \tan \left( \frac{\theta}{2} \right).$$

6. 
$$\int \frac{dx}{(1+x^2)^{\frac{5}{2}}}. \quad , \quad \left( \frac{4+2}{5+3} x^4 + \frac{4}{3} x^2 + 1 \right) \frac{x}{(1+x^2)^{\frac{5}{2}}}.$$

7. 
$$\int x^{2n-1} (a+bx^n)^p dx. \quad , \quad \frac{(a+bx^n)^{p+1} \{ (p+1)bx^n - a \}}{n(p+1)(p+2)b^2}.$$

8. 
$$\int e^{-x} \cos^3 x dx. \quad , \quad \frac{e^{-x}}{10} \left\{ 3(\sin x - \cos x) + \cos^2 x (3 \sin x - \cos x) \right\}.$$

9. If 
$$\int \frac{d\theta}{\sin^m \theta \cos^n \theta} = \frac{A}{\sin^{m-1} \theta \cos^{n-1} \theta} + B \int \frac{d\theta}{\sin^{m-2} \theta \cos^n \theta},$$

determine the values of  $A$  and  $B$  by differentiation.

10. 
$$\int \frac{(x^2 - a^2) dx}{(x^2 + a^2)^3}.$$

11. 
$$\int \frac{\sin^2 \theta d\theta}{(1+\cos \theta)^2}. \quad Ans. 2 \tan \frac{\theta}{2} - \theta.$$

12. Prove that the integral 
$$\int \frac{\sin^m \theta d\theta}{(1+\cos \theta)^n}$$
 transforms into  $2^{m-n+1} \int \frac{\sin^m \phi d\phi}{\cos^{2n-m} \phi}$ ,  
 where  $\theta = 2\phi$ .

13.  $\int \frac{dx}{(a + b \cos x)^3}.$

*Ans.*  $\frac{-b \sin x}{(a^2 - b^2)(a + b \cos x)} + \frac{2a}{(a^2 - b^2)^{\frac{3}{2}}} \tan^{-1} \left\{ \left( \frac{a - b}{a + b} \right)^{\frac{1}{2}} \tan \frac{x}{2} \right\}.$

14.  $\int \frac{\cos \theta d\theta}{(5 + 4 \cos \theta)^2}.$  *Ans.*  $\frac{5}{9} \cdot \frac{\sin \theta}{5 + 4 \cos \theta} - \frac{8}{27} \tan^{-1} \left( \frac{\tan \frac{\theta}{2}}{3} \right).$

15.  $\int (\sin^{-1} x)^4 dx = x \{ (\sin^{-1} x)^4 - 4 \cdot 3 \cdot (\sin^{-1} x)^2 + 4 \cdot 3 \cdot 2 \cdot 1 \}$

$+ 4\sqrt{1 - x^2} \sin^{-1} x \{ (\sin^{-1} x)^2 - 3 \cdot 2 \}.$

16. Prove by Art. 74, that any expression of the form  $\frac{f(\cos x) dx}{(a + b \cos x)^n}$  is capable of being integrated when  $f(\cos x)$  consists of integral powers of  $\cos x$ .

17. Show, in like manner, that the expression

$$\frac{f(\cos x, \sin x) dx}{(a + b \cos x)^n}$$

can be integrated when  $f(\cos x \sin x)$  consists only of integral powers of  $\cos x$  and  $\sin x$ .

18. If  $\int \frac{(A + Bx + Cx^2) dx}{(a + \beta x)(a + bx + cx^2)} = P \log(a + \beta x) + Q \log(a + bx + cx^2)$ ,

$$+ R \int \frac{dx}{a + bx + cx^2},$$

find the values of  $P$ ,  $Q$ , and  $R$ .

19.  $\int \frac{d\theta}{(a \cos^2 \theta + b \sin^2 \theta)^{\frac{3}{2}}}.$  *Ans.*  $\frac{(a + b)\phi}{2(ab)^{\frac{3}{2}}} - \frac{(a - b) \sin 2\phi}{4(ab)^{\frac{3}{2}}},$

where  $\tan \phi = \sqrt{\frac{b}{a}} \tan \theta.$

\* 20. Find the values of  $n$  for which  $\int \frac{x^n dx}{\sqrt{a^{2n} - x^{2n}}}$  is integrable in finite terms.

21. Prove that

$$\int_0^{\pi} \frac{dx}{(1 + \cos \alpha \cos x)^n} = \frac{1}{\sin^{2n-1} \alpha} \int_0^{\pi} (1 - \cos \alpha \cos y)^{n-1} dy.$$

## CHAPTER IV.

## INTEGRATION BY RATIONALIZATION.

77. **Integration of Monomials.**—If an algebraic expression contain fractional powers of the variable  $x$  it can evidently be rendered rational by assuming  $x = z^n$ , where  $n$  is the least common multiple of the denominators of the several fractional powers. By this means the integration of such expressions is reduced to that of rational functions.

For example, to find

$$\int \frac{(1 + x^{\frac{1}{4}})dx}{1 + x^{\frac{1}{2}}}.$$

Let  $x = z^4$ , and the transformed expression is

$$4 \int \frac{z^3(1 + z)dz}{1 + z^2}.$$

Consequently the value of the integral is

$$\frac{4x^{\frac{1}{4}}}{3} + 2x^{\frac{1}{4}} - 4x^{\frac{1}{4}} + 4 \tan^{-1}(x^{\frac{1}{4}}) - 2 \log(1 + x^{\frac{1}{4}}).$$

Again, any algebraic expression containing integral powers of  $x$  along with irrational powers of an expression of the form  $a + bx$  is immediately reduced to the preceding, by the substitution of  $z$  for  $a + bx$ .

## EXAMPLES.

1.  $\int \frac{x^3 dx}{\sqrt{x-1}}$       *Ans.*  $\frac{2\sqrt{x-1}}{5 \cdot 7} [5x^3 + 6x^2 + 8x + 16]$ .

2.  $\int \frac{x dx}{(a + bx)^{\frac{3}{2}}}$       "       $\frac{2}{b^2} \frac{(2a + bx)}{\sqrt{a + bx}}.$

3.  $\int \frac{dx}{x + \sqrt{x-1}}$ .      "       $\log(x + \sqrt{x-1}) - \frac{2}{\sqrt{3}} \tan^{-1} \left( \frac{2\sqrt{x-1} + 1}{\sqrt{3}} \right).$

78. **Rationalization of  $F(x, \sqrt{a + 2bx + cx^2}) dx$ .** It has been observed (Art. 28) that the integration, in a finite form of irrational expressions containing powers of  $x$  beyond the second, is in general impossible without introducing new transcendental functions. We shall accordingly restrict our investigation to the case of an algebraic function containing a single radical of the form  $\sqrt{a + 2bx + cx^2}$ , where  $a, b, c$  are any constants, positive or negative.

Integrals of this form have been already treated by the method of Reduction (Art. 76). We shall discuss them here by the method of rationalization.

The expression\*  $\frac{f(x)}{\phi(x)} \frac{dx}{\sqrt{a + 2bx + cx^2}}$  can be made rational in several ways, which we propose to consider in order:—

$$(1). \text{ Assume } \sqrt{a + 2bx + cx^2} = z - x \sqrt{c} = \sqrt{1 - \frac{x^2}{z^2}} \quad (1)$$

Then  $a + 2bx = z^2 - 2xz \sqrt{c}$ ;  $\therefore bdx = zdz - \sqrt{c}(xdz + zdx)$ ,  
or  $dx(b + z \sqrt{c}) = dz(z - x \sqrt{c}) = dz \sqrt{a + 2bx + cx^2}$ ;

$$\therefore \frac{dx}{\sqrt{a + 2bx + cx^2}} = \frac{dz}{b + z \sqrt{c}} \quad (2)$$

$$\text{Also } x = \frac{z^2 - a}{2(b + z \sqrt{c})} \quad (3)$$

This substitution obviously renders the proposed expression rational; and its integration is reducible to that of the class considered in Chapter II.

\* It will be shown subsequently that the integration of all expressions of the form

$$F(x, \sqrt{a + 2bx + cx^2}) dx$$

is reducible to that of the above when  $F$  is a rational algebraic function.

It may also be observed that, in general, the most expeditious method of integration in practice is that of successive Reduction (Arts. 71, 72, 76).

When  $b = 0$ , we get

$$\frac{dx}{\sqrt{a + cx^2}} = \frac{dz}{z\sqrt{c}}, \text{ and } x = \frac{z^2 - a}{2z\sqrt{c}} \text{ (see Art. 9).}$$

By aid of the preceding substitution the expression

$$\frac{dx}{(x - p)\sqrt{a + 2bx + cx^2}} \text{ (Art. 13)}$$

transforms into  $\frac{dz}{z^2 - 2zp\sqrt{c} - a - 2pb}$ .

For example, to find  $\int \frac{dx}{(p + qx)\sqrt{1 + x^2}}$ .

Here  $x = \frac{z^2 - 1}{2z}$ , and  $\frac{dx}{(p + qx)\sqrt{1 + x^2}} = \frac{2dz}{qz^2 + 2pz - q}$ ;

$$\therefore \int \frac{dx}{(p + qx)\sqrt{1 + x^2}} = \frac{1}{\sqrt{p^2 + q^2}} \log \left( \frac{qz + p - \sqrt{p^2 + q^2}}{qz + p + \sqrt{p^2 + q^2}} \right).$$

When the coefficient  $c$  is negative the preceding method introduces imaginaries: we proceed to other transformations in which they are avoided.

$$(2). \text{ Assume* } \sqrt{a + 2bx + cx^2} = \sqrt{a + xz}. \quad (4)$$

Squaring both sides, we get immediately

$$2b + cx = 2z\sqrt{a + xz^2};$$

$$\therefore dx(c - z^2) = 2dz(\sqrt{a + xz}) = 2dz\sqrt{a + 2bx + cx^2}.$$

$$\text{Hence } \frac{dx}{\sqrt{a + 2bx + cx^2}} = \frac{2dz}{c - z^2}. \quad (5)$$

\* This is reducible to the preceding, by changing  $x$  into  $\frac{y}{y'}$ , and then employing the former transformation.

And

$$x = \frac{2(z\sqrt{a-b})}{c-z^2}. \quad (6)$$

This substitution also evidently renders the proposed expression rational, provided  $a$  be positive.

For example, to find

$$\int \frac{dx}{x\sqrt{1-x^2}}.$$

Assume  $\sqrt{1-x^2} = 1-xz$ , and we get

$$\int \frac{dx}{x\sqrt{1-x^2}} = \int \frac{dz}{z} = \log z = \log \left( \frac{1-\sqrt{1-x^2}}{x} \right).$$

(3). Again, when the roots of  $a+2bx+cx^2$  are real, there is another method of transformation.

For, let  $\alpha$  and  $\beta$  be the roots, and the radical becomes of the form

$$\sqrt{c(x-\alpha)(x-\beta)}, \text{ or } \sqrt{c(x-\alpha)(\beta-x)},$$

according as the coefficient of  $x^2$  is positive or negative.

In the former case, assume  $\sqrt{x-\alpha} = z\sqrt{x-\beta}$ , and we get

$$x = \frac{\alpha - \beta z^2}{1 - z^2}; \text{ hence } x - \beta = \frac{\alpha - \beta}{1 - z^2}; \therefore \frac{dx}{x - \beta} = \frac{2zdz}{1 - z^2}.$$

Accordingly

$$\frac{dx}{\sqrt{c(x-\alpha)(x-\beta)}} = \frac{dx}{z(x-\beta)\sqrt{c}} = \frac{2}{\sqrt{c}} \frac{dz}{1-z^2}. \quad (7)$$

In the latter case, let  $\sqrt{x-\alpha} = z\sqrt{\beta-x}$ , and we get

$$x = \frac{\alpha + \beta z^2}{1 + z^2},$$

and

$$\frac{dx}{\sqrt{c(x-\alpha)(\beta-x)}} = \frac{2}{\sqrt{c}} \frac{dz}{1+z^2}. \quad (8)$$

For example, the integral

$$\int \frac{dx}{(p + qx) \sqrt{1 - x^2}}$$

transforms into

$$\int \frac{2dz}{(p + qz) z^2 + p - q},$$

on making  $x = \frac{z^2 - 1}{z^2 + 1}$ .

The student can compare this method of integrating the preceding example with that of Art. 13, and he will find no difficulty in identifying the results.

It may be observed that in the application of the foregoing methods it is advisable that the student should in each case select whichever method avoids the introduction of imaginaries.

Thus, as already observed, the first should be employed only when  $c$  is positive: in like manner, the second requires  $a$  to be positive; and the third, that the roots be real.

It is easily seen that when  $a$  and  $c$  are both negative, the roots must be real; for the expression

$$\sqrt{-a + 2bx - cx^2}, \text{ or } \sqrt{\frac{b^2 - ac - (cx - b)^2}{c}}$$

is imaginary for all real values of  $x$  unless  $b^2 - ac$  is positive; i.e. unless the roots are real.

Accordingly, the third method is always applicable when the other two fail.

From the preceding investigation it follows that the expression

$$F(x, \sqrt{a + 2bx + cx^2}) dx$$

can be always rationalized;  $F$  denoting a rational algebraic function of  $x$  and of  $\sqrt{a + 2bx + cx^2}$ .

## EXAMPLES.

1. 
$$\int \frac{dx}{(2+3x)\sqrt{4-x^2}}.$$

Ans. 
$$\frac{1}{4\sqrt{2}} \log \frac{\sqrt{4+2x} - \sqrt{2-x}}{\sqrt{4+2x} + \sqrt{2-x}}.$$

2. 
$$\int \frac{dx}{[(a^2+x^2)^{\frac{1}{2}}+x]^{\frac{1}{2}}}.$$

Assume  $z = (a^2+x^2)^{\frac{1}{2}} + x$ , and we get for the value of the proposed integral

$$\frac{2}{3}z^{\frac{1}{2}} - \frac{2}{5}\frac{a^2}{z^{\frac{3}{2}}}.$$

3. 
$$\int dx \sqrt{x + \sqrt{2+x^2}}.$$

Ans. 
$$\frac{2}{3} \frac{x^{\frac{3}{2}} + x \sqrt{2+x^2} - 2}{\sqrt{x + \sqrt{2+x^2}}}.$$

4. 
$$\int x^m \{(a^2+x^2)^{\frac{1}{2}}+x\}^n dx.$$

Making the same assumption as in Ex. 2, the transformed expression is

$$\frac{(x^2-a^2)^m (a^2+z^2)^n dz}{2^{m+1} z^{m-n+2}},$$

which is immediately integrable when  $m$  is a positive integer.

5. 
$$\int \frac{dx}{\{(1+x^2)^{\frac{1}{2}}-x\}^n}.$$
 Ans. 
$$\frac{[(1+x^2)^{\frac{1}{2}}+x]^{n+1}}{2(n+1)} + \frac{[(1+x^2)^{\frac{1}{2}}+x]^{n-1}}{2(n-1)}.$$

6. 
$$\int \frac{\{(1+x^2)^{\frac{1}{2}}+x\}^n dx}{(1+x^2)^{\frac{1}{2}}(1+x^2)^{\frac{1}{2}}}.$$
 
$$\frac{1}{n} \{\{(1+x^2)^{\frac{1}{2}}+x\}^n\}.$$

7. 
$$\int \frac{dx}{\sqrt{a+2bx+cx^2}(\sqrt{a+2bx+cx^2} \pm x\sqrt{c})^n}.$$

Let  $\sqrt{a+2bx+cx^2} \pm x\sqrt{c} = z$ , then, as in Art. 78, we get

$$\frac{dx}{\sqrt{a+2bx+cx^2}} = \frac{dz}{b \pm z\sqrt{c}};$$

hence the proposed expression transforms into

$$\frac{dz}{z^n(b \pm z\sqrt{c})}; \quad \therefore \text{ &c.}$$

79. **General Investigation.**—The following more general investigation may be worthy of the notice of the student.

Let  $R$  denote the quadratic expression  $a + 2bx + cx^2$ ; then, since the even powers of  $\sqrt{R}$  are rational, and the odd contain  $\sqrt{R}$  as a factor, any rational algebraic function of  $x$  and of  $\sqrt{R}$  can evidently be reduced to the form

$$\frac{P + Q\sqrt{R}}{P' + Q'\sqrt{R}},$$

where  $P, Q, P', Q'$  are rational algebraic functions of  $x$ .

On multiplying the numerator and denominator of this fraction by the complementary surd  $P' - Q'\sqrt{R}$ , the denominator becomes rational, and the resulting expression may be written in the form

$$M + N\sqrt{R},$$

where  $M$  and  $N$  are rational functions.

The integration of  $Mdx$  is effected by the methods of Chapter II.

Also  $\int N\sqrt{R}dx = \int \frac{NR dx}{\sqrt{R}};$

which is of the form

$$\int \frac{f(x)dx}{\phi(x)\sqrt{a + 2bx + cx^2}}.$$

Let, as before,  $\sqrt{a + 2bx + cx^2} = \sqrt{c(x - a)(x - \beta)}$ , and substitute  $\frac{\lambda + 2\mu z + \nu z^2}{\lambda' + 2\mu' z + \nu' z^2}$  instead of  $x$ , when the radical becomes

$$\sqrt{c\{\lambda - a\lambda' + 2(\mu - a\mu')z + (\nu - a\nu')z^2\}\{\lambda - \beta\lambda' + 2(\mu - \beta\mu')z + (\nu - \beta\nu')z^2\}}.$$

(9)

Again, if the quadratic factors under this radical be made each a perfect square, the expression obviously becomes rational.

The simplest method of fulfilling these conditions is by reducing one factor to a constant, and the other to the term containing  $z^2$ .

Accordingly, let

$$\lambda - a\lambda' = 0, \quad \mu - a\mu' = 0, \quad \mu - \beta\mu' = 0, \quad \nu - \beta\nu' = 0;$$

$$\text{or} \quad \mu = 0, \quad \mu' = 0, \quad \lambda = a\lambda', \quad \nu = \beta\nu'.$$

On making these substitutions the expression (9) becomes

$$(\beta - a)z \sqrt{-c\lambda'\nu'}, \text{ while } x = \frac{a\lambda' + \beta\nu'z^2}{\lambda' + \nu'z^2}.$$

In order that  $\sqrt{-c\lambda'\nu'}$  should be real,  $\lambda'$  and  $\nu'$  must have opposite signs when  $c$  is positive, and the same sign when  $c$  is negative.

It is also easily seen that without loss\* of generality we may assume  $\lambda' = 1$ , and  $\nu' = \pm 1$ .

Hence, when  $c$  is positive, we get  $x = \frac{a - \beta z^2}{1 - z^2}$ , and when  $c$  is negative,  $x = \frac{a + \beta z^2}{1 + z^2}$ .

These agree with the third transformation in the preceding Article.

More generally, when the factors in (9) are each squares, we must have

$$(\mu - a\mu')^2 - (\lambda - a\lambda')(\nu - a\nu') = 0,$$

$$\text{or} \quad \mu^2 - \lambda\nu + (\lambda\nu' + \nu\lambda' - 2\mu\mu')a + (\mu'^2 - \lambda'\nu')a^2 = 0, \quad (10)$$

and a similar equation with  $\beta$  instead of  $a$ .

Moreover, by hypothesis,  $a$  satisfies the equation

$$a + 2ba + ca^2 = 0.$$

---

\* For the substitution of  $y^2$  for  $\frac{\nu'z^2}{\lambda'}$  transforms

$$\frac{a\lambda' + \beta\nu'z^2}{\lambda' + \nu'z^2} \text{ into } \frac{a + \beta y^2}{1 + y^2}; \quad \therefore \text{ &c.}$$

Accordingly (10) is satisfied if we assume the constants  $\lambda, \mu, \&c.$ , so as to satisfy the equations

$$\mu^2 - \lambda\nu = a, \quad \lambda'\nu + \lambda\nu' - 2\mu\mu' = 2b, \quad \mu'^2 - \lambda'\nu' = c. \quad (11)$$

Again, solving for  $z$  from the equation

$$x(\lambda' + 2\mu'z + \nu'z^2) = \lambda + 2\mu z + \nu z^2, \quad (12)$$

we obtain

$$\begin{aligned} (\nu - x\nu')z + \mu - x\mu' &= \sqrt{\mu^2 - \lambda\nu + (\lambda\nu' + \lambda'\nu - 2\mu\mu')x + (\mu'^2 - \lambda'\nu')x^2} \\ &= \sqrt{a + 2bx + cx^2}. \end{aligned} \quad (13)$$

Also, by differentiation, we get from (12),

$$\begin{aligned} (\lambda' + 2\mu'z + \nu'z^2)dx &= 2\{\mu + \nu z - x(\mu' + \nu'z)\}dz \\ &= 2\sqrt{a + 2bx + cx^2}dz; \end{aligned}$$

$$\therefore \frac{dx}{\sqrt{a + 2bx + cx^2}} = \frac{2dz}{\lambda' + 2\mu'z + \nu'z^2}. \quad (14)$$

Now, since we have but three equations (11) connecting  $\lambda, \mu, \&c.$ , they can be satisfied in an indefinite number of ways.

We proceed to consider the simplest cases for real transformations.

(1). Let  $a$  be positive, and we may assume  $\nu = 0$ , and  $\mu' = 0$ ; this gives

$$\mu = \sqrt{a}, \quad \lambda\nu' = 2b, \quad \lambda'\nu' = -c.$$

Again, without loss of generality, we may assume  $\nu' = -1$ , which gives

$$\lambda = -2b, \quad \lambda' = c; \quad \text{whence } x = \frac{2(z\sqrt{a} - b)}{c - z^2},$$

and

$$\frac{dx}{\sqrt{a + 2bx + cx^2}} = \frac{2dz}{c - z^2}.$$

These agree with the results in (5) and (6).

[7 a]

(2). In like manner, if  $c$  be positive we may assume

$$\nu' = 0, \quad \mu = 0, \quad \text{and} \quad \nu = 1,$$

which gives

$$\mu' = \sqrt{c}, \quad \lambda = -a, \quad \text{and} \quad \lambda' = 2b;$$

$$\therefore x = \frac{z^2 - a}{2(b + z\sqrt{c})}, \quad \text{and} \quad \frac{dx}{\sqrt{a + 2bx + cx^2}} = \frac{dz}{b + z\sqrt{c}};$$

as in (2) and (3).

It may be observed that since these results do not contain the roots  $\alpha$  and  $\beta$ , they hold whether these roots be real or imaginary; as already shown in Art. 78.

It is easily seen that if we make  $\mu = 0$ , and  $\mu' = 0$ , we get the third transformation.

80. If the expression to be integrated be of the form

$$\frac{f(x) dx}{\sqrt{a + 2bx + cx^2}},$$

where  $f(x)$  is a *rational algebraic* function of  $x$ , it is often more convenient to proceed as follows:—

The substitution of  $z - \frac{b}{c}$  for  $x$  transforms the proposed

into 
$$\frac{f\left(z - \frac{b}{c}\right) dz}{\sqrt{a' + cz^2}}, \quad \text{where } a' = \frac{ac - b^2}{c}.$$

If the even and odd powers be separated in the expansion of  $f\left(z - \frac{b}{c}\right)$ , it can plainly be written in the form

$$\phi(z^2) + z\psi(z^2),$$

and the proposed integral becomes

$$\int \frac{\phi(z^2) dz}{\sqrt{a' + cz^2}} + \int \frac{z\psi(z^2) dz}{\sqrt{a' + cz^2}}.$$

The former of these is rationalized (Art. 24), by making  $\sqrt{a' + cz^2} = yz$ , and the latter by making  $\sqrt{a' + cz^2} = y$ .

It may be observed that in general the expression

$$\frac{f(x^2)}{\phi(x^2)} \frac{dx}{\sqrt{a + cx^2}}.$$

is also made rational by the transformation

$$\sqrt{a + cx^2} = xy.$$

**81. Case of a Recurring Biquadratic under the Radical Sign.**—As the solution of a recurring equation of the fourth degree is immediately reducible to that of a quadratic, it is natural to consider in what case an Elliptic Integral (Art. 28), in which the biquadratic under the radical sign is recurring, is reducible by the corresponding substitution.

Writing the expression in the form

$$\frac{\phi(x) dx}{\sqrt{a + 2bx + cx^2 + 2bx^3 + ax^4}}, \text{ or } \frac{\phi(x) dx}{x \sqrt{a \left( x^2 + \frac{1}{x^2} \right) + 2b \left( x + \frac{1}{x} \right) + c}},$$

and, assuming  $x + \frac{1}{x} = z$ , the radical becomes  $\sqrt{az^2 + 2bz + c - 2a}$ ;

and also

$$\frac{dx}{x} \left( x - \frac{1}{x} \right) = dz. \quad |$$

Consequently, in order that the transformed expression should be of the required type, it is obvious that  $\phi(x)$  must be reducible to the form

$$\left( x - \frac{1}{x} \right) f \left( x + \frac{1}{x} \right).$$

In this case

$$\frac{\left( x - \frac{1}{x} \right) f \left( x + \frac{1}{x} \right) dx}{\sqrt{a + 2bx + cx^2 + 2bx^3 + ax^4}}$$

transforms into

$$\frac{f(z) dz}{\sqrt{az^2 + 2bz + c - 2a}}.$$

In like manner, the expression

$$\frac{\left(x + \frac{1}{x}\right)f\left(x - \frac{1}{x}\right)dx}{\sqrt{a + 2bx + cx^2 - 2bx^3 + ax^4}}$$

transforms into  $\frac{f(z) dz}{\sqrt{az^2 - 2bz + 2a - c}}$ , by the assumption

$$x - \frac{1}{x} = z.$$

When  $b = 0$  the expression can in some cases be reduced by assuming either

$$x^2 + \frac{1}{x^2} \text{ or } x^3 - \frac{1}{x^2} = z.$$

### EXAMPLES.

$$1. \int \frac{(x^2 - 1) dx}{x \sqrt{1 + x^4}}. \quad \text{Ans. } \log \frac{1 + x^2 + \sqrt{1 + x^4}}{x}.$$

$$2. \int \frac{(x^2 + 1) dx}{x \sqrt{1 + x^4}}. \quad \text{,} \quad \log \frac{x^2 - 1 + \sqrt{1 + x^4}}{x}.$$

$$3. \int \frac{1 - x^2}{1 + x^2} \frac{dx}{\sqrt{1 + x^4}}. \quad \text{,} \quad \frac{1}{\sqrt{2}} \sin^{-1} \left( \frac{x \sqrt{\sqrt{2}}}{1 + x^2} \right).$$

$$4. \int \frac{1 + x^2}{1 - x^2} \frac{dx}{\sqrt{1 + x^4}}. \quad \text{,} \quad \frac{1}{\sqrt{2}} \log \frac{\sqrt{1 + x^4} + x \sqrt{\sqrt{2}}}{1 - x^2}.$$

This and the preceding were given by Euler (*Calc. Int.*, tom. 4): the connexion, however, of their solution with the method of recurring equations does not appear to have been pointed out by him.

$$5. \int \frac{(x^4 - 1) dx}{x^2 \sqrt{x^4 + x^2 + 1}}. \quad \text{Ans. } \frac{\sqrt{x^4 + x^2 + 1}}{x}.$$

$$\text{Let } x^2 + \frac{1}{x^2} = z, \text{ &c.}$$

$$6. \int \frac{(x^2 - 1) dx}{x \sqrt{(x^2 + ax + 1)(x^2 + \beta x + 1)}}.$$

$$\text{Ans. } 2 \log \frac{\sqrt{x^2 + ax + 1} + \sqrt{x^2 + \beta x + 1}}{\sqrt{x}}.$$

$$7. \int \frac{(1 - x^2) dx}{(1 + x^2) \sqrt{1 + x^2 + x^4}}.$$

$$\text{Ans. } \sin^{-1} \left( \frac{x}{1 + x^2} \right).$$

8.  $\int \frac{x \, dx}{(a+bx)^{\frac{1}{4}}}.$  *Ans.*  $\frac{3(2bx-3a)}{10b^2} (a+bx)^{\frac{5}{4}}.$

9.  $\int \frac{1+x^2}{1-x^2} \frac{dx}{\sqrt{1+x^2+x^4}}.$  "  $\frac{1}{\sqrt{3}} \log \frac{\sqrt{1+x^2+x^4} + x\sqrt{3}}{1-x^2}.$

10.  $\int \frac{dx}{(1+x^4)\{(1+x^4)^{\frac{1}{4}} - x^2\}^{\frac{1}{2}}}.$  "  $\sin^{-1} \left( \frac{x}{(1+x^4)^{\frac{1}{4}}} \right).$

Assume  $x = (1+x^4)^{\frac{1}{4}} \sin \theta, \text{ &c.}$

11.  $\int \frac{dx}{(1+x^{2n})\{(1+x^{2n})^{\frac{1}{n}} - x^2\}^{\frac{1}{2}}}.$  "  $\sin^{-1} \left( \frac{x}{(1+x^{2n})^{\frac{1}{2n}}} \right).$

12.  $\int \frac{x \, dx}{(1+x)^{\frac{1}{4}} + (1+x)^{\frac{1}{2}}}.$

Assume  $1+x = z^8.$

13.  $\int \frac{x^2 \, dx}{(1-x^4)(1+x^4)^{\frac{1}{4}}}.$

*Ans.*  $\frac{1}{4\sqrt{2}} \log \frac{(1+x^4)^{\frac{1}{4}} + x\sqrt{2}}{1-x^2} + \frac{1}{4\sqrt{2}} \tan^{-1} \frac{(1+x^4)^{\frac{1}{4}}}{x\sqrt{2}}.$

14.  $\int \frac{(1+x^4)^{\frac{1}{4}} \, dx}{(1-x^4)^{\frac{3}{2}}}.$

*Ans.*  $\frac{x}{(1-x^4)^{\frac{1}{4}}}.$

15.  $\int \frac{(1+x^4)^{\frac{1}{4}} \, dx}{1-x^4}.$

*Ans.*  $\frac{1}{2\sqrt[4]{2}} \log \left( \frac{\sqrt{1+x^4} + x\sqrt{2}}{1-x^2} \right) + \frac{1}{2\sqrt{2}} \tan^{-1} \frac{x\sqrt{2}}{\sqrt{1+x^4}}.$

16.  $\int \frac{1-x^2}{1+2ax+x^2} \frac{dx}{\sqrt{1+2ax+2bx^2+2ax^3+x^4}}.$

17.  $\int \frac{1-ax^2}{1+ax^2} \frac{dx}{\sqrt{1+2cx^2+a^2x^4}}.$

*Ans.*  $\frac{1}{\sqrt{2(c-a)}} \log \frac{x\sqrt{2(c-a)} + \sqrt{1+2cx^2+a^2x^4}}{1+ax^2}, \text{ when } c > a.$

"  $\frac{1}{\sqrt{2(a-c)}} \sin^{-1} \left( \frac{x\sqrt{2(a-c)}}{1+ax^2} \right), \text{ when } a > c.$

## CHAPTER V.

## MISCELLANEOUS EXAMPLES OF INTEGRATION.

82. **Integration of**  $\frac{(A \cos x + B \sin x + C) dx}{a \cos x + b \sin x + c}.$

Let  $a \cos x + b \sin x + c = u$ , then  $-a \sin x + b \cos x = \frac{du}{dx}$ .

Next assume

$$A \cos x + B \sin x + C = \lambda u + \mu \frac{du}{dx} + \nu,$$

and, equating coefficients, we have

$$A = \lambda a + \mu b, \quad B = \lambda b - \mu a, \quad C = \lambda c + \nu.$$

Solving for  $\lambda, \mu, \nu$ , we get

$$\lambda = \frac{Aa + Bb}{a^2 + b^2}, \quad \mu = \frac{Ab - Ba}{a^2 + b^2}, \quad \nu = C - \frac{(Aa + Bb)c}{a^2 + b^2}.$$

$$\begin{aligned} \text{Hence} \quad & \int \frac{(A \cos x + B \sin x + C) dx}{a \cos x + b \sin x + c} \\ &= \frac{(Aa + Bb)x}{a^2 + b^2} + \frac{Ab - Ba}{a^2 + b^2} \log (a \cos x + b \sin x + c) \\ &+ \frac{(a^2 + b^2) C - (Aa + Bb)c}{a^2 + b^2} \int \frac{dx}{a \cos x + b \sin x + c}. \end{aligned}$$

The latter integral can be readily found; for, if we make  $a = r \cos a, b = r \sin a$ , we get

$$a \cos x + b \sin x = r (\cos x \cos a + \sin x \sin a) = r \cos (x - a).$$

On making  $x - a = \theta$ , the integral reduces to the form considered in Art. 18.

As a simple example, let us take

$$\int \frac{(A + B \tan x) dx}{a + b \tan x}.$$

Here  $\frac{A + B \tan x}{a + b \tan x} = \frac{A \cos x + B \sin x}{a \cos x + b \sin x}$ ,

and we evidently have

$$\int \frac{(A + B \tan x) dx}{a + b \tan x} = \frac{(Aa + Bb)x}{a^2 + b^2} + \frac{Ab - Ba}{a^2 + b^2} \log (a \cos x + b \sin x).$$

83. **Integration of**  $\frac{f(\cos x, \sin x) dx}{a \cos x + b \sin x + c}$ ;

where  $f$  is a rational algebraic function, not involving fractions.

As in the preceding Article, assume  $x = \theta + a$ , and the expression becomes of the form

$$\frac{\phi(\cos \theta, \sin \theta) d\theta}{A \cos \theta + B}.$$

Again, since  $\sin^2 \theta = 1 - \cos^2 \theta$ , any integral function of  $\sin \theta$  and  $\cos \theta$  can be transformed into another of the form

$$\phi_1(\cos \theta) + \sin \theta \phi_2(\cos \theta).$$

Accordingly, the proposed expression is reducible to

$$\frac{\phi_1(\cos \theta) d\theta}{A \cos \theta + B} + \frac{\phi_2(\cos \theta) \sin \theta d\theta}{A \cos \theta + B}.$$

The latter is immediately integrable, by assuming

$$A \cos \theta + B = z.$$

To integrate the former, we divide by  $A \cos \theta + B$ , and integrate each term separately.

## 84. Integration of

$$\frac{f(\cos x)dx}{(a_1 + b_1 \cos x)(a_2 + b_2 \cos x) \dots (a_n + b_n \cos x)},$$

where  $f$ , as before, denotes a rational algebraic function.

Substitute  $z$  for  $\cos x$  and decompose

$$\frac{f(z)}{(a_1 + b_1 z)(a_2 + b_2 z) \dots (a_n + b_n z)}$$

by the method of partial fractions: then the expression to be integrated reduces to the sum of a number of terms of the form

$$\frac{dx}{A + B \cos x},$$

each of which can be immediately integrated.

## EXAMPLES.

1.  $\int \frac{dx}{\cos x (5 + 3 \cos x)}.$  *Ans.*  $\frac{1}{10} \log \left( \frac{1 + \sin x}{1 - \sin x} \right) - \frac{3}{10} \tan^{-1} \left( \frac{\tan \frac{x}{2}}{2} \right).$

2.  $\int \frac{dx}{\sin^2 x (a + b \cos x)},$  when  $a > b.$

*Ans.*  $\frac{b - a \cos x}{(a^2 - b^2) \sin x} - \frac{b^2}{(a^2 - b^2)^{\frac{3}{2}}} \cos^{-1} \left( \frac{b + a \cos x}{a + b \cos x} \right).$

3.  $\int \frac{dx}{\cos^2 x (a + b \cos x)}.$  *Ans.*  $\frac{\tan x}{a} - \frac{b}{a^2} \log \tan \left( \frac{\pi}{4} + \frac{x}{2} \right) + \frac{b^2}{a^2} \int \frac{dx}{a + b \cos x}.$

85. Integration of  $\{f(x) + f'(x)\} e^x dx.$ 

The expression  $e^x P dx$  is immediately integrable whenever  $P$  can be divided into the sum of two functions, one of which is the derived of the other.

For, let  $P = f(x) + f'(x),$

then  $\int e^x P dx = \int e^x f(x) dx + \int e^x f'(x) dx.$

Again, integrating by parts, we have

$$\int e^x f(x) dx = f(x) e^x - \int e^x f'(x) dx.$$

Accordingly,

$$\int \{f(x) + f'(x)\} e^x dx = e^x f(x).$$

For instance, to find

$$\int e^x \frac{x}{(1+x)^2} dx.$$

Here  $\frac{x}{(1+x)^2} = \frac{1}{1+x} - \frac{1}{(1+x)^2}$ ;

consequently the value of the proposed integral is  $\frac{e^x}{1+x}$ .

### EXAMPLES.

1.  $\int e^x (\cos x + \sin x) dx.$  *Ans.*  $e^x \sin x.$

2.  $\int e^x \frac{1+x \log x}{x} dx.$  *Ans.*  $e^x \log x.$

3.  $\int e^x \frac{x^2 + 1}{(x+1)^2} dx.$  *Ans.*  $e^x \frac{x-1}{x+1}.$

4.  $\int e^x \left( \frac{1-x}{1+x^2} \right)^2 dx.$  *Ans.*  $\frac{e^x}{1+x^2}.$

**86. Differentiation under the Sign of Integration.**—The integral of any expression of the form  $\phi(x, a) dx$ , where  $a$  is independent of  $x$ , is obviously a function of  $a$  as well as of  $x$ .

Suppose the integral to be denoted by  $F(x, a)$ , i. e. let

$$F(x, a) = \int \phi(x, a) dx,$$

then  $\frac{d}{dx} \{F(x, a)\} = \phi(x, a).$

Again, differentiating both sides with respect to  $a$ , we have, since  $x$  and  $a$  are independent,

$$\frac{d^2 \cdot F(x, a)}{da dx} = \frac{d \cdot \phi(x, a)}{da},$$

or (Art. 119, Diff. Calc.),

$$\frac{d}{dx} \left( \frac{d \cdot F(x, a)}{da} \right) = \frac{d \cdot \phi(x, a)}{da}.$$

Consequently, integrating with respect to  $x$ , we get

$$\frac{d \cdot F(x, a)}{da} = \int \frac{d \cdot \phi(x, a)}{da} dx,$$

$$\text{i.e. } \frac{d}{da} \int \phi(x, a) dx = \int \frac{d\phi(x, a)}{da} dx. \quad (1)$$

In other words, if

$$u = \int \phi(x, a) dx.$$

then  $\frac{du}{da} = \int \frac{d\phi}{da} dx,$

provided  $a$  be independent of  $x$ ; in which case, accordingly, it is permitted to *differentiate under the sign of integration*.

By continuing the same process of reasoning we obviously get

$$\frac{d^n u}{da^n} = \int \frac{d^n \phi(x, a)}{da^n} dx, \quad (2)$$

where  $u = \int \phi(x, a) dx$ ,  $a$  being independent of  $x$ .

For example, if the equation

$$\int e^{ax} dx = \frac{e^{ax}}{a}$$

be differentiated  $n$  times with respect to  $a$ , we get

$$\begin{aligned} \int x^n e^{ax} dx &= \left( \frac{d}{da} \right)^n \left( \frac{e^{ax}}{a} \right) \\ &= e^{ax} \left( x + \frac{d}{da} \right)^n \left( \frac{1}{a} \right). \end{aligned}$$

(See Art. 49, Diff. Calc.).

Again, in Art. 21 we have seen that

$$\int e^{ax} \sin mx dx = \frac{e^{ax} (a \sin mx - m \cos mx)}{m^2 + a^2}.$$

Accordingly,

$$\int x^n e^{ax} \sin mx dx = \left( \frac{d}{da} \right)^n \left( \frac{e^{ax} (a \sin mx - m \cos mx)}{m^2 + a^2} \right).$$

We now proceed to consider the inverse process, namely, the method of integration under the sign of integration.

**87. Integration under the Sign of Integration.**—If in the last Article we suppose  $\phi(x, a)$  to be the derived with respect to  $a$  of another function  $v$ , i.e. if

$$\phi(x, a) = \frac{dv}{da},$$

then

$$v = \int \phi(x, a) da.$$

Also by the preceding Article we have

$$\frac{d}{da} \left( \int v dx \right) = \int \frac{dv}{da} dx = \int \phi(x, a) dx = F(x, a).$$

Hence  $\int v dx = \int F(x, a) da.$

In other words, if

$$F(x, a) = \int \phi(x, a) dx,$$

then

$$\int F(x, a) da = \int [\int \phi(x, a) da] dx. \quad (3)$$

It may be remarked that the results established in this and in the preceding Article are chiefly of importance in connexion with definite integrals. Some examples of such application will be given in the next Chapter.

88. **Integration by Infinite Series.**—It has been already observed that in most cases we fail in exhibiting the integral of any proposed expression in finite terms. In such cases, however, we can often represent the integral in the form of a series containing an infinite number of terms.

An example of an integral exhibited in such a form has been given in Art. 63.

The simplest mode of seeking the integral of  $f(x)dx$  in the form of an infinite series consists in expanding  $f(x)$  in a series of ascending powers of  $x$ , and integrating each term separately: then if the series thus obtained be convergent, it represents the integral proposed.

It can be easily seen that if the expansion of  $f(x)$  be a convergent series, that of  $\int f(x)dx$  is also convergent.

For let

$$f(x) = a_0 + a_1 x + a_2 x^2 + \dots + a_n x^n + \&c.,$$

then

$$\int f(x) dx = a_0 x + \frac{a_1 x^2}{2} + \frac{a_2 x^3}{3} + \dots + \frac{a_n x^{n+1}}{n+1} + \dots$$

Now (Diff. Calc., Art. 73), the expression for  $f(x)$  is convergent whenever  $\frac{a_n x}{a_{n-1}}$  is less than unity for all values of  $n$  beyond a certain number; and the latter series is convergent provided  $\frac{n}{n+1} \frac{a_n x}{a_{n-1}}$  be less than unity, under the same conditions.

Accordingly, the latter series is convergent whenever the former is so.

## EXAMPLES.

$$1. \int \frac{dx}{\sqrt{1-x^5}} = \frac{x}{1} + \frac{1}{2} \frac{x^6}{6} + \frac{1 \cdot 3}{2 \cdot 4} \frac{x^{11}}{11} + \frac{1 \cdot 3 \cdot 5}{2 \cdot 4 \cdot 6} \frac{x^{16}}{16} + \text{&c.}$$

$$2. \int \frac{dx}{\sqrt{\sin x}} = 2 \sqrt{\sin x} \left( 1 + \frac{1}{2} \frac{\sin^2 x}{5} + \frac{1 \cdot 3}{2 \cdot 4} \frac{\sin^4 x}{9} + \dots \right).$$

$$3. \int (1+cx^n)^{\frac{p}{q}} x^{m-1} dx = x^m \left( \frac{1}{m} + \frac{pc}{q} \frac{x^n}{m+n} + \frac{p(p-q)c^2}{1 \cdot 2 \cdot q^2} \frac{x^{2n}}{m+2n} + \text{&c.} \right).$$

$$89. \text{ Expansion of } \int \log (1 + 2m \cos x + m^2) dx.$$

We shall conclude by showing that the integral

$$\int \log (1 + 2m \cos x + m^2) dx$$

can be exhibited in the form of an infinite series.

For we have

$$1 + 2m \cos x + m^2 = (1 + me^{x\sqrt{-1}})(1 + me^{-x\sqrt{-1}}).$$

Hence

$$\begin{aligned} \log (1 + 2m \cos x + m^2) &= \log (1 + me^{x\sqrt{-1}}) + \log (1 + me^{-x\sqrt{-1}}) \\ &= m (e^{x\sqrt{-1}} + e^{-x\sqrt{-1}}) - \frac{m^2}{2} (e^{2x\sqrt{-1}} + e^{-2x\sqrt{-1}}) + \text{&c.} \\ &= 2 \left( m \cos x - \frac{m^2}{2} \cos 2x + \frac{m^3}{3} \cos 3x - \text{&c.} \right). \end{aligned}$$

Accordingly

$$\int \log (1 + 2m \cos x + m^2) dx = 2 \left( m \sin x - m^2 \frac{\sin 2x}{2^2} + m^3 \frac{\sin 3x}{3^2} - \right). \quad (4)$$

This series becomes divergent when  $m$  is greater than unity. In that case, however, the corresponding series can be easily obtained.

$$\text{For } 1 + 2m \cos x + m^2 = m^2 \left( 1 + \frac{e^{x\sqrt{-1}}}{m} \right) \left( 1 + \frac{e^{-x\sqrt{-1}}}{m} \right),$$

and accordingly

$$\log(1 + 2m \cos x + m^2) = 2 \log m + 2 \left( \frac{\cos x}{m} - \frac{\cos 2x}{2m^2} + \frac{\cos 3x}{3m^3} - \text{&c.} \right).$$

Consequently, when  $m > 1$ , we have

$$\int \log(1 + 2m \cos x + m^2) dx = 2x \log m + 2 \left( \frac{\sin x}{m} - \frac{\sin 2x}{2^2 m^2} + \frac{\sin 3x}{3^2 m^3} - \dots \right).$$

From the above it is easily seen that the integral

$$\int \log(1 + a \cos x) dx$$

can be exhibited in the form of an infinite series when  $a$  is less than unity : for making  $a = \frac{2m}{1 + m^2}$  we have

$$\log(1 + a \cos x) = \log(1 + 2m \cos x + m^2) - \log(1 + m^2).$$

The relation between  $m$  and  $a$  admits of being exhibited in a simple form ; for let  $a = \sin \alpha$ , and we get  $m = \tan \frac{\alpha}{2}$ .

Making this substitution in (4), we get

$$\begin{aligned} \int \log(1 + \sin a \cos x) dx &= 2x \log \left( \cos \frac{a}{2} \right) \\ &+ 2 \left( \tan \frac{a}{2} \sin x - \tan^2 \frac{a}{2} \frac{\sin 2x}{2^2} + \text{&c.} \right). \end{aligned} \quad (5)$$

## EXAMPLES.

1.  $\int \frac{(2 \cos x + 3 \sin x) dx}{3 \cos x + 2 \sin x}$ . *Ans.*  $\frac{12x}{13} - \frac{5}{13} \log(3 \cos x + 2 \sin x)$ .

2.  $\int \frac{d\theta}{1 - \sin^4 \theta}$ . "  $\frac{1}{2} \tan \theta + \frac{1}{2\sqrt{2}} \tan^{-1}(\tan \theta \sqrt{2})$ .

3.  $\int \frac{e^x (x^3 + x + 1) dx}{(1 + x^2)^{\frac{3}{2}}}$ . "  $\frac{e^x x}{\sqrt{1 + x^2}}$ .

4.  $\int \frac{d\theta}{\sin 2\theta - \sin \theta} = \frac{1}{6} \log(1 + \cos \theta) + \frac{1}{2} \log(1 - \cos \theta) - \frac{2}{3} \log(1 - 2 \cos \theta)$ .

5.  $\int \frac{\sin \frac{\theta}{2} \tan \frac{\theta}{2} d\theta}{\cos \theta} = \log\left(\frac{1 - \sin \frac{\theta}{2}}{1 + \sin \frac{\theta}{2}}\right) + \frac{1}{\sqrt{2}} \log\left(\frac{\sqrt{2} \sin \frac{\theta}{2} + 1}{\sqrt{2} \sin \frac{\theta}{2} - 1}\right)$ .

6. When  $x^2 < 1$ , prove that

$$\int \frac{dx}{\sqrt{1 + x^4}} = \frac{x}{1} - \frac{1}{2} \frac{x^5}{5} + \frac{1 + 3}{2 \cdot 4} \frac{x^9}{9} - \frac{1 + 3 + 5}{2 \cdot 4 \cdot 6} \frac{x^{13}}{13} + \dots$$

and when  $x^2 > 1$

$$\int \frac{dx}{\sqrt{1 + x^4}} = -\frac{1}{x} + \frac{1}{2} \frac{1}{5x^5} - \frac{1 + 3}{2} \frac{1}{49x^9} + \frac{1 + 3 + 5}{2 \cdot 4 \cdot 6} \frac{1}{13x^{13}} - \dots$$

7. Prove that

$$\int \frac{e^{ax}}{b+x} dx = e^{-ab} \left\{ \log(b+x) + \frac{a}{1} \frac{b+x}{1} + \frac{a^2}{1 \cdot 2} \frac{(b+x)^2}{2} + \dots \right\},$$

and determine when the series is convergent, and when divergent.

8. Prove that

$$\begin{aligned} \int \frac{e^{\lambda\omega} + e^{-\lambda\omega}}{2} \sin^\mu \omega d\omega &= \frac{\sin^{\mu+1} \omega}{\mu + 1} + \frac{\lambda^2 + 1^2}{1 \cdot 2} \cdot \frac{\sin^{\mu+3} \omega}{\mu + 3} \\ &+ \frac{(\lambda^2 + 1^2)(\lambda^2 + 3^2)}{1 \cdot 2 \cdot 3 \cdot 4} \frac{\sin^{\mu+5} \omega}{\mu + 5} + \dots \end{aligned}$$

Substitute  $\omega$  for  $\sin^{-1} x$  in the expansion of  $e^{\lambda \sin^{-1} x}$  (Diff. Calc., Art. 87), &c.

$$\begin{aligned} 9. \quad \int \frac{e^{\lambda\omega} - e^{-\lambda\omega}}{2} \sin^\mu \omega d\omega &= \frac{\lambda}{1} \cdot \frac{\sin^{\mu+2} \omega}{\mu + 2} + \frac{\lambda(\lambda^2 + 2^2)}{1 \cdot 2 \cdot 3} \frac{\sin^{\mu+4} \omega}{\mu + 4} \\ &+ \frac{\lambda(\lambda^2 + 2^2)(\lambda^2 + 4^2)}{1 \cdot 2 \cdot 3 \cdot 4 \cdot 5} \frac{\sin^{\mu+6} \omega}{\mu + 6} + \&c. \end{aligned}$$

## CHAPTER VI.

## DEFINITE INTEGRALS.

90. **Integration regarded as Summation.**—We have in the commencement observed that the process of integration may be regarded as that of finding the limit of the sum of the series of values of a differential  $f(x)dx$ , when  $x$  varies by indefinitely small increments from any one assigned value to another.

It is in this aspect that the practical importance of integration chiefly consists. For example, in seeking the area of a curve, we conceive it divided into an indefinite number of suitable elementary areas, of which we seek to determine the sum by a process of integration. Applications of finding areas by this method will be given in the next Chapter.

We now proceed to show more fully than in Chapter I. the connexion between the process of integration regarded from this point of view and that from which we have hitherto considered it.

Suppose  $\phi(x)$  to represent a function of  $x$  which is *finite and continuous* for all values of  $x$  between the limits  $X$  and  $x_0$ ; suppose also that  $X - x_0$  is divided into  $n$  intervals  $x_1 - x_0$ ,  $x_2 - x_1$ ,  $x_3 - x_2$ , . . .  $X - x_{n-1}$ ; then by definition (Diff. Calc., Art. 6), we have

$$\frac{\phi(x_1) - \phi(x_0)}{x_1 - x_0} = \phi'(x_0)$$

in the limit when  $x_1 = x_0$ ; accordingly we have

$$\phi(x_1) - \phi(x_0) = (x_1 - x_0)(\phi'(x_0) + \epsilon_0),$$

where  $\epsilon_0$  becomes infinitely small along with  $x_1 - x_0$ . Hence we may write

$$\phi(x_1) - \phi(x_0) = (x_1 - x_0) \{ \phi'(x_0) + \epsilon_0 \},$$

$$\phi(x_2) - \phi(x_1) = (x_2 - x_1) \{ \phi'(x_1) + \epsilon_1 \},$$

$$\phi(x_3) - \phi(x_2) = (x_3 - x_2) \{ \phi'(x_2) + \epsilon_2 \},$$

$$\cdot \quad \cdot \quad \cdot$$

$$\phi(X) - \phi(x_{n-1}) = (X - x_{n-1}) \{ \phi'(x_{n-1}) + \epsilon_{n-1} \},$$

where  $\epsilon_0, \epsilon_1, \dots, \epsilon_{n-1}$  become evanescent when the intervals are taken as infinitely small.

By addition, we have

$$\phi(X) - \phi(x_0) = (x_1 - x_0) \phi'(x_0) + (x_2 - x_1) \phi'(x_1) + \dots$$

$$+ (X - x_{n-1}) \phi'(x_{n-1}) + (x_1 - x_0) \epsilon_0 + (x_2 - x_1) \epsilon_1 + \dots + (X - x_{n-1}) \epsilon_{n-1}.$$

Now if  $\eta$  denote the greatest of the quantities  $\epsilon_0, \epsilon_1, \dots, \epsilon_{n-1}$ , the latter portion of the right-hand side is evidently less than  $(X - x_0) \eta$ ; and accordingly becomes evanescent ultimately (compare Diff. Calc., Art. 39).

Hence

$$\begin{aligned} \phi(X) - \phi(x_0) = \text{limit of } & [(x_1 - x_0) \phi'(x_0) + (x_2 - x_1) \phi'(x_1) + \dots \\ & + (X - x_{n-1}) \phi'(x_{n-1})], \quad (1) \end{aligned}$$

when  $n$  is increased indefinitely.

This result can also be written in the form

$$\phi(X) - \phi(x_0) = \Sigma \phi'(x) dx,$$

where the sign of summation  $\Sigma$  is supposed to extend through all values of  $x$  between the limits  $x_0$  and  $X$ .

**91. Definite Integrals, Limits of Integration.**—The result just arrived at, as already stated in Art. 31, is written in the form

$$f(X) - f(x_0) = \int_{x_0}^X f'(x) dx, \quad (2)$$

where  $X$  is called the *superior*, and  $x_0$  the *inferior limit* of the integral.

Again, the expression

$$\int_{x_0}^X \phi(x) dx$$

is called the *definite integral* of  $\phi(x) dx$  between the limits  $x_0$  and  $X$ , and represents the limit of the sum of the infinitely small elements  $\phi(x) dx$ , taken between the proposed limits.

From equation (1) we see that the limit of

$$(x_1 - x_0) f'(x_0) + (x_2 - x_1) f'(x_1) + \dots + (X - x_{n-1}) f'(x_{n-1}),$$

when  $x_1 - x_0, x_2 - x_1, \dots, X - x_{n-1}$  become evanescent, is got by finding the integral of  $f'(x) dx$  (i. e. the function of which  $f'(x)$  is the derived), and substituting the limits  $x_0, X$  for  $x$  in it, and subtracting the value for the lower limit from that for the upper.

If we write  $x$  instead of  $X$  in (2) we have

$$f(x) - f(x_0) = \int_{x_0}^x f'(x) dx, \quad (3)$$

in which the upper limit\*  $x$  may be regarded as variable. Again, as the lower limit  $x_0$  may be assumed arbitrarily,  $f(x_0)$  may have any value, and may be regarded as an arbitrary constant. This agrees with the results hitherto arrived at.

In contradistinction, the name *indefinite integrals* is often applied to integrals such as have been considered in the previous chapters, in which the form of the function is merely taken into account, without regard to any assigned limits.

As already observed, the definite integral of any expression between assigned limits can be at once found whenever the indefinite integral is known.

A few easy examples are added for illustration.

\* The student should observe that in (3) the letter  $x$  which stands for the superior limit and the  $x$  in the element  $f'(x) dx$  must be considered as being entirely distinct. The want of attention to this distinction often causes much confusion in the mind of the beginner.

## EXAMPLES.

1.  $\int_a^b x^n dx.$

Ans.  $\frac{b^{n+1} - a^{n+1}}{n+1}.$

2.  $\int_0^{\frac{\pi}{4}} \frac{\sin \theta d\theta}{\cos^2 \theta}.$

"  $\sqrt{2} - 1.$

3.  $\int_0^a \frac{dx}{\sqrt{x+a} + \sqrt{x}}.$

"  $\frac{4}{3} \sqrt{a} (\sqrt{2} - 1).$

4.  $\int_0^{\infty} \frac{dx}{a^2 + x^2}.$

"  $\frac{\pi}{2a}.$

5.  $\int_0^a \frac{dx}{\sqrt{a^2 - x^2}}.$

"  $\frac{\pi}{2}.$

6.  $\int_0^{\infty} e^{-ax} dx \text{ (} a \text{ positive).}$

"  $\frac{1}{a}.$

7.  $\int_0^1 \frac{dx}{1 + 2x \cos \phi + x^2}.$

"  $\frac{\phi}{2 \sin \phi}.$

8.  $\int_0^{\infty} \frac{dx}{1 + 2x \cos \phi + x^2}.$

"  $\frac{\phi}{\sin \phi}.$

9.  $\int_0^{\infty} e^{-ax} \sin mx dx.$

"  $\frac{m}{a^2 + m^2}.$

10.  $\int_0^{\infty} e^{-ax} \cos mx dx.$

"  $\left| \frac{a}{a^2 + m^2} \right|$

11.  $\int_{-\infty}^{+\infty} \frac{dx}{a + 2bx + cx^2} = \frac{\pi}{\sqrt{ac - b^2}}, \text{ when } ac - b^2 \text{ is positive.}$

## 92. To prove that

$$\int_0^1 x^{n-1} (1-x)^{m-1} dx = \int_0^1 x^{m-1} (1-x)^{n-1} dx = \frac{1 \cdot 2 \cdot 3 \dots (m-1)}{n(n+1)\dots(n+m-1)},$$

*when m and n are positive, and m is an integer.*

The first relation is evident from (34), Art. 32.  
Again, integrating by parts, we have

$$\int x^{n-1} (1-x)^{m-1} dx = \frac{x^n}{n} (1-x)^{m-1} + \frac{m-1}{n} \int x^n (1-x)^{m-2} dx.$$

Moreover, since  $n$  and  $m-1$  are positive, the term  $x^n (1-x)^{m-1}$  vanishes for both limits;

$$\therefore \int_0^1 x^{n-1} (1-x)^{m-1} dx = \frac{m-1}{n} \int_0^1 x^n (1-x)^{m-2} dx.$$

The repeated application of this formula reduces the integral to depend on  $\int_0^1 x^{m+n-2} dx$ , the value of which is  $\frac{1}{m+n-1}$ .

Hence we have

$$\int_0^1 x^{n-1} (1-x)^{m-1} dx = \frac{1 \cdot 2 \cdot 3 \cdot \dots \cdot (m-1)}{n(n+1) \cdot \dots \cdot (n+m-1)}. \quad (4)$$

This formula, combined with the equation

$$\int_0^1 x^{n-1} (1-x)^{m-1} dx = \int_0^1 x^{m-1} (1-x)^{n-1} dx,$$

shows that when either  $m$  or  $n$  is an integer the definite integral

$$\int_0^1 x^{n-1} (1-x)^{m-1} dx$$

can be easily evaluated.

When  $m$  and  $n$  are both fractional, the preceding is one of the most important definite integrals in analysis.

We purpose in a subsequent part of the Chapter to give an investigation of some of its simplest properties.

### EXAMPLES.

1.  $\int_0^1 x^3 (1-x)^{\frac{1}{2}} dx.$

Ans.  $\frac{2^{\frac{1}{2}}}{3 \cdot 7 \cdot 11 \cdot 13}.$

2.  $\int_0^1 x^4 (1-x)^{\frac{1}{2}} dx.$

"  $\frac{2^{\frac{13}{2}}}{5 \cdot 7 \cdot 9 \cdot 13 \cdot 17}.$

93. **Values of**  $\int_0^{\frac{\pi}{2}} \sin^n x dx$  **and**  $\int_0^{\frac{\pi}{2}} \cos^n x dx$ .

One of the simplest and most useful applications of definite integration is to the case of the circular integrals considered in the commencement of Chapter III.

We begin with the simple case of

$$\int_0^{\frac{\pi}{2}} \sin^n x dx.$$

$$\int \sin^n x \sin^{n-1} x dx \\ = \sin^{n-1} x \cos x$$

If in the equation (Art. 56)

$$\int \sin^n x dx = -\frac{\cos x \sin^{n-1} x}{n} + \frac{n-1}{n} \int \sin^{n-2} x dx$$

we take 0 and  $\frac{\pi}{2}$  for limits, the term  $\frac{\cos x \sin^{n-1} x}{n}$  vanishes for both limits, and we have

$$\int_0^{\frac{\pi}{2}} \sin^n x dx = \frac{n-1}{n} \int_0^{\frac{\pi}{2}} \sin^{n-2} x dx.$$

Now, if  $n$  be an integer, the definite integral can be easily obtained; its form, however, depends on whether the index  $n$  is even or odd.

(1). Suppose the index even, and represented by  $2m$ , then

$$\int_0^{\frac{\pi}{2}} \sin^{2m} x dx = \frac{2m-1}{2m} \int_0^{\frac{\pi}{2}} \sin^{2m-2} x dx.$$

Similarly,

$$\int_0^{\frac{\pi}{2}} \sin^{2m-2} x dx = \frac{2m-3}{2m-2} \int_0^{\frac{\pi}{2}} \sin^{2m-4} x dx;$$

and by successive application of the formula, we get

$$\int_0^{\frac{\pi}{2}} \sin^{2m} x dx = \frac{1 \cdot 3 \cdot 5 \dots (2m-1)}{2 \cdot 4 \cdot 6 \dots 2m} \cdot \frac{\pi}{2}. \quad (5)$$

(2). Suppose the index odd, and represented by  $2m + 1$ , then

$$\int_0^{\frac{\pi}{2}} \sin^{2m+1} x dx = \frac{2m}{2m+1} \int_0^{\frac{\pi}{2}} \sin^{2m-1} x dx.$$

Hence, it is easily seen that

$$\int_0^{\frac{\pi}{2}} \sin^{2m+1} x dx = \frac{2 \cdot 4 \cdot 6 \cdot \dots \cdot 2m}{3 \cdot 5 \cdot 7 \cdot \dots \cdot (2m+1)}. \quad (6)$$

Again, it is evident from (35), Art. 32, that

$$\int_0^{\frac{\pi}{2}} \cos^n x dx = \int_0^{\frac{\pi}{2}} \sin^n x dx,$$

and consequently (5) and (6) hold when  $\cos x$  is substituted for  $\sin x$ .

94. **Investigation of**  $\int_0^{\frac{\pi}{2}} \sin^m x \cos^n x dx$ .

From Art. 55, when  $m$  and  $n$  are positive, we have

$$\int_0^{\frac{\pi}{2}} \sin^m x \cos^n x dx = \frac{n-1}{m+n} \int_0^{\frac{\pi}{2}} \sin^m x \cos^{n-2} x dx,$$

and  $\int_0^{\frac{\pi}{2}} \sin^m x \cos^n x dx = \frac{m-1}{m+n} \int_0^{\frac{\pi}{2}} \sin^{m-2} x \cos^n x dx.$

Hence, when one of the indices is an odd integer, the value of the definite\* integral is easily found.

\* The result in this case follows also immediately from Art. 92, by making  $\cos^2 x = z$ ; for this substitution transforms the integral into

$$\frac{1}{2} \int_0^1 (1-z)^m z^{\frac{n-1}{2}} dz.$$

For, writing  $2m+1$  instead of  $m$ , we have

$$\int_0^{\frac{\pi}{2}} \sin^{2m+1} x \cos^n x dx = \frac{2m}{2m+n+1} \int_0^{\frac{\pi}{2}} \sin^{2m-1} x \cos^n x dx.$$

Hence

$$\begin{aligned} & \int_0^{\frac{\pi}{2}} \sin^{2m+1} x \cos^n x dx \\ &= \frac{2m(2m-2) \dots 2}{(2m+n+1)(2m+n-1) \dots (n+3)} \int_0^{\frac{\pi}{2}} \sin x \cos^n x dx \\ &= \frac{2 \cdot 4 \cdot 6 \dots (2m)}{(n+1)(n+3) \dots (n+2m+1)}. \end{aligned} \quad (7)$$

In like manner,

$$\int_0^{\frac{\pi}{2}} \sin^{2m} x \cos^{2n} x dx = \frac{2n-1}{2(m+n)} \int_0^{\frac{\pi}{2}} \sin^{2m} x \cos^{2n-2} x dx.$$

Hence

$$\begin{aligned} & \int_0^{\frac{\pi}{2}} \sin^{2m} x \cos^{2n} x dx = \frac{1 \cdot 3 \cdot 5 \dots (2n-1)}{(2m+2) \dots (2m+2n)} \int_0^{\frac{\pi}{2}} \sin^{2m} x dx \\ &= \frac{1 \cdot 3 \cdot 5 \dots (2n-1) \cdot 1 \cdot 3 \cdot 5 \dots (2m-1)}{2 \cdot 4 \cdot 6 \cdot \dots \cdot (2m+2n)} \cdot \frac{\pi}{2}, \end{aligned} \quad (8)$$

in which  $m$  and  $n$  are supposed both positive integers.

Many elementary definite integrals are immediately reducible to one or other of the preceding forms.

For example, on making  $x = \tan \theta$ , we get

$$\int_0^{\infty} \frac{dx}{(1+x^2)^n} = \int_0^{\frac{\pi}{2}} \cos^{2n-2} \theta d\theta = \frac{1 \cdot 3 \cdot 5 \dots (2n-3)}{2 \cdot 4 \cdot 6 \dots (2n-2)} \cdot \frac{\pi}{2}. \quad (9)$$

Similarly, by  $x = a \sin \theta$ ,  $\int_0^a x^n (a^2 - x^2)^{\frac{m}{2}} dx$  transforms into

$$a^{n+m+1} \int_0^{\frac{\pi}{2}} \sin^n \theta \cos^{m+1} \theta d\theta.$$

In like manner  $\int_0^a (2ax - x^2)^{\frac{m}{2}} dx,$

on making  $x = a(1 - \cos \theta)$ , becomes

$$a^{m+1} \int_0^{\frac{\pi}{2}} \sin^{m+1} \theta d\theta.$$

The expressions for these integrals, when  $m$  and  $n$  are fractional in form, will be given in a subsequent Article.

### EXAMPLES.

1.  $\int_0^{\frac{\pi}{2}} \sin^7 x \cos^4 x dx.$  *Ans.*  $\frac{4^3}{3 \cdot 5 \cdot 7 \cdot 11}.$

2.  $\int_0^{\frac{\pi}{2}} \sin^9 x \cos^8 x dx.$  "  $\frac{5 \cdot 10 \cdot 20 \cdot 30 \cdot 40}{9 \cdot 19 \cdot 29 \cdot 39 \cdot 49}.$

3.  $\int_0^{\frac{\pi}{2}} \sin^{2n-1} x \cos^{2n-1} x dx.$  "  $\frac{1 \cdot 2 \cdot 3 \dots}{n \cdot (n+1) \dots} \frac{(m-1)}{(n+m-1)}.$

4.  $\int_0^1 (1 - x^2)^n dx.$  "  $\frac{2 \cdot 4 \cdot 6 \dots}{3 \cdot 5 \cdot 7 \dots} \frac{(2n)}{(2n+1)}.$

5.  $\int_0^1 \frac{x^{2n} dx}{\sqrt{1 - x^2}}.$  "  $\frac{1 \cdot 3 \cdot 5 \dots (2n-1)}{2 \cdot 4 \cdot 6 \dots 2n} \cdot \frac{\pi}{2}.$

6.  $\int_0^1 \frac{x^{2n+1} dx}{\sqrt{1 - x^2}}.$  "  $\frac{2 \cdot 4 \cdot 6 \dots 2n}{3 \cdot 5 \cdot 7 \dots (2n+1)}.$

7. Deduce Wallis's value for  $\pi$  by aid of the two preceding definite integrals.

8.  $\int_0^{\infty} \frac{x^n dx}{(a + bx^2)^{\frac{n+1}{2}}}.$  *Ans.*  $\frac{2 \cdot 4 \cdot 6 \dots (n-1)}{3 \cdot 5 \cdot 7 \dots n} \frac{1}{\sqrt{ab^{n+1}}},$

when  $n$  is an odd integer.

9.  $\int_0^a x^3 (2ax - x^2)^{\frac{m}{2}} dx.$

**95. Value of  $\int_0^{\infty} e^{-x} x^n dx$ , when  $n$  is a positive integer.**  
In Art. 63 we have seen that

$$\int e^{-x} x^n dx = -e^{-x} x^n + n \int e^{-x} x^{n-1} dx.$$

Again, the expression  $\frac{x^n}{e^x}$  vanishes when  $x = 0$ , and also when  $x = \infty$  (Diff. Calc., Art. 94, Ex. 2).

Hence  $\int_0^{\infty} e^{-x} x^n dx = n \int_0^{\infty} e^{-x} x^{n-1} dx.$  (10)

Consequently  $\int_0^{\infty} e^{-x} x^n dx = 1 \cdot 2 \cdot 3 \dots n.$  (11)

Many other forms are immediately reducible to the preceding definite integral.

For example, if we make  $x = az$  we get

$$\int_0^{\infty} e^{-az} z^n dz = \frac{1 \cdot 2 \cdot 3 \dots n}{a^{n+1}},$$
 (12)

in which  $a$  is supposed to be positive.

Again, to find  $\int_0^1 x^m (\log x)^n dx$ ; let  $x = e^{-z}$ , and the integral becomes

$$(-1)^n \int_0^{\infty} e^{-(m+1)z} z^n dz = (-1)^n \frac{1 \cdot 2 \cdot 3 \dots n}{(m+1)^{n+1}}.$$

Since  $\log x = -\log \left(\frac{1}{x}\right)$ , this result may be written in the form

$$\int_0^1 x^m \left(\log \frac{1}{x}\right)^n dx = \frac{1 \cdot 2 \cdot 3 \dots n}{(m+1)^{n+1}}.$$
 (13)

The definite integral  $\int_0^{\infty} e^{-x} x^{n-1} dx$  is sometimes known as The Second\* Eulerian Integral, and is fundamental in the theory of definite integrals. Being obviously a function of  $n$ , it is denoted by the symbol  $\Gamma(n)$ , and is styled the Gamma-Function.

It follows from (10) that

$$\Gamma(n+1) = n\Gamma(n). \quad (14)$$

Also, when  $n$  is an integer we have

$$\Gamma(n+1) = 1 \cdot 2 \cdot 3 \cdots n. \quad (15)$$

Again, when  $x$  is less than unity, we have

$$\begin{aligned} \frac{1}{1-x} &= 1 + x + x^2 + x^3 + \&c; \\ \therefore \int_0^1 \log x \frac{dx}{1-x} &= \int_0^1 \log x (1 + x + x^2 + \dots) dx \\ &= - \left( 1 + \frac{1}{2^2} + \frac{1}{3^2} + \dots \right) = - \frac{\pi^2}{6}, \end{aligned}$$

(by a well-known result in Trigonometry).

In like manner we get

$$\int_0^1 \frac{\log x \, dx}{1+x} = - \frac{\pi^2}{12}.$$

An account of the more elementary properties of Gamma-Functions will be given at the end of this Chapter.

\* The integral  $\int_0^1 x^{n-1} (1-x)^{n-1} dx$ , considered in Art. 92, is sometimes called the First Eulerian Integral; we shall show subsequently how it can be expressed in terms of Gamma-Functions.

## EXAMPLES.

1.  $\int_0^1 \left\{ \log \left( \frac{1}{x} \right) \right\}^n dx.$  *Ans.* 1 . 2 . 3 . . . n.

2.  $\int_0^\infty a^{-x} x^n dx.$  "  $\frac{1 \cdot 2 \cdot \dots \cdot n}{(\log a)^{n+1}}.$

3.  $\int_0^1 \frac{\log x}{1 - x^2} dx.$  "  $-\frac{\pi^2}{8}.$

4.  $\int_0^1 \frac{dx (\log x)^{2n-1}}{1-x} = -1 \cdot 2 \cdot 3 \dots (2n-1) \left[ 1 + \frac{1}{2^{2n}} + \frac{1}{3^{2n}} + \dots \right].$

5.  $\int_0^2 \frac{dx}{x} \log \left( \frac{1+x}{1-x} \right).$  *Ans.*  $\frac{\pi^2}{4}.$

96. If  $u$  and  $v$  be both functions of  $x$ , and if  $v$  preserve the same sign while  $x$  varies from  $x_0$  to  $X$ , then we shall have

$$\int_{x_0}^X uv dx = U \int_{x_0}^X v dx,$$

where  $U$  is some quantity comprised between the greatest and the least values of  $u$ , between the assigned limits.

For, let  $A$  and  $B$  be the greatest and the least values of  $u$ , and we shall have, when  $v$  is positive,

$$Av > uv > Bv;$$

when  $v$  is negative,

$$Av < uv < Bv.$$

Consequently, for all values of  $x$  between  $x_0$  and  $X$  the expression  $uv dx$  lies between  $Av dx$  and  $Bv dx$ , and accordingly, if the sign of  $v$  does not change between the limits,

$$\int_{x_0}^X uv dx \text{ lies between } A \int_{x_0}^X v dx \text{ and } B \int_{x_0}^X v dx,$$

which establishes the theorem proposed.

Cor. If  $f(x)$  be finite and continuous for all values of  $x$  between the finite limits  $x_0$  and  $X$ , then the integral

$$\int_{x_0}^X f(x) dx$$

will also have a finite value.

For, let  $A$  be the greatest value of  $f(x)$ , and  $B$  the least, then  $\int_{x_0}^X f(x) dx$  evidently lies between the quantities

$$A \int_{x_0}^X dx \text{ and } B \int_{x_0}^X dx;$$

$$\therefore \int_{x_0}^X f(x) dx > B(X - x_0) \text{ and } < A(X - x_0).$$

§ 97. **Taylor's Theorem.**—The method of definite integration combined with that of integration by parts furnishes a simple proof of Taylor's series.

For, if in the equation

$$f(X + h) - f(X) = \int_X^{X+h} f'(x) dx$$

we assume  $x = X + h - z$ , we get  $dx = - dz$ , and also

$$\int_X^{X+h} f'(x) dx = \int_0^h f'(X + h - z) dz;$$

$$\therefore f(X + h) - f(X) = \int_0^h f'(X + h - z) dz.$$

Again, integrating by parts, we have

$$\int f'(X + h - z) dz = zf'(X + h - z) + \int zf''(X + h - z) dz.$$

Hence, substituting the limits, we have

$$\int_0^h f'(X + h - z) dz = hf'(X) + \int_0^h zf''(X + h - z) dz.$$

In like manner,

$$\int z f''(X + h - z) dz = \frac{z^2}{2} f''(X + h - z) + \int \frac{z^2}{2} f'''(X + h - z) dz,$$

which gives

$$\int_0^h z f''(X + h - z) dz = \frac{h^2}{2} f''(X) + \int_0^h \frac{z^2}{2} f'''(X + h - z) dz;$$

and so on.

Accordingly, we have finally

$$f(X + h) = f(X) + \frac{h}{1} f'(X) + \frac{h^2}{1 \cdot 2} f''(X) + \dots + \frac{h^{n-1}}{n-1} f^{(n-1)}(X) + \int_0^h f^{(n)}(X + h - z) \frac{z^{n-1} dz}{n-1}. \quad (16)$$

This is Taylor's well-known expansion.\*

98. **Remainder in Taylor's Theorem expressed as a Definite Integral.**—Let  $R_n$  represent the remainder after  $n$  terms in Taylor's series, then by the preceding Article we have

$$R_n = \int_0^h f^{(n)}(X + h - z) \frac{z^{n-1} dz}{n-1}. \quad (17)$$

There is no difficulty in deducing Lagrange's form for the remainder from this result.

For, by Art. 96, we have

$$R_n = U \int_0^h \frac{z^{n-1} dz}{1 \cdot 2 \cdot 3 \dots (n-1)} = U \frac{h^n}{1 \cdot 2 \dots n},$$

where  $U$  lies between the greatest and least values which  $f^{(n)}(X + h - z)$  assumes while  $z$  varies between 0 and  $h$ .

\* The student will observe that it is essential for the validity of this proof (Art. 90), that the successive derived functions,  $f'(x)$ ,  $f''(x)$ , &c., should be finite and continuous for all values of  $x$  between the limits  $X$  and  $X + h$ . Compare Articles 54 and 75, *Diff. Calc.*

Hence, as in Art. 75, Diff. Calc. (since any value of  $z$  between 0 and  $h$  may be represented by  $(1 - \theta)h$ , where  $\theta > 0$  and  $< 1$ ); we have

$$R_n = \frac{h^n}{1 \cdot 2 \dots n} f^{(n)}(X + \theta h)$$

where  $\theta$  is some quantity between the limits zero and unity.

99. **Bernoulli's Series.**—If we apply the method of integration by parts to the expression  $f(x)dx$  we get

$$\int f(x) dx = xf(x) - \int xf'(x)dx;$$

$$\therefore \int_0^X f(x) dx = Xf(X) - \int_0^X f'(x) x dx.$$

In like manner,

$$\int_0^X f'(x) x dx = \frac{X^2}{1 \cdot 2} f'(X) - \int_0^X f''(x) \frac{x^2 dx}{1 \cdot 2},$$

$$\int_0^X f''(x) \frac{x^2 dx}{1 \cdot 2} = \frac{X^3}{1 \cdot 2 \cdot 3} f''(X) - \int_0^X f'''(x) \frac{x^3 dx}{1 \cdot 2 \cdot 3},$$

and so on.

Hence, we get finally

$$\int_0^X f(x) dx = \frac{X}{1} f(X) - \frac{X^2}{1 \cdot 2} f'(X) + \frac{X^3}{1 \cdot 2 \cdot 3} f''(X) - \&c. \dots \quad (18)$$

Compare Art 66, Diff. Calc., where the result was obtained directly from Taylor's expansion.

100. **Exceptional Cases in Definite Integrals.**—In the foregoing discussion of definite integrals we have supposed that the function  $f(x)$ , under the sign of integration, has a finite value for all values of  $x$  between the limits. We have also supposed that the limits are finite. We purpose now to give a short discussion of the exceptional cases.\* They may

\* The complete investigation of definite integrals in these exceptional cases is due to Cauchy. For a more general discussion the student is referred to M. Moigno's *Calcul Intégral*, as also to those of M. Serret and M. Bertrand.

be classed as follows:—(1). When  $f(x)$  becomes infinite at one of the limits of integration. (2). When  $f(x)$  becomes infinite for one or more values of  $x$  between the limits of integration. (3). When one or both of the limits become infinite.

In these cases, the integral  $\int_{x_0}^X f(x) dx$  may still have a finite value, or it may be infinite, or indeterminate: depending on the form of the function  $f(x)$  in each particular case. The following investigation will be found to comprise the cases which usually arise.

**101. Case in which  $f(x)$  becomes infinite at one of the Limits.**—Suppose that  $f(x)$  is finite for all values of  $x$  between  $x_0$  and  $X$ , but that it becomes infinite when  $x = X$ .

The case that most commonly arises is where  $f(x)$  is of the form  $\frac{\psi(x) dx}{(X-x)^n}$ , in which  $\psi(x)$  is finite for all values between the limits, and  $n$  is a positive index.

Let  $a$  be assumed so that  $\psi(x)$  preserves the same sign between the limits  $a$  and  $X$ ; then

$$\int_{x_0}^X \frac{\psi(x) dx}{(X-x)^n} = \int_{x_0}^a \frac{\psi(x) dx}{(X-x)^n} + \int_a^X \frac{\psi(x) dx}{(X-x)^n}.$$

The former of the integrals at the right-hand side is finite by Art. 96. The consideration of the latter resolves into two cases, according as  $n$  is less or greater than unity.

(1). Let  $n < 1$ , and also let  $A$  and  $B$  be the greatest and least values of  $\psi(x)$  between the limits  $a$  and  $X$ : then, by Art. 96, the integral

$$\int_a^X \frac{\psi(x) dx}{(X-x)^n} \text{ lies between } A \int_a^X \frac{dx}{(X-x)^n} \text{ and } B \int_a^X \frac{dx}{(X-x)^n}.$$

Moreover, since  $n < 1$ , we have evidently.

$$\int_a^X \frac{dx}{(X-x)^n} = \frac{(X-a)^{1-n}}{1-n},$$

and consequently, in this case, the proposed integral has a finite value.

(2). Let  $n > 1$ , and, as before, suppose  $A$  and  $B$  the greatest and least values of  $\psi(x)$  between  $a$  and  $X$ ; then

$\int_a^X \frac{\psi(x) dx}{(X-x)^n}$  lies between  $A \int_a^X \frac{dx}{(X-x)^n}$  and  $B \int_a^X \frac{dx}{(X-x)^n}$ .

Again, we have

$$\int \frac{dx}{(X-x)^n} = \frac{1}{(n-1)(X-x)^{n-1}}.$$

Now  $\frac{1}{(X-x)^{n-1}}$  becomes infinite when  $x = X$ , but has a finite value when  $x = a$ ; consequently the definite integral proposed has an infinite value in this case.

When  $n = 1$ ,  $\int \frac{dx}{(X-x)} = -\log(X-x)$ . This becomes infinite when  $x = X$ ; and consequently in this case also the proposed integral becomes infinite.

The investigation when  $f(x)$  becomes infinite for  $x = x_0$  follows from the preceding by interchanging the limits.

**102. Case where  $f(x)$  becomes infinite between the Limits.**—Suppose  $f(x)$  becomes infinite when  $x = a$ , where  $a$  lies between the limits  $x_0$  and  $X$ ; then since

$$\int_{x_0}^X f(x) dx = \int_{x_0}^a f(x) dx + \int_a^X f(x) dx,$$

the investigation is reduced to two integrals, each of which may be treated as in the preceding Article.

Hence, if we suppose  $f(x) = \frac{\psi(x)}{(x-a)^n}$ , it follows, as in the last Article, that  $\int_{x_0}^X f(x) dx$  has a finite or an infinite value according as  $n$  is *less* or *not less* than unity.

The case in which  $f(x)$  becomes infinite for two or more values between the limits is treated in a similar manner.

For example, if

$$f(a_1) = \infty, \quad f(a_2) = \infty, \quad \dots \quad f(a_n) = \infty,$$

where  $a_1, a_2, \dots, a_n$  lie between the limits  $X$  and  $x_0$ ; then

$$\int_{x_0}^X f(x) dx = \int_{x_0}^{a_1} f(x) dx + \int_{a_1}^{a_2} f(x) dx + \text{etc.} + \int_{a_n}^X f(x) dx,$$

each of which can be treated separately.

**103. Case of Infinite Limits.**—Suppose the superior limit  $X$  to be infinite, and, as in the preceding discussion, let  $f(x)$  be of the form  $\frac{\psi(x)}{(x-a)^n}$ , where  $\psi(x)$  is finite for all values of  $x$ .

As before, we have

$$\int_{x_0}^X f(x) dx = \int_{x_0}^a f(x) dx + \int_a^X f(x) dx.$$

The integral between the finite limits  $x_0$  and  $a$  has a finite value as before. The investigation of the other integral consists again of two cases.

(1). Let  $n > 1$ , and let  $A$  be the greatest value of  $\psi(x)$  between the limits  $a$  and  $\infty$ , then

$$\int_a^\infty \frac{\psi(x) dx}{(x-a)^n} \text{ is less than } A \int_a^\infty \frac{dx}{(x-a)^n}.$$

But 
$$\int_a^X \frac{dx}{(x-a)^n} = \frac{1}{n-1} \left[ \frac{1}{(a-a)^{n-1}} - \frac{1}{(X-a)^{n-1}} \right].$$

The latter term becomes evanescent when  $X = \infty$ : accordingly in this case the proposed integral has a finite value.

In like manner it is easily seen that if  $n$  be not greater than unity, the definite integral

$$\int_a^\infty \frac{dx}{(x-a)^n}$$

[9 a]

has an infinite value ; and consequently

$$\int_a^{\infty} \frac{\psi(x) dx}{(x-a)^n}$$

is also infinite, provided  $\psi(x)$  does not become evanescent for infinite values of  $x$ .

Hence, the definite integral

$$\int_{x_0}^{\infty} \frac{\psi(x) dx}{(x-a)^n}$$

has, in general, a finite or an infinite value according as  $n$  is greater or not greater than unity :  $\psi(x)$  being supposed finite, and  $x_0$  being greater than  $a$ .

If  $X$  become  $-\infty$ , a similar investigation is applicable; for on changing  $x$  into  $-x$ , we have

$$\int_{x_0}^X f(x) dx = - \int_{-x_0}^{-X} f(-x) dx,$$

in which the superior limit becomes  $\infty$ .

**2104. Principal and General Values of a Definite Integral.**—We shall conclude this discussion with a short account of Cauchy's\* method of investigation.

Suppose  $f(x)$  to be infinite when  $x = a$ , where  $a$  lies between the limits  $x_0$  and  $X$ ; then the integral  $\int_{x_0}^X f(x) dx$  is regarded as the limit towards which the sum

$$\int_{x_0}^{a-\mu\epsilon} f(x) dx + \int_{a+\nu\epsilon}^X f(x) dx$$

approaches when  $\epsilon$  becomes evanescent ;  $\mu$  and  $\nu$  being any arbitrary constants.

\* This and the four following Articles have been taken, with some modifications, from Moigno's *Calcul Integral*.

This value depends on the nature of  $f(x)$ , and may be finite and determinate, or infinite, or indeterminate.

If we suppose  $\mu = \nu$ , the limiting value of the preceding sum is called the *principal value* of the proposed integral; while that given above is called its *general value*.

For example, let us consider the integral  $\int_{-x_0}^X \frac{dx}{x}$ .

Here  $\int_{-x_0}^X \frac{dx}{x} = \text{limit} \left[ \int_{\nu \epsilon}^X \frac{dx}{x} + \int_{-x_0}^{-\mu \epsilon} \frac{dx}{x} \right]$ .

But  $\int_{\nu \epsilon}^X \frac{dx}{x} = \log\left(\frac{X}{\nu \epsilon}\right)$ .

Also, making  $x = -z$ ,

$$\int_{-x_0}^{-\mu \epsilon} \frac{dx}{x} = \int_{x_0}^{\mu \epsilon} \frac{dz}{z} = \log\left(\frac{\mu \epsilon}{x_0}\right).$$

Accordingly, the principal value of  $\int_{-x_0}^X \frac{dx}{x}$  is  $\log\left(\frac{X}{x_0}\right)$ ; while its general value is  $\log\left(\frac{X}{x_0}\right) + \log\left(\frac{\mu}{\nu}\right)$ . The latter expression is perfectly arbitrary and indeterminate.

Again, let us take  $\int_{-x_0}^X \frac{dx}{x^2}$ .

As before,  $\int_{-x_0}^X \frac{dx}{x^2} = \text{limit} \left[ \int_{\nu \epsilon}^X \frac{dx}{x^2} + \int_{-x_0}^{-\mu \epsilon} \frac{dx}{x^2} \right]$ .

But  $\int_{\nu \epsilon}^X \frac{dx}{x^2} = \frac{1}{\nu \epsilon} - \frac{1}{X}$ ; and  $\int_{-x_0}^{-\mu \epsilon} \frac{dx}{x^2} = \frac{1}{\mu \epsilon} - \frac{1}{x_0}$ ;

$$\therefore \int_{-x_0}^X \frac{dx}{x^2} = \text{limit} \left[ \frac{1}{\mu \epsilon} + \frac{1}{\nu \epsilon} - \frac{1}{X} - \frac{1}{x_0} \right].$$

Consequently, both the principal and the general value of the integral are infinite in this case.

In like manner,

$$\int_{-x_0}^X \frac{dx}{x^3} = \text{limit of } \frac{1}{2} \left( \frac{1}{v^2 \epsilon^2} - \frac{1}{\mu^2 \epsilon^2} + \frac{1}{x_0^2} - \frac{1}{X^2} \right).$$

Hence the general value of the integral is infinite, while its principal value is  $\frac{1}{2} \left( \frac{1}{x_0^2} - \frac{1}{X^2} \right)$ .

It may be observed that the principal value of

$$\int_{-x_0}^X \frac{dx}{x^3} \text{ is equal to } \int_{x_0}^X \frac{dx}{x^3}.$$

This holds also whenever  $f(x)$  is a function of an odd order: i.e. when  $f(-x) = -f(x)$ .

For we have

$$\int_{-x_0}^{x_0} f(x) dx = \int_0^{x_0} f(x) dx + \int_{-x_0}^0 f(x) dx.$$

$$\text{But } \int_{-x_0}^0 f(x) dx = - \int_{x_0}^0 f(-x) dx = \int_0^{x_0} f(-x) dx;$$

$$\therefore \int_{-x_0}^{x_0} f(x) dx = \int_0^{x_0} \{f(x) + f(-x)\} dx. \quad (19)$$

Accordingly, if  $f(-x) = -f(x)$ , we get

$$\int_{-x_0}^{x_0} f(x) dx = 0.$$

Again, if  $f(x)$  be of an even order, i.e. if  $f(-x) = f(x)$ , we have

$$\int_{-x_0}^{x_0} f(x) dx = 2 \int_0^{x_0} f(x) dx.$$

**Q 105. Singular Definite Integral.**—The difference between the general and the principal value of the integral considered at the commencement of the preceding Article is represented by

$$\int_{a+\nu\epsilon}^{a+\mu\epsilon} f(x) dx,$$

in which  $f(a) = \infty$ , and  $\epsilon$  is evanescent.

Such an integral is called by Cauchy a *singular definite integral*, in which the limits differ by an infinitely small quantity. The preceding discussion shows that such an integral may be either *infinite* or *indeterminate*.

6106. **Infinite Limits.**—If the superior limit be infinite, we regard  $\int_{x_0}^{\infty} f(x) dx$  as the limit of  $\int_{x_0}^{\frac{1}{\mu\epsilon}} f(x) dx$ , when  $\epsilon$  becomes evanescent.

Also  $\int_{-\infty}^{\infty} f(x) dx = \text{limit of } \int_{-\frac{1}{\mu\epsilon}}^{\frac{1}{\mu\epsilon}} f(x) dx$  when  $\epsilon$  is evanescent.

In the latter case the value of the definite integral when  $\mu = \nu$  is, as before, called the *principal value* of

$$\int_{-\infty}^{\infty} f(x) dx.$$

In this we assume that  $f(x)$  does not become infinite for any real value of  $x$ .

107. **Example.**—Suppose  $\frac{f(x)}{F(x)}$  to be a rational algebraic fraction, in which  $f(x)$  is at least two degrees lower in  $x$  than  $F(x)$ , and suppose all the roots of  $F(x) = 0$  to be imaginary, it is required to find the value of

$$\int_{-\infty}^{\infty} \frac{f(x)}{F(x)} dx.$$

From the foregoing conditions it follows that  $\frac{f(x)}{F(x)}$  cannot become infinite for any real value of  $x$ : accordingly the true value of the integral is the limit of

$$\int_{-\frac{1}{\mu\epsilon}}^{\frac{1}{\nu\epsilon}} \frac{f(x)}{F(x)} dx$$

when  $\epsilon$  vanishes.

To find this value, suppose  $\frac{f(x)}{F(x)}$  decomposed by the method of partial fractions, and let

$$\frac{A - B\sqrt{-1}}{x - a - b\sqrt{-1}} \text{ and } \frac{A + B\sqrt{-1}}{x - a + b\sqrt{-1}}$$

be the fractions corresponding to the pair of conjugate roots

$$a + b\sqrt{-1} \text{ and } a - b\sqrt{-1}, \text{ of } F(x) = 0;$$

then the corresponding quadratic fraction is the sum of

$$\frac{A - B\sqrt{-1}}{x - a - b\sqrt{-1}} \text{ and } \frac{A + B\sqrt{-1}}{x - a + b\sqrt{-1}},$$

$$\text{i.e. } \frac{2A(x - a) + 2Bb}{(x - a)^2 + b^2}.$$

$$\text{Again } \int \frac{2Bb dx}{(x - a)^2 + b^2} = 2B \tan^{-1} \left( \frac{x - a}{b} \right);$$

$$\therefore \int_{-\frac{1}{\mu\epsilon}}^{\frac{1}{\nu\epsilon}} \frac{2Bb dx}{(x - a)^2 + b^2} = 2\pi B \text{ when } \epsilon \text{ vanishes.}$$

$$\text{Also } \int \frac{2A(x - a) dx}{(x - a)^2 + b^2} = A \log \{(x - a)^2 + b^2\};$$

$$\therefore \int_{-\frac{1}{\mu\epsilon}}^{\frac{1}{\nu\epsilon}} \frac{2A(x - a) dx}{(x - a)^2 + b^2} = A \log \left\{ \frac{\mu^2(1 - a\nu\epsilon)^2 + b^2\nu^2\epsilon^2}{\nu^2(1 + a\mu\epsilon)^2 + b^2\mu^2\epsilon^2} \right\}$$

$$= 2A \log \frac{\mu}{\nu}, \text{ when } \epsilon = 0.$$

$$\text{Hence } \int_{-\frac{1}{\mu\varepsilon}}^{\frac{1}{\nu\varepsilon}} \frac{\{2A(x-a) + 2B\} dx}{(x-a)^2 + b^2} = 2A \log\left(\frac{\mu}{\nu}\right) + 2\pi B. \quad (20)$$

Now, suppose  $F(x)$  to be of the degree  $2n$  in  $x$ , and let the values of  $A$  and  $B$ , corresponding to the  $n$  pairs of imaginary roots, be denoted by  $A_1, A_2, \dots, A_n$ , and  $B_1, B_2, \dots, B_n$ , respectively; then we have

$$\begin{aligned} \int_{-\frac{1}{\mu\varepsilon}}^{\frac{1}{\nu\varepsilon}} \frac{f(x)}{F(x)} dx &= 2(A_1 + A_2 + \dots + A_n) \log\left(\frac{\mu}{\nu}\right) \\ &\quad + 2\pi(B_1 + B_2 + \dots + B_n). \end{aligned}$$

Again, since  $f(x)$  is of the degree  $2n-2$  at most, we have

$$A_1 + A_2 + \dots + A_n = 0.$$

For, if we clear the equation

$$\frac{f(x)}{F(x)} = \frac{2A_1(x-a_1) + 2B_1b_1}{(x-a_1)^2 + b_1^2} + \dots + \frac{2A_n(x-a_n) + 2B_nb_n}{(x-a_n)^2 + b_n^2}$$

from fractions, the coefficient of  $x^{2n-1}$  at the right-hand side is evidently

$$2(A_1 + A_2 + \dots + A_n);$$

which must be zero, as there is no corresponding term on the other side.

Accordingly we have, in this\* case,

$$\int_{-\infty}^{\infty} \frac{f(x)}{F(x)} dx = 2\pi(B_1 + B_2 + \dots + B_n). \quad (21)$$

\* It may be observed that when  $f(x)$  is but one degree lower than  $F(x)$ , the principal value of  $\int_{-\infty}^{\infty} \frac{f(x)}{F(x)} dx$  is still of the form given in (21).

We proceed to apply this result to an important example.

108. **Value of**  $\int_0^{\infty} \frac{x^{2m} dx}{1+x^{2n}}$  **when m and n are Positive Integers, and**  $n > m$ .

Let  $a$  be a root of  $x^{2n} + 1 = 0$ , and, by Art. 37, we have

$$A - B\sqrt{-1} = \frac{a^{2m}}{2n a^{2n-1}} = -\frac{a^{2m+1}}{2n}.$$

Again, by the theory of equations,  $a$  is of the form

$$\cos \frac{(2k+1)\pi}{2n} + \sqrt{-1} \sin \frac{(2k+1)\pi}{2n},$$

in which  $k$  is either zero or a positive integer less than  $n$ ;

$$\therefore a^{2m+1} = \cos (2k+1)\theta + \sqrt{-1} \sin (2k+1)\theta,$$

where  $\theta = \frac{(2m+1)\pi}{2n}.$

Hence  $B = \frac{\sin (2k+1)\theta}{2n}$ ; and accordingly we have

$$B_1 + B_2 + \dots + B_n = \frac{1}{2n} (\sin \theta + \sin 3\theta + \dots + \sin (2n-1)\theta).$$

To find this sum, let

$$S = \sin \theta + \sin 3\theta + \dots + \sin (2n-1)\theta;$$

then

$$\begin{aligned} 2S \sin \theta &= 2 \sin^2 \theta + 2 \sin \theta \sin 3\theta + \dots + 2 \sin \theta \sin (2n-1)\theta \\ &= 1 - \cos 2\theta + \cos 2\theta - \cos 4\theta + \dots + \cos (2n-2)\theta - \cos 2n\theta \\ &= 1 - \cos 2n\theta = 2 \sin^2 n\theta = 2 \sin^2 (2m+1) \frac{\pi}{2} = 2; \end{aligned}$$

$$\therefore S = \frac{1}{\sin \theta} = \frac{1}{\sin \frac{(2m+1)\pi}{2n}}.$$

$$\text{Value of } \int_0^{\infty} \frac{x^{2m}}{1+x^{2n}} dx.$$

Accordingly, we have

$$\int_{-\infty}^{\infty} \frac{x^{2m} dx}{1+x^{2n}} = \frac{\pi}{n \sin \frac{(2m+1)\pi}{2n}}.$$

Hence, by (19),

$$\int_0^{\infty} \frac{x^{2m} dx}{1+x^{2n}} = \frac{1}{2} \int_{-\infty}^{\infty} \frac{x^{2m} dx}{1+x^{2n}} = \frac{\pi}{2n} \frac{1}{\sin \frac{(2m+1)\pi}{2n}}. \quad (22)$$

We now proceed to consider the analogous integral  $\int_0^{\infty} \frac{x^{2m} dx}{1-x^{2n}}$ , where  $m$  and  $n$ , as before, are positive integers, and  $n > m$ .

109. **Investigation of**  $\int_0^{\infty} \frac{x^{2m}}{1-x^{2n}} dx$ .

We commence by showing that

$$\int_0^{\infty} \frac{dx}{1-x^2} = 0.$$

This is easily seen as follows :

$$\int_0^{\infty} \frac{dx}{1-x^2} = \int_0^1 \frac{dx}{1-x^2} + \int_1^{\infty} \frac{dx}{1-x^2}.$$

Now, transform the latter integral, by making  $x = \frac{1}{z}$ , and we get

$$\begin{aligned} \int_1^{\infty} \frac{dx}{1-x^2} &= \int_1^0 \frac{dz}{1-z^2} = - \int_0^1 \frac{dz}{1-z^2} = - \int_0^1 \frac{dx}{1-x^2}; \\ \therefore \int_0^{\infty} \frac{dx}{1-x^2} &= 0. \end{aligned}$$

Again, proceeding to the integral

$$\int_0^{\infty} \frac{x^{2m} dx}{1-x^{2n}},$$

we observe that  $1+x$  and  $1-x$  are the only real factors of  $1-x^{2n}$ , and that the corresponding partial quadratic fraction in the decomposition of

$$\frac{x^{2m}}{1-x^{2n}} \text{ is } \frac{1}{n(1-x^2)}.$$

Consequently, the part of the definite integral which corresponds to the real roots disappears.

Moreover, it is easily seen that the method of Arts. 107 and 108 applies to the fractions arising from the  $n-1$  pairs of imaginary roots, and accordingly

$$\int_{-1}^1 \frac{x^{2m} dx}{1-x^{2n}} = 2\pi (B_1 + B_2 + \dots + B_{n-1}),$$

where  $B_1, B_2, \dots, B_{n-1}$  have the same signification as before.

Again, since the roots of  $x^{2n} - 1 = 0$  are of the form

$$\cos \frac{k\pi}{n} \pm \sqrt{-1} \sin \frac{k\pi}{n},$$

it follows, as in Art. 108, that

$$B_1 + B_2 + \dots + B_{n-1} = \frac{1}{2n} [\sin 2\theta + \sin 4\theta + \dots + \sin 2(n-1)\theta],$$

$$\text{where } \theta = \frac{(2m+1)\pi}{2n}, \text{ as before.}$$

Proceeding as in the former case, it is easily seen that

$$\begin{aligned} & \sin 2\theta + \sin 4\theta + \dots + \sin 2(n-1)\theta \\ &= \frac{\cos \theta - \cos (2n-1)\theta}{2 \sin \theta} = \cot \left( \frac{2m+1}{2n} \pi \right). \end{aligned}$$

Hence

$$\int_{-1}^1 \frac{x^{2m} dx}{1-x^{2n}} = \frac{\pi}{n} \cot \frac{2m+1}{2n} \pi;$$

$$\therefore \int_0^1 \frac{x^{2m} dx}{1-x^{2n}} = \frac{\pi}{2n} \cot \frac{2m+1}{2n} \pi. \quad (23)$$

Again, if we transform (22) and (23) by making  $x^{2n} = z$  and  $a = \frac{2m+1}{2n}$ , we get

$$\sqrt[n]{\int_0^\infty \frac{z^{a-1} dz}{1+z}} = \frac{\pi}{\sin a\pi}, \quad \int_0^\infty \frac{z^{a-1} dz}{1-z} = \pi \cot a\pi. \quad (24)$$

The conditions imposed on  $m$  and  $n$  require that  $a$  should be positive and less than unity.

Moreover, since the results in (24) hold for all integer values of  $m$  and  $n$ , provided  $n > m$ , we assume, by the law of continuity, that they hold for all values of  $a$ , so long as it is positive and less than unity.

110. The definite integrals discussed in the two preceding Articles admit of several important transformations, of which we proceed to add a few.

For example, on making  $u = z^a$  in (24), we get

$$\int_0^\infty \frac{du}{1+u^{\frac{1}{a}}} = \frac{a\pi}{\sin a\pi}; \quad \int_0^\infty \frac{du}{1-u^{\frac{1}{a}}} = a\pi \cot a\pi.$$

If  $\frac{1}{a} = r$ , these become

$$\int_0^\infty \frac{du}{1+u^r} = \frac{\pi}{r \sin \frac{\pi}{r}}, \quad \int_0^\infty \frac{du}{1-u^r} = \frac{\pi}{r} \cot \frac{\pi}{r}, \quad (25)$$

where  $r$  is positive and greater than unity.

Again

$$\int_0^\infty \frac{x^n dx}{1+x^2} = \int_0^1 \frac{x^n dx}{1+x^2} + \int_1^\infty \frac{x^n dx}{1+x^2}.$$

Now, if in the latter integral we make  $x = \frac{1}{z}$ , we get

$$\int_1^\infty \frac{x^n dx}{1+x^2} = - \int_1^0 \frac{z^{-n} dz}{1+z^2} = \int_0^1 \frac{x^{-n} dx}{1+x^2};$$

$$\therefore \int_0^\infty \frac{x^n dx}{1+x^2} = \int_0^1 \frac{x^n + x^{-n}}{1+x^2} dx. \quad (26)$$

Moreover, from (22), when  $n$  is less than unity, we have

$$\int_0^\pi \frac{x^n dx}{1+x^2} = \frac{\pi}{2 \cos \frac{n\pi}{2}}. \quad (27)$$

Accordingly

$$\int_0^1 \frac{x^n + x^{-n}}{x + x^{-1}} \frac{dx}{x} = \frac{\pi}{2 \cos \frac{n\pi}{2}}. \quad (28)$$

In like manner, it is easily seen that

$$\int_0^1 \frac{x^n - x^{-n}}{x - x^{-1}} \frac{dx}{x} = \frac{\pi}{2} \tan \frac{n\pi}{2}. \quad (29)$$

It should be noted, that in these results  $n$  must be less than unity.

Again, transform (28) and (29) by making  $x = e^{-\pi z}$  and  $n\pi = a$ , and we get

$$\int_0^\infty \frac{e^{az} + e^{-az}}{e^{\pi z} + e^{-\pi z}} dz = \frac{1}{2} \sec \frac{a}{2}, \quad \int_0^\infty \frac{e^{az} - e^{-az}}{e^{\pi z} - e^{-\pi z}} dz = \frac{1}{2} \tan \frac{a}{2}. \quad (30)$$

We add a few examples for illustration.

### EXAMPLES.

1.  $\int_0^a \frac{dx}{(a^n - x^n)^{\frac{1}{n}}}.$  *Ans.*  $\frac{\pi}{n \sin \frac{\pi}{n}}$ .
2.  $\int_0^\infty \frac{dx}{(x^2 + a^2)(x^2 + b^2)}.$  "  $\frac{\pi}{2ab(a + b)}$ .
3.  $\int_0^\infty \frac{dx}{1 - x^4}.$  "  $\frac{\pi}{4}$ .
4.  $\int_0^{\frac{\pi}{2}} \tan^n \theta d\theta$ , where  $n$  lies between + 1 and - 1. "  $\frac{\pi}{2 \cos \frac{n\pi}{2}}$ .

5.  $\int_0^1 \frac{x^m + x^{-m}}{x^n + x^{-n}} \frac{dx}{x}$ , where  $n > m$ .

Ans.  $\frac{\pi}{2n \cos \frac{m\pi}{2n}}$ .

6.  $\int_0^\infty \frac{(e^{ax} + e^{-ax})(e^{bx} + e^{-bx})}{e^{\pi x} + e^{-\pi x}} dx$ .

,"  $\frac{2 \cos \frac{a}{2} \cos \frac{b}{2}}{\cos a + \cos b}$ .

7.  $\int_0^\infty \frac{(e^{ax} + e^{-ax})(e^{bx} - e^{-bx})}{e^{\pi x} - e^{-\pi x}} dx$ .

,"  $\frac{\sin b}{\cos a + \cos b}$ .

It should be observed, that in these we must have  $a + b < \pi$ .

8. Hence, when  $b < \pi$ , prove that

$$\int_0^\infty \frac{e^{bx} + e^{-bx}}{e^{\pi x} + e^{-\pi x}} \cos ax dx = \frac{\left( e^{\frac{a}{2}} + e^{-\frac{a}{2}} \right) \cos \frac{b}{2}}{e^a + 2 \cos b + e^{-a}}.$$

$$\int_0^\infty \frac{e^{bx} - e^{-bx}}{e^{\pi x} - e^{-\pi x}} \cos ax dx = \frac{\sin b}{e^a + 2 \cos b + e^{-a}}.$$

$$\int_0^\infty \frac{e^{bx} + e^{-bx}}{e^{\pi x} - e^{-\pi x}} \sin ax dx = \frac{1}{2} \frac{e^a - e^{-a}}{e^a + 2 \cos b + e^{-a}}.$$

9.  $\int_0^1 \frac{z^a - z^{-a}}{1 - z} dz$ .

Ans.  $\pi \cot a\pi - \frac{1}{a}$ .

III. **Differentiation of Definite Integrals.**—It is plain from Art. 86 that the method of *differentiation under the sign of integration* applies to definite as well as to indefinite integrals, provided the limits of integration are independent of the quantity with respect to which we differentiate.

On account of the importance of this principle we add an independent proof, as follows:—

Suppose  $u$  to denote the definite integral in question, i.e. let

$$u = \int_a^b \phi(x, a) dx,$$

where  $a$  and  $b$  are independent of  $a$ .

To find  $\frac{du}{da}$  let  $\Delta u$  denote the change in  $u$  arising from the change  $\Delta a$  in  $a$ ; then, since the limits are unaltered,

$$\Delta u = \int_a^b \{ \phi(x, a + \Delta a) - \phi(x, a) \} dx;$$

$$\therefore \frac{\Delta u}{\Delta a} = \int_a^b \frac{\phi(x, a + \Delta a) - \phi(x, a)}{\Delta a} dx.$$

Hence, on passing to the limit,\* we have

$$\frac{du}{da} = \int_a^b \frac{d\phi(x, a)}{da} dx.$$

Also, if we differentiate  $n$  times in succession, we obviously have

$$\frac{d^n u}{da^n} = \int_a^b \frac{d^n \phi(x, a)}{da^n} dx.$$

The importance of this method will be best exhibited by a few elementary examples.

**112. Integrals deduced by Differentiation.**—If the equation

$$\int_0^\infty e^{-ax} dx = \frac{1}{a}$$

be differentiated  $n$  times with respect to  $a$ , we get

$$\int_0^\infty x^n e^{-ax} dx = \frac{1 \cdot 2 \cdot 3 \dots n}{a^{n+1}},$$

as in Art. 95.

Again, from the equation

$$\int_0^\infty \frac{dx}{x^2 + a} = \frac{\pi}{2} \frac{1}{a^{\frac{1}{2}}},$$

we get, after  $n$  differentiations with respect to  $a$ ,

$$\int_0^\infty \frac{dx}{(x^2 + a)^{n+1}} = \frac{\pi}{2} \frac{1 \cdot 3 \cdot 5 \dots (2n-1)}{2 \cdot 4 \cdot 6 \dots 2n} \frac{1}{a^{n+\frac{1}{2}}};$$

which agrees with Art. 94.

\* For exceptions to this general result the student is referred to Bertrand's *Calcul Intégral*, p. 181.

Again, if we take 0 and  $\infty$  for limits in the integrals (23) and (24) of Art. 21, we get

$$\int_0^\infty e^{-ax} \cos mx dx = \frac{a}{a^2 + m^2}, \quad \int_0^\infty e^{-ax} \sin mx dx = \frac{m}{a^2 + m^2}. \quad (31)$$

Now, differentiate each of these  $n$  times with respect to  $a$ , and we get

$$\begin{aligned} \int_0^\infty e^{-ax} x^n \cos mx dx &= (-1)^n \left( \frac{d}{da} \right)^n \left( \frac{a}{a^2 + m^2} \right) \\ &= \frac{[n \cdot \cos(n+1)\theta]}{(a^2 + m^2)^{\frac{n+1}{2}}}, \end{aligned}$$

$$\int_0^\infty e^{-ax} x^n \sin mx dx = \frac{[n \cdot \sin(n+1)\theta]}{(a^2 + m^2)^{\frac{n+1}{2}}}, \quad (32)$$

where  $m = a \tan \theta$ . (See Ex. 17, 18, Diff. Calo., pp. 58, 59.)

Next, from (24) we have

$$\int_0^\infty \frac{x^{n-1} dx}{1-x} = \pi \cot a\pi.$$

Accordingly, if we differentiate with respect to  $a$ , we have

$$\int_0^\infty \frac{x^{n-1} \log x dx}{1-x} = -\frac{\pi^2}{\sin^2 a\pi}.$$

Again, if the equation

$$\int_0^1 y^{n-1} dy = \frac{1}{n}$$

be transformed, by making  $y = \frac{bx}{a+bx}$ , it evidently gives

$$\int_0^\infty \frac{x^{n-1} dx}{(a+bx)^{n+1}} = \frac{1}{nab^n}.$$

Now, differentiating with respect to  $a$ , we have

$$\int_0^\infty \frac{x^{n-1} dx}{(a + bx)^{n+2}} = \frac{1}{n(n+1)a^2 b^n}.$$

If we proceed to differentiate  $m - 1$  times with regard to  $a$ , we have

$$\int_0^\infty \frac{x^{n-1} dx}{(a + bx)^{m+n}} = \frac{1 \cdot 2 \cdot 3 \dots (m-1)}{n \cdot (n+1)(n+2) \dots (n+m-1)} \cdot \frac{1}{a^m b^n}.$$

113. By aid of the preceding method the determination of a definite integral can often be reduced to a known integral. We shall illustrate this statement by one or two examples.

Ex. 1. To find

$$\int_0^\pi \frac{\log(1 + \sin a \cos x)}{\cos x} dx.$$

Denote the definite integral by  $u$ , and differentiate with respect to  $a$ ; then

$$\frac{du}{da} = \int_0^\pi \frac{\cos a dx}{1 + \sin a \cos x} = \pi \text{ (by Art. 18).}$$

Hence, we get

$$\int_0^\pi \frac{dx \log(1 + \sin a \cos x)}{\cos x} = \pi a.$$

No constant is added since the integral evidently vanishes along with  $a$ .

$$\text{Ex. 2. } u = \int_0^\infty \frac{e^{-ax} \sin mx}{x} dx.$$

In this case

$$\frac{du}{dm} = \int_0^\infty e^{-ax} \cos mx dx = \frac{a}{a^2 + m^2};$$

$$\therefore u = a \int \frac{dm}{a^2 + m^2} = \tan^{-1} \left( \frac{m}{a} \right).$$

No constant is added since  $u$  vanishes with  $m$ .

Ex. 3. Next suppose

$$u = \int_0^\infty \frac{\log(1 + a^2 x^2)}{1 + b^2 x^2} dx.$$

Here  $\frac{du}{da} = \int_0^\infty \frac{2ax^2 dx}{(1 + a^2 x^2)(1 + b^2 x^2)}$

$$= \frac{1}{a^2 - b^2} \left[ \int_0^\infty \frac{2adx}{1 + b^2 x^2} - \int_0^\infty \frac{2adx}{1 + a^2 x^2} \right]$$

$$= \frac{1}{a^2 - b^2} \left( \frac{a}{b} - 1 \right) \pi = \frac{\pi}{b(a + b)};$$

$$\therefore u = \frac{\pi}{b} \int \frac{da}{a + b} = \frac{\pi}{b} \log(a + b) + \text{const.}$$

To determine the constant: let  $a = 0$ , and we obviously have  $u = 0$ .

Consequently, the constant is  $-\frac{\pi}{b} \log b$ ;

$$\therefore \int_0^\infty \frac{\log(1 + a^2 x^2)}{1 + b^2 x^2} dx = \frac{\pi}{b} \log\left(\frac{a + b}{b}\right).$$

The method adopted in this Article is plainly equivalent to a process of integration under the sign of integration. Before proceeding to this method we shall consider the case of differentiation when the limits  $a$  and  $b$  are functions of the quantity with respect to which we differentiate.

**114. Differentiation where the Limits are Variable.**—Let the indefinite integral of the expression  $\phi(x, a)dx$  be denoted by  $F(x, a)$ ; then, by Art. 91, we have

$$u = \int_a^b \phi(x, a) dx = F(b, a) - F(a, a);$$

$$\therefore \frac{du}{db} = \frac{d \cdot F(b, a)}{db} = \phi(b, a),$$

[10 a]

and

$$\frac{du}{da} = -\frac{dF(a, a)}{da} = -\phi(a, a).$$

Again, taking the total differential coefficient of  $u$  regarding  $a$  and  $b$  as functions of  $a$ , we have

$$\begin{aligned} \frac{du}{da} &= \int_a^b \frac{d\phi(x, a)}{da} dx + \frac{du}{db} \frac{db}{da} + \frac{du}{da} \frac{da}{da} \\ &= \int_a^b \frac{d\phi(x, a)}{da} dx + \phi(b, a) \frac{db}{da} - \phi(a, a) \frac{da}{da}. \end{aligned} \quad (33)$$

By repeating this process, the values of  $\frac{d^2u}{da^2}$ ,  $\frac{d^3u}{da^3}$ , &c., can be obtained, if required. \

**115. Integration under the Sign of Integration.**— Returning to the equation

$$u = \int_a^b \phi(x, a) dx,$$

where the limits are independent of  $a$ , it is obvious, as in Art. 87, that

$$\int u da = \int_a^b \left[ \int \phi(x, a) da \right] dx,$$

provided  $a$  be taken between the same limits in both cases.

If we denote the limits of  $a$  by  $a_0$  and  $a_1$ , we get

$$\int_{a_0}^{a_1} u da = \int_a^b \left[ \int_{a_0}^{a_1} \phi(x, a) da \right] dx,$$

$$\text{or } \int_{a_0}^{a_1} \left[ \int_a^b \phi(x, a) dx \right] da = \int_a^b \left[ \int_{a_0}^{a_1} \phi(x, a) da \right] dx. \quad (34)$$

This result is easily written in the form

$$\int_{a_0}^{a_1} \int_a^b \phi(x, a) dx da = \int_a^b \int_{a_0}^{a_1} \phi(x, a) du dx. \quad (35)$$

These expressions are called *double definite integrals*, as involving successive integrations with respect to two variables, taken between limits.

It may be observed that the expression

$$\int_{a_0}^{a_1} \int_a^b \phi(x, a) dx da$$

is here taken as an abbreviation of

$$\int_{a_0}^{a_1} \left[ \int_a^b \phi(x, a) dx \right] da,$$

in which the definite integral between the brackets is supposed to be first determined, and the result afterwards integrated with respect to  $a$ , between the limits  $a_0$  and  $a_1$ .

The principle\* established above may be otherwise stated, thus: *In the determination of the integral of the expression*

$$\int \phi(x, a) dx da$$

*between the respective limits  $x_0, x_1$ , and  $a_0, a_1$ , we may effect the integrations in either order, provided the limits of  $x$  and  $a$  are independent of each other.*

In a subsequent chapter the geometrical interpretation of this, as well as of a more general theorem, will be given.

We now proceed to illustrate the importance of this method by a few examples.

### 116. Applications of Integration under the Sign ∫.

Ex. 1. From the equation

$$\int_0^1 x^{a-1} dx = \frac{1}{a}$$

we get

$$\int_0^1 \int_{a_0}^{a_1} x^{a-1} da dx = \int_{a_0}^{a_1} \frac{da}{a} = \log \left( \frac{a_1}{a_0} \right).$$

\* It should be noted that this principle fails whenever  $\phi(x, a)$ , or either of its integrals with respect to  $a$ , or to  $x$ , becomes infinite for any values of  $x$  and  $a$  contained between the limits of integration. The student will find that the examples here given are exempt from such failure.

Hence

$$\int_0^1 \frac{x^{a_1-1} - x^{a_0-1}}{\log x} dx = \log\left(\frac{a_1}{a_0}\right).$$

Again, if we make  $x = e^{-z}$  in this equation, we get

$$\int_0^\infty \frac{e^{-a_1 z} - e^{-a_0 z}}{z} dz = \log\left(\frac{a_0}{a_1}\right).$$

Ex. 2. We have already seen that

$$\int_0^\infty e^{-ax} \cos mx dx = \frac{a}{a^2 + m^2}.$$

Hence

$$\begin{aligned} \int_0^\infty \int_{a_0}^{a_1} e^{-ax} da \cos mx dx &= \int_{a_0}^{a_1} \frac{a da}{a^2 + m^2} \\ &= \frac{1}{2} \log\left(\frac{a_1^2 + m^2}{a_0^2 + m^2}\right), \end{aligned}$$

or  $\int_0^\infty \frac{e^{-a_1 x} - e^{-a_0 x}}{x} \cos mx dx = \frac{1}{2} \log\left(\frac{a_1^2 + m^2}{a_0^2 + m^2}\right).$

Ex. 3. Again, from the equation

$$\int_0^\infty e^{-ax} \sin mx dx = \frac{m}{a^2 + m^2},$$

we get

$$\int_0^\infty \int_{a_0}^{a_1} e^{-ax} \sin mx da dx = \int_{a_0}^{a_1} \frac{m da}{a^2 + m^2};$$

$$\therefore \int_0^\infty \frac{e^{-a_0 x} - e^{-a_1 x}}{x} \sin mx dx = \tan^{-1}\left(\frac{a_1}{m}\right) - \tan^{-1}\left(\frac{a_0}{m}\right).$$

Compare Ex. 2, Art. 113.

If we make  $a_0 = 0$  and  $a_1 = \infty$  in the latter result, we obtain

$$\int_0^\infty \frac{\sin mx}{x} dx = \frac{\pi}{2}.$$

Value of  $\int_0^\infty e^{-x^2} dx$ .

Ex. 4. To find the value of

$$\int_0^\infty e^{-x^2} dx.$$

Denoting the proposed integral by  $k$ , and substituting  $ax$  for  $x$ , we obviously have

$$\int_0^\infty e^{-a^2 x^2} a dx = k;$$

$$\therefore \int_0^\infty e^{-a^2(1+x^2)} a dx = k e^{-a^2}.$$

Hence

$$\int_0^\infty \left( \int_0^\infty e^{-a^2(1+x^2)} a da \right) dx = k \int_0^\infty e^{-a^2} da = k^2.$$

But

$$\int_0^\infty e^{-a^2(1+x^2)} a da = \frac{1}{2} \frac{1}{1+x^2};$$

$$\therefore \frac{1}{2} \int_0^\infty \frac{dx}{1+x^2} = k^2; \quad \therefore \frac{\pi}{4} = k^2.$$

Hence

$$\int_0^\infty e^{-x^2} dx = k = \frac{1}{2} \sqrt{\pi}. \quad (36)$$

This definite integral is of considerable importance, and several others are readily deduced from it.

117. For example, to find

$$(A) \quad u = \int_0^\infty e^{-x^2 - \frac{a^2}{x^2}} dx.$$

Here

$$\frac{du}{da} = -2 \int_0^\infty e^{-x^2 - \frac{a^2}{x^2}} a \frac{dx}{x^3}.$$

Again, let  $z = \frac{a}{x}$ , and we get

$$\int_0^{\infty} e^{-x^2 - \frac{a^2}{x^2}} \frac{a^2}{x^2} dx = \int_0^{\infty} e^{-z^2 - \frac{a^2}{z^2}} dz = u ;$$

$$\therefore \frac{du}{da} = -2u ; \text{ hence } u = Ce^{-2a}.$$

To determine  $C$ , let  $a = 0$ , and, by the preceding example,  $u$  becomes  $\frac{\sqrt{\pi}}{2}$ .

Consequently

$$\int_0^{\infty} e^{-x^2 - \frac{a^2}{x^2}} dx = \frac{\sqrt{\pi}}{2} e^{-2a}. \quad (37)$$

Again, to find

$$(B) \quad u = \int_0^{\infty} e^{-a^2 x^2} \cos 2bx dx.$$

Here

$$\frac{du}{db} = -2 \int_0^{\infty} e^{-a^2 x^2} x \sin 2bx dx.$$

But, integrating by parts, we have

$$2 \int e^{-a^2 x^2} \sin 2bx x dx = -\frac{e^{-a^2 x^2} \sin 2bx}{a^2} + \frac{2b}{a^2} \int e^{-a^2 x^2} \cos 2bx dx;$$

$$\therefore \int_0^{\infty} e^{-a^2 x^2} \sin 2bx x dx = \frac{2b}{a^2} \int_0^{\infty} e^{-a^2 x^2} \cos 2bx dx.$$

Hence

$$\frac{du}{db} = -\frac{2bu}{a^2}, \text{ or } \frac{du}{u} = -\frac{2b}{a^2} db.$$

$$\text{Hence } u = Ce^{-\frac{b^2}{a^2}}.$$

Also, when  $b = 0$ ,  $u$  becomes  $\frac{\sqrt{\pi}}{2a}$ ,

$$\therefore \int_0^{\infty} e^{-a^2 x^2} \cos 2bx dx = \frac{\sqrt{\pi}}{2a} e^{-\frac{b^2}{a^2}}. \quad (38)$$

Again, if we differentiate  $n$  times, with respect to  $a$ , the equation

$$\int_0^{\infty} e^{-ax^2} dx = \frac{\sqrt{\pi}}{2\sqrt{a}},$$

and afterwards make  $a = 1$ , we get

$$(C) \quad \int_0^{\infty} e^{-x^2} x^{2n} dx = \frac{1 \cdot 3 \cdot 5 \dots (2n-1)}{2^{n+1}} \sqrt{\pi}.$$

Next, to find

$$(D) \quad \int_0^{\infty} \frac{\cos mx dx}{1+x^2}.$$

We obviously have

$$2 \int_0^{\infty} a e^{-a^2(1+x^2)} da = \frac{1}{1+x^2};$$

$$\therefore 2 \int_0^{\infty} \int_0^{\infty} a e^{-a^2(1+x^2)} \cos mx dx da = \int_0^{\infty} \frac{\cos mx dx}{1+x^2}.$$

But, by (38), we have

$$2 \int_0^{\infty} e^{-a^2 x^2} \cos mx dx = \frac{\sqrt{\pi}}{a} e^{-\frac{m^2}{4a^2}};$$

$$\therefore \sqrt{\pi} \int_0^{\infty} e^{-a^2 - \frac{m^2}{4a^2}} da = \int_0^{\infty} \frac{\cos mx dx}{1+x^2}.$$

Hence, by (37), we have

$$\int_0^{\infty} \frac{\cos mx dx}{1+x^2} = \frac{\pi}{2} e^{-m}. \quad (39)$$

Again, differentiating with respect to  $m$ , we obtain

$$\int_0^{\infty} \frac{x \sin mx dx}{1+x^2} = \frac{\pi}{2} e^{-m}. \quad (40)$$

## EXAMPLES.

1.  $\int_0^\infty \frac{e^{ax} + e^{-ax}}{e^{\pi x} - e^{-\pi x}} x dx.$  *Ans.*  $\frac{1}{4} \sec^2 \frac{a}{2}.$

2.  $\int_0^1 \frac{x^{a-1} - x^{-a}}{1+x} \frac{dx}{\log x},$  *,,*  $\log \left( \tan \frac{a\pi}{2} \right).$

when  $a > 0$  and  $< 1.$

3.  $\int_0^1 \frac{z^a + z^{-a} - 2}{1-z} \frac{dz}{\log z}.$  *,,*  $\log \left( \frac{a\pi}{\sin a\pi} \right).$

4.  $\int_0^{\frac{\pi}{2}} \log (1 + \cos \theta \cos x) \frac{dx}{\cos x}.$  *,,*  $\frac{1}{2} \left( \frac{\pi^2}{4} - \theta^2 \right).$

5.  $\int_0^\infty \cos x \log \left( \frac{x^2 + \beta^2}{x^2 + a^2} \right) dx.$  *,,*  $\pi \left( e^{-a} - e^{-\beta} \right).$

6.  $\int_0^\infty \frac{z^r \log z dz}{1+z^2}.$  *,,*  $\frac{\pi^2}{4} \frac{\sin \frac{r\pi}{2}}{\cos^2 \frac{r\pi}{2}}.$

7.  $\int_0^\infty \frac{\sin a\theta d\theta}{e^{\pi\theta} - e^{-\pi\theta}}.$  *,,*  $\frac{1}{4} \frac{e^a - 1}{e^a + 1}.$

118. The values of some important definite integrals can be easily deduced from formula (34), Art. 32.

For example,\* to find

$$\int_0^{\frac{\pi}{2}} \log (\sin \theta) d\theta.$$

Here  $\int_0^{\frac{\pi}{2}} \log (\sin \theta) d\theta = \int_0^{\frac{\pi}{2}} \log (\cos \theta) d\theta.$

Hence, denoting either integral by  $u$ , we have

$$2u = \int_0^{\frac{\pi}{2}} \{ \log (\sin \theta) + \log (\cos \theta) \} d\theta$$

\* These examples are taken from a Paper, signed "H. G.," in the *Cambridge Mathematical Journal*, Vol. 3.

$$= \int_0^{\frac{\pi}{2}} \log (\sin 2\theta) d\theta - \frac{\pi}{2} \log 2.$$

Again, if  $z = 2\theta$ , we have

$$\begin{aligned} \int_0^{\frac{\pi}{2}} \log (\sin 2\theta) d\theta &= \frac{1}{2} \int_0^{\pi} \log (\sin z) dz \\ &= \frac{1}{2} \int_0^{\frac{\pi}{2}} \log (\sin z) dz + \frac{1}{2} \int_{\frac{\pi}{2}}^{\pi} \log (\sin z) dz; \end{aligned}$$

but, since  $\sin(\pi - z) = \sin z$ ,

$$\int_{\frac{\pi}{2}}^{\pi} \log (\sin z) dz = \int_0^{\frac{\pi}{2}} \log (\sin z) dz.$$

Consequently

$$\begin{aligned} \int_0^{\frac{\pi}{2}} \log (\sin 2\theta) d\theta &= \int_0^{\frac{\pi}{2}} \log (\sin \theta) d\theta; \\ \therefore \int_0^{\frac{\pi}{2}} \log (\sin \theta) d\theta &= -\frac{\pi}{2} \log (2). \end{aligned} \quad (41)$$

Again, to find

$$\int_0^{\pi} \theta \log (\sin \theta) d\theta.$$

Here

$$\begin{aligned} \int_0^{\pi} \theta \log (\sin \theta) d\theta &= \int_0^{\pi} (\pi - \theta) \log (\sin \theta) d\theta; \\ \therefore \int_0^{\pi} \theta \log (\sin \theta) d\theta &= \frac{\pi}{2} \int_0^{\pi} \log (\sin \theta) d\theta = -\frac{\pi^2}{2} \log (2). \end{aligned}$$

119. **Theorem of Frullani.**—To prove that

$$\int_0^{\infty} \frac{\phi(ax) - \phi(bx)}{x} dx = \phi(0) \log \left( \frac{b}{a} \right).$$

Let  $u = \int_0^h \frac{\phi(z) - \phi(0)}{z} dz$ ; substitute  $ax$  for  $z$ , and we get

$$u = \int_0^h \frac{\phi(ax) - \phi(0)}{x} dx.$$

If we substitute  $b$  for  $a$ , we get

$$u = \int_0^h \frac{\phi(bx) - \phi(0)}{x} dx;$$

$$\therefore \int_0^a \frac{\phi(ax) dx}{x} - \int_0^b \frac{\phi(bx) dx}{x} = \phi(0) \int_{\frac{h}{b}}^{\frac{h}{a}} \frac{dx}{x} = \phi(0) \log \frac{b}{a}. \quad (42)$$

$$\text{Hence } \int_0^h \frac{\phi(ax) - \phi(bx)}{x} dx - \int_{\frac{h}{b}}^{\frac{h}{a}} \frac{\phi(bx)}{x} dx = \phi(0) \log \left( \frac{b}{a} \right). \quad (43)$$

If we suppose  $h = \infty$ , we get

$$\int_0^\infty \frac{\phi(ax) - \phi(bx)}{x} dx = \phi(0) \log \left( \frac{b}{a} \right), \quad (44)$$

provided  $\int_{\frac{h}{b}}^{\frac{h}{a}} \frac{\phi(bx)}{x} dx = 0$  when  $h = \infty$ .

For example, let  $\phi(x) = \cos x$ , and, since the integral

$$\int_{\frac{h}{b}}^{\frac{h}{a}} \frac{\cos bx}{x} dx$$

evidently vanishes when  $h = \infty$ , we have

$$\int_0^\infty \frac{\cos ax - \cos bx}{x} dx = \log \frac{b}{a}.$$

Frullani's theorem plainly fails when  $\phi(ax)$  tends to a definite limit when  $x$  becomes infinitely great. The formulæ can be exhibited, however, in this case in a simple shape, as was shown by Mr. E. B. Elliott.\*

For, in (42) let  $h = ab$ , and it becomes

$$\int_0^b \frac{\phi(ax)dx}{x} - \int_0^a \frac{\phi(bx)dx}{x} = \phi(0) \log\left(\frac{b}{a}\right). \quad (45)$$

Again, if  $\phi(\infty)$  denote the definite value to which  $\phi(ax)$  tends when  $x$  increases indefinitely, then when  $h$  becomes infinite we may substitute  $\phi(\infty)$  instead of  $\phi(bx)$  in the integral

$$\int_{\frac{h}{a}}^{\frac{h}{b}} \frac{\phi(bx)}{x} dx;$$

in which case it becomes

$$\phi(\infty) \int_{\frac{h}{a}}^{\frac{h}{b}} \frac{dx}{x} = \phi(\infty) \log\left(\frac{a}{b}\right).$$

On making this substitution in (43), we get

$$\int_0^{\infty} \frac{\phi(ax) - \phi(bx)}{x} dx = \left\{ \phi(\infty) - \phi(0) \right\} \log\left(\frac{a}{b}\right).$$

(46)

For example, let  $\phi(ax) = \tan^{-1}(ax)$  then we have  $\phi(0) = 0$ , and  $\phi(\infty) = \frac{\pi}{2}$ .

Accordingly we have

$$\int_0^{\infty} \frac{\tan^{-1} ax - \tan^{-1} bx}{x} dx = \frac{\pi}{2} \int_{\frac{h}{a}}^{\frac{h}{b}} \frac{dx}{x} = \frac{\pi}{2} \log\left(\frac{a}{b}\right).$$

\* *Educational Times*, 1875. The student will find some remarkable extensions of the formulæ, given above, to Multiple Definite Integrals, by Mr. Elliott, in the *Proceedings of the London Mathematical Society*, 1876, 1877. Also by Mr. Lendesdorf, in the same Journal, 1878.

119 a. **Remainder in Lagrange's Series.**—We next proceed to show that the remainder in Lagrange's series (Diff. Calc., Art. 125) admits of being represented by a definite integral. This result, I believe, was first given by M. Popoff (*Comptes Rendus*, 1861, pp. 795-8).

The following proof, which at the same time affords a demonstration of the series, of a simple character, is due to M. Zolotareff :—

Let  $z = x + y \phi(z)$ ; and consider the definite integral

$$s_n = \int_x^z \{y \phi(u) + x - u\}^n F'(u) du.$$

Differentiating this with respect to  $x$ , we get, by (33), Art. 114,

$$\frac{ds_n}{dx} = n s_{n-1} - y^n \{\phi(x)\}^n F'(x). \quad (47)$$

If in this we make  $n = 1$ , we get

$$s_0 = y \phi(x) F'(x) + \frac{ds_1}{dx};$$

but

$$s_0 = F(z) - F(x);$$

$$\therefore F(z) = F(x) + y \phi(x) F'(x) + \frac{ds_1}{dx}. \quad (48)$$

In like manner, making  $n = 2$ , we have

$$2s_1 = y^2 \{\phi(x)\}^2 F'(x) + \frac{ds_2}{dx};$$

$$\therefore \frac{ds_1}{dx} = \frac{y^2}{1 \cdot 2} \frac{d}{dx} \left[ \{\phi(x)\}^2 F'(x) \right] + \frac{1}{1 \cdot 2} \frac{d^2 s_2}{dx^2}.$$

Substituting in (48) it becomes

$$F(z) = F(x) + \frac{y}{1} \phi(x) F'(x) + \frac{y^2}{1 \cdot 2} \frac{d}{dx} \left[ \{\phi(x)\}^2 F'(x) \right] + \frac{1}{1 \cdot 2} \frac{d^2 s_2}{dx^2}.$$

Again,

$$s_2 = \frac{y^3}{3} \{\phi(x)\}^2 F'(x) + \frac{ds_3}{dx};$$

$$\begin{aligned} \therefore \frac{1}{1 \cdot 2} \frac{d^2 s_2}{dx^2} &= \frac{y^3}{1 \cdot 2 \cdot 3} \frac{d^2}{dx^2} \left[ \{\phi(x)\}^3 F'(x) \right] + \frac{1}{1 \cdot 2 \cdot 3} \frac{d^3 s_3}{dx^3} \\ &\quad \cdot \quad \cdot \quad \cdot \quad \cdot \quad \cdot \\ n s_{n-1} &= y^n \{\phi(x)\}^n F'(x) + \frac{d s_n}{dx}, \\ \frac{1}{1 \cdot 2 \dots n-1} \frac{d^{n-1} s_{n-1}}{dx^{n-1}} &= \frac{1}{1 \cdot 2 \dots n} \frac{d^{n-1}}{dx^{n-1}} \left[ \{\phi(x)\}^n F'(x) \right] \\ &\quad + \frac{1}{1 \cdot 2 \dots n} \frac{d^n s_n}{dx^n}. \end{aligned}$$

Hence we get finally

$$\begin{aligned} F(z) &= F(x) + \frac{y}{1} \phi(x) F'(x) + \frac{y^2}{1 \cdot 2} \frac{d}{dx} \left[ \{\phi(x)\}^2 F'(x) \right] + \text{&c.} \\ &\quad + \frac{1}{1 \cdot 2 \dots n} \left( \frac{d}{dx} \right)^n \int_x^z [y \phi(u) + x - u]^n F'(u) du. \quad (49) \end{aligned}$$

Consequently the remainder in Lagrange's series is always represented by a definite integral.

We next proceed to consider a general class of Definite Integrals first introduced into analysis by Euler.

**120. Gamma Functions.**—It may be observed that there is no branch of analysis which has occupied the attention of mathematicians more than that which treats of Definite Integrals, both single and multiple; nor in which the results arrived at are of greater elegance and interest. It would be manifestly impossible in the limits of an elementary treatise to give more than a sketch of the results arrived at. At the same time the Gamma or Eulerian Integrals hold so fundamental a place, that no treatise, however elementary, would be complete without giving at least an outline of their properties. With such an outline we propose to conclude this Chapter.

The definitions of the Eulerian Integrals, both First and Second, have been given already in Art. 95.

The First Eulerian Integral, viz.,

$$\int_0^1 x^{m-1} (1-x)^{n-1} dx,$$

is evidently a function of its two parameters,  $m$  and  $n$ ; it is usually represented by the notation  $B(m, n)$ .

Thus, we have by definition

$$\int_0^1 x^{m-1} (1-x)^{n-1} dx = B(m, n). \quad (50)$$

$$\int_0^\infty e^{-x} x^{p-1} dx = \Gamma(p).$$

The constants  $m, n$ , are supposed *positive* in all cases.

It is evident that the result in equation (14), Art. 95, still holds when  $p$  is of fractional form.

Hence, we have in all cases

$$\Gamma(p+1) = p\Gamma(p). \quad (51)$$

This may be regarded as the fundamental property of Gamma Functions, and by aid of it the calculations of all such functions can be reduced to those for which the parameter  $p$  is comprised between any two consecutive integers. For this purpose the values of  $\Gamma(p)$ , or rather of  $\log \Gamma(p)$ , have been tabulated by Legendre\* to 12 decimal places, for all values of  $p$  (between 1 and 2) to 3 decimal places. The student will find Tables to 6 decimal places at the end of this chapter. By aid of such Tables we can readily calculate the approximate values of all definite integrals which are reducible to Gamma Functions.

It may be remarked that we have

$$\Gamma(1) = 1, \quad \Gamma(0) = \infty, \quad \Gamma(-p) = \infty,$$

$p$  being any integer. For negative values of  $p$  which are not integer the function has a finite value.

Again, if we substitute  $zx$  instead of  $x$ , where  $z$  is a constant with respect to  $x$ , we obviously have

$$\int_0^\infty e^{-zx} x^{m-1} dx = \frac{\Gamma(m)}{z^m}. \quad (52)$$

\* See *Traité des Fonctions Elliptiques*, Tome 2, Int. Euler, chap. 16.

With respect to the First Eulerian Integral, we have already seen (Art. 92) that

$$\int_0^1 x^{m-1} (1-x)^{n-1} dx = \int_0^1 x^{n-1} (1-x)^{m-1} dx;$$

$$\therefore B(m, n) = B(n, m).$$

Hence, the interchange of the constants  $m$  and  $n$  does not alter the value of the integral.

Again, if we substitute  $\frac{y}{1+y}$  for  $x$ , we get

$$\int_0^1 x^{m-1} (1-x)^{n-1} dx = \int_0^{\infty} \frac{y^{m-1} dy}{(1+y)^{m+n}}.$$

$$\text{Hence } \int_0^{\infty} \frac{y^{m-1} dy}{(1+y)^{m+n}} = B(m, n). \quad (53)$$

We now proceed to express  $B(m, n)$  in terms of Gamma Functions.

### 121. To prove that

$$B(m, n) = \frac{\Gamma(m) \Gamma(n)}{\Gamma(m+n)}.$$

From equation (52) we have

$$\Gamma(m) = \int_0^{\infty} e^{-zx} z^m x^{m-1} dx.$$

Hence

$$\Gamma(m) e^{-z} z^{n-1} = \int_0^{\infty} e^{-z(1+x)} z^{m+n-1} x^{m-1} dx;$$

$$\therefore \Gamma(m) \int_0^{\infty} e^{-z} z^{n-1} dz = \int_0^{\infty} \left[ \int_0^{\infty} e^{-z(1+x)} z^{m+n-1} dx \right] dz. \quad [11]$$

But, if  $z(1+x) = y$ , we get

$$\int_0^\infty e^{-z(1+x)} z^{m+n-1} dz = \frac{1}{(1+x)^{m+n}} \int_0^\infty e^{-y} y^{m+n-1} dy = \frac{\Gamma(m+n)}{(1+x)^{m+n}};$$

$$\therefore \Gamma(m) \Gamma(n) = \Gamma(m+n) \int_0^\infty \frac{x^{m-1} dx}{(1+x)^{m+n}}.$$

Accordingly, by (53), we have

$$B(m, n) = \frac{\Gamma(m) \Gamma(n)}{\Gamma(m+n)}. \quad (54)$$

Again, if  $m = 1 - n$ , we get, by (24),

$$\Gamma(n) \Gamma(1-n) = \int_0^\infty \frac{x^{n-1} dx}{1+x} = \frac{\pi}{\sin n\pi}. \quad (55)$$

If in this  $n = \frac{1}{2}$ , we get

$$\Gamma\left(\frac{1}{2}\right) = \sqrt{\pi}.$$

This agrees with (36), for if we make  $x^2 = z$ , we get

$$\int_0^\infty e^{-x^2} dx = \frac{1}{2} \int_0^\infty e^{-z} z^{-\frac{1}{2}} dz = \frac{\Gamma\left(\frac{1}{2}\right)}{2}. \quad (56)$$

Again, if we suppose in the double integral

$$\iint x^{m-1} y^{n-1} dx dy$$

$x$  and  $y$  extended to all positive values, subject to the condition that  $x + y$  is not greater than unity; then, integrating with respect to  $y$ , between the limits 0 and  $1-x$ , the integral becomes

$$\frac{1}{n} \int_0^1 x^{m-1} (1-x)^n dx = \frac{1}{n} \frac{\Gamma(m) \Gamma(n+1)}{\Gamma(m+n+1)}, \text{ by (54);}$$

$$\therefore \iint x^{m-1} y^{n-1} dx dy = \frac{\Gamma(m) \Gamma(n)}{\Gamma(m+n+1)}; \quad (57)$$

in which  $x$  and  $y$  are always positive, and subject to the condition  $x + y < 1$ .

122. By aid of the relation in (54) a number of definite integrals are reducible to Gamma Functions.

For instance, we have

$$\int_0^{\infty} \frac{y^{m-1} dy}{(1+y)^{m+n}} = \int_0^1 \frac{y^{m-1} dy}{(1+y)^{m+n}} + \int_1^{\infty} \frac{y^{m-1} dy}{(1+y)^{m+n}}.$$

Now, substituting  $\frac{1}{x}$  for  $y$  in the last integral, we get

$$\int_1^{\infty} \frac{y^{m-1} dy}{(1+y)^{m+n}} = \int_0^1 \frac{x^{n-1} dx}{(1+x)^{m+n}}.$$

Hence

$$\int_0^1 \frac{x^{m-1} + x^{n-1}}{(1+x)^{m+n}} dx = \frac{\Gamma(m) \Gamma(n)}{\Gamma(m+n)}. \quad (58)$$

Next, if we make  $x = \frac{ay}{b}$ , we get

$$\begin{aligned} \int_0^{\infty} \frac{x^{m-1} dx}{(1+x)^{m+n}} &= a^m b^n \int_0^{\infty} \frac{y^{m-1} dy}{(ay+b)^{m+n}}; \\ \therefore \int_0^{\infty} \frac{y^{m-1} dy}{(ay+b)^{m+n}} &= \frac{\Gamma(m) \Gamma(n)}{a^m b^n \Gamma(m+n)}. \end{aligned} \quad (59)$$

Again,\* let  $x = \sin^2 \theta$ , and we get

$$\begin{aligned} \int_0^1 x^{m-1} (1-x)^{n-1} dx &= 2 \int_0^{\frac{\pi}{2}} \sin^{2m-1} \theta \cos^{2n-1} \theta d\theta; \\ \therefore \int_0^{\frac{\pi}{2}} \sin^{2m-1} \theta \cos^{2n-1} \theta d\theta &= \frac{\Gamma(m) \Gamma(n)}{2 \Gamma(m+n)}. \end{aligned} \quad (60)$$

This result may also be written as follows:

$$\int_0^{\frac{\pi}{2}} \sin^{p-1} \theta \cos^{q-1} \theta d\theta = \frac{\Gamma\left(\frac{p}{2}\right) \Gamma\left(\frac{q}{2}\right)}{2 \Gamma\left(\frac{p+q}{2}\right)}. \quad (61)$$

\* These results may be regarded as generalizations of the formulae given in Arts. 93, 94, to which the student can readily see that they are reducible when the indices are integers.

If we make  $q = 1$ , we get

$$\int_0^{\frac{\pi}{2}} \sin^{p-1} \theta d\theta = \frac{\sqrt{\pi}}{2} \frac{\Gamma\left(\frac{p}{2}\right)}{\Gamma\left(\frac{p+1}{2}\right)}. \quad (62)$$

Again, if  $p = q$  in (61) it becomes

$$\frac{\left\{\Gamma\left(\frac{p}{2}\right)\right\}^2}{2 \Gamma(p)} = \int_0^{\frac{\pi}{2}} \sin^{p-1} \theta \cos^{p-1} \theta d\theta = \frac{1}{2^{p-1}} \int_0^{\frac{\pi}{2}} \sin^{p-1} 2\theta d\theta.$$

Let  $2\theta = z$ , and we have

$$\begin{aligned} \int_0^{\frac{\pi}{2}} \sin^{p-1} 2\theta d\theta &= \frac{1}{2} \int_0^{\pi} \sin^{p-1} z dz = \int_0^{\frac{\pi}{2}} \sin^{p-1} z dz \\ &= \frac{\sqrt{\pi}}{2} \frac{\Gamma\left(\frac{p}{2}\right)}{\Gamma\left(\frac{p+1}{2}\right)}. \end{aligned}$$

Hence  $\Gamma\left(\frac{p}{2}\right) \Gamma\left(\frac{p+1}{2}\right) = \frac{\sqrt{\pi}}{2^{p-1}} \Gamma(p).$

If we substitute  $2m$  for  $p$ , this becomes

$$\Gamma(m) \Gamma\left(m + \frac{1}{2}\right) = \frac{\sqrt{\pi}}{2^{2m-1}} \Gamma(2m). \quad (63)$$

Again, make  $y = \tan^2 \theta$  in (59), and we get

$$\int_0^{\frac{\pi}{2}} \frac{\sin^{2m-1} \theta \cos^{2n-1} \theta d\theta}{(a \sin^2 \theta + b \cos^2 \theta)^{m+n}} = \frac{\Gamma(m) \Gamma(n)}{2a^m b^n \Gamma(m+n)}. \quad (64)$$

### 123. To find the Value\* of

$$\Gamma\left(\frac{1}{n}\right) \Gamma\left(\frac{2}{n}\right) \Gamma\left(\frac{3}{n}\right) \dots \Gamma\left(\frac{n-1}{n}\right),$$

$n$  being any integer.

\* This important theorem is due to Euler, by whom, as already noticed, the Gamma Functions were first investigated.

Multiply the expression by itself, reversing the order of the factors, and we get its square under the form

$$\Gamma\left(\frac{1}{n}\right) \Gamma\left(1 - \frac{1}{n}\right) \Gamma\left(\frac{2}{n}\right) \Gamma\left(1 - \frac{2}{n}\right) \dots \Gamma\left(\frac{n-1}{n}\right) \Gamma\left(1 - \frac{n-1}{n}\right),$$

that is, by (55),

$$\frac{\pi^{n-1}}{\sin \frac{\pi}{n} \sin \frac{2\pi}{n} \sin \frac{3\pi}{n} \dots \sin \frac{(n-1)\pi}{n}}.$$

To calculate this expression, we have by the theory of equations

$$\frac{1 - x^{2n}}{1 - x^2}$$

$$= \left(1 - 2x \cos \frac{\pi}{n} + x^2\right) \left(1 - 2x \cos \frac{2\pi}{n} + x^2\right) \dots \left(1 - 2x \cos \frac{(n-1)\pi}{n} + x^2\right)$$

Making successively in this,  $x = 1$ , and  $x = -1$ , and replacing the first member by its true value  $n$ , we get

$$n = \left(2 \sin \frac{\pi}{2n}\right)^2 \left(2 \sin \frac{2\pi}{2n}\right)^2 \dots \left(2 \sin \frac{(n-1)\pi}{2n}\right)^2,$$

$$n = \left(2 \cos \frac{\pi}{2n}\right)^2 \left(2 \cos \frac{2\pi}{2n}\right)^2 \dots \left(2 \cos \frac{(n-1)\pi}{2n}\right)^2,$$

whence, multiplying and extracting the square root,

$$n = 2^{n-1} \sin \frac{\pi}{n} \sin \frac{2\pi}{n} \dots \sin \frac{(n-1)\pi}{n}.$$

Hence, it follows that

$$\Gamma\left(\frac{1}{n}\right) \Gamma\left(\frac{2}{n}\right) \dots \Gamma\left(\frac{n-1}{n}\right) = \frac{(2\pi)^{\frac{n-1}{2}}}{n^{\frac{1}{2}}}. \quad (65)$$

## 124. To find the values of

$$\int_0^\infty e^{-ax} \cos bx x^{m-1} dx, \text{ and } \int_0^\infty e^{-ax} \sin bx x^{m-1} dx.$$

If in (52)  $a - b\sqrt{-1}$  be substituted\* for  $z$  the equation becomes

$$\int_0^\infty e^{-ax} e^{bx\sqrt{-1}} x^{m-1} dx = \frac{\Gamma(m)}{(a - b\sqrt{-1})^m} = \frac{\Gamma(m)(a + b\sqrt{-1})^m}{(a^2 + b^2)^m}.$$

Let  $a = (a^2 + b^2)^{\frac{1}{2}} \cos \theta$ , then  $b = (a^2 + b^2)^{\frac{1}{2}} \sin \theta$ , and the preceding result becomes

$$\begin{aligned} & \int_0^\infty e^{-ax} (\cos bx + \sqrt{-1} \sin bx) x^{m-1} dx \\ &= \frac{\Gamma(m)}{(a^2 + b^2)^{\frac{m}{2}}} (\cos \theta + \sqrt{-1} \sin \theta)^m \\ &= \frac{\Gamma(m)}{(a^2 + b^2)^{\frac{m}{2}}} (\cos m\theta + \sqrt{-1} \sin m\theta). \end{aligned}$$

Hence, equating real and imaginary parts, we have

$$\left. \begin{aligned} \int_0^\infty e^{-ax} \cos bx x^{m-1} dx &= \frac{\Gamma(m)}{(a^2 + b^2)^{\frac{m}{2}}} \cos m\theta \\ \int_0^\infty e^{-ax} \sin bx x^{m-1} dx &= \frac{\Gamma(m)}{(a^2 + b^2)^{\frac{m}{2}}} \sin m\theta \end{aligned} \right\}, \quad (66)$$

in which  $\theta = \tan^{-1}\left(\frac{b}{a}\right)$ .

If we make  $a = 0$ ,  $\theta$  becomes  $\frac{\pi}{2}$ , and these formulæ become

\* For a rigorous proof of the validity of this transformation the student is referred to Serrett's *Calc. Int.*, p. 194.

$$\left. \begin{aligned} \int_0^\infty \cos bx x^{m-1} dx &= \frac{\Gamma(m)}{b^m} \cos \frac{m\pi}{2}, \\ \int_0^\infty \sin bx x^{m-1} dx &= \frac{\Gamma(m)}{b^m} \sin \frac{m\pi}{2} \end{aligned} \right\}. \quad (67)$$

It may be observed that these latter integrals can be arrived at in another manner, as follows:—

From (52) we have

$$\Gamma(n) \frac{\cos bz}{z^n} = \int_0^\infty e^{-zx} x^{n-1} \cos bz dx;$$

$$\therefore \Gamma(n) \int_0^\infty \frac{\cos bz dz}{z^n} = \int_0^\infty \int_0^\infty e^{-zx} \cos bz x^{n-1} dx dz.$$

But, by (32), we have

$$\int_0^\infty e^{-zx} \cos bz dz = \frac{x}{b^2 + x^2};$$

$$\therefore \int_0^\infty \frac{\cos bz dz}{z^n} = \frac{1}{\Gamma(n)} \int_0^\infty \frac{x^n dx}{b^2 + x^2}$$

$$= \frac{b^{n-1}}{\Gamma(n)} \frac{\pi}{2 \cos \frac{n\pi}{2}}, \text{ by (27),}$$

in which  $n$  must be positive and  $< 1$ .

In like manner we find

$$\int_0^\infty \frac{\sin bz dz}{z^n} = \frac{b^{n-1}}{\Gamma(n)} \frac{\pi}{2 \sin \frac{n\pi}{2}}.$$

The results in (67) follow from these by aid of the relation contained in equation (55).

## EXAMPLES.

1.  $\int_0^1 x^m (1 - x^n)^p dx.$

*Ans.*  $\frac{\Gamma(p+1) \Gamma\left(\frac{m+1}{n}\right)}{n \Gamma\left(p+1 + \frac{m+1}{n}\right)}.$

2.  $\int_0^1 \frac{x^{m-1} (1 - x)^{n-1} dx}{(a+x)^{m+n}}.$

"  $\frac{\Gamma(m) \Gamma(n)}{a^n (1+a)^{m+n} \Gamma(m+n)}.$

3. Prove that

$\int_0^1 \frac{x^2 dx}{(1-x^4)^{\frac{1}{4}}} \times \int_0^1 \frac{dx}{(1+x^4)^{\frac{1}{4}}} = \frac{\pi}{4\sqrt{2}}.$

4.  $\int_0^{\infty} \cos(bz^{\frac{1}{n}}) dz.$

"  $\frac{\Gamma(n+1) \cos\left(n\frac{\pi}{2}\right)}{b^n}.$

5.  $\int_0^1 \frac{dx}{\sqrt[4]{1-x^n}}.$

"  $\frac{\sqrt{-\pi}}{n} \frac{\Gamma\left(\frac{1}{n}\right)}{\Gamma\left(\frac{1}{2} + \frac{1}{n}\right)}.$

6.  $\int_0^{\infty} \frac{\sin bx}{x} dx.$

"  $\frac{\pi}{2}.$

**125. Numerical Calculation of Gamma Functions.**—The following Table gives the values of  $\log \Gamma(p)$ , to six decimal places, for all values of  $p$  between 1 and 2 (taken to three decimal places).

It may be observed that we have  $\Gamma(1) = \Gamma(2) = 1$ , and that for all values of  $p$  between 1 and 2,  $\Gamma(p)$  is positive and less than unity; and hence the values of  $\log \Gamma(p)$  are negative for all such values. Consequently, as in ordinary trigonometrical logarithmic Tables, the Tabular logarithm is obtained by adding 10 to the natural logarithm. The method of calculating these Tables is too complicated for insertion in an elementary Treatise.

Log  $\Gamma(p)$ .

<i>p.</i>	<b>0</b>	<b>1</b>	<b>2</b>	<b>3</b>	<b>4</b>	<b>5</b>	<b>6</b>	<b>7</b>	<b>8</b>	<b>9</b>
1.00										
1.01	9.997529	9750	9500	9251	9003	8755	8509	8263	8017	7773
1.02	5128	7285	7043	6801	6560	6320	6080	5841	5602	5365
1.03	2796	2567	2338	2110	1883	1656	1430	1205	981	3026
1.04	0533	0311	0089	9686	9647	9427	9208	8989	8772	8554
1.05	9.988338	8122	7907	7692	7478	7265	7052	6841	6629	6419
1.06	6209	6000	5791	5583	5378	5169	4963	4758	4553	4349
1.07	4145	3943	3741	3539	3338	3138	2939	2740	2541	2344
1.08	2147	1951	1755	1560	1365	1172	9978	9786	9594	9403
1.09	0212	0022	9833	9644	9456	9269	9082	8900	8710	8525
1.10	9.978341	8157	7974	7791	7610	7428	7248	7068	6888	6709
1.11	6531	6354	6177	6000	5825	5650	5475	5301	5128	4955
1.12	4783	4612	4441	4271	4101	3932	3764	3596	3429	3262
1.13	3096	2931	2766	2602	2438	2275	2113	1951	1790	1629
1.14	1469	1309	1150	0992	0835	0677	0521	0365	0210	0055
1.15	9.969901	9747	9594	9442	9290	9139	8988	8838	8688	8539
1.16	8390	8243	8096	7949	7803	7658	7513	7369	7225	7082
1.17	6939	6797	6655	6514	6374	6234	6095	5957	5818	5681
1.18	5544	5408	5272	5137	5002	4868	4734	4601	4469	4337
1.19	4205	4075	3944	3815	3686	3557	3429	3302	3175	3048
1.20	2922	2797	2672	2548	2425	2302	2179	2057	1936	1815
1.21	1695	1575	1456	1337	1219	1101	9984	867	0751	0636
1.22	0521	0407	0293	0180	0067	9955	9843	9732	9621	9511
1.23	9.959401	9292	9184	9076	8968	8861	8755	8649	8544	8439
1.24	8335	8231	8128	8025	7923	7821	7720	7620	7520	7420
1.25	7321	7223	7125	7027	6930	6834	6738	6642	6547	6453
1.26	6359	6267	6173	6081	5989	5898	5807	5716	5627	5537
1.27	5449	5360	5273	5185	5099	5013	4927	4842	4757	4673
1.28	4589	4506	4423	4341	4259	4178	4097	4017	3938	3858
1.29	3780	3702	3624	3547	3470	3394	3318	3243	3168	3094
1.30	3020	2947	2874	2802	2730	2659	2588	2518	2448	2379
1.31	2310	2242	2174	2106	2040	1973	1907	1842	1777	1712
1.32	1648	1585	1522	1459	1397	1336	1275	1214	1154	1094
1.33	1035	0977	0918	0861	0803	0747	0690	0634	0579	0524
1.34	0470	0416	0362	0309	0257	0205	0153	0102	0051	0001
1.35	9.949951	9902	9853	9805	9757	9710	9663	9617	9571	9525
1.36	9480	9435	9391	9348	9304	9262	9219	9178	9136	9095
1.37	9054	9015	8975	8936	8898	8859	8822	8785	8748	8711
1.38	8676	8640	8605	8571	8537	8503	8470	8437	8405	8373
1.39	8342	8311	8280	8250	8221	8192	8163	8135	8107	8080
1.40	8053	8026	8000	7975	7950	7925	7901	7877	7854	7831
1.41	7808	7786	7765	7744	7723	7703	7683	7664	7645	7626
1.42	7608	7590	7573	7556	7540	7524	7509	7494	7479	7465
1.43	7451	7438	7425	7413	7401	7389	7378	7368	7357	7348
1.44	7338	7329	7321	7312	7305	7298	7291	7284	7278	7273
1.45	7262	7263	7259	7255	7251	7248	7246	7244	7242	7241
1.46	7240	7239	7239	7234	7240	7242	7243	7245	7248	7251
1.47	7254	7258	7262	7266	7271	7277	7282	7289	7295	7302
1.48	7310	7317	7326	7334	7343	7353	7363	7373	7384	7395
1.49	7407	7419	7431	7444	7457	7471	7485	7499	7514	7529

Log  $\Gamma(p)$ .

$p$	0	1	2	3	4	5	6	7	8	9
1.50	9.947545	7561	7577	7594	7612	7629	7647	7666	7685	7704
1.51	7724	7744	7764	7785	7806	7828	7850	7873	7896	7919
1.52	7943	7967	7991	8016	8041	8067	8093	8120	8146	8174
1.53	8201	8229	8258	8287	8316	8346	8376	8406	8437	8468
1.54	8500	8532	8564	8597	8630	8664	8698	8732	8767	8802
1.55	8837	8873	8910	8946	8983	9021	9059	9097	9135	9174
1.56	9214	9254	9294	9334	9375	9417	9458	9500	9543	9586
1.57	9629	9672	9716	9761	9806	9851	9896	9942	9989	0035
1.58	9.950082	0130	0177	0225	0274	0323	0372	0422	0472	0522
1.59	0573	0624	0676	0728	0780	0833	0886	0939	0993	1047
1.60	1102	1157	1212	1268	1324	1380	1437	1494	1552	1610
1.61	1668	1727	1786	1845	1905	1965	2025	2086	2147	2209
1.62	2271	2333	2396	2459	2522	2586	2650	2715	2780	2845
1.63	2911	2977	3043	3110	3177	3244	3312	3380	3449	3517
1.64	3587	3656	3726	3797	3867	3938	4010	4081	4154	4226
1.65	4299	4372	4446	4519	4594	4668	4743	4819	4894	4970
1.66	5047	5124	5201	5278	5356	5434	5513	5592	5671	5740
1.67	5830	5911	5991	6072	6154	6235	6317	6400	6482	6566
1.68	6649	6733	6817	6901	6986	7072	7157	7243	7322	7416
1.69	7503	7590	7678	7766	7854	7943	8032	8122	8211	8301
1.70	8391	8482	8573	8664	8756	8848	8941	9034	9127	9220
1.71	9314	9409	9502	9598	9693	9788	9884	9980	0077	0174
1.72	9.960271	0369	0467	0565	0664	0763	0862	0961	1061	1162
1.73	1262	1363	1464	1566	1668	1770	1873	1976	2079	2183
1.74	2287	2391	2496	2601	2706	2812	2918	3024	3131	3238
1.75	3345	3453	3561	3669	3778	3887	3996	4105	4215	4326
1.76	4436	4547	4659	4770	4882	4994	5107	5220	5333	5447
1.77	5561	5675	5789	5904	6019	6135	6251	6367	6484	6600
1.78	6718	6835	6953	7071	7189	7308	7427	7547	7666	7787
1.79	7907	8023	8149	8270	8392	8514	8636	8759	8882	9005
1.80	9129	9253	9377	9501	9626	9751	9877	0008	0129	0255
1.81	9.970383	0509	0637	0765	0893	1021	1150	1279	1408	1538
1.82	1668	1798	1929	2060	2191	2322	2454	2586	2719	2852
1.83	2985	3118	3252	3386	3520	3655	3790	3925	4061	4197
1.84	4333	4470	4606	4744	4881	5019	5157	5295	5434	5573
1.85	5712	5852	5992	6132	6273	6414	6555	6697	6838	6980
1.86	7123	7266	7408	7552	7696	7840	7984	8128	8273	8419
1.87	8564	8710	8856	9002	9149	9296	9443	9591	9739	9887
1.88	9.980036	9184	0333	0483	0633	0783	0933	1084	1234	1386
1.89	1537	1689	1841	1994	2147	2299	2453	2607	2761	2915
1.90	3069	3224	3379	3535	3690	3846	4003	4159	4316	4474
1.91	4631	4789	4947	5105	5264	5423	5582	5742	5902	6062
1.92	6223	6383	6544	6706	6867	7029	7192	7354	7517	7680
1.93	7844	8007	8171	8336	8500	8665	8830	8996	9161	9327
1.94	9494	9660	9827	9995	0162	0330	0498	0666	0835	1004
1.95	9.991173	1343	1512	1683	1853	2024	2195	2366	2537	2709
1.96	2881	3054	3227	3399	3573	3746	3920	4094	4269	4443
1.97	4618	4794	4969	5145	5321	5498	5674	5851	6029	6206
1.98	6384	6562	6740	6919	7098	7277	7457	7637	7817	7997
1.99	8178	8359	8540	8722	8903	9085	9268	9450	9633	9816

## EXAMPLES.

1.  $\int_0^a \frac{dx}{\sqrt{a-x}}.$  *Ans.*  $2\sqrt{a}.$

2. If  $f(x) = f(a+x)$  for all values of  $x$ , prove that

$$\int_0^{na} f(x) dx = n \int_0^a f(x) dx,$$

where  $n$  is an integer.

3.  $\int_0^a \frac{dx}{\sqrt{ax-x^2}}.$  *Ans.*  $\pi.$

4.  $\int_1^2 \frac{dx}{x\sqrt{x^2-1}}.$  *Ans.*  $\frac{\pi}{3}.$

5.  $\int_0^1 \sin^{-1} x dx.$  *Ans.*  $\frac{\pi}{2} - 1.$

6.  $\int_0^1 \frac{dx}{(1+x)\sqrt{1+2x-x^2}}.$  *Ans.*  $\frac{\pi}{4\sqrt{2}}.$

7.  $\int_{-\infty}^{\infty} \frac{dx}{a+2bx+cx^2},$   $ac-b^2$  being positive. *Ans.*  $\frac{\pi}{\sqrt{ac-b^2}}.$

8. Prove that

$$\int_0^{\infty} \frac{dx}{a+2bx^2+cx^4} = \frac{\pi}{2\sqrt{ah}}, \text{ where } h = 2(\sqrt{ac} + b).$$

9.  $\int_0^{\pi} \frac{dx}{1+\cos \theta \cos x}.$  *Ans.*  $\frac{\pi}{\sin \theta}.$

10.  $\int_0^{\frac{\pi}{2}} \frac{dx}{1+\cos \theta \cos x}.$  *Ans.*  $\frac{\theta}{\sin \theta}.$

11.  $\int_0^{\frac{\pi}{2}} \frac{dx}{a^2 \sin^2 x + b^2 \cos^2 x}.$  *Ans.*  $\frac{\pi}{2ab}.$

12.  $\int_0^{\frac{\pi}{2}} \frac{dx}{(a^2 \sin^2 x + b^2 \cos^2 x)^2}.$  *Ans.*  $\frac{\pi(a^2 + b^2)}{4a^3 b^3}.$

13.  $\int_0^a \sqrt{a^2 - x^2} \cos^{-1} \frac{x}{a} dx.$  *Ans.*  $\frac{\pi a^2}{16} + \frac{a^3}{4}.$

14.  $\int_{-1}^{+1} \frac{dx}{(a - bx) \sqrt{1 - x^2}}, a > b.$  *Ans.*  $\frac{\pi}{\sqrt{a^2 - b^2}}.$

15.  $\int_a^\beta \frac{dx}{\sqrt{(x - a)(\beta - x)}}.$  *Ans.*  $\pi.$

16.  $\int_{a-\sqrt{a^2-b^2}}^{a+\sqrt{a^2-b^2}} \frac{(y^2 + b^2) y dy}{\sqrt{4a^2 y^2 - (y^2 + b^2)^2}}.$  *Ans.*  $\pi a^2.$

17. Show that  $\int_0^\infty \frac{\sin ax \cos bx}{x} dx = \frac{\pi}{2}$ , or 0, according as  $a >$  or  $< b$ ; and that when  $a = b$  the value of the integral is  $\frac{\pi}{4}$ .

18.  $\int_{-1}^1 \frac{dx}{\sqrt{(1 - 2ax + a^2)(1 - 2bx + b^2)}}, ab < 1.$  *Ans.*  $\frac{1}{\sqrt{ab}} \log \left( \frac{1 + \sqrt{ab}}{1 - \sqrt{ab}} \right).$

19.  $\int_0^{\frac{\pi}{4}} \tan^5 x dx.$  *Ans.*  $\frac{1}{2} \left( \log 2 - \frac{1}{2} \right).$

20.  $\int_0^{\frac{3\pi}{4}} \frac{\sin x dx}{1 + \cos^2 x}.$  *Ans.*  $\frac{\pi}{4} + \tan^{-1} \frac{1}{\sqrt{2}}.$

21. If every infinitesimal element of the side  $c$  of any triangle be divided by its distance from the opposite angle  $C$ , and the sum taken, show that its value is

$$\log \left( \cot \frac{A}{2} \cot \frac{B}{2} \right).$$

22. Being given the base of a triangle; if the sum of every element of the base multiplied by the square of the distance from the vertex be constant, show that the locus of the vertex is a circle.

23.  $\int_0^{\frac{\pi}{2}} \frac{\cos^2 \theta \sin \theta d\theta}{1 + e^2 \cos^2 \theta}.$  *Ans.*  $\frac{1}{e^2} - \frac{\tan^{-1} e}{e^2}.$

24.  $\int_0^{\frac{\pi}{2}} \frac{\cos^2 \theta \sin \theta d\theta}{\sqrt{1 + e^2 \cos^2 \theta}}.$  *Ans.*  $\frac{\sqrt{1 + e^2}}{2e^2} - \frac{\log (e + \sqrt{1 + e^2})}{2e^2}.$

25. Deduce the expansions for  $\sin x$  and  $\cos x$  from Bernoulli's series.

26. Show that the integral

$$\int_0^1 x^n (\log x)^m dx$$

can be immediately evaluated by the method of Art. 111, when  $m$  is an integer.

$$27. \int_0^\infty \frac{\tan^{-1}(ax) dx}{x(1+x^2)} \quad Ans. \frac{\pi}{2} \log(1+a).$$

28. Find the value of

$$\int_0^\pi \log(1 - 2a \cos x + a^2) dx,$$

distinguishing between the cases where  $a$  is  $>$  or  $<$  1.

$$Ans. \begin{cases} a < 1, \text{ its value is } 0. \\ a > 1, \text{ its value is } 2\pi \log a. \end{cases}$$

29. If  $f(x)$  can be expanded in a series of the form

$$a_0 + a_1 \cos x + a_2 \cos 2x + \dots + a_n \cos nx + \dots,$$

show that any coefficient after  $a_0$  can be exhibited in the form of a definite integral.

$$Ans. a_n = \frac{2}{\pi} \int_0^\pi f(x) \cos nx dx.$$

30. Find the analogous theorem when  $f(x)$  can be expanded in a series of sines of multiples of  $x$ ; and apply the method to prove the relation

$$x = 2 \left( \sin x - \frac{\sin 2x}{2} + \frac{\sin 3x}{3} - \text{&c.} \right),$$

when  $x$  lies between  $\pm \pi$ .

31. Prove the relation

$$\int_0^{\frac{\pi}{2}} \frac{d\theta}{\sqrt{\sin \theta}} \times \int_0^{\frac{\pi}{2}} \sqrt{\sin \theta} d\theta = \pi.$$

32. Express the definite integral

$$\int_0^{\frac{\pi}{2}} \frac{d\theta}{\sqrt{1 - \kappa^2 \sin^2 \theta}}$$

in the form of a series,  $\kappa$  being  $< 1$ .

$$Ans. \frac{\pi}{2} \left( 1 + \left( \frac{1}{2} \right)^2 \kappa^4 + \left( \frac{1+3}{2+4} \right)^2 \kappa^8 + \left( \frac{1+3+5}{2+4+6} \right)^2 \kappa^{16} + \text{&c.} \right).$$

33. 
$$\int_0^{\frac{\pi}{2}} \frac{\log(1 + \cos a \cos x) dx}{\cos x}.$$
 Ans.  $\frac{1}{2} \left( \frac{\pi^2}{4} - a^2 \right).$

34. 
$$\int_0^{\infty} x e^{-ax} \cos bx dx, \text{ where } a > 0.$$
 "  $\frac{a^2 - b^2}{(a^2 + b^2)^2}.$

35. 
$$\int_0^{\infty} \frac{\tan^{-1} \alpha x \tan^{-1} \beta x}{x^2} dx.$$
 "  $\frac{\pi}{2} \log \left\{ \frac{(\alpha + \beta)^{\alpha + \beta}}{\alpha^\alpha \beta^\beta} \right\}.$

36. 
$$\int_0^{\frac{\pi}{2}} \log(\alpha^2 \cos^2 \theta + \beta^2 \sin^2 \theta) d\theta.$$
 "  $\pi \log \frac{\alpha + \beta}{2}.$

37. 
$$\int_0^{\frac{\pi}{2}} \log \left( \frac{a + b \sin \theta}{a - b \sin \theta} \right) \frac{d\theta}{\sin \theta}, \text{ where } a > b.$$
 "  $\pi \sin^{-1} \left( \frac{b}{a} \right).$

38. 
$$\int_0^1 \frac{dx}{(1 - x^3)^{\frac{1}{3}}}.$$
 "  $\frac{\pi}{3}.$

39. 
$$\int_0^1 \frac{dx}{(1 - x^n)^{\frac{1}{n}}}.$$
 "  $\frac{\pi}{n \sin \frac{\pi}{n}}.$

40. 
$$\int_0^{\pi} \frac{\cos rx dx}{1 - 2a \cos x + a^2}.$$
 "  $\frac{\pi a^r}{1 - a^2}.$

41. Find the sum of the series

$$\frac{n}{n^2 + 1^2} + \frac{n}{n^2 + 2^2} + \frac{n}{n^2 + 3^2} + \dots + \frac{n}{2n^2}.$$

when  $n$  is increased indefinitely.

This is evidently represented by the definite integral

$$\int_0^1 \frac{dx}{1 + x^2}, \text{ or } = \frac{\pi}{4}.$$

42. Find the limit of the sum

$$\frac{1}{\sqrt{n^2 - 1^2}} + \frac{1}{\sqrt{n^2 - 2^2}} + \frac{1}{\sqrt{n^2 - 3^2}} + \dots + \frac{1}{\sqrt{n^2 - (n-1)^2}},$$

when  $n = \infty$ ,

Ans.  $\frac{\pi}{2}.$

43. Prove that

$$\int_0^{\frac{\pi}{2}} \cos^m x \cos nx dx = \frac{m(m-1)}{m^2 - n^2} \int_0^{\frac{\pi}{2}} \cos^{m-2} x \cos nx dx;$$

and hence, deduce the values of the integrals

$$\int_0^{\frac{\pi}{2}} \cos^{2m} x \cos(2n+1)x dx, \text{ and } \int_0^{\frac{\pi}{2}} \cos^{2m+1} x \cos 2nx dx,$$

when  $m$  and  $n$  are integers.

44.  $\int_0^{\pi} \log(1 - 2a \cos \theta + a^2) \cos n\theta d\theta$ , when  $a^2 < 1$ . *Ans.*  $-\frac{\pi a^n}{n}$ .

45.  $\int_{-\infty}^{\infty} \cos \frac{\pi x^2}{2} dx$ . *Ans.* 1.

46.  $\int_0^1 \frac{\log(1+x)}{1+x^2} dx$ . *Ans.*  $\frac{\pi}{8} \log 2$ .

47. Prove the following equation :

$$\int_0^{\pi} \frac{d\theta}{(1 - 2a \cos \theta + a^2)^n} = \frac{1}{(1 - a^2)^{n-1}} \int_0^{\pi} (1 - 2a \cos \theta + a^2)^{n-1} d\theta.$$

48. Prove the more general equation

$$\int_0^{\pi} \frac{\sin^m \theta d\theta}{(1 - 2a \cos \theta + a^2)^n} = \frac{1}{(1 - a^2)^{2n-m-1}} \int_0^{\pi} \frac{\sin^m \theta d\theta}{(1 - 2a \cos \theta + a^2)^{1+m-n}},$$

in which  $m+1$  is positive.

## CHAPTER VII.

AREAS OF PLANE CURVES.

126. **Areas of Curves.**—The simplest method of regarding the area of a curve is to suppose it referred to rectangular axes of co-ordinates; then, the area included between the curve, the axis of  $x$ , and the two ordinates corresponding to the values  $x_0$  and  $x_1$  of  $x$ , is represented by the definite integral

$$\int_{x_0}^{x_1} y dx.$$

For, let the area in question be represented by the space  $ABVT$ , and suppose  $BV$  divided into  $n$  equal intervals, and the corresponding ordinates drawn, as in the accompanying figure.

Then the area of the portion  $PMNQ$  is less than the rectangle  $pMNQ$ , and greater than  $PMNq$ .

Hence the entire area  $ABVT$  is less than the sum of the rectangles represented by  $pMNQ$ , and greater than the sum of the rectangles  $PMNq$ ; but the difference between these latter sums is the sum of the rectangles  $PpQq$ , or (since the rectangles have equal bases) the rectangle under  $MN$  and the difference between  $TV$  and  $AB$ . Now, by supposing the number  $n$  increased indefinitely,  $MN$  can be made indefinitely small, and hence the rectangle  $MN$  ( $TV - AB$ ) also becomes infinitely small. Consequently the difference between the area  $ABVT$  and the sum of the rectangles  $PMNq$  becomes evanescent at the same time.

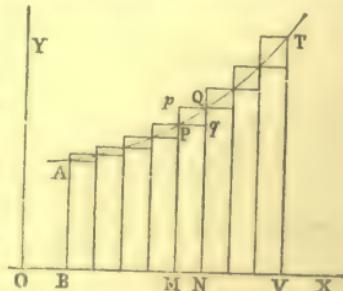


Fig. I.

If now the co-ordinates of  $P$  be denoted by  $x$  and  $y$ , and  $MN$  by  $\Delta x$ , it follows that the area  $ABVT$  is the limiting value\* of  $\Sigma(y \Delta x)$  when the increment  $\Delta x$  becomes infinitely small ; or area  $ABVT = \int_{x_0}^{x_1} y dx$ ; where  $x_1 = OV$ ,  $x_0 = OB$ .

It should be observed that this result requires that  $y$  continue finite, and of the same sign, between the limits of integration.

If  $y$  change its sign between the limits, i.e. if the curve cut the axis of  $x$ , the preceding definite integral represents the difference of the areas at opposite sides of the axis of  $x$ .

In such cases it is preferable to consider each area separately, by dividing the integral into two parts, separated by the value of  $x$  for which  $y$  vanishes.

The preceding mode of proof obviously applies also to the case where the co-ordinate axes are oblique ; in which case the area is represented by

$$\sin \omega \int_{x_0}^{x_1} y dx,$$

where  $\omega$  represents the angle between the axes.

In applying these formulæ the value of  $y$  is found in terms of  $x$  by means of the equation of the curve : thus, if  $y = f(x)$  be this equation, the area is represented by

$$\int f(x) dx,$$

taken between suitable limits.

Conversely, the value of any definite integral, such as

$$\int_a^b f(x) dx,$$

may be represented geometrically by the area of a definite portion of the curve represented by the equation

$$y = f(x).$$

\* This demonstration is substantially that given by Newton (see *Principia*, Lib. I., Sect. 1., Lemma 2) ; and is the geometrical representation of the result established in Art. 90.

The modification in the proof when the elements of  $BV$  are considered unequal, but each infinitely small, is easily seen. It may be remarked that the result here given is but a particular case of the general principle laid down in Arts. 38, 39, *Diff. Calc.*

On account of this property the process of integration was called, by Newton and the early writers on the Calculus, the *method of quadratures*.

Again, it is plain that the area between the curve, the axis of  $y$ , and two ordinates to that axis, is represented by

$$\int x \, dy,$$

taken between the proper limits: the co-ordinate axes being supposed rectangular.

We proceed to illustrate this method of determining areas by a few applications, commencing with the simplest examples.

127. **The Circle.**—Taking the equation of a circle in the form

$x^2 + y^2 = a^2$ , we get  $y = \sqrt{a^2 - x^2}$ ,

and the area is represented by

$$\int \sqrt{a^2 - x^2} dx,$$

taken between proper limits.

For instance, to find the area of the portion represented by  $APDE$  in the accompanying figure. Let  $x = a \cos \theta$ , then the area in question plainly is represented by

$$a^2 \int_0^a \sin^2 \theta \, d\theta = \frac{a^2}{2} (a - \sin a \cos a); \text{ where } a = \angle DCA.$$

This result is also evident from geometry; for the area  $DPAE$  is the difference between  $DPAC$  and  $DCE$ , or is

$$\frac{a^2 a}{2} - \frac{a^2 \sin a \cos a}{2}.$$

The area of the quadrant  $ACB$  is got by making  $a = \frac{\pi}{2}$ ;

and accordingly is  $\frac{\pi a^2}{4}$ : hence the entire area of the circle is  $\pi a^2$ .

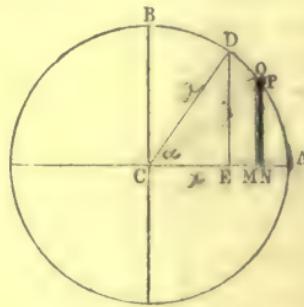


Fig. 2.

128. **The Ellipse.**—From the equation of the ellipse

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1, \text{ we get } y = \frac{b}{a} \sqrt{a^2 - x^2},$$

and the element of area is

$$\frac{b}{a} \sqrt{a^2 - x^2} dx;$$

but this is  $\frac{b}{a}$  times the area of the corresponding element of the circle whose radius is  $a$ : consequently the area of any portion of the ellipse is  $\frac{b}{a}$  times that of the corresponding part of the circle. This is also evident from geometry.

The area of the entire ellipse is  $\pi ab$ .

Again, if the equation of an ellipse be given in the form  $Ax^2 + By^2 = C$ , its area is evidently  $\frac{\pi C}{\sqrt{AB}}$ .

As an application of oblique axes, let it be proposed to find the area of the segment of an ellipse cut off by any chord  $DD'$ .

Draw the diameter  $AA'$ , conjugate to the chord, and  $BB'$  parallel to it. Then,  $C$  being the centre, let

$$CA' = a', CB' = b', ACB' = \omega,$$

Fig. 3.

and the equation of the ellipse is  $\frac{x^2}{a'^2} + \frac{y^2}{b'^2} = 1$ ; hence the area  $DA'D'$  is represented by

$$2 \frac{b'}{a'} \sin \omega \int_{CE}^{CA'} \sqrt{a'^2 - x^2} dx = a'b' \sin \omega (a - \sin a \cos a),$$

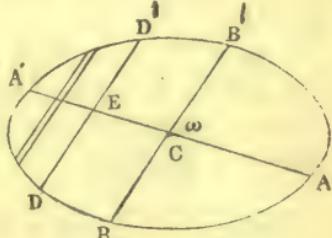
where

$$\cos a = \frac{CE}{CA'}$$

Again,  $a'b' \sin \omega = ab$ , by an elementary property of the ellipse,  $a$  and  $b$  being the semiaxes.

Hence the area of the segment in question is

$$ab(a - \sin a \cos a).$$



This result can also be deduced immediately from the circle by the method of orthogonal projection.

It may be observed that if we denote the area of an elliptic sector, measured from the axis major to a point whose co-ordinates are  $x, y$ , by  $S$ , we may write

$$\frac{x}{a} = \cos \frac{2S}{ab} = \cos a, \quad \frac{y}{b} = \sin \frac{2S}{ab} = \sin a.$$

**129. The Parabola.**—Taking the equation of the parabola in the form

$$y^2 = px, \text{ we get } y = \sqrt{px}.$$

Hence the area of the portion  $APN$  is

$$p^{\frac{1}{2}} \int x^{\frac{1}{2}} dx, \text{ or } \frac{2}{3} p^{\frac{1}{2}} x^{\frac{3}{2}}, \text{ i.e. } \frac{2}{3} xy.$$

Consequently, the area of the segment  $PAP'$ , cut off by a chord perpendicular to the axis, is  $\frac{2}{3}$  of the rectangle  $PMMP'$ .

It is easily seen that a similar relation holds for the segment cut off by any chord.

More generally, let the equation of the curve be  $y = ax^n$ , where  $n$  is positive.

$$\text{Here } \int y dx = a \int x^n dx = \frac{ax^{n+1}}{n+1} + \text{const.}$$

If the area be counted from the origin, the constant vanishes, and the expression for the area becomes

$$\frac{ax^{n+1}}{n+1}, \text{ or } \frac{xy}{n+1}.$$

Hence, the area is in a constant ratio to the rectangle under the co-ordinates. A corresponding result holds for oblique axes. The discussion, when  $n$  is negative, is left to the student.

#### EXAMPLE.

Express the area of a segment of a parabola cut off by any focal chord in terms of  $l$ , the length of the chord, and  $p$ , the parameter of the parabola.

$$\text{Ans. } \frac{l^3 p^{\frac{1}{2}}}{6}.$$

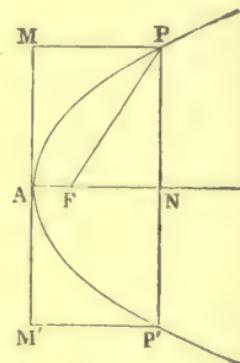


Fig 4.

130. **The Hyperbola.**—The simplest form of the equation of a hyperbola is where the asymptotes are taken for co-ordinate axes; in this case its equation is of the form  $xy = c^2$ .

Hence, denoting the angle between the asymptotes by  $\omega$ , the area between the curve and an asymptote is denoted by

$$c^2 \sin \omega \int \frac{dx}{x}, \text{ or } c^2 \sin \omega \log \left( \frac{x_1}{x_0} \right),$$

where  $x_1$  and  $x_0$  are the abscissæ of the limiting points.

If the curve be referred to its axes, its equation is

$$\frac{x^2}{a^2} - \frac{y^2}{b^2} = 1;$$

and the element of area  $y dx$  becomes

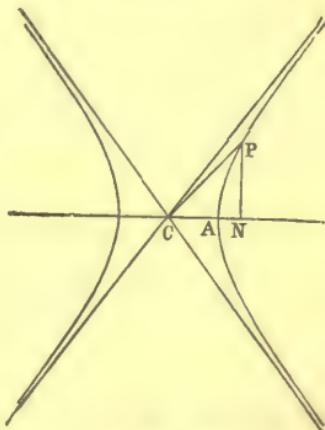
$$\frac{b}{a} \sqrt{x^2 - a^2} dx.$$

Hence the area is represented by

$$\frac{b}{a} \int \sqrt{x^2 - a^2} dx,$$

taken between proper limits.

Fig. 5.



$$\text{Again, } \int \sqrt{x^2 - a^2} dx = \int \frac{x^2 dx}{\sqrt{x^2 - a^2}} - a^2 \int \frac{dx}{\sqrt{x^2 - a^2}}.$$

Also, integrating by parts, we have

$$\int \sqrt{x^2 - a^2} dx = x \sqrt{x^2 - a^2} - \int \frac{x^2 dx}{\sqrt{x^2 - a^2}}.$$

Adding, and dividing by 2, we get

$$\begin{aligned} \int \sqrt{x^2 - a^2} dx &= \frac{x \sqrt{x^2 - a^2}}{2} - \frac{a^2}{2} \int \frac{dx}{\sqrt{x^2 - a^2}} \\ &= \frac{x \sqrt{x^2 - a^2}}{2} - \frac{a^2}{2} \log (x + \sqrt{x^2 - a^2}). \end{aligned}$$

Accordingly, if we suppose the area counted from the summit  $A$ , we have

$$\begin{aligned} APN &= \frac{b}{2a} x \sqrt{x^2 - a^2} - \frac{ab}{2} \log \left( \frac{x + \sqrt{x^2 - a^2}}{a} \right) \\ &= \frac{xy}{2} - \frac{ab}{2} \log \left( \frac{x}{a} + \frac{y}{b} \right). \end{aligned}$$

Again, since the triangle  $CPN = \frac{1}{2} xy$ , it follows that

$$\text{sector } ACP = \frac{ab}{2} \log \left( \frac{x}{a} + \frac{y}{b} \right).$$

For a geometrical method of finding the area of a hyperbolic sector, see Salmon's *Conics*, Art. 395.

130 (a). **Hyperbolic Sine and Cosine.**—If  $S$  represent the sector  $ACP$ , the final equation of the preceding Article becomes

$$\frac{ab}{2} \log \left( \frac{x}{a} + \frac{y}{b} \right) \therefore S, \quad (1)$$

which may also be written

$$\frac{x}{a} + \frac{y}{b} = e^v,$$

introducing a single letter  $v$  to denote the quantity

$$\log \left( \frac{x}{a} + \frac{y}{b} \right) = \frac{2S}{ab} = v.$$

Hence, by the equation of the hyperbola, we get

$$\frac{x}{a} - \frac{y}{b} = e^{-v}.$$

Thus, in analogy with the last result of Art. 128, calling the following functions the hyperbolic cosine and hyperbolic sine of  $v$ , and for brevity writing them  $\cosh v$ , and  $\sinh v$ ,

$$e^v + e^{-v} = 2 \cosh v, \quad e^v - e^{-v} = 2 \sinh v, \quad (2)$$

the co-ordinates of any point on the curve are

$$\frac{x}{a} = \cosh v = \cosh \frac{2S}{ab}, \quad \frac{y}{b} = \sinh v = \sinh \frac{2S}{ab}.$$

We might have treated the matter differently by introducing the angle  $\phi$  defined by the equation  $x = a \sec \phi$ , and therefore  $y = b \tan \phi$  (for the geometric meaning of this transformation, see Salmon's *Conics*, Art. 232); whence (1) may be written\*

$$\frac{2S}{ab} = v = \log \tan \left( \frac{\pi}{4} + \frac{\phi}{2} \right);$$

and we see that the hyperbolic cosine of a real quantity is the secant, and the hyperbolic sine the tangent of the same real angle. Also, since

$$\sin \phi = \frac{\sinh v}{\cosh v}, \cos \phi = \frac{1}{\cosh v}, \cot \phi = \frac{1}{\sinh v}, \operatorname{cosec} \phi = \frac{\cosh v}{\sinh v},$$

we can obviously extend the names of the other trigonometrical functions likewise. Again, putting in (2) for  $v$ ,  $u\sqrt{-1}$ , or  $iu$ , they become, by Art. 8,

$$\cos u = \cosh iu, \quad i \sin u = \sinh iu.$$

**131. The Catenary.**—If an inelastic string of uniform density be allowed to hang freely from two fixed points, the curve which it assumes is called the Catenary.

Its equation can be easily arrived at from elementary mechanics, as follows:—

Let  $V$  be the lowest point on the curve; then any portion  $VP$  of the string must be in equilibrium under the action of the tensions at its extremities, and its own weight,  $W$ .

Let  $A$  be the tension at  $V$ ;  $T$  that at  $P$ , which acts along  $PR$ , the tangent at  $P$ ;  $\angle PRM = \phi$ . Then, by the property of the triangle of force, we have

$$W : A = PM : RM;$$

$$\therefore W = A \tan \phi.$$

\* When  $\phi$  is related to  $v$  by this equation,  $\phi$  is what Professor Cayley (*Elliptic Functions*, p. 56) calls the gudermannian of  $v$ , after Professor Gudermann, and writes the inverse equation  $\phi = gd v$ .

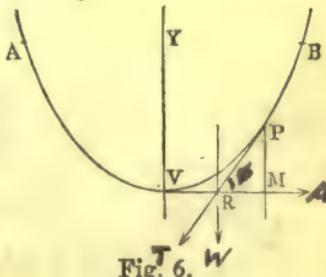


Fig. 6.

Again, if  $s$  be the length of  $VP$ , and  $a$  that of the portion of the string whose weight is  $A$ , we have, since the string is uniform,

$$W = A \frac{s}{a};$$

$$\therefore s = a \tan \phi.$$

This is the intrinsic equation of the catenary. (Diff. Calc., Art. 242 (a).)

Its equation in Cartesian co-ordinates can be easily arrived at.

For, on the vertical through  $V$  take  $VO = a$ , and draw  $OX$  in the horizontal direction, and assume  $OX$  and  $OY$  as axes of co-ordinates. Let

$$PN = y, \quad ON = x,$$

then

$$\frac{dy}{dx} = \tan \phi,$$

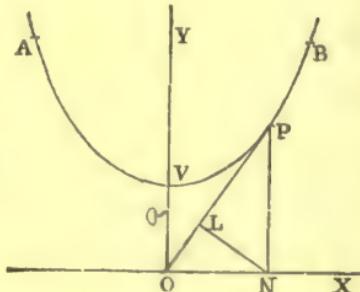


Fig. 7.

$$\frac{dy}{ds} = \sin \phi, \quad \frac{dx}{ds} = \cos \phi;$$

$$\therefore \frac{dy}{d\phi} = \frac{dy}{ds} \frac{ds}{d\phi} = a \frac{\sin \phi}{\cos^2 \phi}, \quad \frac{dx}{d\phi} = \frac{a}{\cos \phi}.$$

$$\text{Hence } y = a \sec \phi, \quad x = a \log (\sec \phi + \tan \phi). \quad (3)$$

No constant is added to either integral, since  $y = a$ , and  $x = 0$ , when  $\phi = 0$ .

From the latter equation we get

$$\sec \phi + \tan \phi = e^{\frac{x}{a}};$$

$$\text{also } \sec \phi - \tan \phi = \frac{1}{\sec \phi + \tan \phi} = e^{-\frac{x}{a}}.$$

Hence, we have

$$2 \sec \phi = e^{\frac{x}{a}} + e^{-\frac{x}{a}}, \quad 2 \tan \phi = e^{\frac{x}{a}} - e^{-\frac{x}{a}}.$$

Consequently,

$$y = \frac{a}{2} \left( e^{\frac{x}{a}} + e^{-\frac{x}{a}} \right). \quad (4)$$

Also

$$s = \frac{a}{2} \left( e^{\frac{x}{a}} - e^{-\frac{x}{a}} \right). \quad (5)$$

In the notation of last Article these equations may be written

$$\frac{y}{a} = \cosh \frac{x}{a} \text{ and } \frac{s}{a} = \sinh \frac{x}{a}.$$

Again, if  $NL$  be drawn perpendicular to the tangent at  $P$ , we have

$$NL = PN \cos \phi; \therefore NL = a. \quad (6)$$

$$\text{Also } PL = NL \tan \phi; \therefore PL = s = PV. \quad (7)$$

The area of any portion  $VPNO$  is

$$\frac{a}{2} \int_0^x \left( e^{\frac{x}{a}} + e^{-\frac{x}{a}} \right) dx = \frac{a^2}{2} \left( e^{\frac{x}{a}} - e^{-\frac{x}{a}} \right) = a(y^2 - a^2)^{\frac{1}{2}}. \quad (8)$$

Accordingly, the area  $VPNO$  is double that of the triangle  $PNL$ .

### EXAMPLES.

1. To find the area of the oval of the parabola of the third degree with a double point

$$cy^2 = (x - a)(x - b)^2.$$

The area in question is represented by

$$\frac{2}{\sqrt{c}} \int_a^b (b - x) \sqrt{x - a} dx.$$

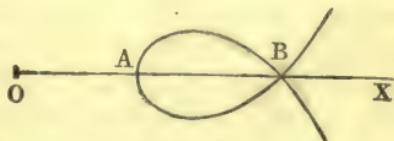


Fig. 8.

Let  $x - a = z^2$ , and we easily find the area\* to be  $\frac{8(b-a)^{\frac{3}{2}}}{3 \cdot 5 \cdot 4!}$ .

2. Find the whole area of the curve  $a^2 y^2 = x^3(2a - x)$ . *Ans.*  $\pi a^2$ .  
 3. Find the whole area between the cissoid  $x^3 = y^2(a - x)$  and its asymptote.

\* The student will find little difficulty in proving that this area is  $\frac{2\sqrt{2}}{5}$  times the rectangle which circumscribes the oval, having its sides parallel to the co-ordinate axes.

Since  $x - a = 0$  is the equation of the asymptote the area in question is represented by

$$\int_0^a \frac{x^{\frac{3}{2}} dx}{(a - x)^{\frac{1}{2}}}.$$

Let  $x = a \sin^2 \theta$ , and this becomes

$$2a^2 \int_0^{\frac{\pi}{2}} \sin^4 \theta d\theta :$$

hence the area in question is  $\frac{3}{8} \pi a^2$ .

4. Find the area of the loop of the curve

$$a^3 y^2 = x^4 (b + x).$$

This curve has been considered in Art. 262, Diff. Calc. Its form is exhibited in the annexed figure; and the area of the loop is plainly

$$\frac{2}{a^{\frac{3}{2}}} \int_{-b}^0 x^2 \sqrt{b + x} dx.$$

Let  $b + x = z^2$ , and it is easily seen that the area in question is represented by

$$\frac{8 \cdot b^{\frac{3}{2}}}{3 \cdot 5 \cdot 7 \cdot a^{\frac{3}{2}}}.$$

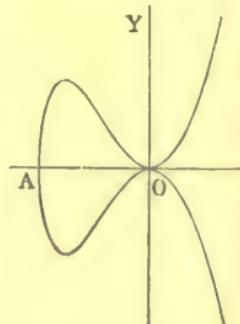
5. Find the area between the witch of Agnesi

$$xy^2 = 4a^2(2a - x)$$

and its asymptote.

Fig. 9.

Ans.  $4\pi a^2$ .



132. In finding the whole area of a closed curve, such as that represented in the figure, we suppose lines,  $PM$ ,  $QN$ , &c., drawn parallel to the axis of  $y$ ; then, assuming each of these lines to meet the curve in but two points, and making  $PM = y_2$ ,  $P'M = y_1$ , the elementary area  $PQQ'P'$  is represented by  $(y_2 - y_1)dx$ , and the entire\* area by

$$\int_{OB}^{OB'} (y_2 - y_1) dx;$$

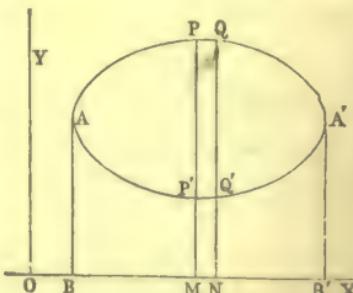


Fig. 10.

in which  $OB$ ,  $OB'$  are the limiting values of  $x$ .

\* This form still holds when the axis of  $x$  intersects the curve, for the ordinates below that axis have a negative sign, and  $(y_2 - y_1)dx$  will still represent the element of the area between two parallel ordinates.

For example, let it be proposed to find the whole area of an ellipse given by the general equation

$$ax^2 + 2hxy + by^2 + 2gx + 2fy + c = 0.$$

Here, solving for  $y$ , we easily find

$$y_2 - y_1 = \frac{2}{b} \sqrt{(h^2 - ab)x^2 + 2(hf - bg)x + f^2 - bc}.$$

Also, the limiting values of  $x$  are the roots of the quadratic expression under the radical sign.

Accordingly, denoting these roots by  $\alpha$  and  $\beta$ , and observing that  $h^2 - ab$  is negative for an ellipse, the entire area is represented by

$$\frac{2\sqrt{ab - h^2}}{b} \int_{\alpha}^{\beta} \sqrt{(x - a)(\beta - x)} dx.$$

To find this, assume  $x - a = (\beta - a) \sin^2 \theta$  ;  
then  $\beta - x = (\beta - a) \cos^2 \theta$ ,  
and we get

$$\begin{aligned} \int_{\alpha}^{\beta} \sqrt{(x - a)(\beta - x)} dx &= 2(\beta - a)^2 \int_0^{\frac{\pi}{2}} \sin^2 \theta \cos^2 \theta d\theta \\ &= \frac{\pi}{8} (\beta - a)^2. \end{aligned}$$

$$\begin{aligned} \text{Again, } (\beta - a)^2 &= 4 \cdot \frac{(hf - bg)^2 + (f^2 - bc)(ab - h^2)}{(ab - h^2)^2} \\ &= \frac{4b(af^2 + bg^2 + ch^2 - 2fgh - abc)}{(ab - h^2)^2}. \end{aligned}$$

Hence the area of the ellipse is represented by

$$\frac{\pi(af^2 + bg^2 + ch^2 - 2fgh - abc)}{(ab - h^2)^{\frac{3}{2}}}.$$

This result can be verified without difficulty, by determining the value of the rectangle under the semiaxes of an ellipse, in terms of the coefficients of its general equation.

It is worthy of observation that if we suppose a closed curve to be described by the motion of a point round its entire perimeter, the whole inclosed area is represented by  $\int y dx$ , taken for every point around the entire curve.

Thus, in the preceding figure, if we proceed from  $A$  to  $A'$  along the upper portion of the curve, the corresponding part of the integral  $\int y dx$  represents the area  $APA'B'B$ . Again, in returning from  $A'$  to  $A$  along the lower part of the curve, the increment  $dx$  is negative, and the corresponding part of  $\int y dx$  is also negative (assuming that the curve does not intersect the axis of  $x$ ), and represents the area  $A'P'ABB'$ , taken with a negative sign. Consequently, the whole area of the closed curve is represented by the integral  $\int y dx$ , taken for all points on the curve.

The student will find no difficulty in showing that this proof is general, whatever be the form of the curve, and whatever the number of points in which it is met by the parallel ordinates.

To avoid ambiguity, the preceding result may be stated as follows:—*The area of any closed curve is represented by*

$$\int y \frac{dx}{ds} ds$$

*taken through the entire perimeter of the curve, the element of the curve being regarded as positive throughout.*

The preceding is on the hypothesis that the curve has no double point. If the curve cut itself, so as to form two loops, it is easily seen that  $\int y \frac{dx}{ds} ds$ , when taken round the entire perimeter, represents the difference between the areas of the two loops. The corresponding result in the case of three or more loops can be readily determined.

133. In many cases, instead of determining  $y$  in terms of  $x$ , we can express them both in terms of a single variable, and thus determine the area by expressing its element in terms of that variable.

For instance, in the ellipse, if we make  $x = a \sin \phi$ , we get  $y = b \cos \phi$ , and  $y dx$  becomes  $ab \cos^2 \phi d\phi$ , the integral of which gives the same result as before.

In like manner, to find the area of the curve

$$\left(\frac{x}{a}\right)^3 + \left(\frac{y}{b}\right)^3 = 1.$$

Let  $x = a \sin^3 \phi$ , then  $y = b \cos^3 \phi$ , and  $y dx$  becomes

$$3ab \sin^2 \phi \cos^4 \phi d\phi :$$

hence the entire area of the curve is represented by

$$12ab \int_0^{\frac{\pi}{2}} \sin^2 \phi \cos^4 \phi d\phi = \frac{3}{8} \pi ab.$$

EXAMPLES.

1. Find the whole area of the evolute of the ellipse

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1. \quad \text{Ans. } \frac{3\pi(a^2 - b^2)^2}{8ab}.$$

2. Find the whole area of the curve

$$\left(\frac{x}{a}\right)^{\frac{2}{2m+1}} + \left(\frac{y}{b}\right)^{\frac{2}{2n+1}} = 1.$$

$$\text{Ans. } \frac{1 \cdot 3 \cdot 5 \dots (2m+1) \cdot 1 \cdot 3 \cdot 5 \dots (2n+1)}{2 \cdot 4 \cdot 6 \dots \dots \dots \cdot 2(m+n+1)} \pi ab.$$

134. **The Cycloid.**—In the cycloid, we have (Diff. Calc., Art. 272),

$$x = a(\theta - \sin \theta), \quad y = a(1 - \cos \theta);$$

$$\therefore \int y dx = a^2 \int (1 - \cos \theta)^2 d\theta = 4a^2 \int \sin^4 \frac{\theta}{2} d\theta.$$

Taking  $\theta$  between 0 and  $\pi$ , we get  $3\pi a^2$  for the entire area between the cycloid and its base.

The area of the cycloid admits also of an elementary geometrical deduction, as follows:—

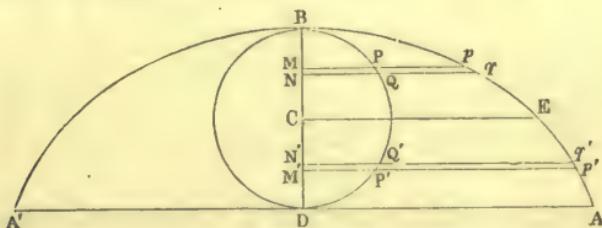


Fig. II.

It is obviously sufficient to find the area between the semicircle  $BPD$  and the semi-cycloid  $BpA$ . To determine this, let points  $P$  and  $P'$  be taken on the semicircle such that  $\text{arc } BP = \text{arc } DP$ : draw  $MPp$  and  $M'P'p'$  perpendicular to  $BD$ . Take  $MN$  and  $M'N'$  of equal length, and draw  $Nq$  and  $N'q'$ , also perpendicular to  $BD$ : then, by the fundamental property of the cycloid, the line  $Pp = \text{arc } BP$ , and  $P'p' = \text{arc } BP'$ :  $\therefore Pp + P'p' = \text{semicircle} = \pi a$ .

Now, if the interval  $MN$  be regarded as indefinitely small, the sum of the elementary areas  $PpqQ$  and  $P'p'q'Q'$  is equal to the rectangle under  $MN$  and the sum of  $Pp$  and  $P'p'$ , or to  $\pi a \times MN$ .

Again, if the entire figure be supposed divided in like manner, it is obvious that the whole area between the semi-circle and the cycloid is equal to  $\pi a$  multiplied by the sum of the elements  $MN$ , taken from  $B$  to the centre  $C$ , i.e. equal to  $\pi a^2$ .

Consequently the whole area of the cycloid is  $3\pi a^2$ , as before.

The area of a prolate or curtate cycloid can be obtained in like manner.

135. **Areas in Polar Co-ordinates.**—Suppose the curve  $APB$  to be referred to polar co-ordinates,  $O$  being the pole, and let  $OP, OQ, OR$  represent consecutive radii vectores, and  $PL, QM$ , arcs of circles described with  $O$  as centre. Then the area  $OPQ = OPL + PLQ$ ; but  $PLQ$  becomes evanescent in comparison with  $OPL$  when  $P$  and  $Q$  are infinitely near points; consequently, in the limit the elementary area  $OPQ = \text{area } OPL = \frac{r^2 d\theta}{2}$ ;  $r$  and  $\theta$  being the polar co-ordinates of  $P$ .

Hence the sectorial area  $AOB$  is represented by

$$\frac{1}{2} \int_{\beta}^{\alpha} r^2 d\theta,$$

where  $\alpha$  and  $\beta$  are the values of  $\theta$  corresponding to the limiting points  $A$  and  $B$ .

136. **Area of Pedals of Ellipse and Hyperbola.**—For example, let it be proposed to find the area of the locus of the foot of the perpendicular from the centre on a tangent to an ellipse.

Writing the equation of the ellipse in the form  $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$ , the equation of the locus in question is obviously

$$r^2 = a^2 \cos^2 \theta + b^2 \sin^2 \theta.$$

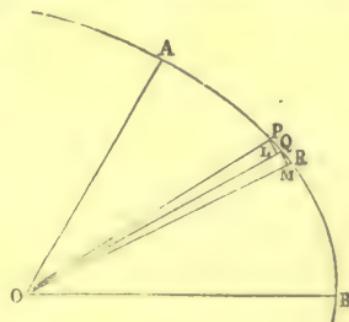


Fig. 12.

Hence its area is

$$\frac{a^2}{2} \int \cos^2 \theta d\theta + \frac{b^2}{2} \int \sin^2 \theta d\theta = \frac{a^2 + b^2}{4} \theta + \frac{a^2 - b^2}{4} \sin \theta \cos \theta.$$

The entire area of the locus is

$$\frac{\pi}{2} (a^2 + b^2).$$

The equation of the corresponding locus for the hyperbola is

$$r^2 = a^2 \cos^2 \theta - b^2 \sin^2 \theta.$$

In finding its area, since  $r$  must be real, we must have  $a^2 \cos^2 \theta - b^2 \sin^2 \theta$  positive: accordingly, the limits for  $\theta$  are 0 and  $\tan^{-1} \frac{a}{b}$ .

Integrating between these limits, and multiplying by 4, we get for the entire area

$$ab + (a^2 - b^2) \tan^{-1} \frac{a}{b}.$$

In this case, if we had at once integrated between  $\theta = 0$  and  $\theta = 2\pi$ , we should have found for the area  $(a^2 - b^2) \frac{\pi}{2}$ .

This anomaly would arise from our having integrated through an interval for which  $r^2$  is negative, and for which, therefore, the corresponding part of the curve is imaginary.

The expression for the area of the pedal of an ellipse with respect to any origin will be given in a subsequent Article.

### EXAMPLES.

1. Show that the entire area of the Lemniscate

$$r^2 = a^2 \cos 2\theta$$

is  $a^2$ .

2. In the hyperbolic spiral

$$r\theta = a,$$

prove that the area bounded by any two radii vectores is proportional to the difference between their lengths.

3. Find the area of a loop of the curve

$$r^2 = a^2 \cos n\theta.$$

$$\text{Ans. } \frac{a^2}{n}.$$

4. Find the area of the loop of the Folium of Descartes, whose equation is

$$x^3 + y^3 = 3axy.$$

Transforming to polar co-ordinates, we have

$$r = \frac{3a \cos \theta \sin \theta}{\sin^3 \theta + \cos^3 \theta}.$$

Again, the limiting values of  $\theta$  are 0 and  $\frac{\pi}{2}$ ;

$$\therefore \text{Area} = \frac{9a^2}{2} \int_0^{\frac{\pi}{2}} \frac{\sin^2 \theta \cos^2 \theta d\theta}{(\sin^3 \theta + \cos^3 \theta)^2}.$$

Let  $\tan \theta = u$ , and this expression becomes

$$\frac{9a^2}{2} \int_0^{\infty} \frac{u^2 du}{(1+u^3)^2} = \frac{3a^2}{2}.$$

5. To find the area of the Limaçon

$$r = a \cos \theta + b.$$

Here we must distinguish between two cases.

(1). Let  $b > a$ . In this case the curve consists of one loop, and its area is

$$\frac{1}{2} \int_0^{2\pi} (a \cos \theta + b)^2 d\theta = \left( b^2 + \frac{a^2}{2} \right) \pi.$$

When  $b = a$ , the curve becomes a Cardioid, and the area  $\frac{3\pi a^2}{2}$ .

(2). Let  $b < a$ . The curve in this case has two loops, as in the figure (see Diff. Calc., Art. 269), the outer loop corresponding to

$$r = a \cos \theta + b,$$

the inner to

$$r = a \cos \theta - b.$$

To find the area of the inner loop, we take  $\theta$  between the limits 0 and  $\alpha$ , where

$$\alpha = \cos^{-1} \left( \frac{b}{a} \right); \text{ and the entire area is}$$

$$\begin{aligned} & \int_0^\alpha (a \cos \theta - b)^2 d\theta \\ &= \int_0^\alpha (a^2 \cos^2 \theta - 2ab \cos \theta + b^2) d\theta \\ &= \left( \frac{a^2}{2} + b^2 \right) \alpha + \frac{a^2}{2} \sin \alpha \cos \alpha - 2ab \sin \alpha \\ &= \left( \frac{a^2}{2} + b^2 \right) \cos^{-1} \frac{b}{a} - \frac{3}{2} b \sqrt{a^2 - b^2}. \end{aligned}$$

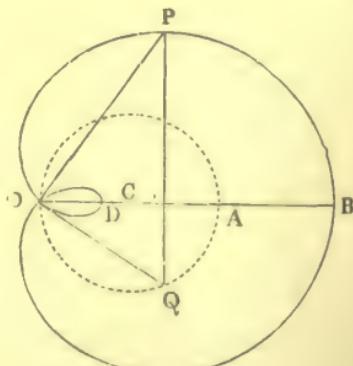


Fig. 13.

It is easily seen that the sum of the areas of the two loops is obtained by integrating between the limits  $0$  and  $2\pi$ , and accordingly is

$$\pi \left( \frac{a^2}{2} + b^2 \right),$$

as in the former case.

**137. Area of a Closed Curve by Polar Co-ordinates.**—In finding the whole area of a closed curve by polar co-ordinates we distinguish between two cases. When the origin  $O$  is outside, we suppose tangents  $OT$ ,  $OT'$ , drawn from  $O$ , and vectors  $OP$ ,  $OQ$ , &c., drawn to cut the curve; then, if these lines intersect it in but two points each, the element of area  $PpqQ$  is the difference between the areas  $POQ$  and  $pOq$ ; or, in the limit, is  $\frac{1}{2}(r_1^2 - r_2^2)d\theta$ , where  $OP = r_1$ ,  $Oq = r_2$ .

Hence, the expression

$$\frac{1}{2} \int (r_1^2 - r_2^2) d\theta,$$

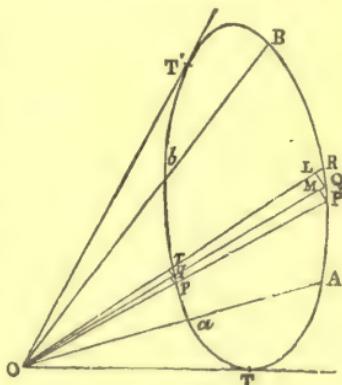


Fig. 14.

taken between the limits corresponding to the tangents  $OT$  and  $OT'$ , represents the entire included area.

If the origin lie inside the curve, its whole area is in general represented by  $\frac{1}{2} \int (r_1^2 + r_2^2) d\theta$ , taken between the limits  $\theta = 0$ , and  $\theta = \pi$ .

We shall illustrate these results by applying them to the circle

$$r^2 - 2rc \cos \theta + c^2 = a^2.$$

If the origin be outside, we have  $c > a$ , and  $r_1 + r_2 = 2c \cos \theta$ , and  $r_1 r_2 = c^2 - a^2$ ;  $r_1 - r_2 = 2\sqrt{a^2 - c^2 \sin^2 \theta}$ .

Hence  $(r_1^2 - r_2^2)d\theta = 4c \cos \theta \sqrt{a^2 - c^2 \sin^2 \theta} d\theta$ ; and the limiting values of  $\theta$  are  $\pm \sin^{-1} \frac{a}{c}$ .

Hence the whole area is

$$2c \int_{-\sin^{-1} \frac{a}{c}}^{\sin^{-1} \frac{a}{c}} \cos \theta \sqrt{a^2 - c^2 \sin^2 \theta} d\theta.$$

Let  $c \sin \theta = a \sin \phi$ , and this integral transforms into

$$2a^2 \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos^2 \phi \, d\phi = \pi a^2.$$

Again, if the origin be inside, we have  $c < a$ , and

$$\frac{1}{2} (r_1^2 + r_2^2) = a^2 + c^2 \cos 2\theta;$$

$$\therefore \int_0^\pi (r_1^2 + r_2^2) \, d\theta = \int_0^\pi (a^2 + c^2 \cos 2\theta) \, d\theta = \pi a^2.$$

The method given above may be applied to find the area included between two branches of the same spiral curve. As an example, let us consider the spiral of Archimedes.

**138. The Spiral of Archimedes.**—The equation of this curve is  $r = a\theta$ , and its form, for *positive*\* values of  $\theta$ , is represented in the accompanying figure, in which  $O$  is the pole and  $OA$  the line from which  $\theta$  is measured. Let any line drawn through  $O$  meet the different branches of the spiral in points  $P, Q, R, \&c.$ : then, if  $OP = r$ , and  $\angle POA = \theta$ , we have, from the equation of the curve,

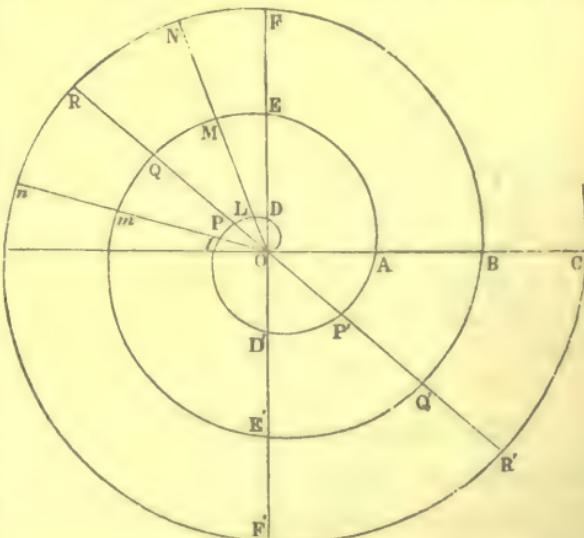


Fig. 15.

$$OP = a\theta, \quad OQ = a(\theta + 2\pi), \quad OR = a(\theta + 4\pi), \&c.$$

\* It should be noted that when negative values of  $\theta$  are taken, we get for the remaining half of the spiral a curve symmetrically situated with respect to the prime vector  $OA$ .

Hence  $PQ = QR = \&c., = 2a\pi = c$  (suppose); i.e. the intercepts between any two consecutive branches of the spiral are of constant length.

Again, let  $OQ = r_1$ ,  $OR = r_2 = r_1 + c$ , and the area between the two corresponding branches is

$$\frac{1}{2} \int (r_2^2 - r_1^2) d\theta = c \int r_1 d\theta + \frac{c^2}{2} \int d\theta.$$

Now, suppose  $MN$  and  $mn$  represent the limiting lines, and let  $\beta$  and  $a$  be the corresponding values of  $\theta$ ; then the area  $nNMm$  will be equal to

$$\begin{aligned} c \int_a^\beta a\theta d\theta + \frac{c^2}{2} \int_a^\beta d\theta &= \frac{c}{2} (\beta - a) (aa + a\beta + c) \\ &= \frac{c}{2} (\beta - a) (OM + On). \end{aligned} \quad (9)$$

If  $\beta - a = \pi$ , this gives for the area of the portion between two consecutive branches  $QE'Q'$  and  $RF'R'$ , intercepted by any right line  $RR'$  drawn through the pole,  $\frac{\pi}{2}RQ \cdot QR'$ , i.e. half the area of the ellipse whose semi-axes are  $RQ$  and  $R'Q$ .

139. **Another Expression for Area.**—The formula in Article 137 still holds, obviously, when  $AB$  and  $ab$  represent portions of different curves.

It is also easily seen, as in Art. 132, that if a point be supposed to move round any closed boundary, the included area is in all cases represented by  $\frac{1}{2} \int r^2 d\theta$ , taken round the entire boundary, whatever be its form; the elementary angle  $d\theta$  being taken with its proper sign throughout.

Again, if we transform to rectangular axes by the relations  $x = r \cos \theta$ ,  $y = r \sin \theta$ , we get

$$\tan \theta = \frac{y}{x}; \therefore \frac{d\theta}{\cos^2 \theta} = \frac{xdy - ydx}{x^2}.$$

Hence

$$r^2 d\theta = xdy - ydx;$$

[13 a].

and the area swept out by the radius vector is represented by the integral

$$\frac{1}{2} \int (xdy - ydx),$$

taken between suitable limits; a result which can also be easily arrived at geometrically.

**140. Area of Elliptic Sector. Lambert's Theorem.**—It is of importance in Astronomy to be able to express the area  $AFP$  swept out by the focal radius vector of an ellipse. This can be arrived at by integration from the polar equation of the curve; it is, however, more easily obtained geometrically.

For, if the ordinate  $PN$  be produced to meet the auxiliary circle in  $Q$ , we have

$$\begin{aligned} \text{area } AFP &= \frac{b}{a} \times \text{area } AFQ = \frac{b}{a} (ACQ - CFQ) \\ &= \frac{ab}{2} (u - e \sin u), \end{aligned} \quad (10)$$

where  $u = \angle ACQ$ .

By aid of this result, the area of any elliptic sector can be expressed in terms of the focal distances of its extremities, and of the chord joining them.

For (Fig. 17), let  $QFP$  represent the sector, and let  $FP = \rho$ ,  $FQ = \rho'$ ,  $PQ = \delta$ ; then, denoting by  $u$  and  $u'$  the eccentric angles corresponding to  $P$  and  $Q$ , the area of the sector  $QFP$ , by (10), is represented by

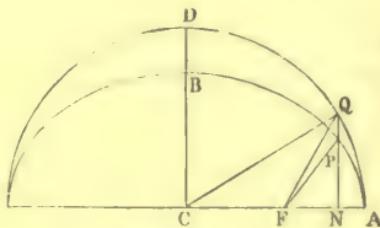


Fig. 16.

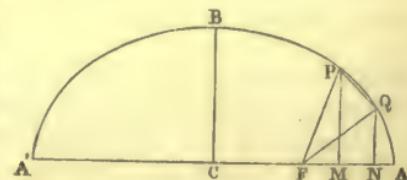


Fig. 17.

$$\frac{ab}{2} \left\{ u - u' - e(\sin u - \sin u') \right\}.$$

We proceed to show that this result can be written in the form

$$\frac{ab}{2} \{ \phi - \phi' - (\sin \phi - \sin \phi') \}. \quad (11)$$

where  $\phi$  and  $\phi'$  are given by the equations

$$\sin \frac{\phi}{2} = \frac{1}{2} \sqrt{\frac{\rho + \rho' + \delta}{a}}, \quad \sin \frac{\phi'}{2} = \frac{1}{2} \sqrt{\frac{\rho + \rho' - \delta}{a}}.$$

For, assume that  $\phi$  and  $\phi'$  are determined by the equations

$$u - u' = \phi - \phi', \quad e(\sin u - \sin u') = \sin \phi - \sin \phi'. \quad (a)$$

The latter gives

$$e \sin \frac{u - u'}{2} \cos \frac{u + u'}{2} = \sin \frac{\phi - \phi'}{2} \cos \frac{\phi + \phi'}{2},$$

or by the former,  $e \cos \frac{u + u'}{2} = \cos \frac{\phi + \phi'}{2}$ .

Again, since the co-ordinates of  $P$  and  $Q$  are  $a \cos u$ ,  $b \sin u$ , and  $a \cos u'$ ,  $b \sin u'$ , respectively, we have

$$\begin{aligned} \delta^2 &= a^2 (\cos u - \cos u')^2 + b^2 (\sin u - \sin u')^2 \\ &= 4 \sin^2 \frac{u - u'}{2} \left( a^2 \sin^2 \frac{u + u'}{2} + b^2 \cos^2 \frac{u + u'}{2} \right) \\ &= 4a^2 \sin^2 \frac{u - u'}{2} \left( 1 - e^2 \cos^2 \frac{u + u'}{2} \right) \\ &= 4a^2 \sin^2 \frac{\phi - \phi'}{2} \sin^2 \frac{\phi + \phi'}{2}; \end{aligned}$$

$$\therefore \delta = 2a \sin \frac{\phi - \phi'}{2} \sin \frac{\phi + \phi'}{2} = a(\cos \phi' - \cos \phi). \quad (b)$$

Again, from the ellipse, we have

$$\rho = a(1 - e \cos u), \quad \rho' = a(1 - e \cos u'),$$

$$\begin{aligned} \therefore \rho + \rho' &= 2a - ae(\cos u + \cos u') = 2a - 2ae \cos \frac{u + u'}{2} \cos \frac{u - u'}{2} \\ &= 2a - 2a \cos \frac{\phi + \phi'}{2} \cos \frac{\phi - \phi'}{2} = 2a - a(\cos \phi + \cos \phi'). \quad (c) \end{aligned}$$

Hence, adding and subtracting (b) and (c), we get

$$\frac{\rho + \rho' + \delta}{a} = 2(1 - \cos \phi) = 4 \sin^2 \frac{\phi}{2},$$

$$\frac{\rho + \rho' - \delta}{a} = 2(1 - \cos \phi') = 4 \sin^2 \frac{\phi'}{2},$$

which proves the theorem in question.

Consequently, the *area\** of any focal sector of an ellipse can be expressed in terms of the focal distances of its extremities, of the chord which joins them, and of the axes of the curve.

141. We next proceed to an elementary principle which is sometimes useful in determining areas, viz. :—

*The area of any portion of the curve represented by the equation*

$$F\left(\frac{x}{a}, \frac{y}{b}\right) = c$$

*is ab times the area of the corresponding portion of the curve*

$$F(x, y) = c.$$

This result is obvious, for the former equation is transformed into the latter, by the assumption  $\frac{x}{a} = x'$ ,  $\frac{y}{b} = y'$ ; and hence  $ydx$  becomes  $aby'dx'$ ;

$$\therefore \int ydx = ab \int y'dx',$$

the integrals being taken through corresponding limits—a result which is also easily shown by projection.

Thus, for example, the area of the ellipse  $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$

\* This remarkable result is an extension, by Lambert (in his treatise entitled : *Insigniores orbitæ cometarum proprietates*, published in 1761), of the corresponding formula for a parabola given by Euler in *Miscell. Berolin*, 1743. It furnishes an expression for the time of describing any arc of a planet's orbit, in terms of its chord, the distances of its extremities from the sun, and the major axis of the orbit; neglecting the disturbing action of the other bodies of the solar system.

reduces to that of the circle ; and the area of the hyperbola

$$\frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$$

to that of the equilateral hyperbola  $x^2 - y^2 = 1$ .

Again, let it be proposed to find the area of the curve

$$\left(\frac{x^2}{a^2} + \frac{y^2}{b^2}\right)^2 = \frac{x^2}{l^2} + \frac{y^2}{m^2}.$$

The transformed equation is

$$(x^2 + y^2)^2 = \frac{a^2 x^2}{l^2} + \frac{b^2 y^2}{m^2};$$

or, in polar co-ordinates,

$$r^2 = \frac{a^2 \cos^2 \theta}{l^2} + \frac{b^2 \sin^2 \theta}{m^2}.$$

But the whole area of this (Art. 136) is  $\frac{\pi}{2} \left( \frac{a^2}{l^2} + \frac{b^2}{m^2} \right)$ .

Consequently the whole area of the proposed curve is

$$\frac{\pi}{2} ab \left( \frac{a^2}{l^2} + \frac{b^2}{m^2} \right).$$

It may be remarked that the equations

$$F\left(\frac{x}{a}, \frac{y}{a}\right) = c, \quad F(x, y) = c,$$

represent similar curves, and their corresponding linear dimensions are as  $a : 1$ . Consequently the areas of similar curves are as the squares of their dimensions ; as is also obvious from geometry.

**142. Area of a Pedal Curve.**—If from any point perpendiculars be drawn to the tangents to any curve, the

locus of their feet is a new curve, called the *pedal* of the original (Diff. Calc., Art. 187).

If  $p$  and  $\omega$  be the polar coordinates of  $N$ , the foot of the perpendicular from the origin  $O$ , then the polar element of area of the locus described by  $N$  is plainly  $\frac{p^2 d\omega}{2}$ , and the sectorial area of any portion is accordingly represented by

$$\frac{1}{2} \int p^2 d\omega,$$

taken between proper limits.

There is another expression for the area of a closed pedal curve which is sometimes useful.

Let  $S_1$  denote the whole area of the pedal, and  $S$  that of the original curve; then the area included between the two curves is ultimately equal to the sum of the elements represented by  $NTN'$  in the figure.

$$\text{Hence } S_1 = S + \Sigma NTN' = S + \frac{1}{2} \int PN^2 d\omega. \quad (12)$$

Again, by the preceding,

$$S_1 = \frac{1}{2} \int ON^2 d\omega.$$

Accordingly, by addition,

$$2S_1 = S + \frac{1}{2} \int OP^2 d\omega. \quad (13)$$

It is easily seen that equation (12) admits of being stated in the following form:—

*The whole area of the pedal of any closed curve is equal to the sum of the areas of the curve and of the pedal of its evolute: both pedals having the same origin.*

For,  $PN$  is equal in length to the perpendicular from  $O$  on the normal at  $P$ : and hence  $\frac{1}{2} PN^2 d\omega$  represents the ele-

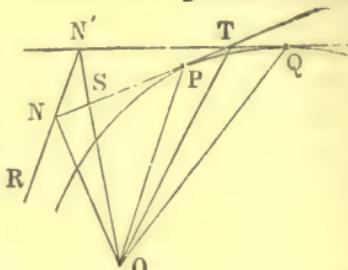


Fig. 18.

ment of area of the locus described by the foot of this perpendicular, i.e. of the pedal of the evolute of the original curve.

For example, it follows from Art. 136 that *the area of the pedal of the evolute of an ellipse is  $\frac{\pi}{2}(a - b)^2$ , the centre being origin.*

**143. Area of Pedal of Ellipse for any Origin.**— Suppose  $O$  to be the pedal origin, and  $OM, OM'$  perpendiculars on two parallel tangents to the ellipse; draw  $CN$  the perpendicular from the centre  $C$ ; let  $OM = p_1, OM' = p_2, CN = p, OC = c, \angle OCA = a, \angle ACN = \omega$ ; then

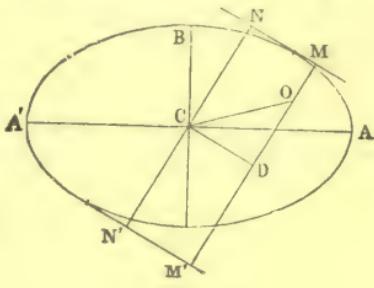


Fig. 19.

$$p_1 = MD - OD = p - c \cos(\omega - a),$$

$$p_2 = p + c \cos(\omega - a).$$

Again, the whole area of the pedal is

$$\begin{aligned} \frac{1}{2} \int_0^\pi (p_1^2 + p_2^2) d\omega &= \int_0^\pi \{p^2 + c^2 \cos^2(\omega - a)\} d\omega \\ &= \int_0^\pi p^2 d\omega + c^2 \int_0^\pi \cos^2(\omega - a) d\omega = \frac{\pi}{2}(a^2 + b^2 + c^2). \end{aligned} \quad (14)$$

That is, the area of the pedal with respect to  $O$  as origin exceeds the area of its pedal with respect to  $C$  by half the area of the circle whose radius is  $OC$ .

If the origin  $O$  lie outside the ellipse, the pedal consists of two loops intersecting at  $O$  and lying one inside the other; and in that case the expression in (14) represents the sum of the areas of the two loops, as can be easily seen.

The result established above is a particular case of a general theorem of Steiner, which we next proceed to consider.

**144. Steiner's Theorem on Areas of Pedal Curves.** Suppose  $A$  to be the whole area of the pedal of any closed curve with respect to any internal origin  $O$ , and  $A'$  the area

of its pedal with respect to another origin  $O'$ ; then, if  $p$  and  $p'$  be the lengths of the perpendiculars from  $O$  and  $O'$  on a tangent to the curve, we have

$$A = \frac{1}{2} \int_0^{2\pi} p^2 d\omega, \quad A' = \frac{1}{2} \int_0^{2\pi} p'^2 d\omega.$$

Also, adopting the notation of the last article,

$$p' = p - c \cos(\omega - a) = p - x \cos \omega - y \sin \omega;$$

where  $x, y$  represent the co-ordinates of  $O'$  with respect to rectangular axes drawn through  $O$ . Hence we get

$$A' - A = \frac{1}{2} \int_0^{2\pi} (x \cos \omega + y \sin \omega)^2 d\omega$$

$$- x \int_0^{2\pi} p \cos \omega d\omega - y \int_0^{2\pi} p \sin \omega d\omega.$$

But  $\int_0^{2\pi} \cos^2 \omega d\omega = \pi$ ,  $\int_0^{2\pi} \sin^2 \omega d\omega = \pi$ ,  $\int_0^{2\pi} \sin \omega \cos \omega d\omega = 0$ .

Also, for a given curve,  $\int_0^{2\pi} p \cos \omega d\omega$  and  $\int_0^{2\pi} p \sin \omega d\omega$  are constants when  $O$  is given. Denoting their values by  $g$  and  $h$ , we have

$$A' - A = \frac{\pi}{2} (x^2 + y^2) - gx - hy. \quad (15)$$

This equation shows that if  $O$  be fixed, the locus of the origin  $O'$ , for which the area of the pedal of a closed curve is constant, is a circle.\* The centre of this circle is the same, whatever be the given area, and all the circles got by varying the pedal area are concentric.

\* It can be seen, without difficulty, from the demonstration given above, that when the curve is not closed, the locus of the origin for pedals of equal area is a conic: a theorem due to Prof. Raabe, of Zurich. See *Crell's Journal*, vol. 1., p. 193.

The student will find a discussion of these theorems by Prof. Hirst in the *Transactions of the Royal Society*, 1863, in which he has investigated the corresponding relations connecting the volumes of the pedals of surfaces.

If the origin  $O$  be supposed taken at the centre of this circle, the constants  $g$  and  $h$  will disappear; and, in this case, the pedal area is a minimum, and the difference between the areas of the pedals is equal to half the area of the circle whose radius is the distance between the pedal origins.

For example, if we take the origin at the centre, the pedal of a circle, whose radius is  $a$ , is the circle itself. For any other origin the pedal is a limaçon; hence the whole area of a limaçon is  $\pi \left( a^2 + \frac{b^2}{2} \right)$ , as found in Art. 136, Ex. 5.

**†145. Areas of Roulettes on Rectilinear Bases.** The connexion between the areas of roulettes and of pedals is contained in a very elegant theorem,\* also due to Steiner, which may be stated as follows:—

*When a closed curve rolls on a right line, the area between the right line and the roulette generated in a complete revolution by any point invariably connected with the rolling curve is double the area of the pedal of the rolling curve, this pedal being taken with respect to the generating point as origin.*

To prove this, suppose  $O$  to be the describing point in any

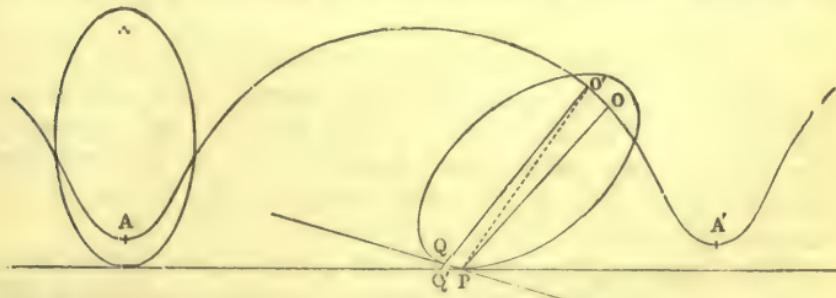


Fig 20.

position of the rolling curve, and  $P$  the corresponding point of contact. Let  $O'$  represent an infinitely near position of the describing point,  $Q'$  the corresponding point of contact, and  $Q$

\* See *Crell's Journal*, vol. xxi. The corresponding theorem of Steiner connecting the lengths of roulettes and pedals will be given in the next Chapter.

By the area of a roulette we understand the area between the roulette, the base, and the normals drawn at the extremities of one segment of the roulette.

a point on the curve such that  $PQ = PQ'$ ; then  $Q$  is the point which coincides with  $Q'$  in the new position of the rolling curve; and, denoting the angle between the tangents at  $P$  and  $Q$  (the angle of contingence) by  $d\omega$ , we have  $OPO' = d\omega$ , since we may regard the curve as turning round  $P$  at the instant (Diff. Calc., Art. 275).

Moreover,  $QQ'$  ultimately is infinitely small in comparison with  $QP$ , and consequently the elementary area  $OPQ'O'$  is ultimately the sum of the areas  $POO'$  and  $QO'P$ , neglecting an area which is infinitely small in comparison with either of these areas.

Again, if  $OP = r$ , we have  $POO' = \frac{r^2 d\omega}{2}$ , and area  $QO'P$  =  $QOP$  in the limit.

Also the sum of the elements  $QOP$  in an entire revolution is equal to the area ( $S$ ) of the rolling curve. Consequently the entire area of the roulette described by  $O$  is

$$S + \frac{1}{2} \int r^2 d\omega.$$

But we have already seen (13) that this is double the area of the pedal of the curve with respect to the point  $O$ ; which establishes our proposition.

Again, from Art. 144, it follows that there is one point in any closed curve for which the entire area of the corresponding roulette is a minimum. Also, the area of the roulette described by any other point exceeds that of the minimum roulette by the area of the circle whose radius is the distance between the points.

For instance, if a circle roll on a right line, its centre describes a parallel line, and the area between these lines after a complete revolution is equal to the rectangle under the radius of the circle and its circumference; i.e. is  $2\pi a^2$ ; denoting the radius by  $a$ .

Consequently, for a point on the circumference, the area generated is  $2\pi a^2 + \pi a^2$ , or  $3\pi a^2$ ; which agrees with the area found already for the cycloid.

In like manner, by Steiner's theorem, the area of the ordinary cycloid is the same as that of the cardioid: and the area of a prolate or curtate cycloid the same as that of a limagon.

Again, if an ellipse roll on a right line, the area of the path described by any point can be immediately obtained.

For example, the pedal of an ellipse with respect to a focus is the circle described on its axis major. Hence, *if an ellipse roll upon a right line, the area of the roulette described by its focus in a complete revolution is double the area of the auxiliary circle.* Also, the area of the roulette described by the centre of the ellipse is equal to the sum of the circles described on the axes of the ellipse as diameters, and is less than the area of the roulette described by any other point.

\* 146. **General Case of Area of Roulette.**—If the curve, instead of rolling on a right line, roll on another curve, it is easily seen that the method of proof given in the last article still holds; provided we take, instead of  $d\omega$ , the sum of the angles of contingence of the two curves at the point  $P$ .

Hence the element of area  $OP\omega$  is in this case

$$\frac{1}{2} OP^2 d\omega \left( 1 + \frac{d\omega'}{d\omega} \right), \text{ or } \frac{1}{2} OP^2 d\omega \left( 1 + \frac{\rho}{\rho'} \right),$$

where  $\rho$  and  $\rho'$  are the radii of curvature at  $P$  of the rolling and fixed curves, respectively.

Hence it follows that the area between the roulette, the fixed curve, and the two extreme normals, after a complete revolution, is represented by

$$S + \frac{1}{2} \int r^2 d\omega \left( 1 + \frac{\rho}{\rho'} \right).$$

If a closed curve roll on a curve identical with itself, having corresponding points always in contact, the formula for the area generated becomes

$$S + \int r^2 d\omega.$$

In this case the area generated is four times that of the corresponding pedal; a result which appears at once geometrically by drawing a figure.

## EXAMPLES.

1. If  $A$  be the area of a loop of the curve  $r^m = a^m \cos m\theta$ , and  $A_1$  the area of its pedal with respect to the polar origin, prove that

$$A_1 = \left(1 + \frac{m}{2}\right) A.$$

It is easily seen, as in Diff. Calc., Art. 190, that the angle between the radius vector and the perpendicular on the tangent is  $m\theta$ ; and  $\therefore \omega = (m + 1)\theta$

Hence, by Art. 142,

$$2A_1 = A + \frac{m+1}{2} \int r^2 d\theta = (m+2)A.$$

2. If a circle of radius  $b$  roll on a circle of radius  $a$ , and if  $A$  denote the area, after a complete revolution, between the fixed circle, the roulette described by any point, and the extreme normals; and if  $A'$  be the area of the pedal of the circle with respect to the generating point, prove that

$$Aa + Bb = 2(a+b)A'.$$

where  $B$  is the area of the rolling circle.

3. Apply this result to find the area included between the fixed circle and the arc of an epicycloid extending from one cusp to the next.

147. **Holditch's Theorem.**\*—If a line  $CC'$  of a given length move with its extremities on two fixed closed curves, to find, in terms of the areas of the two fixed curves, an expression for the whole area of the curve generated, in a complete revolution, by any given point  $P$  situated on the moving line.

Let  $CP = c$ ,  $PC' = c'$ , and suppose  $(x_1, y_1)$ ,  $(x, y)$ , and  $(x_2, y_2)$  to be the co-ordinates of the points  $C$ ,  $P$ , and  $C'$ , respectively, with reference to any rectangular axes.

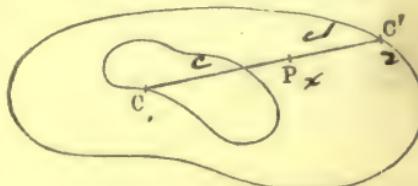


Fig. 21.

\* This simple and elegant theorem appeared, in a modified form, as the Prize Question, by Mr. Holditch, under the name of "Petrarch," in the Lady's and Gentleman's Diary for the year 1858. The first proof given above is due to Mr. Woolhouse, and contains his extension of Mr. Holditch's theorem.

Then, if  $\theta$  be the angle made by  $CC'$  with the axis of  $y$ , we have evidently

$$x_1 = x - c \sin \theta, \quad y_1 = y - c \cos \theta,$$

$$x_2 = x + c' \sin \theta, \quad y_2 = y + c' \cos \theta.$$

Hence we have

$$y_1 dx_1 = y dx - c \cos \theta (dx + y d\theta) + c^2 \cos^2 \theta d\theta;$$

$$y_2 dx_2 = y dx + c' \cos \theta (dx + y d\theta) + c'^2 \cos^2 \theta d\theta.$$

Multiplying the former equation by  $c'$ , and the latter by  $c$ , and adding, we get

$$c' y_1 dx_1 + c y_2 dx_2 = (c + c') y dx + (c + c') cc' \cos^2 \theta d\theta;$$

$$\therefore c' \int y_1 dx_1 + c \int y_2 dx_2 = (c + c') \int y dx + (c + c') cc' \int \cos^2 \theta d\theta.$$

If we suppose the rod to make a complete revolution, so as to return to its original position, and if we denote by  $(C)$ ,  $(C')$ ,  $(P)$ , the areas of the curves described by the points  $C$ ,  $C'$ , and  $P$ , respectively, we shall have (since in this case the angle  $\theta$  revolves through  $2\pi$ )

$$c'(C) + c(C') = (c + c')(P) + \pi(c + c')cc',$$

$$\text{or } \frac{c'(C) + c(C')}{c + c'} = (P) + \pi cc'. \quad (16)$$

This determines the area  $(P)$  in terms of the areas  $(C)$ ,  $(C')$  and of the segments  $c$ ,  $c'$ .

When the extremities  $C$ ,  $C'$  move on the same identical curve we have  $(C) = (C')$ , and hence  $(C) - (P) = \pi cc'$ .

Consequently, if a chord of given length move inside any closed curve, having a tracing point  $P$  at the distances  $c$  and  $c'$  from its ends, the area comprised between the two curves is equal to  $\pi cc'$ .

More generally, if the extremities  $C$ ,  $C'$  move on curves of equal area, we have, as before,

$$(C) - (P) = \pi cc'. \quad (17)$$

Should the extremities, instead of revolving, oscillate back to their former positions, then  $(C) = 0$ ,  $(C') = 0$ , and

$\therefore (P) = -\pi cc'$ . The negative sign implies that the area is described in a direction contrary to that in which the rod revolves.

Again, if the rod returns to its original position after  $n$  revolutions, the limits for  $\theta$  become 0 and  $2n\pi$ , and equation (16) becomes

$$\frac{c'(C) + c(C')}{c + c'} = (P) + n\pi cc'. \quad (18)$$

If  $(C) = (C')$ , this gives

$$(C) - (P) = n\pi cc'. \quad (19)$$

If the line oscillate back to its former position, without making a revolution, we have  $n = 0$ , and (19) becomes

$$(C) = (P).$$

Hence, in this case, if two points describe curves of equal area, then any point on the line joining these points describes a curve of the same area.

The theorem in (16) can also be proved simply in another manner, as follows:—

Let  $O$  denote the point of intersection of the moving line  $CC'$  with its infinitely near position; that is to say, the point of contact with its envelope; and let  $OP = r$ . Adopting the same notation as before, let  $(O)$  represent the area of the envelope, and it is easily seen that

$$(C) - (O) = \frac{1}{2} \int_0^{2\pi} (OC)^2 d\theta = \frac{1}{2} \int_0^{2\pi} (c - r)^2 d\theta,$$

$$(C') - (O) = \frac{1}{2} \int_0^{2\pi} (OC')^2 d\theta = \frac{1}{2} \int_0^{2\pi} (c' + r)^2 d\theta,$$

$$(P) - (O) = \frac{1}{2} \int (OP)^2 d\theta = \frac{1}{2} \int r^2 d\theta;$$

hence

$$\begin{aligned} c'(C) + c(C') - (c + c')(P) &\approx \frac{1}{2} \int_0^{2\pi} \{c'(c - r)^2 + c(c' + r)^2 - (c + c')r^2\} d\theta \\ &= cc'(c + c')\pi, \end{aligned}$$

as before.

A remarkable extension of Holditch's theorem was given by Mr. E. B. Elliott, in the *Messenger of Mathematics*, February, 1878.

Mr. Elliott supposed the length of the moving line  $C'C$  to vary, but that it is in all positions divided in the constant ratio  $m : n$  in a point  $P$ .

Then, if  $C$  travel round the perimeter of any closed area ( $C$ ), and  $C'$  move simultaneously round another area ( $C'$ ), the two motions being quite independent and subject to no restrictions whatever, except that both are continuous, having no abrupt passage from one position to another finitely differing from it, then  $P$  will travel simultaneously round the perimeter of another closed area ( $P$ ).

Adopting the same notation as before, we have

$$(m+n)x = mx_1 + nx_2, \quad (m+n)y = my_1 + ny_2;$$

$$\begin{aligned} \therefore (m+n)^2 y dx &= (my_1 + ny_2)(m dx_1 + n dx_2) \\ &= m^2 y_1 dx_1 + n^2 y_2 dx_2 + mn (y_2 dx_1 + y_1 dx_2) \\ &= (m+n)(my_1 dx_1 + ny_2 dx_2) - mn (y_2 - y_1) d(x_2 - x_1). \end{aligned}$$

Integrating for a complete circuit, and dividing by  $(m+n)$ , we have

$$(m+n)(P) = m(C) + n(C') - \frac{mn}{m+n} \int (y_2 - y_1) d(x_2 - x_1). \quad (20)$$

This result is stated as follows by Mr. Elliott:—

Through any fixed point in the plane of a closed area  $S$  let radii vectores be drawn to all points in its perimeter, and let chords  $AB$ , parallel and equal to the radii vectores, be placed with one extremity  $A$  in each case in the perimeter of a closed area ( $A$ ), and the other  $B$  on that of another ( $B$ ); then, if the points  $A, B$ , travel respectively all round the perimeters, and do not in either case return to their first positions from the same sides as that towards which they left them; and, if

(C) represent the area described by a point always dividing BA in the constant ratio  $m : n$ , then the areas (A), (B), (C), (S) are connected by the following relation :

$$(C) = \frac{m(A) + n(B)}{m+n} - \frac{mn}{(m+n)^2} (S). \quad (21)$$

This follows immediately from (20) by altering the notation.

Areas described in opposite directions of rotation must be taken with opposite signs.

For particular modifications in this result, as also for its extension to surfaces, the student is referred to Mr. Elliott's paper ; as also to Mr. Leudesdorf's papers in the same Journal.

147 (a). **Kempe's Theorem.**—We next proceed to the consideration of a singularly elegant theorem\* discovered by Mr. Kempe, and which may be stated as follows :—

If one plane sliding upon another start from any position, move in any manner, and return to its original position after making one or more complete revolutions ; then every point in the moving area describes a closed curve, and the locus, in the moving plane, of points which describe equal areas is a circle ; and by varying the area we get a system of concentric circles for loci.

This result can be readily deduced from Holditch's theorem, for if we suppose A, B, C, to be three points which generate equal areas ; it can easily be seen that any fourth point, D, which generates the same area, lies on the circle circumscribing ABC.

Let AB and CD intersect in P, then, let (P) represent the area described by the point P, as before ; and  $n$  the number of revolutions made before AB returns to its original position : then we have, by (19), denoting by

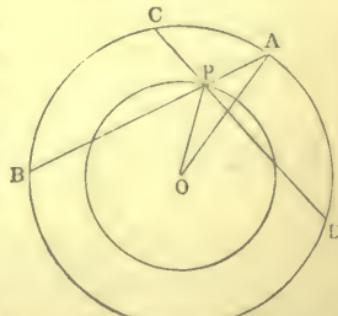


Fig. 22.

\* *Messenger of Mathematics*, July, 1878.

(C) the common area described by each of the points  $A, B, C, D$ ,

$$(C) - (P) = n\pi AP \cdot PB,$$

and, by same theorem,

$$(C) - (P) = n\pi CP \cdot PD;$$

hence

$$AP \cdot PB = CP \cdot PD;$$

consequently  $A, B, C, D$ , lie on the circumference of the same circle.

Again, let  $O$  be the centre of this circle, and join  $OP$  and  $OA$ , then the preceding equation gives

$$(C) - (P) = n\pi (OA^2 - OP^2).$$

Hence all points which describe an area equal to that of (P) lie on a circle, having  $O$  for centre, and  $OP$  for radius, which establishes the second part of the theorem.

For the effect of two or more loops in the area described by a moving point see Art. 132.

**148. Areas by Approximation.**—In many cases it is necessary to approximate to the value of the area included within a closed contour. The usual method is by drawing a convenient number of parallel ordinates at equal intervals; then, when a rough approximation is sufficient, we may regard the area of the curve as that of the polygon got by joining the points of intersection of the parallel ordinates with the curve. Hence, if  $h$  be the common distance between the ordinates, and if

$$y_0, y_1, y_2, \&c., y_n,$$

represent the system of parallel ordinates, the area of the polygon, since it consists of a number of trapezia of equal breadth, is plainly represented by

$$h \left\{ \frac{y_0 + y_n}{2} + y_1 + y_2 + \&c. + y_{n-1} \right\}.$$

[14 a]

Hence the rule: *add together the halves of the extreme ordinates, and the whole of the intermediate ordinates, and multiply the result by the common interval.*

When a nearer approximation is required, the method next in simplicity supposes the curve to consist of a number of parabolic arcs; each parabola having its axis parallel to the equidistant ordinates, and being determined by three of those ordinates.

To find the area of the parabola passing through the points whose ordinates are  $y_0, y_1, y_2$ ; let  $y = a + \beta x + \gamma x^2$  be the equation of the parabola, and, for simplicity, assume the origin at the foot of the intermediate ordinate  $y_1$ , then we have

$$y_0 = a - \beta h + \gamma h^2, \quad y_1 = a, \quad y_2 = a + \beta h + \gamma h^2.$$

Again, the area between the first and third ordinate is

$$\int_{-h}^h (a + \beta x + \gamma x^2) dx = 2h \left( a + \gamma \frac{h^2}{3} \right).$$

But  $y_0 + y_2 = 2y_1 + 2\gamma h^2$ : hence the area in question is

$$\frac{h}{3} \{ y_0 + 4y_1 + y_2 \}.$$

Now, if we suppose the number of intervals  $n$  to be even, and add the different parabolic areas, we get, as an approximation to the area, the expression

$$\frac{h}{3} \{ y_0 + y_n + 4(y_1 + y_3 + \&c. + y_{n-1}) + 2(y_2 + y_4 + \&c. + y_{n-2}) \}.$$

Hence the rule: *add together the first and last ordinates, twice every second intermediate ordinate, and four times each remaining ordinate; and multiply by one-third of the common interval.*

We get a closer approximation by supposing the number of equal intervals a multiple of 3, and regarding the curve as a series of parabolæ of the third degree, each being determined by four equidistant ordinates. To find the area corresponding to one of these parabolic curves, let  $y_0, y_1, y_2, y_3$  be four equidistant ordinates, and for convenience assume

the origin midway between  $y_1$  and  $y_2$ ; then if the equation of the parabolic curve be

$$y = a + \beta x + \gamma x^2 + \delta x^3,$$

and the common interval on the axis of  $x$  be denoted by  $2h$ , we have

$$y_0 = a - 3\beta h + 9\gamma h^2 - 27\delta h^3,$$

$$y_1 = a - \beta h + \gamma h^2 - \delta h^3,$$

$$y_2 = a + \beta h + \gamma h^2 + \delta h^3,$$

$$y_3 = a + 3\beta h + 9\gamma h^2 + 27\delta h^3.$$

Hence  $y_0 + y_3 = 2(a + 9\gamma h^2)$ ,  $y_1 + y_2 = 2(a + \gamma h^2)$ .

Again, the parabolic area between  $y_0$  and  $y_3$  is

$$\int_{-3h}^{3h} (a + \beta x + \gamma x^2 + \delta x^3) dx = 3h(2a + 6\gamma h^2).$$

Substituting in this the values of  $a$  and  $\gamma$  obtained from the two preceding equations, the expression for the area becomes

$$\frac{3h}{4} \{y_0 + y_3 + 3(y_1 + y_2)\}.$$

If the corresponding expressions be added together, we easily arrive at the following rule:—Add together the first and last ordinates, *twice* every third intermediate ordinate, and *thrice* each remaining ordinate; and multiply by  $\frac{3}{8}$ ths of the common interval.

It is readily seen that these rules also apply to the approximation to any closed area, by drawing a system of lines, parallel and equidistant, and adopting the intercepts made by the curve instead of the ordinates, in each rule.

Since every definite integral may be represented by a

\* This and the preceding are commonly called "Simpson's rules" for calculating areas; they were however previously noticed by Newton (see *Opuscula. Method. Diff.*, Prop. 6, scholium) as a particular application of the method of interpolation. By taking seven equidistant ordinates, Mr. Weddle (*Camb. and Dub. Math. Jour.*, 1854), obtained the following simple and important rule for finding the area:—*To five times the sum of the even ordinates add the middle ordinate and all the odd ordinates, multiply the sum by three-tenths of the common interval, and the product will be the required area, approximately.* The proof, which is too long for insertion here, will be found in Mr. Weddle's memoir: and also, with applications, in Boole's *Calculus of Finite Differences*. The student is referred to Bertrand's *Cale. Int.*, l. 1, ch. xii., for more general and accurate methods of approximation by Cotes and Gauss.

curvilinear area, the methods given above are applicable to the approximate determination of any such integral.

In practice the accuracy of these methods is increased by increasing the number of intervals.

149. **Planimeters.**—Several mechanical contrivances have been introduced for the purpose of practically estimating the area inclosed within any curved boundary. Such instruments are called Planimeters. The simplest and most elegant is that of Professor Amsler of Schaffhausen. It consists of two arms jointed together so as to move in perfect freedom in one plane. A point at the extremity of one arm is made a fixed centre round which the instrument turns; and a wheel is fixed to, and turns on the other arm as an axis, and records by its revolution the area of the figure traced out by a point on this arm. From its construction it is plain that the revolving wheel registers only the motion which is perpendicular to the moving arm on which it revolves.

In the practical application of the instrument it is necessary that the two arms,  $CA$  and  $AB$ , should return to their original position after the tracing point  $B$  has been moved round the entire boundary of the required area.

We shall commence by showing that the length registered by the wheel while  $B$  has moved round the entire closed area is independent of the wheel's position on the moving arm; i.e. is the same as if the wheel be supposed placed at the joint.

To prove this, suppose  $P$  to represent the point on the arm at which the centre of the revolving wheel is situated. Let  $A'B'$  represent a new position of  $AB$  very near to  $AB$ , and  $P'$  the corresponding position of the point  $P$ . Draw  $PN$  perpendicular to  $A'B'$ ; then  $PN$  represents the length registered by the wheel while the arm moves from  $AB$  to the infinitely near position  $A'B'$ .

Next, draw  $AN'$  perpendicular, and  $AL$  parallel, to  $A'B'$ .

Let  $PN = ds'$ ,  $AN' = ds$ ,  $AP = c$ ,  $PAL = d\phi$ ; then  $PN = PL + AN'$ , or  $ds' = ds + c d\phi$ .

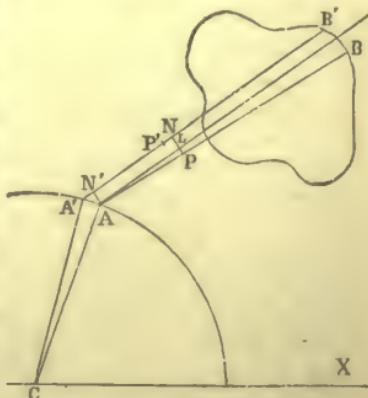


Fig. 23.

Now, if we suppose  $AB$  after a complete circuit of the curve to return to its original position, we have obviously  $\Sigma(d\phi) = 0$ ; and therefore  $\Sigma(ds') = \Sigma(ds)$ , i.e. the whole length registered by the revolving wheel at  $P$  is the same as if it were placed at  $A$ .

Next, let  $x$  and  $y$  be the co-ordinates of  $B$  with respect to rectangular axes drawn through  $C$ , and let  $AC = a$ ,  $AB = b$ ,  $\angle ACX = \theta$ ; and suppose  $\phi$  the angle which  $BA$  produced makes with the axis of  $x$ ; then we shall have

$$x = a \cos \theta + b \cos \phi, \quad y = a \sin \theta + b \sin \phi.$$

$$\text{Hence } xdy - ydx = a^2 d\theta + b^2 d\phi + ab \cos(\theta - \phi) d(\theta + \phi).$$

$$\text{Also } ds = AN' = AA' \sin AA'N = a d\theta \cos(\theta - \phi).$$

$$\text{But } \theta + \phi = 2\theta - (\theta - \phi);$$

$$\therefore ab \cos(\theta - \phi) d(\theta + \phi)$$

$$= 2ab \cos(\theta - \phi) d\theta - ab \cos(\theta - \phi) d(\theta - \phi)$$

$$= 2bds - ab \cos(\theta - \phi) d(\theta - \phi).$$

Consequently

$$xdy - ydx = a^2 d\theta + b^2 d\phi + 2bds - ab \cos(\theta - \phi) d(\theta - \phi).$$

But, by Art. 139, the area traced out by  $B$  in a complete revolution is represented by  $\frac{1}{2} \int (xdy - ydx)$  taken around the entire curve.

Also, since  $AC$  and  $AB$  return to their original positions, the integrals of the terms  $a^2 d\theta$ ,  $b^2 d\phi$  and  $ab \cos(\theta - \phi) d(\theta - \phi)$  disappear; and hence the area in question is equal to  $bS$ , where  $S$  denotes the entire length registered by the revolving wheel.

On account of the importance of the principle of this instrument, the following proof, for which I am indebted to Prof. Ball, based on elementary geometrical principles, is also added.

Let  $C, A, B$  represent, as before, the positions of the fixed centre, the joint, and the tracing point, respectively; and suppose  $R$  to represent the position of the roller, or revolving wheel; then draw  $CP$  and  $RS$  perpendicular to  $AB$ .

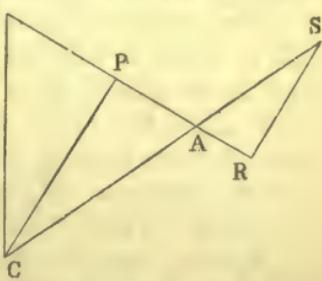


Fig. 24.

Let  $AC = a$ ,  $AB = b$ ,  $AR = l$ ,  $BC = r$ .

Now, if the instrument be rotated about  $C$  through an angle  $\theta$  without altering the angle  $CAB$ , it is easily seen that the circumference of the roller is rotated through an arc represented by

$$PR \cdot \theta = \left( l + \frac{a^2 + b^2 - r^2}{2b} \right) \theta.$$

Again, if the instrument be rotated about  $S$  through a small angle the roller does not revolve. Hence a curve can be drawn through  $B$ , such that, if the tracing point  $B$  be moved along it, the roller will not revolve.

Now, let  $\lambda\mu$ ,  $\lambda'\mu'$  be the two adjacent circles described with  $C$  as centre, and suppose  $aa'$  and  $\beta\beta'$  two adjacent non-rolling curves, such as just stated: and suppose the tracing point  $B$  to move round the indefinitely small area  $aa'\beta\beta'$ : then the arc through which the roller has turned is represented by

$$\left( l + \frac{a^2 + b^2 - r^2}{2b} \right) \delta\theta - \left( l + \frac{a^2 + b^2 - (r + \delta r)^2}{2b} \right) \delta\theta$$

$$= \frac{r \delta r \delta\theta}{b} = \text{area of } \frac{aa'\beta'\beta}{b},$$

since  $a\beta = r\delta\theta$ ; and  $\delta r = aa' \sin \beta$ .

Now suppose the instrument works correctly for the area  $\lambda\lambda'a'a$ , then it will work correctly for the area  $\lambda\lambda'\beta'\beta$ ; for, start from  $a$  to  $\lambda$ ,  $\lambda'$ ,  $a'$ , then the area  $a\lambda\lambda'a'$  must be registered, since the roller does not turn in moving from  $a'$  to  $a$ ; proceed then from  $a'$  to  $\beta'$ ,  $\beta$ ,  $a$ , then, by what has been just proved, the area  $a'\beta'\beta a$  will be added. Hence the instrument will work correctly for the strip  $\lambda\lambda'\mu'\mu$ .

Again, suppose the instrument works correctly for the area  $\lambda\mu\rho$ , then it will work correctly for  $\lambda'\mu'\rho$ ; for suppose we start from  $\lambda$  to  $\rho$ ,  $\mu$ , and back to  $\lambda$ : then start from  $\lambda$  to

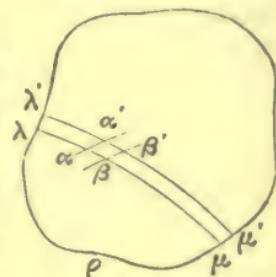


Fig. 25.

$\mu$ ,  $\mu'$ ,  $\lambda'$  and  $\lambda$ ; the two journeys from  $\lambda$  to  $\mu$  and  $\mu$  to  $\lambda$  will neutralize each other, and it follows that if the instrument works correctly for the area  $\lambda\mu\rho$ , it will work correctly for the area  $\lambda'\mu'\rho$ : hence, if the instrument works correctly for any portion of the area, however small, it works correctly for the entire area.

The student will find a description of Amsler's Planimeter, with another mode of demonstration, in a communication by Mr. F. J. Bramwell, C.E., to the British Association.—See Report, 1872, pp. 401-412.

## EXAMPLES.

1. Find the whole area between the curve

$$x^2 y^2 + a^2 b^2 = a^2 y^2$$

and its asymptotes.

$$Ans. 2\pi ab.$$

2. Find the whole area of the curve

$$a^2 y^4 = x^4 (a^2 - x^2). \quad , , \quad \frac{8a^3}{5}.$$

3. Find the whole area of the curve

$$\left(\frac{x}{a}\right)^2 + \left(\frac{y}{b}\right)^{\frac{3}{2}} = 1. \quad , , \quad \frac{3}{4} \pi ab.$$

4. Find the whole area included between the folium of Descartes

$$x^3 + y^3 - 3axy = 0$$

and its asymptote.

$$Ans. \frac{3a^2}{2}.$$

5. In the logarithmic curve  $y = a^x$ , prove that the area between the axis of  $x$  and any two ordinates is proportional to the difference between the ordinates.

6. Find the area of a loop of the curve

$$r = a \cos n\theta. \quad Ans. \frac{\pi a^2}{n}.$$

7. Find the area of a loop of the curve

$$r = a \cos n\theta + b \sin n\theta. \quad , , \quad (a^2 + b^2) \frac{\pi}{n}.$$

The equation of the curve may be written in the form

$$r = \sqrt{a^2 + b^2} \cos(n\theta + \alpha),$$

where  $\tan \alpha = -\frac{b}{a}$ ; and consequently its area can be found from the preceding example.

8. Find the area of a loop of the curve

$$r^2 = a^2 \cos n\theta + b^2 \sin n\theta. \quad Ans. \frac{\sqrt{a^4 + b^4}}{n}.$$

## 9. Find the area of the tractrix.

The characteristic property of the tractrix is that the intercept on a tangent to the curve between its point of contact and a fixed right line is constant.

Denoting the constant by  $a$ , and taking the origin  $O$  at the point for which the tangent  $OA$  is perpendicular to the axis, we have,  $P$  being any point on the curve

$$PT = a, \quad PN = y,$$

$$\frac{dy}{dx} = -\tan PTN = -\frac{y}{\sqrt{a^2 - y^2}};$$

$$\therefore y dx = -\sqrt{a^2 - y^2} dy.$$

Hence the element of the area of the tractrix is equal to that of a circle of radius  $a$ .

It follows immediately that the whole area between the four infinite branches of the tractrix is equal to  $\pi a^2$ . This example furnishes an instance of our being able to determine the area of a curve from a geometrical property of the curve, without a previous determination of its equation.

If the equation of the tractrix be required, it can be derived from its differential equation

$$dx = -\frac{\sqrt{a^2 - y^2} dy}{y},$$

from which we get

$$x + \sqrt{a^2 - y^2} = a \log \frac{a + \sqrt{a^2 - y^2}}{y}.$$

That the equation of the tractrix depends on logarithms was noticed by Newton. See his Second Epistle to Oldenburg (Oct. 1676). This was, I believe, the first example of the determination of the equation of a curve by integration; or, what at the time was called the *inverse method of tangents*.

10. If each focal radius vector of an ellipse be produced a constant length  $c$ , show that the area between the curve so formed and the ellipse is  $\pi c(2b + c)$ ,  $b$  being the semi-axis minor of the ellipse.

11. Find the area of a loop of the curve  $r^n = a^n \cos n\theta$ .

$$Ans. \frac{a^2 \sqrt{\pi}}{2} \frac{\Gamma\left(\frac{1}{2} + \frac{1}{n}\right)}{\Gamma\left(\frac{1}{n}\right)}$$

12. If a right line carrying three tracing points  $A$ ,  $B$ ,  $C$ , move in any manner in a plane, returning to its original position after making a complete revolution; and if  $(A)$ ,  $(B)$ ,  $(C)$  represent the entire areas of the closed curves described by the points  $A$ ,  $B$ ,  $C$ , respectively, prove that

$$BC \times (A) + CA \times (B) + AB \times (C) + \pi \cdot AB \cdot BC \cdot CA = 0,$$

in which the lines  $AB$ ,  $BC$ , &c., are taken with their proper signs; i.e.,  $AB = -BA$ , &c.

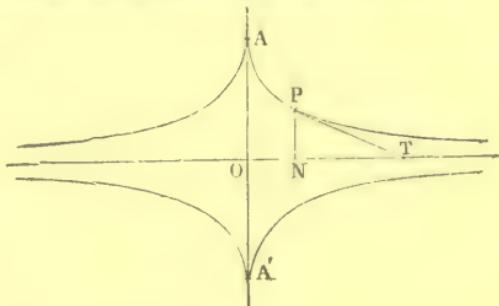


Fig. 26.

13.  $A, B, C, D$ , are four points rigidly connected together, and moving in any way in a plane; if they describe closed curves, of areas  $(A)$ ,  $(B)$ ,  $(C)$ ,  $(D)$ , respectively; and if  $x, y, z$ , be the areolar coordinates of  $D$  referred to the triangle  $ABC$ , prove that

$$(D) = x(A) + y(B) + z(C) + \pi t^2.$$

where  $t$  is the length of the tangent from  $D$  to the circle circumscribed to the triangle  $ABC$ . Mr. Leudesdorf, *Messenger of Mathematics*, 1878.

This follows immediately: for let  $P$  be the point of intersection of the lines  $AB$  and  $CD$ , then, by (18), we get a relation between  $(A)$ ,  $(B)$ , and  $(P)$ ; and also between  $(C)$ ,  $(D)$ , and  $(P)$ . If  $P$  be eliminated between these equations we get the required result.

14. Show that a corresponding equation connects the areas of the pedals of any given closed curve with respect to four points  $A, B, C, D$ , taken respectively as pedal origin. *Mr. Leudesdorf.*

15. If a curve be referred to its radius vector  $r$  and the perpendicular  $p$  on the tangent, prove that its area is represented by

$$\frac{1}{2} \int \frac{pr dr}{\sqrt{r^2 - p^2}}.$$

16. A chord of constant length  $(c)$  moves about within a parabola, and tangents are drawn at its extremities; find the total area between the parabola and the locus of intersection of the tangents.

$$\text{Ans. } \frac{\pi c^2}{2}.$$

17. From the centre of an ellipse a tangent is drawn to a semicircle described on an ordinate to the axis major; prove that the polar equation of the locus of the point of contact is

$$r^2 = \frac{a^2 b^2}{b^2 + (a^2 + b^2) \tan^2 \theta};$$

and that the whole area of the locus is

$$\frac{\pi}{2} \frac{a^2 b}{\sqrt{a^2 + b^2 + b}}.$$

18. Apply the three methods of approximation of Art. 148 to the calculation to 6 decimal places of the definite integral  $\int_0^1 \frac{dx}{1+x}$ , adopting  $\frac{1}{12}$  as the common interval in each case. *Ans.* (1), .693669. (2), .693266. (3), .693224.

The real value of the integral being  $\log 2$ , or .693147, to the same number of decimal places.

19. Prove that the sectorial area bounded by two focal vectors  $r$  and  $r'$  of a parabola is represented by

$$\frac{a^2}{3} \left\{ \left( \frac{r + r' + c}{2} \right)^{\frac{3}{2}} - \left( \frac{r + r' - c}{2} \right)^{\frac{3}{2}} \right\},$$

where  $c$  is the chord of the arc, and  $a$  the semiparameter of the parabola.

20. Show that the whole area of the inverse of the ellipse  $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$  is represented by

$$\frac{\pi k^4}{\left(1 - \frac{\alpha^2}{a^2} - \frac{\beta^2}{b^2}\right)^2} \left\{ \frac{1}{a^2} + \frac{1}{b^2} + \left( \frac{1}{a^2} - \frac{1}{b^2} \right) \left( \frac{\alpha^2}{a^2} - \frac{\beta^2}{b^2} \right) \right\},$$

where  $\alpha, \beta$ , are the co-ordinates of the origin of inversion, and  $k$  is the radius of the circle of inversion.

21. A given arc of a plane curve turns through a given angle round a fixed point in its plane; what is the area described?

22. Given the base of a triangle, prove that the polar equation of the locus of its vertex, when the vertical angle is double one of its base angles is

$$r = \frac{a(2 \cos 2\theta + 1)}{2 \cos \theta}.$$

Hence show that the entire area of the loop of the curve is  $\frac{3a^2\sqrt{3}}{4}$ .

23.  $O$  is a point within a closed oval curve,  $P$  any point on the curve,  $QPO$  a straight line drawn in a given direction such that  $QP = PQ' = PO$ ; prove that as  $P$  moves round the curve,  $Q, Q'$ , trace out two closed loops the sum of whose areas is twice the area of the original curve. *Camb. Trip. Exam., 1874.*

24. Prove that the area of the pedal of the cardioid  $r = a(1 - \cos \theta)$  taken with respect to an internal point at the distance  $c$  from the pole is

$$\frac{3\pi}{8} (5a^2 - 2ac + 2c^2). \quad (\text{Ibid., 1876.})$$

25. The co-ordinates of a point are expressed as follows :

$$x = \frac{3\theta}{\theta^3 + 1}, \quad y = \frac{3\theta^2}{\theta^3 + 1};$$

Find the equation of the curve described by the point, and the area of the portion of the plane inclosed thereby.

## CHAPTER VIII.

## LENGTHS OF CURVES.

150. **Length of Curves referred to Rectangular Axes.** The usual mode of considering the length of a curve is by treating it as the limit of a polygon when each of its sides is infinitely small. If the curve be referred to rectangular axes of co-ordinates, the length of the chord joining the points  $(x, y)$  and  $(x + dx, y + dy)$  is  $\sqrt{dx^2 + dy^2}$ , and, consequently, if  $s$  represent the length of the curve measured from a fixed point on it, we shall have  $ds = \sqrt{dx^2 + dy^2}$ , or, integrating,

$$s = \int \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx, \quad (1)$$

taken between suitable limits.

The value of  $\frac{dy}{dx}$  in terms of  $x$  is to be got from the equation of the curve, and thus the finding of  $s$  is reducible to a question of integration.

The determination of the length of an arc of a curve is called its *rectification*.

It is evident that if  $y$  be taken for the independent variable we shall have

$$s = \int \sqrt{1 + \left(\frac{dx}{dy}\right)^2} dy.$$

Again, when  $x$  and  $y$  are given functions of a single variable  $\phi$ , we have

$$s = \int \left\{ \left(\frac{dx}{d\phi}\right)^2 + \left(\frac{dy}{d\phi}\right)^2 \right\}^{\frac{1}{2}} d\phi.$$

In each case the form of the equation of the curve determines which of these formulæ should be employed.

The curves whose lengths can be obtained in finite terms (compare Art. 2) are very limited in number. We proceed to consider some of the simplest cases.

**151. The Parabola.**—Writing the equation of the parabola in the form  $y^2 = 2mx$ , we get  $\frac{dx}{dy} = \frac{y}{m}$ .

Hence  $s = \frac{1}{m} \int \sqrt{y^2 + m^2} dy.$

The value of this integral can be obtained from that of the area of a hyperbola (Art. 130), by substituting  $y$  for  $x$ , and  $m^2$  for  $-a^2$ .

Thus we have

$$s = \frac{y \sqrt{y^2 + m^2}}{2m} + \frac{m}{2} \log \left( \frac{y + \sqrt{y^2 + m^2}}{m} \right), \quad (2)$$

the arc being measured from the vertex of the curve.

**152. The Catenary.**—The equation of the catenary (Art. 131), is

$$y = \frac{a}{2} \left( e^{\frac{x}{a}} + e^{-\frac{x}{a}} \right).$$

Hence

$$\frac{dy}{dx} = \frac{1}{2} \left( e^{\frac{x}{a}} - e^{-\frac{x}{a}} \right),$$

$$\frac{ds}{dx} = \left( 1 + \frac{dy^2}{dx^2} \right)^{\frac{1}{2}} = \frac{1}{2} \left( e^{\frac{x}{a}} + e^{-\frac{x}{a}} \right),$$

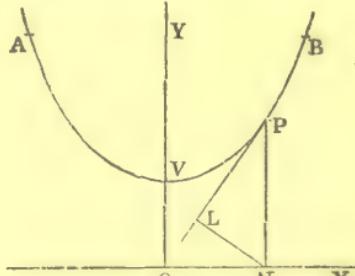


Fig. 27.

$$\therefore s = \frac{1}{2} \int e^{\frac{x}{a}} dx + \frac{1}{2} \int e^{-\frac{x}{a}} dx = \frac{a}{2} \left( e^{\frac{x}{a}} - e^{-\frac{x}{a}} \right) + \text{const.}$$

If  $s$  be measured from the vertex  $V$ , we have

$$s = \frac{a}{2} \left( e^{\frac{x}{a}} - e^{-\frac{x}{a}} \right);$$

the same result as already arrived at in Art. 131.

Again, since  $PL = PV$ , and  $NL$  is constant, it follows that the catenary is the evolute of the tractrix (see Ex. 9, p. 219).

153. **Semi-cubical Parabola.**—The equation of this curve is of the form  $ay^2 = x^3$ .

hence  $y = \frac{x^{\frac{3}{2}}}{a^{\frac{1}{2}}}; \therefore \frac{dy}{dx} = \frac{3}{2} \left( \frac{x}{a} \right)^{\frac{1}{2}}, \quad \frac{ds}{dx} = \left( 1 + \frac{9x}{4a} \right)^{\frac{1}{2}};$   
 $\therefore s = \int \left( 1 + \frac{9x}{4a} \right)^{\frac{1}{2}} dx = \frac{8a}{27} \left( 1 + \frac{9x}{4a} \right)^{\frac{3}{2}} + \text{const.}$

If the arc be measured from the vertex, we get

$$s = \frac{8a}{27} \left\{ \left( 1 + \frac{9x}{4a} \right)^{\frac{3}{2}} - 1 \right\}.$$

The semi-cubical parabola is the first curve whose length was determined. This result was discovered by William Neil, in 1660.

154. **Rectification of Evolutes.**—It may be noted that the rectification of the semi-cubical parabola is an immediate consequence of its being the evolute of the ordinary parabola (see Diff. Calc., Art. 239). In like manner the length of any curve can be found if it be the evolute of a known curve, from the property that any portion of the arc of the evolute is the difference between the two corresponding radii of curvature of the curve of which it is the evolute.

For example, we get by this means the lengths of the cycloid, the epicycloid and the hypocycloid.

Again, since the equation of the evolute of an ellipse is

$$(ax)^{\frac{2}{3}} + (by)^{\frac{2}{3}} = (a^2 - b^2)^{\frac{2}{3}},$$

the length of any arc of this curve can be at once found.

This can also be readily got otherwise; for, writing the equation in the form

$$\left( \frac{x}{a} \right)^{\frac{2}{3}} + \left( \frac{y}{\beta} \right)^{\frac{2}{3}} = 1,$$

and making  $x = a \sin^3 \phi$ , we get  $y = \beta \cos^3 \phi$ , and

$$ds = (dx^2 + dy^2)^{\frac{1}{2}} = 3 \sin \phi \cos \phi (a^2 \sin^2 \phi + \beta^2 \cos^2 \phi)^{\frac{1}{2}} d\phi$$

$$= \frac{3(a^2 \sin^2 \phi + \beta^2 \cos^2 \phi)^{\frac{1}{2}}}{2(a^2 - \beta^2)} d(a^2 \sin^2 \phi + \beta^2 \cos^2 \phi).$$

Hence

$$s = \frac{(a^2 \sin^2 \phi + \beta^2 \cos^2 \phi)^{\frac{1}{2}}}{a^2 - \beta^2} + \text{const.}$$

If the arc be measured from the point  $x = 0, y = \beta$ , we get the constant

$$= \frac{-\beta^3}{a^2 - \beta^2}, \text{ and } s = \frac{(a^2 \sin^2 \phi + \beta^2 \cos^2 \phi)^{\frac{1}{2}} - \beta^3}{a^2 - \beta^2}.$$

If  $a = \beta$ , the expression for  $ds$  becomes  $3a \sin \phi \cos \phi d\phi$ ; hence we get  $s = \frac{3}{2} a \sin^2 \phi$ , the arc being measured from the same point as above.

### EXAMPLES.

1. Find the length of the logarithmic curve  $y = ca^x$ .

Here  $\log y = x \log a + \log c$ ;  $\therefore \frac{dx}{dy} = \frac{b}{y}$ , where  $b = \frac{1}{\log a}$ .

Hence  $s = \int \frac{(b^2 + y^2)^{\frac{1}{2}} dy}{y} = \int \frac{y dy}{(b^2 + y^2)^{\frac{1}{2}}} + \int \frac{b^2 dy}{y(b^2 + y^2)^{\frac{1}{2}}}$   
 $= (b^2 + y^2)^{\frac{1}{2}} + b \log \frac{(b^2 + y^2)^{\frac{1}{2}} - b}{y}.$

2. Find the length of the tractrix.

Here, by definition (see fig. 26), we have  $PT = a$ ;

$$\therefore \sin PTN = \frac{y}{a}, \quad \text{hence } \frac{ds}{dy} = -\frac{a}{y};$$

$$\therefore s = -a \int \frac{dy}{y} = -a \log y + \text{const.}$$

If the arc be measured from the vertex  $A$ , we get

$$\text{arc } AP = a \log \left( \frac{a}{y} \right).$$

3. Find in what cases the curves represented by  $a^m y^n = x^{m+n}$  are rectifiable.

Here we have

$$s = \int \left\{ 1 + \left( \frac{m+n}{n} \right)^2 \left( \frac{x}{a} \right)^{\frac{2m}{n}} \right\}^{\frac{1}{2}} dx.$$

Substituting  $b$  for  $\frac{(m+n)^2}{\frac{2m}{n^2 a^n}}$ , and making  $1 + bx^{\frac{2m}{n}} = z^2$ , this becomes

$$s = \frac{n}{mb} \int \left( \frac{z^2 - 1}{b} \right)^{\frac{n}{2m} - 1} z^2 dz.$$

This expression is immediately integrable when  $\frac{n}{2m}$  is a positive integer.

Hence, if  $\frac{n}{2m} = r$ , we see that curves of the form  $ay^{2r} = x^{2r+1}$  are rectifiable.

Again, if  $\frac{n}{2m}$  be a negative integer, the expression under the integral sign becomes rational, and can accordingly be integrated. This leads to the form  $y^{2r} = ax^{2r-1}$ . Accordingly, all curves comprised in the equation  $ay^m = x^{m+1}$  are rectifiable,  $m$  being any integer. (Compare Art. 62).

**155. The Ellipse.**—The simplest expression for the arc of an ellipse is obtained by taking  $x = a \sin \phi$ , whence

$$y = b \cos \phi, \text{ and } ds = (a^2 \cos^2 \phi + b^2 \sin^2 \phi)^{\frac{1}{2}} d\phi;$$

$$\therefore s = \int (a^2 \cos^2 \phi + b^2 \sin^2 \phi)^{\frac{1}{2}} d\phi.$$

It is often more convenient to write this in the form

$$s = a \int (1 - e^2 \sin^2 \phi)^{\frac{1}{2}} d\phi, \quad (3)$$

$e$  being the eccentricity of the ellipse.

It may be observed that  $\phi$  is the complement of the *eccentric angle* belonging to the point  $(x, y)$ .

The length of an elliptic quadrant is represented by the definite integral

$$a \int_0^{\frac{\pi}{2}} (1 - e^2 \sin^2 \phi)^{\frac{1}{2}} d\phi.$$

We postpone the further consideration of elliptic arcs to a subsequent part of the Chapter.

**156. Rectification in Polar Co-ordinates.**—If the curve be referred to polar co-ordinates we plainly have (Diff. Calc., Art. 180)  $ds^2 = dr^2 + r^2 d\theta^2$ ; hence we get

$$s = \int \left( r^2 + \frac{dr^2}{d\theta^2} \right)^{\frac{1}{2}} d\theta, \quad \text{or } s = \int \left( 1 + \frac{r^2 d\theta^2}{dr^2} \right)^{\frac{1}{2}} dr. \quad (4)$$

For example, the length of the spiral of Archimedes,  $r = a\theta$ , is given by the equation

$$s = \frac{1}{a} \int (r^2 + a^2)^{\frac{1}{2}} dr.$$

Comparing this with the formula (2) for the parabola, it follows that the length of any arc of the spiral, measured from its pole, is equal to that of a parabola measured from its vertex.

### EXAMPLES.

1. Cardioid,  $r = a(1 + \cos \theta)$ .

Here  $\frac{dr}{d\theta} = -a \sin \theta$ , and hence

$$s = a \int \{(1 + \cos \theta)^2 + \sin^2 \theta\}^{\frac{1}{2}} d\theta = 2a \int \cos \frac{\theta}{2} d\theta = 4a \sin \frac{\theta}{2} + \text{constant}.$$

The constant becomes zero if we measure  $s$  from the point for which  $\theta = 0$ .

2. Logarithmic spiral,  $r = a\theta$ .

Here, if  $b = \frac{1}{\log a}$ , we get

$$\frac{r d\theta}{dr} = b; \quad \therefore s = \int_{r_0}^{r_1} (1 + b^2)^{\frac{1}{2}} dr = (1 + b^2)^{\frac{1}{2}} (r_1 - r_0).$$

Accordingly, the length of any arc is proportional to the difference between the vectors of its extremities; a result which also follows immediately from the property that the curve cuts its radius vector at a constant angle.

3.  $r^m = a^m \cos m\theta$ .

Taking the logarithmic differentials, we get  $\frac{dr}{r d\theta} = -\tan m\theta$ ;

$$\therefore \frac{ds}{r d\theta} = \sec m\theta.$$

Hence  $s = a \int (\cos m\theta)^{\frac{1}{m}-1} d\theta$ .

Or, writing  $\phi$  for  $m\theta$ ,

$$s = \frac{a}{m} \int (\cos \phi)^{\frac{1}{m}-1} d\phi.$$

This is readily integrated when  $\frac{1}{m}$  is an integer (see Art. 56).

Whatever be the value of  $m$ , we can express the complete length of a loop of the curve in Gamma Functions. For if we integrate between 0 and  $\frac{\pi}{2}$ , we obviously get the length of half the loop.

Hence the length of the loop (Art. 122) is

$$\frac{a\sqrt{\pi}}{m} \frac{\Gamma\left(\frac{1}{2m}\right)}{\Gamma\left(\frac{m+1}{2m}\right)}.$$

**157. Formula of Legendre on Rectification.**—Another formula\* of considerable utility in rectification follows immediately from the result obtained in Art. 192, Diff. Calc. For, if this result be written in the form

$$\frac{d(s-t)}{d\omega} = p, \text{ we get } s-t = \int pd\omega. \quad (5)$$

Consequently, the total increment of  $s-t$  between any two points on a curve is equal to  $\int pd\omega$  taken between the same two points.

For example, in the parabola we have  $p = \frac{a}{\cos \omega}$ , and hence

$$s-t = a \int \frac{d\omega}{\cos \omega} = a \log \tan \left( \frac{\pi}{4} + \frac{\omega}{2} \right) + \text{const.}$$

If we measure the arc from the vertex of the curve, and observe that  $t = \frac{dp}{d\omega}$ , this gives

$$s = \frac{a \sin \omega}{\cos^2 \omega} + a \log \tan \left( \frac{\pi}{4} + \frac{\omega}{2} \right).$$

The student can without difficulty identify this result with that given in Art. 151.

\* This theorem is due to Legendre. See *Traité des Fonctions Elliptiques*, tome ii., p. 588.

It should be observed that when the curve is closed, its whole length is, in general, represented by

$$\int_0^{2\pi} p d\omega.$$

Equation (5) furnishes a simple method of expressing the intrinsic equation of a curve, when we are given its equation in terms of  $p$  and  $\omega$ .

For, if  $p = f(\omega)$  we have

$$s = \frac{dp}{d\omega} + \int p d\omega = f'(\omega) + \int f(\omega) d\omega, \quad (6)$$

taken between suitable limits.

**158. Application to Ellipse. Fagnani's Theorem.** In the ellipse we have

$$p^2 = a^2 \cos^2 \omega + b^2 \sin^2 \omega.$$

Hence, measuring the arc from the vertex  $A$ , and observing that in this case  $PN$  is to be taken with a negative sign, we have

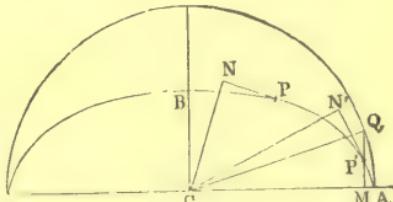


Fig. 28.

$$\text{arc } AP + PN = \int_0^a (a^2 \cos^2 \omega + b^2 \sin^2 \omega)^{\frac{1}{2}} d\omega,$$

where  $a = \angle ACN$ .

But, in Art. 155, we have found that if  $\phi$  be measured from the vertex  $B$ , the arc is represented by

$$\int (a^2 \cos^2 \phi + b^2 \sin^2 \phi)^{\frac{1}{2}} d\phi.$$

Consequently, if we make  $\angle BCQ = a = \angle ACN$ , and draw  $QM$  perpendicular to the axis major meeting the curve in  $P'$ , we shall have

$$\text{arc } BP' = \text{arc } AP + PN,$$

or, taking away the common arc  $PP'$ ,

$$BP - AP' = PN. \quad (7)$$

This remarkable result is known as Fagnani's Theorem\*, and shows that we can in an indefinite number of ways find two arcs of an ellipse whose difference is expressible by a right line.

We add a few properties connecting the points  $P$  and  $P'$  in this construction.

### EXAMPLES.

1. If  $(x, y)$  and  $(x', y')$  be the co-ordinates of  $P$  and  $P'$ , respectively; prove the following:—

$$(1). \quad PN = \frac{e^2 xx'}{a}, \quad (2). \quad PN = P'N', \quad (3). \quad CN \cdot CN' = CA \cdot CB,$$

$$(4). \quad CP^2 + CN'^2 = CA^2 + CB^2 = CP'^2 + CN^2.$$

2. Divide an elliptic quadrant into two parts whose difference shall be equal to the difference of the semiaxes.

This takes place when  $P$  and  $P'$  coincide; in which case  $CN = \sqrt{ab}$ , and  $PN = a - b$ .

We shall designate the point so determined on the elliptic quadrant as Fagnani's point.

3. Show that if a tangent be drawn at Fagnani's point, the intercepts between its point of contact and its points of intersection with the axes are respectively equal in length to the semi-axes of the ellipse.

4. If the lines  $PN$  and  $P'N'$  be produced to meet, show that they intersect on the confocal hyperbola which passes through the points of intersection of the tangents to the ellipse at its vertices. Show also that this hyperbola cuts the ellipse in Fagnani's point.

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\* Fagnani, *Giornale de' Letterati d'Italia*, 1716, reprinted in his *Produzioni Matematiche*, 1750. It may be noted that if we integrate the equation of Art. 116, *Diff. Calc.*, taking the angle  $C$  as obtuse, and adopting zero for the lowest limit in each integral, we obtain

$$\begin{aligned} & \int_0^a \sqrt{1 - k^2 \sin^2 a} da + \int_0^b \sqrt{1 - k^2 \sin^2 b} db \\ &= \int_0^e \sqrt{1 - k^2 \sin^2 c} dc + k^2 \sin a \sin b \sin e, \end{aligned}$$

where  $k$  is defined by the equation  $\sin C = k \sin e$ , and  $a, b, e$  are connected by the relation

$$\cos e = \cos a \cos b - \sin a \sin b \sqrt{1 - k^2 \sin^2 e}.$$

This equation furnishes a relation between three elliptic arcs, from which Fagnani's theorem can be readily deduced, as well as many other theorems connected with such arcs. See Legendre, *Fonc. Ellip.*, tome i., ch. 9.

The equation of  $PN$  is

$$x \sin \theta + y \cos \theta = \sqrt{a^2 \sin^2 \theta + b^2 \cos^2 \theta},$$

and that of  $P'N'$  is

$$\frac{x \cos \theta}{a} + \frac{y \sin \theta}{b} = 1.$$

If we eliminate  $\theta$ , we get

$$\frac{x^2}{a^2} - \frac{y^2}{b^2} = a - b,$$

which represents the hyperbola in question.

**159. The Hyperbola.**—In the hyperbola we have

$$p^2 = a^2 \cos^2 \omega - b^2 \sin^2 \omega.$$

Hence, measuring the arc from the vertex  $A$  of the curve, we find, since  $\omega$  is measured below the axis,

$$PN - AP = \int_0^\alpha (a^2 \cos^2 \omega - b^2 \sin^2 \omega)^{\frac{1}{2}} d\omega, \quad (8)$$

where  $a = \angle ACN$ .

As we proceed along the hyperbola the perpendicular  $p$  diminishes, and vanishes when the tangent becomes the asymptote.

Moreover, as the limit of  $\omega$  in this case becomes  $\tan^{-1} \frac{a}{b}$ , it follows that the difference between the asymptote and the infinite hyperbolic arc, measured from the vertex, is represented by the definite integral

$$\int_0^{\tan^{-1} \frac{a}{b}} (a^2 \cos^2 \omega - b^2 \sin^2 \omega)^{\frac{1}{2}} d\omega.$$

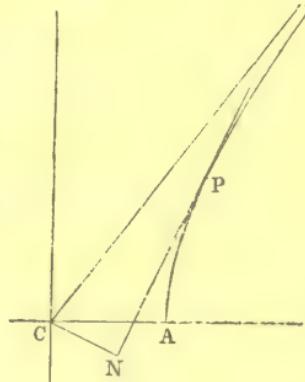


Fig. 29.

#### EXAMPLES.

1. If  $a > b$ , prove that

$$\int (a + b \cos \phi)^{\frac{1}{2}} d\phi$$

is represented by an elliptic arc, and that the semiaxes of the ellipse are the greatest and least values of  $(a + b \cos \phi)^{\frac{1}{2}}$ .

2. If  $a < b$ , prove that

$$\int (a + b \cos \phi)^{\frac{1}{2}} d\phi$$

is represented by the difference between a right line and a hyperbolic arc.

160. **Landen's Theorem on a Hyperbolic Arc.**—We next proceed to establish an important theorem, due to Landen;\* namely, that *any arc of a hyperbola can be expressed in terms of the arcs of two ellipses*.

This can be easily seen as follows:—In any triangle, adopting the usual notation, we have

$$c = a \cos B + b \cos A.$$

Now, representing by  $C$  the external angle at the vertex  $C$ , we have  $C = A + B$ , and hence

$$cdC = (a \cos B + b \cos A) dA + (a \cos B + b \cos A) dB.$$

Consequently, supposing the sides  $a$  and  $b$  constant, and the remaining parts variable, we have

$$\int cdC = \int a \cos B dA + \int b \cos A dB + 2a \sin B + \text{const.},$$

or

$$\int \sqrt{a^2 + b^2 + 2ab \cos C} dC = \int \sqrt{a^2 - b^2 \sin^2 A} dA + \int \sqrt{b^2 - a^2 \sin^2 B} dB \\ + 2a \sin B + \text{const.} \quad (9)$$

Now, if we suppose  $a > b$ ,  $\int \sqrt{a^2 - b^2 \sin^2 A} dA$  represents (Art. 155) the arc of an ellipse, of axis major  $2a$  and eccentricity  $\frac{b}{a}$ . Also  $\int \sqrt{b^2 - a^2 \sin^2 B} dB$  represents (Art. 159) the difference between a right line and the arc of a hyperbola, whose axis major is  $b$  and eccentricity  $\frac{a}{b}$ .

$$\text{Again, } \sqrt{a^2 + b^2 + 2ab \cos C} = \sqrt{(a - b)^2 \sin^2 \frac{C}{2} + (a + b)^2 \cos^2 \frac{C}{2}},$$

\* Landen, *Philosophical Transactions*, 1775; also, *Mathematical Memoirs*, 1780.

and consequently the integral

$$\int \sqrt{a^2 + b^2 + 2ab \cos C} dC$$

represents an arc of the ellipse whose semiaxes are  $a + b$  and  $a - b$ .

Hence, Landen's theorem follows immediately.

It should be noted that the limiting values of  $A$ ,  $B$  and  $C$  are connected by the relations

$$a \sin B = b \sin A, \text{ and } C = A + B.$$

Again, if we suppose the angle  $A$  to increase from  $0$  to  $\pi$ , the external angle  $C$  will increase at the same time from  $0$  to  $\pi$ , while  $B$  will commence by increasing from  $0$  to  $a$ , and afterwards diminish from  $a$  to  $0$  (where  $a = \sin^{-1} \frac{b}{a}$ ).

Moreover, in the latter stage  $b \cos A$  is negative, and  $dB$  also negative, consequently the term  $b \cos A dB$  is positive throughout the entire integration ; and the total value of

$$\int \sqrt{b^2 - a^2 \sin^2 B} dB \text{ is represented by } 2 \int_0^a \sqrt{b^2 - a^2 \sin^2 B} dB.$$

Hence, substituting  $\phi$  for  $\frac{C}{2}$ , and integrating between the limits indicated, we get, after dividing by 2,

$$\begin{aligned} & \int_0^{\frac{\pi}{2}} \{ (a + b)^2 \sin^2 \phi + (a - b)^2 \cos^2 \phi \}^{\frac{1}{2}} d\phi \\ &= \int_0^{\frac{\pi}{2}} (a^2 - b^2 \sin^2 A)^{\frac{1}{2}} dA + \int_0^a (b^2 - a^2 \sin^2 B)^{\frac{1}{2}} dB. \quad (10) \end{aligned}$$

Accordingly, the difference between the length of the asymptote and of the infinite arc of a hyperbola is equal to the difference between two elliptic quadrants. This result is also due to Landen.

We next proceed to two important theorems, which may be regarded as extensions of Fagnani's theorem.

161. **Theorem\* of Dr. Graves.**—If from any point  $P$  on the exterior of two confocal ellipses, tangents  $PT$  and  $PT'$  be drawn to the interior, then the difference  $(PT + PT' - TT')$  between the sum of the tangents and the arc between their points of contact is constant.

For, draw the tangents  $QS$  and  $QS'$  from a point  $Q$ , regarded as infinitely near to  $P$ , and drop the perpendiculars  $PN$  and  $QN'$ ; then, since the conics are confocal, we have

$$\angle PQN = \angle QPN' ; \therefore PN' = QN.$$

$$\begin{aligned} \text{Also, } PT &= TR + RN = TR + RS + SN = TS + SN \\ &= TS + SQ - QN. \end{aligned}$$

In like manner

$$PT' = PN' + S'Q - T'S' ;$$

$$\therefore PT + PT' = QS + QS' + TS - T'S' ,$$

$$\text{or } PT + PT' - TT' = QS + QS' - SS' .$$

Hence,  $PT + PT' - TT'$  does not change in passing to the consecutive point  $Q$ ; which proves that  $PT + PT' - TT'$  has a constant value.

\* This elegant theorem was arrived at by Dr. Graves, now Bishop of Limerick, for the more general case of spherical conics, from the reciprocal theorem, viz.:—If two spherical conics have the same cyclic arcs, then any arc touching the inner will cut from the outer a segment of constant area. (See Graves' translation of Chasles on *Cones and Spherical Conics*, p. 77, Dublin, 1841.)

It should be remarked that the theorems of this and of the following article were investigated independently by M. Chasles. The student will find in the *Comptes Rendus*, 1843, 1844, a number of beautiful applications by that great geometrician of these theorems, as well to properties of confocal conics, as also to the addition of elliptic functions of the first species.

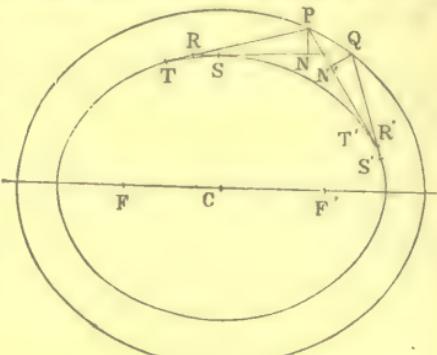


Fig. 30.

This value can be readily expressed by taking the point at  $B'$ , one of the extremities of the minor axis of the exterior ellipse. Let  $D$  be the point of contact of the tangent drawn from  $B'$ , and drop  $DM$ , and  $DN$  perpendicular to  $CA$  and  $CB$ , respectively.

Let  $CA = a$ ,  $CB = b$ ,  $CA' = a'$ ,  $CB' = b'$ ,  $e$  the eccentricity of interior ellipse. Then, by Art. 155, the length of arc

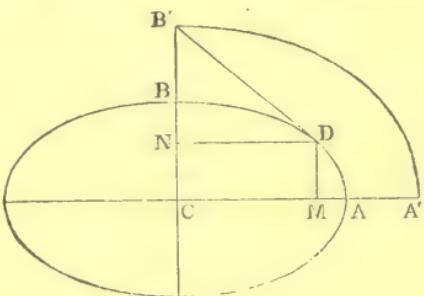


Fig. 31.

$$BD = a \int_0^a (1 - e^2 \sin^2 \phi)^{\frac{1}{2}} d\phi,$$

where

$$\cos a = \frac{DN}{CB} = \frac{CN}{CB} = \frac{CR}{CB'} = \frac{b}{b'}.$$

Again,

$$\begin{aligned} B'D^2 &= B'N^2 + DN^2 = (b' - b \cos a)^2 + a^2 \sin^2 a \\ &= \left( b' - \frac{b^2}{b'} \right)^2 + a^2 \left( 1 - \frac{b^2}{b'^2} \right); \end{aligned}$$

hence

$$B'D = \frac{a'}{b'} \sqrt{b'^2 - b^2} = a' \sin a.$$

Consequently we have

$$B'D - BD = a' \sin a - a \int_0^a (1 - e^2 \sin^2 \phi)^{\frac{1}{2}} d\phi,$$

Hence, in general,

$$PT + PT' - TT' = 2a' \sin a - 2a \int_0^a (1 - e^2 \sin^2 \phi)^{\frac{1}{2}} d\phi, \quad (11)$$

where

$$a = \cos^{-1} \left( \frac{b}{b'} \right).$$

The analogous theorem, due to Professor Mac Cullagh, may be stated as follows :—

162. **Theorem.**—If tangents  $PT$ ,  $PT'$  be drawn to an ellipse from any point on a confocal hyperbola, then the difference of the tangents is equal to the difference of the arcs  $TK$  and  $KT'$ .

The proof is left to the student, and is nearly identical with that given for the previous theorem.

This result still holds when the tangents are drawn from a point on an ellipse to a confocal hyperbola, provided that the tangents both touch the same branch of the hyperbola; as can be seen without difficulty.

As an application\* we shall prove another theorem of Landen; viz., that the difference between the length of the asymptote and of the infinite branch of a hyperbola can be expressed in terms of an arc of the hyperbola.

For, let the tangent at  $A$  meet the asymptote in  $D$ , and suppose a confocal ellipse drawn through  $D$ . Then, regarding  $DT$  as a tangent to the hyperbola, it follows, by the theorem just established, that the difference between  $DT$  and  $KT$  is equal to the difference between  $DA$  and  $AK$ .

Consequently the difference between the asymptote  $CT$  and the hyperbolic branch  $AT$  is equal to  $DA + DC - 2KA$ . Consequently the required difference is expressible in terms of given lines and of the hyperbolic arc  $AK$ .

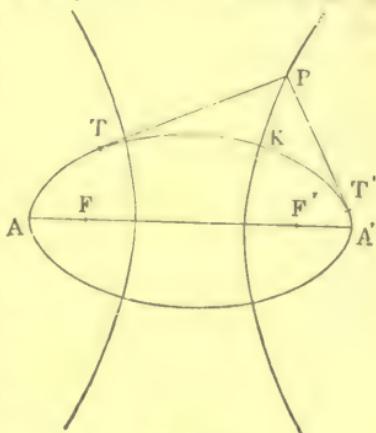


Fig. 32.

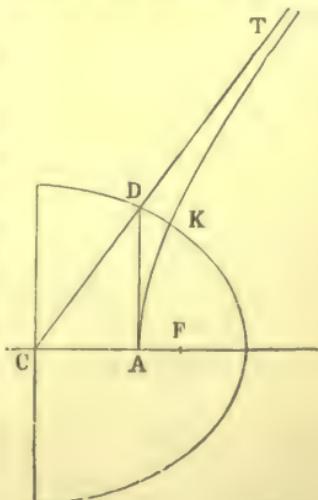


Fig. 33.

\* I am indebted to Dr. Ingram for this application of Professor M'Cullagh's theorem.

We next proceed to consider two important curves whose rectification depends on that of the ellipse.

163. **The Limaçon.**—From the equation of the limaçon,

$$r = a \cos \theta + b, \text{ we get } \frac{dr}{d\theta} = -a \sin \theta,$$

and hence

$$ds = (a^2 + b^2 + 2ab \cos \theta)^{\frac{1}{2}} d\theta;$$

$$\therefore s = \int \left\{ (a + b)^2 \cos^2 \frac{\theta}{2} + (a - b)^2 \sin^2 \frac{\theta}{2} \right\}^{\frac{1}{2}} d\theta.$$

Accordingly, the rectification of the limaçon depends on that of the ellipse whose semiaxes are  $a + b$  and  $a - b$ .

164. **The Epitrochoid and Hypotrochoid.**—The epitrochoid is represented by the equations (see Diff. Calc., Art. 284)

$$x = (a + b) \cos \theta - c \cos \frac{a + b}{b} \theta,$$

$$y = (a + b) \sin \theta - c \sin \frac{a + b}{b} \theta.$$

Hence

$$\frac{dx}{d\theta} = - (a + b) \left\{ \sin \theta - \frac{c}{b} \sin \frac{a + b}{b} \theta \right\},$$

$$\frac{dy}{d\theta} = (a + b) \left\{ \cos \theta - \frac{c}{b} \cos \frac{a + b}{b} \theta \right\}.$$

Squaring and adding we get

$$\left( \frac{ds}{d\theta} \right)^2 = \left( \frac{a + b}{b} \right)^2 \left\{ b^2 + c^2 - 2bc \cos \frac{a\theta}{b} \right\};$$

$$\therefore s = \frac{a + b}{b} \int \left\{ b^2 + c^2 - 2bc \cos \frac{a\theta}{b} \right\}^{\frac{1}{2}} d\theta.$$

Hence, substituting  $\frac{2b\phi}{a}$  for  $\theta$ , we get

$$s = \frac{2(a + b)}{a} \int \{(b + c)^2 \sin^2 \phi + (b - c)^2 \cos^2 \phi\}^{\frac{1}{2}} d\phi.$$

Consequently the length of an arc of the epitrochoid is equal to that of an ellipse.

The corresponding form for the hypotrochoid is obtained by changing the sign of  $b$ .

**165. Steiner's Theorem on Rectification of Roulettes.**—If any curve roll on a right line, the length of the arc of the roulette described by any point is equal to that of the corresponding arc of the pedal, taken with respect to the generating point as origin.

For (see fig. 20, Art. 145), the element  $OO'$  of the roulette is equal to  $OPd\omega$ .

Again, to find the element of the pedal. Since the angles at  $N$  and  $N'$  are right, the quadrilateral  $NN'TO$  is inscribable in a circle, and consequently  $NN' = OT \sin NON'$ . But, in the limit,  $NN'$  becomes the element of the pedal, and  $OT$  becomes  $OP$ : hence the element of pedal is  $OPd\omega$ ; consequently the element of the pedal is equal to the corresponding element of the roulette;  $\therefore$  &c.

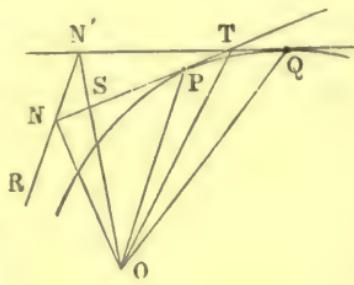


Fig. 34.

We proceed to point out a few elementary examples of this principle. In the first place it follows that the length of an arc of the cycloid is the same as that of the cardioid; and the length of the trochoid as that of the limaçon. Again, if an ellipse roll on a right line, the length of the roulette described by either focus is equal to the corresponding arc of the auxiliary circle.

Moreover, it is easily seen, as in Art. 146, that, if one curve roll on another, the elements  $ds$  and  $ds'$ , of the roulette, and of the corresponding pedal are connected by the relation

$$ds = ds' \left( 1 + \frac{\rho}{\rho'} \right).$$

In the case of one circle rolling on another, this relation shows that the arcs of epicycloids and of epitrochoids are proportional to the arcs of cardioids and of limaçons, which agrees with the results established already.

166. **Oval of Descartes.**—We next proceed to the rectification of the Ovals of Descartes, some properties of which curves we have given in chapter xx., Diff. Calc.

The curve is defined as the locus of a point whose distances,  $r$  and  $r'$ , from two fixed points are connected by the equation

$$mr + lr' = d,$$

where  $l, m, d$  are constants.

For convenience we shall write the equation in the form

$$mr + lr' = nc, \quad (12)$$

where  $c$  is the distance between the fixed points.

The polar equation of the curve is easily got. For, let  $I$  and  $F_1$  be the fixed points, and  $\angle F_1 F P = \theta$ , then we have

$$r'^2 = r^2 + c^2 - 2rc \cos \theta;$$

also from (12),

$$l^2 r'^2 = (nc - mr)^2,$$

hence the polar equation of the locus is readily seen to be

$$r^2 - 2rc \frac{mn - l^2 \cos \theta}{m^2 - l^2} + c^2 \frac{n^2 - l^2}{m^2 - l^2} = 0. \quad (13)$$

For simplicity we shall write this in the form

$$r^2 - 2r\Omega + C = 0. \quad (14)$$

Solving this equation for  $r$ , we get

$$r = \Omega \pm \sqrt{\Omega^2 - C}, \text{ or } FP_1 = \Omega + \sqrt{\Omega^2 - C}, \quad FP = \Omega - \sqrt{\Omega^2 - C}.$$

It can be seen without difficulty that, so long as  $l, m, n$  are real and unequal, the curve consists of two ovals, one lying inside the other, as in the figure.

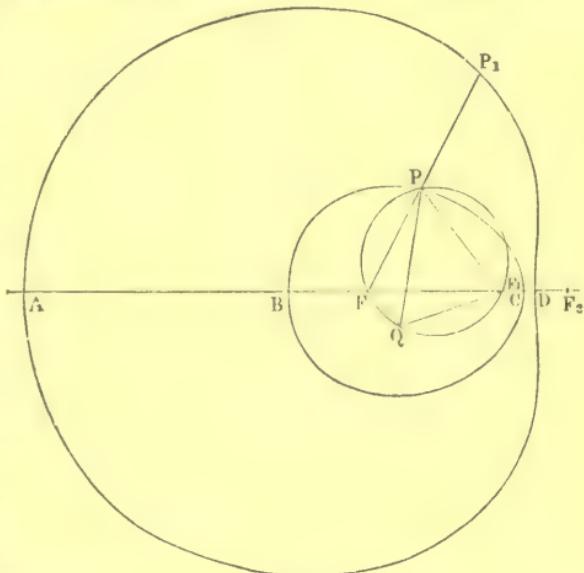


Fig. 35.

Again we get from (14), by differentiation

$$(r - \Omega) dr = r \Omega' d\theta, \quad \text{where } \Omega' = \frac{d\Omega}{d\theta};$$

$$\therefore \frac{dr}{rd\theta} = \frac{\Omega'}{r - \Omega} = \frac{\Omega'}{\sqrt{\Omega^2 - C}}; \quad \text{hence } \frac{ds}{rd\theta} = \frac{\sqrt{\Omega^2 + \Omega'^2 - C}}{\sqrt{\Omega^2 - C}}.$$

$$\text{Or } ds = \frac{\Omega \sqrt{\Omega^2 + \Omega'^2 - C}}{\sqrt{\Omega^2 - C}} d\theta \pm \sqrt{\Omega^2 + \Omega'^2 - C} d\theta, \quad (15)$$

the upper sign corresponding to the outer oval, and the lower to the inner.

Hence the difference between the two corresponding elementary arcs is equal to

$$2\sqrt{\Omega^2 + \Omega'^2 - C} d\theta, \quad \text{or, } 2\sqrt{a^2 + 2ab \cos \theta + b^2 - C} d\theta,$$

(writing  $\Omega$  in the form  $a + b \cos \theta$ ); this plainly represents the element of an ellipse. Consequently, the difference between two corresponding arcs of the ovals can be represented by the arc of an ellipse. This remarkable theorem is due to Mr. W. Roberts (Liouville, 1847, p. 195). Some years after its publication it was shown by Professor Genocchi (Tortolini, 1864, p. 97), that the arc\* of a Cartesian is expressible in terms of three elliptic arcs.

In order to establish this result we commence by proving one or two elementary properties of the curve.

Suppose a circle described through  $F$ ,  $F_1$ , and  $P$ ; and let  $PQ$  be the normal at  $P$  to the oval, meeting the circle in  $Q$ , and join  $FQ$  and  $F_1Q$ ; then let  $\angle FPQ = \omega$ , and  $F_1PQ = \omega'$ ; and since  $m \frac{dr}{ds} + l \frac{dr'}{ds} = 0$ , we have  $l \sin \omega' = m \sin \omega$ ;

$$\therefore FQ : F_1Q = l : m.$$

\* For the proof of this theorem given in the text I am indebted to Dr. Panton. A very simple demonstration by Mr. Russell will be found in a Note at the end of the book.

Also, since  $mr + lr' = nc$ ; and (by Ptolemy's theorem)

$$FP \cdot F_1Q + F_1P \cdot FQ = FF_1 \cdot PQ,$$

we have

$$\frac{FQ}{l} = \frac{F_1Q}{m} = \frac{PQ}{n}.$$

Hence, denoting the common value of these fractions by  $u$ , we have

$$FQ = lu, \quad F_1Q = mu, \quad PQ = nu.$$

Again

$$\tan \omega = \frac{dr}{rd\theta} = \frac{\Omega'}{\sqrt{\Omega^2 - C}}; \quad \therefore \cos \omega = \frac{\sqrt{\Omega^2 - C}}{\sqrt{\Omega^2 + \Omega'^2 - C}}.$$

Hence the first term in the expression for  $ds$  in (15) is equal to

$$\frac{\Omega d\theta}{\cos \omega} = \frac{c}{m^2 - l^2} \frac{mn - l^2 \cos \theta}{\cos \omega} d\theta.$$

Again, let  $\angle FPF_1 = \psi$ ,  $\angle PF_1C = \phi$ ,

and we have the two following relations between the angles  $\theta, \phi, \psi$ :

$$\phi = \theta + \psi, \quad l \sin \theta + m \sin \phi = n \sin \psi. \quad (16)$$

Hence

$$d\phi - d\theta = d\psi, \quad l \cos \theta d\theta + m \cos \phi d\phi = n \cos \psi d\psi;$$

$$\therefore (mn - l^2 \cos \theta) d\theta = m(n + l \cos \phi) d\phi - n(m + l \cos \psi) d\psi,$$

or

$$\frac{mn - l^2 \cos \theta}{\cos \omega} d\theta = m \frac{n + l \cos \phi}{\cos \omega} d\phi - n \frac{m + l \cos \psi}{\cos \omega} d\psi. \quad (17)$$

Again, from the triangle  $FPQ$ , we have

$$r \cos \omega = PQ + FQ \cos \phi = (n + l \cos \phi)u;$$

$$\therefore \frac{n + l \cos \phi}{\cos \omega} = \frac{r}{u} = \sqrt{l^2 + n^2 + 2ln \cos \phi}.$$

In the same manner it can be shown that

$$\frac{m + l \cos \psi}{\cos \omega} = \frac{c}{u} = \sqrt{l^2 + m^2 + 2lm \cos \psi}.$$

Hence we have

$$\begin{aligned} \int \frac{\Omega d\theta}{\cos \omega} &= \frac{mc}{m^2 - l^2} \int \sqrt{l^2 + n^2 + 2ln \cos \phi} d\phi \\ &- \frac{nc}{m^2 - l^2} \int \sqrt{l^2 + m^2 + 2lm \cos \psi} d\psi. \end{aligned} \quad (18)$$

Each of these latter integrals is represented by the arc of an ellipse, and, accordingly, the arc of a Cartesian Oval is expressible in the required manner.

It should be noted that the limiting values of  $\theta$ ,  $\phi$ , and  $\psi$  are connected by the relations given in (16).

Again, it can be shown without difficulty that *the axes of the ellipses are the lines (AB, CD), (AC, BD), and (AD, BC), respectively*: a result also given by Signor Genocchi. First, with respect to the ellipse whose element is  $\sqrt{\Omega^2 + \Omega'^2 - C} d\theta$ , it is plain that its axes are the greatest and least values of  $2\sqrt{\Omega^2 + \Omega'^2 - C}$ , or of  $2\sqrt{a^2 + b^2 + 2ab \cos \theta - C}$ ; but these are  $2\sqrt{(a + b)^2 - C}$  and  $2\sqrt{(a - b)^2 - C}$ , which are plainly the same as the greatest and least values of  $PP_1$ ; and, consequently, are *AB* and *CD*.

Again, from the equation  $mr + lr' = nc$ , we get

$$mFB + l(FB + c) = nc; \quad \therefore FB = \frac{(n - l)c}{l + m}.$$

In like manner,

$$FC = \frac{(n + l)c}{l + m}.$$

Again, since we get the points on the outer oval by changing the sign of  $l$ , we have

$$FA = \frac{(n + l)c}{m - l}, \quad FD = \frac{(n - l)c}{m - l};$$

and, consequently,

$$AD = \frac{2nc}{m-l}, \quad BC = \frac{2nc}{l+m},$$

$$AC = \frac{2mc(n+l)}{m^2-l^2}, \quad BD = \frac{2mc(n-l)}{m^2-l^2};$$

but these are readily seen to be the values for the axes of the ellipses in (18).

It should be noted that if we substitute in (15) the values for  $a$  and  $b$ , the expression for the element  $ds$  becomes of the following symmetrical form :

$$ds = \frac{mc}{m^2-l^2} \sqrt{l^2+n^2+2ln \cos \phi} d\phi - \frac{nc}{m^2-l^2} \sqrt{l^2+m^2+2lm \cos \psi} d\psi$$

$$\pm \frac{lc}{m^2-l^2} \sqrt{m^2+n^2-2mn \cos \theta} d\theta. \quad (19)$$

We shall conclude the Chapter with a brief account of the rectification of curves of double curvature.

**167. Rectification of Curves of Double Curvature.** If the points in a curve be not situated in the same plane, the curve is said to be one of double curvature. The expression for its length is obtained in an analogous manner to that adopted for plane curves ; for, if we refer the curve to a system of rectangular axes in space, and denote the co-ordinates of two consecutive points by  $(x, y, z)$ ,  $(x+dx, y+dy, z+dz)$ , we get for the element of length,  $ds$ , the value

$$ds = \sqrt{dx^2 + dy^2 + dz^2}.$$

The curve is commonly supposed to be determined by the intersection of two cylindrical surfaces, whose equations are of the form

$$f(x, y) = 0, \quad \phi(x, z) = 0.$$

From these equations, if  $\frac{dy}{dx}$  and  $\frac{dz}{dx}$  be determined, the formula of rectification is

$$s = \int \left\{ 1 + \left( \frac{dy}{dx} \right)^2 + \left( \frac{dz}{dx} \right)^2 \right\}^{\frac{1}{2}} dx. \quad (20)$$

[16 a]

When  $z$  is taken as the independent variable, this formula becomes

$$s = \int \left\{ 1 + \left( \frac{dx}{dz} \right)^2 + \left( \frac{dy}{dz} \right)^2 \right\}^{\frac{1}{2}} dz;$$

the limits being in each case determined by the conditions of the question.

The simplest example is that of the helix, or the curve formed by the thread of a screw. From its mode of generation it is easily seen that the helix is represented by two equations of the form

$$x = a \cos \left( \frac{z}{b} \right), \quad y = a \sin \left( \frac{z}{b} \right).$$

Hence

$$\frac{dx}{dz} = -\frac{a}{b} \sin \left( \frac{z}{b} \right), \quad \frac{dy}{dz} = \frac{a}{b} \cos \left( \frac{z}{b} \right);$$

$$\therefore ds = \left( 1 + \frac{a^2}{b^2} \right)^{\frac{1}{2}} dz, \quad \text{or } s = \left( 1 + \frac{a^2}{b^2} \right)^{\frac{1}{2}} z;$$

the arc being measured from the point in which the helix meets the plane of  $xy$ .

This result can also be readily established geometrically.

#### EXAMPLES.

- Find the length of the curve whose equations are

$$y = \frac{x^2}{2a}, \quad z = \frac{x^3}{6a^2}.$$

$$\text{Here } s = \int \left( 1 + \frac{x^2}{a^2} + \frac{x^4}{4a^4} \right)^{\frac{1}{2}} dx = \int \left( 1 + \frac{x^2}{2a^2} \right) dx = x + \frac{x^3}{6a^2} = x + z;$$

the arc being measured from the origin.

This is a case of a system of curves which are readily rectified; for, in general, whenever

$$\left( \frac{dy}{dx} \right)^2 = z^2 \frac{dz}{dx},$$

$$\text{we have } \left( 1 + \frac{dy^2}{dx^2} + \frac{dz^2}{dx^2} \right)^{\frac{1}{2}} = \left( 1 + \frac{dz}{dx} \right),$$

and therefore  $ds = dx + dz$ , or  $s = x + z + \text{const.}$

Thus, if  $y = f(x)$  be one of the equations of a curve, we get  $\frac{dy}{dx} = f'(x)$ , and hence, if a second equation be determined from the equation

$$\frac{dz}{dx} = \frac{1}{2} \left\{ f'(x) \right\}^2,$$

the length of the curve is represented by  $x + z + \text{const.}$ ; the value of the constant being determined by the conditions of the problem.

For instance, if  $y = a \sin x$ , we get  $f'(x) = a \cos x$ , and

$$\frac{dz}{dx} = \frac{a^2}{2} \cos^2 x; \quad \therefore z = \frac{a^2}{4} (x + \cos x \sin x).$$

Hence the length of the curve of intersection of the cylindrical surfaces

$$y = a \sin x, \quad z = \frac{a^2}{4} (x + \cos x \sin x)$$

is  $x + z$ ; the length being measured from the origin.

$$2. \quad y = 2 \sqrt{ax} - x, \quad z = x - \frac{2}{3} \sqrt{\frac{x^3}{a}}. \quad \text{Ans. } s = x + y - z.$$

$$3. \quad \frac{x^2}{a^2} - \frac{y^2}{b^2} = 1, \quad x = \frac{a}{2} (e^{\frac{x}{a}} + e^{-\frac{x}{a}}), \text{ the length being measured from the point}$$

of intersection of the curve with the plane of  $xy$ .

$$\text{Ans. } s = \frac{(a^2 + b^2)^{\frac{1}{2}}}{a} (x^2 - a^2)^{\frac{1}{2}}.$$

## EXAMPLES.

1. Find the length of any arc of the catenary

$$y = \frac{a}{2} \left( e^{\frac{x}{a}} + e^{-\frac{x}{a}} \right),$$

and show that the area between the curve, the axis of  $x$ , and the ordinates at two points on the curve, is equal to  $a$  times the length of the arc terminated by these points.

2. In any curve prove that  $\int \frac{r dr}{\sqrt{r^2 - p^2}}$ , and hence find the length of a parabolic arc.

3. Show that the integral  $\int \frac{x dx}{\sqrt{bx^2 - x^4 - c^2}}$  may be represented by an arc of a circle, and find the limiting values of  $x$  for its possibility.

4. Show that the length of an elliptic arc is represented by  $\int \sqrt{\frac{a^2 - e^2 x^2}{a^2 - x^2}} dx$ , where  $a$  is the semiaxis major, and  $e$  the eccentricity.

5. Express the length of an elliptic quadrant in a series of ascending powers of its eccentricity.

$$Ans. \frac{\pi a}{2} \left\{ 1 - \left(\frac{1}{2}\right)^2 \frac{e^2}{1} - \left(\frac{1 \cdot 3}{2 \cdot 4}\right)^2 \frac{e^4}{3} - \left(\frac{1 \cdot 3 \cdot 5}{2 \cdot 4 \cdot 6}\right)^2 \frac{e^6}{5} - \dots \right\}.$$

6. Prove that the integral of

$$\frac{x^2 dx}{\sqrt{(x^2 - \beta^2)(x^2 - \alpha^2)}}$$

can be represented by an arc of the ellipse whose semiaxes are  $\alpha$  and  $\beta$ .

7. Show that the rectification of the sinusoid  $y = b \sin x$  is the same as that of an ellipse.

8. Prove that the whole length of the *first negative pedal* of an ellipse, taken with respect to a focus, is equal to the circumference of the circle described on the axis minor as diameter.

9. Show that the length of an arc of the curve  $r = a \sin \alpha \theta$  is equal to that of an arc of the ellipse whose semiaxes are  $a$  and  $a\alpha$ .

10. If, from the equation of a curve referred to rectangular co-ordinates, we form an equation in polar co-ordinates, by taking  $r = y$  and  $r d\theta = dx$ , then the lengths of the corresponding arcs of the two curves are equal, and the area  $\int y dx$  of the former curve is equal to the corresponding sectorial area of the latter.

11. Prove that the difference between the lengths of the two loops of the limacon  $r = a \cos \theta + b$  is equal to  $bb$ :  $a$  being greater than  $b$ .

12. Being given three points  $A$ ,  $B$ ,  $C$  on the circumference of an ellipse, show that we can always find, at either side of  $C$ , a fourth point  $D$  such that the difference between  $AB$  and  $CD$  shall be equal to a right line.

13. If a circle be described touching two tangents to an ellipse and also touching the ellipse, prove that the point of contact with the ellipse divides the elliptic arc between the points of contact of the tangents into two parts, whose difference is equal to the difference of the lengths of the tangents (J. Math. Comptes Rendus, 1843).

14. Prove that the entire length of any closed curve is represented by  $\int \frac{p ds}{\rho}$  taken round the entire curve;  $\rho$  being the radius of curvature at any point, and  $p$  the length of the perpendicular from any fixed point on the tangent.

15. If  $\sigma = \frac{e^x + 1}{e^x - 1}$  be the equation of a curve, prove that  $\frac{ds}{dx} = \frac{e^{2x} + 1}{e^{2x} - 1}$ , and hence rectify the curve.

16. Calculate approximately, by the tables of Art. 153, the whole length of a loop of the curve  $r = s^{\frac{1}{5}} \cos \frac{4}{5}\theta$ .

Here, by Ex. 3, Art. 156, the required length is

$$\frac{5}{4} s \sqrt{\pi} \frac{\Gamma\left(\frac{5}{4}\right)}{\Gamma\left(\frac{9}{5}\right)}, \text{ or } 2s\sqrt{\pi} \frac{\Gamma\left(\frac{13}{5}\right)}{\Gamma\left(\frac{2}{5}\right)}.$$

Hence, taking logarithms, and observing that  $\frac{13}{5} = 1.6:5$ , and  $\frac{9}{5} = 1.125$ , we get as the required approximation  $s \times 3.29433$ . The figure of this curve is exhibited in Art. 268, Diff. Calc.

17. In a Cartesian Oval whose two internal foci coincide, prove that the difference of the two areas, intercepted by any two transversals from the external focus, is equal to a straight line which may be found. [The above curve is the inverse of an ellipse from a focus.]—Professor Crofton, *Edin. Times*, June, 1874.

From (13) Art. 166, it follows, making  $n = m$ , that the equation of the limacon, in this case, is

$$r^2 + 2r \frac{b \cos \theta - m^2}{b^2 - m^2} + b^2 = 0,$$

which is of the form

$$r^2 + 2r(a \cos \theta - \beta) + (a - \beta)^2 = 0.$$

Hence, by (15), the difference between two corresponding elementary arcs is

$$4\sqrt{ab} \cos \frac{\theta}{2} d\theta.$$

Consequently, if  $\theta_1$  and  $\theta_2$  be the values of  $\theta$  for the two transversals in question, we get the difference of the corresponding arcs

$$= 8\sqrt{ab} \left( \sin \frac{\theta_2}{2} - \sin \frac{\theta_1}{2} \right).$$

Also, it can be readily seen that the distance between the vertices of the limacon is  $2\sqrt{ab}$ ; i.e.  $4a$ .

18. Show that the length of an arc of the ellipse  $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$  is represented by the integral

$$a^2 b^2 \int \frac{d\theta}{(a^2 \cos^2 \theta + b^2 \sin^2 \theta)^{\frac{3}{2}}}$$

This result is easily seen, for we have  $ds = \rho d\theta$ , and  $\rho = \frac{a^2 b^2}{\rho^3}; \therefore \&c.$

19. Show, in like manner, that the length of a hyperbolic arc is represented by

$$a^2 b^2 \int \frac{d\theta}{(a^2 \cos^2 \theta - b^2 \sin^2 \theta)^{\frac{3}{2}}}$$

20. Hence prove that the integral

$$\int \frac{dx}{(a - bx^2)^{\frac{1}{2}} (a' - b'x^2)^{\frac{1}{2}}}$$

is represented by an elliptic arc when  $ab' > ba'$ , and by a hyperbolic arc when  $ab' < ba'$ .

21. Prove that the differential of the arc of the curve found by cutting in the ratio  $n : 1$  the normals to the cycloid

$$y = a + b \cos u, \quad x = au + b \sin u,$$

is  $\sqrt{(a + nb)^2 + 4nab \sin^2 \frac{u}{2}} du.$

22. Each element of the periphery of an ellipse is divided by the diameter parallel to it: find the sum of all the elementary quotients extended to the entire ellipse. *Ans.  $\pi$ .*

23. In the figure of Art. 158, if  $\alpha = \angle ACN'$ , and  $\beta = \angle BCN$ , prove that

$$\frac{\tan \alpha}{a} = \frac{\tan \beta}{b}.$$

24. Find the length, measured from the origin, of the curve

$$x^2 = a^2 (1 - \frac{y}{e^a}).$$

$$\text{Ans. } s = a \log \left( \frac{a+x}{a-x} \right) - x.$$

25. Find the length, measured from  $\phi = 0$ , of the curve which is represented by the equations

$$x = (2a - b) \sin \phi - (a - b) \sin^3 \phi,$$

$$y = (2b - a) \cos \phi - (b - a) \cos^3 \phi.$$

$$\text{Ans. } s = \frac{1}{2} (a + b) \phi + \frac{3}{2} (a - b) \sin \phi \cos \phi.$$

26. Prove that the sides of a polygon of maximum perimeter inscribed in a conic are tangents to a confocal conic.—Chasles, *Comptes Rendus*, 1845.

27. To two arcs of an equilateral hyperbola, whose difference is rectifiable, correspond equal arcs of the lemniscate which is the pedal of the hyperbola. *Ibid.*

28. The tangents at the extremities of two arcs of a conic, whose difference is rectifiable, form a quadrilateral, whose sides are tangents to the same circle.—*Ibid.*

29. In an equilateral hyperbola prove that

$$rds = \frac{1}{2}a^2 d(\tan 2\theta),$$

and hence show that  $\int rds$  taken between any two points on the curve is equal to the rectangle under the chord joining the points and the line connecting the middle point of the chord with the centre of the hyperbola. Mr. W. S. M'Cay.

30. If

$$x = a \frac{z + z^3}{1 + z^4}, \quad y = a \frac{z - z^3}{1 + z^4}$$

be any point on a curve, show that the arc is the integral of

$$a \sqrt{z} \frac{dz}{\sqrt{1 + z^4}}. \quad (\text{M. Serret})$$

What curve do the equations represent?

31. Through any point in a plane two conics of a confocal system can be drawn. If the distance between the foci be  $2c$ , and the transverse semi-axes of these conics be  $\mu, \nu$ , prove the following expression for any arc of a curve

$$ds^2 = (\mu^2 - \nu^2) \left\{ \frac{d\mu^2}{\mu^2 - c^2} + \frac{d\nu^2}{c^2 - \nu^2} \right\}.$$

32. Prove that the following relation is satisfied by the  $\mu$  and  $\nu$  of any point on a tangent to the ellipse for which  $\mu$  has the value  $\mu_1$ :

$$\frac{d\mu}{\sqrt{(\mu^2 - c^2)(\mu^2 - \mu_1^2)}} \pm \frac{d\nu}{\sqrt{(c^2 - \nu^2)(\mu_1^2 - \nu^2)}} = 0.$$

33. The arc of the envelope of the right line  $x \sin \alpha - y \cos \alpha = f(\alpha)$  is the integral of  $(f(\alpha) + f''(\alpha)) d\alpha$ . (Hermite, *Cours d'Analyse*.)

34. The arc of the curve in which  $y^2 + a^2 x^2 - 2ax = 0$  and  $z^2 - b^2 x^2 + 2bx = 0$  intersect, if  $a^2 = 1 + b^2$ , is

$$\int \frac{\sqrt{2(a-b)} dx}{\sqrt{x(2-ax)(2-bx)}}. \quad (\text{Ibid.})$$

35. Show that the arc of the curve  $\frac{x^m}{a^m} + \frac{y^m}{b^m} = 1$  depends on an integral of the form

$$\int dz \sqrt{a^2(1+z)^k + b^2(1-z)^k}, \text{ where } k = \frac{2}{m} - 2.$$

36. Show that rectification may, in general, be reduced to quadratures as follows:—

Produce each ordinate of the curve to be rectified until the whole length is in a constant ratio to the corresponding normal divided by the old ordinate, then the locus of the extremity of the ordinate so produced is a curve whose area is in a constant ratio to the length of the given curve.

By this theorem Van Huraert rectified the semi-cubical parabola nearly simultaneously with Wm. Neil.

## CHAPTER IX.

## VOLUMES AND SURFACES OF SOLIDS.

168. **Solids.—The Prism and Cylinder.**—The most simple solid is the cube, which is accordingly the measure of all solids, as the square is that of all areas. Hence the finding the volume of a solid is called its *cubature*. Before proceeding to the application of the Integral Calculus to finding the volumes and surfaces of solids we propose to show how, in certain cases, such volumes and surfaces can be found from geometrical considerations. In the first place, the volume of a rectangular parallelepiped is measured by the continued product of the three adjacent edges; and that of any parallelepiped by the area of a face multiplied by its distance from the opposite face.

Again, the volume of a right prism is measured by the product of its altitude into the area of its base. For example, the volume of the right prism represented in the figure is measured by the area of the polygon  $ABCDE$ , multiplied by the altitude  $AA'$ . Again, since each lateral face,  $AB'B'A'$  for example, is a rectangle, it follows that the sum of the areas of all the faces (exclusive of the two bases), i.e. the area of the surface of the prism, is equal to the rectangle under the altitude and the perimeter of the polygon which forms its base.

This and the preceding result still hold in the limit, when the base, instead of a polygon, is a closed curve of any form, in which case the surface generated is called a *cylinder*. Hence, if  $V$  denote the volume of the portion of a cylinder bounded by two planes drawn perpendicular to its edges,  $h$  its height, and  $A$  the area of its base, we get  $V = Ah$ .

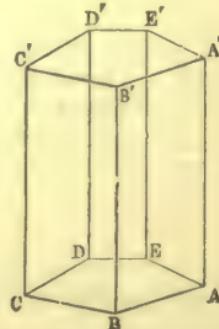


Fig. 36.

Again, if  $\Sigma$  denote the superficial area of a cylinder, bounded as before, and  $S$  the length of the curve which forms its base, we have  $\Sigma = Sh$ .

**169. The Pyramid and Cone.**—If the angular points of a polygon be joined to any external point, the solid so formed is called a *pyramid*. Any section of a pyramid by a plane parallel to its base is a polygon similar to that which forms the base, and the ratio of their homologous sides is the same as that of the distances of the planes from the vertex of the pyramid. Hence it follows that pyramids standing on the same base, and whose vertices lie in a plane parallel to the base, are equal in volume. For, the sections made by any plane parallel to the base are equal in every respect; and, consequently, if we suppose the pyramids divided into an indefinite number of slices by planes parallel to the base, the volumes of the corresponding slices will be the same for all the pyramids; and hence the entire volumes are equal.

Also, if two pyramids have equal altitudes, but stand on different polygonal bases, the volumes of the pyramids will be to each other in the same proportion as the areas of the polygonal bases. For, this proportion holds between the areas of the sections made by any plane parallel to the base; and consequently between the slices made by two infinitely near planes.

Again, the pyramid whose base is one of the faces of a cube, and whose vertex is at the centre of the cube, is the one-sixth part of the cube; for the entire cube can be divided into six equal pyramids, one for each face. Hence, denoting the side of a cube by  $a$ , the volume of the pyramid in question is represented by  $\frac{a^3}{6}$ ; i. e. by the product of the area of its base into one-third of its height.

Now, if we vary the base, without altering the height, from what has been established above it follows that the volume of any pyramid is the area of its base multiplied by one-third of its height.\*

\* This demonstration is taken from Clairaut's *Élémens de Géométrie*. The student is supposed familiar with the more ancient proof, from the property that a triangular prism can be divided into three pyramids of equal volume.

If the base of the pyramid be any closed curve, the solid so formed is called a cone; and we infer that the *volume of a cone is equal to one-third of the product of the area of its base into its height.*

If the base of a pyramid be a regular polygon, and the vertex be equidistant from the angular points of the polygon, the pyramid is called a *right pyramid*.

In this case each *face* of the pyramid is an isosceles triangle, whose area is the rectangle under the side of the polygon and half the perpendicular of the triangle. Hence the surface of the pyramid is equal to the rectangle under the semi-perimeter of the regular polygon and the perpendicular common to each face of the pyramid.

Again, if we suppose the number of sides of the regular polygon to become infinite, the pyramid becomes a right cone; and we infer that the entire surface of a right cone is equal to the rectangle under the semi-circumference of its circular base and the length of an edge of the cone.

Hence, if  $a$  be the semi-angle of the cone,  $l$  the length of an edge, and  $r$  the radius of its base, we have  $r = l \sin a$ , and the surface of the cone is represented by  $\pi l^2 \sin a$ .

If a right cone be divided by two planes  $ABC$ ,  $DEF$ , perpendicular to its axis, as in figure, the part intercepted by the planes is called a *truncated cone*.

The surface of a truncated cone is easily expressed; for if  $OA = l$ ,  $OD = l'$ , the required surface is  $\pi \sin a (l^2 - l'^2)$ , or  $\pi(l - l')(l + l') \sin a$ .

Now, if the circular section  $LMN$  be drawn bisecting the distance between  $ABC$  and  $DEF$ , the circumference of the circle  $LMN$  is  $\pi(l + l') \sin a$ . Hence the surface of the truncated cone is equal to the rectangle under the edge  $AD$  and the circumference of  $LMN$  its mean section.

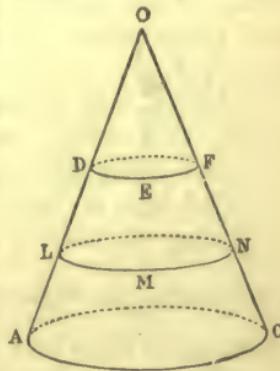


Fig. 37.

**170. Surface and Volume of a Sphere.**—To find the superficial area of a sphere; suppose a regular polygon inscribed in a semicircle, and let the figure revolve around the diameter  $AB$ ; then each side of the polygon,  $PQ$  for example, will describe a truncated cone.

Now, from the centre  $C$  draw  $CD$  perpendicular to  $PQ$ , and construct, as in figure; then, by the preceding Article, the surface generated by  $PQ$  is equal to  $2\pi PQ \cdot DI$ .

Again, by similar triangles, we have  $DC : DI = PQ : MN$ ;  
 $\therefore PQ \cdot DI = DC \cdot MN$ .

Accordingly, since the perpendicular  $CD$  is of same length for each side of the polygon, the surface generated by the entire polygon in a complete revolution is equal to  $2\pi CD \cdot AB = 4\pi R^2 \cos \frac{\pi}{n}$ ;

where  $n$  represents the number of sides of the polygon, and  $R$  the radius of the circle.

If we suppose  $n$  to become infinite, the solid generated by the polygon becomes a sphere; and we get  $4\pi R^2$  for the entire surface of the sphere. Hence, the surface of a sphere is equal to four times the area of one of its great circles.

Again, it is easy to find the surface generated by any number of sides of the polygon. Thus, for example, that generated by all the sides lying between the points  $A$  and  $Q$  is plainly equal to  $2\pi CD \cdot AN$ .

Hence, in the limit, the surface generated in a complete revolution by the arc  $AQ$  is equal to  $2\pi \cdot AC \cdot AN$ . Such a portion of a sphere is called a *spherical cap*.

Again, suppose the points  $A$  and  $Q$  connected; then, since  $AQ^2 = AB \cdot AN$ , it follows that the area of the spherical cap generated by the arc  $AQ$  is equal to the area of the circle whose radius is the chord  $AQ$ .

The volume of a sphere is readily found from its surface; for we may regard the volume as consisting of an infinitely great number of pyramids, having their common vertex at the centre, and whose bases form the entire surface. But the volume of each pyramid is represented by the product of one-third of its height (i. e. the radius) by its base. Hence the entire volume of the sphere is one-third of its radius multiplied by its surface, i. e.  $\frac{4\pi}{3} R^3$ .

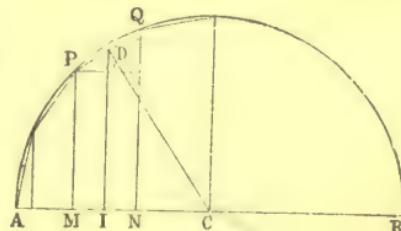


Fig. 38.

## EXAMPLES.

1. If a sphere and its circumscribing cylinder be cut by planes perpendicular to the axis of the cylinder, prove that the intercepted portions of the surfaces are equal in area.
2. Prove that the volume of a sphere is to that of its circumscribing cylinder in the proportion of 2 to 3: and that their surfaces also are in the same proportion. These results were discovered by Archimedes.

**171. Surfaces of Revolution.**—In the preceding we have regarded a sphere as generated by the revolution of a circle around a diameter. In general, if any plane be supposed to revolve around a fixed line situated in it, every point in the plane will describe a circle, and any curve lying in the plane will generate a surface.

Such a surface is called a *surface of revolution*; and the fixed line, round which the revolution takes place, is called the *axis of revolution*.

It is obvious that the section of a surface of revolution made by any plane drawn perpendicular to its axis is a circle.

If we suppose any solid of revolution to be cut by a series of planes perpendicular to its axis, the volume of the solid intercepted between any two such sections may be regarded as the limit of the sum of an indefinite number of thin cylindrical plates.

Now, if we suppose the generating curve to be referred to rectangular axes, the axis of revolution being that of  $x$ , the area of the circle generated by a point  $(x, y)$  is plainly equal to  $\pi y^2$ , and the cylindrical plate standing on it, whose thickness is  $dx$ , is represented by  $\pi y^2 dx$ .

Hence, the element of volume of the surface of revolution is  $\pi y^2 dx$ , and the entire volume comprised between two sections, corresponding to the abscissæ  $\alpha$  and  $\beta$ , is obviously represented by the definite integral

$$\pi \int_{\alpha}^{\beta} y^2 dx,$$

in which the value of  $y$  in terms of  $x$  is to be got from the equation of the generating curve.

In like manner, the volume of the surface generated by the revolution of a curve around the axis of  $y$  is represented by  $\pi \int x^2 dy$ , taken between suitable limits.

Again, we may regard the surface generated by any element  $ds$  of the curve as being ultimately a portion of the surface of a truncated cone, as in Art. 170; and hence the surface generated by  $ds$  in a complete revolution round the axis of  $x$  is represented by  $2\pi y ds$ ; and accordingly the entire surface generated is represented by

$$2\pi \int y ds,$$

taken between proper limits.

We proceed to apply these formulæ to a few elementary examples.

172. **The Sphere.**—Let  $x^2 + y^2 = a^2$  be the equation of the generating circle; then, substituting  $a^2 - x^2$  for  $y^2$ , we get for the volume

$$V = \pi \int (a^2 - x^2) dx = \pi \left( a^2 x - \frac{x^3}{3} \right) + \text{const.}$$

If we take 0 and  $a$  as limits, we get  $\frac{2\pi a^3}{3}$  for the volume of the hemisphere;  $\therefore$  the entire volume of the sphere is  $\frac{4\pi a^3}{3}$ , as in Art. 170.

To find the volume of a spherical cap, let  $h$  be the length of the portion of the diameter cut off by the bounding plane, and we get for the corresponding volume

$$\pi \int_{a-h}^a (a^2 - x^2) dx = \pi h^2 \left( a - \frac{h}{3} \right).$$

Again, to find the superficial area, we have

$$ds = \left( 1 + \frac{dy^2}{dx^2} \right)^{\frac{1}{2}} dx = \left( 1 + \frac{x^2}{y^2} \right) dx = \frac{a}{y} dx; \therefore y ds = a dx.$$

Hence, the surface of the zone contained between two parallel planes corresponding to the abscissæ  $x_1$  and  $x_0$  is

$$2\pi \int_{x_0}^{x_1} a dx = 2\pi a (x_1 - x_0);$$

that is the product of the circumference of a great circle by the breadth of the zone. This agrees with Art. 170.

173. **Right Cone.**—If  $a$  denote, as before, the angle which the right line which generates a cone makes with its axis of revolution, we get  $y = x \tan a$ , taking the vertex of the cone as origin, and the axis of revolution as that of  $x$ ; accordingly, the element of volume is  $\pi \tan^2 a x^2 dx$ .

Hence, if  $h$  denote the height of the cone, we get its volume equal to

$$\pi \tan^2 a \int_0^h x^2 dx = \frac{\pi h^3}{3} \tan^2 a;$$

i.e.  $\frac{h}{3} \times$  area of its base, as in Art. 169.

Again, to find its surface, we have  $ds = \sec a dx$ ;

$$\therefore 2\pi \int y ds = 2\pi \tan a \sec a \int_0^h x dx = \pi h^2 \tan a \sec a;$$

which agrees with the result already obtained.

#### EXAMPLES.

1. The base of a cylinder is a circle whose area is equal to the surface of a sphere of radius 5 ft.; being given that the volume of the cylinder is equal to the sum of the volumes of two spheres of radii 9 ft. and 16 ft., find the height of the cylinder.

*Ans.*  $64\frac{1}{3}$  ft.

2. A solid sector is cut out of a sphere of 10 ft. radius, by a cone the angle of which is  $120^\circ$ ; find the radius of the sphere whose solid contents are equal to those of the sector.

*Ans.*  $5\sqrt[3]{2}$ .

3. Two cones have a common base, the radius of which is 12 ft.; the altitude of one is 9 ft.; and that of the other is 5 ft.; find the radius of a sphere whose entire surface is equal to the sum of the areas of the cones.

*Ans.*  $2\sqrt{21}$  ft.

174. **Paraboloid of Revolution.**—Writing the equation of a parabola in the form  $y^2 = 2mx$ , we get for the volume of the solid generated by its revolution round the axis of  $x$

$$2\pi m \int x dx = \pi mx^2 + \text{const.} = \frac{\pi}{2} y^2 x + \text{const.}$$

Hence, the volume of the surface generated by the revolution of the part of a parabola between its vertex and the point  $(x_1, y_1)$  is represented by  $\frac{\pi}{2} y_1^2 x_1$ , i.e. is equal to half the volume of the circumscribing cylinder.

Again, to find the surface of the paraboloid, we have

$$y \, ds = y \left( 1 + \frac{y^2}{m^2} \right)^{\frac{1}{2}} \, dy = \frac{1}{m} (y^2 + m^2)^{\frac{1}{2}} y \, dy.$$

Hence, the surface of the paraboloid, between the same limits as above, is represented by

$$\frac{2\pi}{m} \int_0^{y_1} (y^2 + m^2)^{\frac{1}{2}} y \, dy = \frac{2\pi}{3m} \left\{ (y_1^2 + m^2)^{\frac{3}{2}} - m^3 \right\}.$$

**175. Spheroids of Revolution.**—If we suppose an ellipse to revolve round its axis major, the surface generated by the revolving curve is called a *prolate spheroid*. If it revolve round the axis minor the surface is called an *oblate spheroid*.

The volume of a spheroid is easily obtained ; for, taking  $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$  as the equation of the curve, we get, on substituting  $b^2 \left( 1 - \frac{x^2}{a^2} \right)$  for  $y^2$ ,

$$V = \pi \frac{b^2}{a^2} \int (a^2 - x^2) \, dx = \frac{\pi b^2}{a^2} x \left( a^2 - \frac{x^2}{3} \right) + \text{const.}$$

Hence the entire volume is  $\frac{4\pi}{3} ab^2$ . In like manner, the volume of an oblate spheroid is obviously  $\frac{4\pi}{3} ba^2$ .

**176. Surface of Spheroid.**—In the case of a prolate spheroid we have

$$ds = \left( 1 + \frac{b^4 x^2}{a^4 y^2} \right)^{\frac{1}{2}} \, dx;$$

$$\therefore y \, ds = \left( y^2 + \frac{b^4}{a^4} x^2 \right)^{\frac{1}{2}} \, dx = \left( b^2 - \frac{b^2}{a^2} e^2 x^2 \right)^{\frac{1}{2}} \, dx = \frac{be}{a} \left( \frac{a^2}{e^2} - x^2 \right)^{\frac{1}{2}} \, dx.$$

Hence, if  $CN = x_1$ ,  $CM = x_0$ , we get for  $S$ , the zone generated in a complete revolution by the arc  $PQ$ ,

$$S = 2\pi \frac{be}{a} \int_{x_0}^{x_1} \left( \frac{a^2}{e^2} - x^2 \right)^{\frac{1}{2}} dx.$$

Now, if we take  $CD = \frac{a}{e}$ ,

and construct an ellipse whose semiaxes are  $CD$  and  $CB$ , it is easily seen

(Art. 129) that the elementary area between two consecutive ordinates of this ellipse is  $\frac{be}{a} \left( \frac{a^2}{e^2} - x^2 \right)^{\frac{1}{2}} dx$ . Hence it follows that the area of the zone generated by the arc  $PQ$  is  $\pi$  times the area of the portion  $P_1 Q_1 Q_2 P_2$  of this ellipse.

Again, if  $AE_1$  be the tangent at the vertex of the original ellipse, we see that the entire surface of the spheroid is  $4\pi \times$  the area  $BCAE_1$ ; but this is seen, without difficulty, to be

$$2\pi b^2 + 2\pi \frac{ab}{e} \sin^{-1} e. \quad (1)$$

In like manner, we get for the surface  $S$  generated by the revolution of an ellipse round its minor axis

$$\begin{aligned} S &= 2\pi \int x ds = 2\pi \int \left( a^2 + \frac{a^4 e^2}{b^4} y^2 \right)^{\frac{1}{2}} dy \\ &= 2\pi \frac{a^2 e}{b^2} \int \left( y^2 + \frac{b^4}{a^2 e^2} \right)^{\frac{1}{2}} dy. \end{aligned}$$

If this be integrated, as in Art. 151, we get, after some obvious reductions,

$$S = \pi \frac{ay}{b^2} (a^2 e^2 y^2 + b^4)^{\frac{1}{2}} + \pi \frac{b^2}{e} \log \frac{ae y + (a^2 e^2 y^2 + b^4)^{\frac{1}{2}}}{b^2}.$$

If this be taken between the limits 0 and  $b$ , and doubled, we get for the entire surface of the ellipsoid

$$2\pi a^2 + \pi \frac{b^2}{e} \log \left( \frac{1+e}{1-e} \right). \quad (2)$$

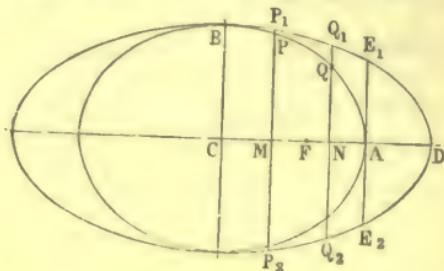


Fig. 39.

It is readily seen, as in the former case, that the surface of any zone of this ellipsoid is  $\pi$  times the area of a corresponding portion of the hyperbola

$$\frac{x^2}{a^2} - \frac{a^2 e^2 y^2}{b^4} = 1$$

bounded by lines drawn parallel to the axis of  $x$ .

The area of the surface generated by the revolution of a hyperbola round either axis admits of a similar investigation.

EXAMPLES.

1. Find the volume of the surface generated by the revolution of a cycloid round its base.

Here, referring the cycloid to  $DA$  and  $DB$  as co-ordinate axes, we have (see Diff. Calc., Art. 272)

$$x = a(\phi + \sin \phi), \quad y = a(1 + \cos \phi),$$

where  $\angle PCL = \phi$ .

Hence

$$dV = \pi y^2 dx = \pi a^3 (1 + \cos \phi)^3 d\phi;$$

$\therefore$  for the entire volume  $V$ , we get

$$V = 2\pi a^3 \int_0^\pi (1 + \cos \phi)^3 d\phi = 16\pi a^3 \int_0^\pi \cos^6 \frac{\phi}{2} d\phi$$

$$= 32\pi a^3 \int_0^{\frac{\pi}{2}} \cos^6 \theta d\theta, \quad \text{making } \frac{\phi}{2} = \theta.$$

Hence

$$V = 5\pi^2 a^3.$$

2. Find the whole surface generated in the same case.

Here  $S = 2\pi \int y ds = 4\pi a^2 \int (1 + \cos \phi) \cos \frac{\phi}{2} d\phi;$

hence the entire surface is

$$32\pi a^2 \int_0^\pi \cos^3 \frac{\phi}{2} d\phi = \frac{64\pi a^3}{3}.$$

[17 a]

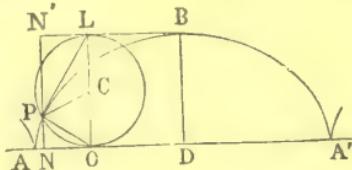


Fig. 40.

3. Find the volume and the surface of the solid generated by the revolution of the tractrix round its axis.

(1). Here we have

$$y^2 dx = -(a^2 - y^2)^{\frac{1}{2}} y dy;$$

hence the volume generated by the portion  $AP$  is

$$\pi \int_y^a (a^2 - y^2)^{\frac{1}{2}} y dy = \frac{\pi}{3} (a^2 - y^2)^{\frac{3}{2}}.$$

The volume generated by the entire tractrix is  $\frac{2\pi}{3} a^3$ ; i. e. half the volume of the sphere whose radius is  $OA$ .

(2). The surface generated by  $AP$  is

$$2\pi \int y ds = 2\pi a \int_y^a dy \quad (\text{see Ex. 2, Art. 154})$$

$$= 2\pi a (a - y).$$

Hence the entire surface generated is  $2\pi a^2$ ; i. e. half the surface of the sphere of radius  $OA$ .

4. Find the volume, and also the surface, generated by the revolution of the catenary around the axis of  $x$ .

(1). Here the volume of the solid generated by  $VP$  is represented by

$$\begin{aligned} \pi \int_0^x y^2 dx &= \frac{\pi a^2}{4} \int_0^x \left( e^{\frac{2x}{a}} + e^{-\frac{2x}{a}} + 2 \right) dx \\ &= \frac{\pi a^2}{4} \left\{ \frac{a}{2} \left( e^{\frac{2x}{a}} - e^{-\frac{2x}{a}} \right) + 2x \right\} \\ &= \frac{\pi a}{2} (ys + ax), \end{aligned}$$

where  $s = PV$ .

(2). Again, since

$$ds = \frac{1}{2} \left( e^{\frac{x}{a}} + e^{-\frac{x}{a}} \right) dx = \frac{y dx}{a},$$

we have

$$2\pi \int y ds = \frac{2\pi}{a} \int y^2 dx.$$

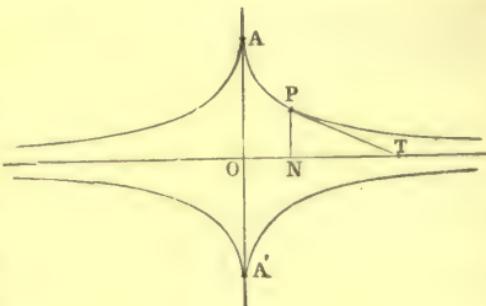


Fig. 41.

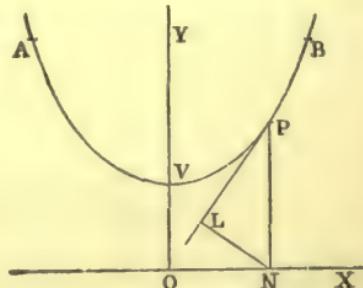


Fig. 42.

Consequently the surface generated by  $PV$  in a complete revolution is  $\frac{2}{a} \times$  the volume generated; i.e.  $= \pi (ys + ax)$ .

5. In the same curve to find the surface generated by its revolution round the axis  $OV$ .

Here

$$S = 2\pi \int x ds = \pi \int x e^{\frac{x}{a}} dx + \pi \int x e^{-\frac{x}{a}} dx.$$

Again

$$\int_0^x x e^{\frac{x}{a}} dx = a x e^{\frac{x}{a}} - a \int_0^x e^{\frac{x}{a}} dx = a (x e^{\frac{x}{a}} - a e^{\frac{x}{a}} + a).$$

Also the value of

$$\int_0^x x e^{-\frac{x}{a}} dx$$

is obtained by changing the sign of  $a$  in the last result.

Hence

$$\begin{aligned} \int_0^x x e^{-\frac{x}{a}} dx &= a^2 - a x e^{-\frac{x}{a}} - a^2 e^{-\frac{x}{a}}; \\ \therefore S &= \pi \left\{ 2a^2 + ax \left( e^{\frac{x}{a}} - e^{-\frac{x}{a}} \right) - a^2 \left( e^{\frac{x}{a}} + e^{-\frac{x}{a}} \right) \right\} \\ &= 2\pi (a^2 + xs - ay). \end{aligned}$$

177. **Annular Solids.**—If a closed curve, which is symmetrical with respect to a right line, be made to revolve round a parallel line, then the superficial area generated in a complete revolution is equal to the product of the length of the moving curve into the circumference of the circle whose radius is the distance between the parallel lines.

This is easily proved: for let

$APBP'$  be any curve, symmetrical with respect to  $AB$ , and suppose  $OX$  to be the axis of revolution; and draw  $PN, QM$  two indefinitely near lines perpendicular to the axis. It is evident that  $PQ = P'Q'$ . Again, let  $PN = y, P'N = y', PQ = P'Q' = ds, DN = b$ ; then the sum of the elementary zones described by  $PQ$  and  $P'Q'$  in a complete revolution is represented by

$$2\pi (y + y') ds = 4\pi b ds.$$

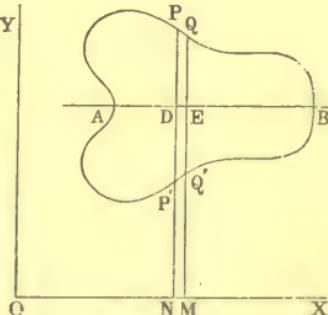


Fig. 43.

Consequently the surface generated by the entire curve is  $2\pi bS$ , where  $S$  denotes the whole length of the curve.

A similar theorem holds for the volume of the solid generated: viz., the volume generated is equal to the product of the area of the revolving curve into the circumference of the same circle as before.

For the volume of this solid is plainly represented by

$$\pi \int (y^2 - y'^2) dx,$$

or by  $\pi \int (y - y')(y + y') dx = 2\pi b \int (y - y') dx$ .

But the area of the curve is represented by

$$\int (y - y') dx:$$

consequently, denoting this area by  $A$ , and the volume by  $V$ , we have

$$V = 2\pi b \times A.$$

In these results the axis of revolution is supposed not to intersect the curve; if it does, the expression  $2\pi b \times A$  represents the difference between the volumes of the surfaces generated by the portions of the curve lying at opposite sides of the axis of revolution; as is readily seen. A similar alteration must be made in the former theorem in this case.

If a circle revolve round any external axis situated in its plane, the surface generated is called a spherical ring. From the preceding it follows that the entire surface of such a ring is  $4\pi^2 ab$ ; where  $a$  is the radius of the circle, and  $b$  the distance of its centre from the axis of revolution.

In like manner the volume of the ring is  $2\pi^2 a^2 b$ .

It would be easy to add other applications of these theorems.

**178. Guldin's\* Theorems.**—The results established in the preceding Article are but particular cases of two general

\* Guldin, *Centrobaryica, seu de centro gravitatis trium specierum quantitatis continuæ*, 1635. Guldin arrived at his principle by induction from a small number of elementary cases, but his attempt at a general demonstration was an eminent failure. See Montucla *Hist. des Math.*, tom. ii. p. 34. Montucla has shown, tom. ii. p. 92, that Guldin's theorems can be established from geometrical considerations, without recourse to the Calculus.

propositions, usually called Guldin's Theorems, but originally enunciated by Pappus (see Walton's *Mechanical Problems*, p. 42, third Edition). They may be stated as follows :—

(1). If a plane curve revolve round any external axis, situated in its plane, *the area of the surface generated is equal to the product of the perimeter of the revolving curve by the length of the path described, during the revolution, by the centre of gravity of that perimeter.*

(2). Under the same circumstances, *the volume of the solid generated is equal to the product of the area of the generating curve into the path described by the centre of gravity of the revolving area.*

To prove the former, let  $s$  denote the whole length of the curve,  $x, y$ , the co-ordinates of one of its points,  $\bar{x}, \bar{y}$ , those of the centre of gravity of the curve ; then, from the definition of these latter, we have

$$\bar{y} = \frac{\int y \, ds}{s};$$

$$\therefore 2\pi \bar{y} s = 2\pi \int y \, ds,$$

i.e. the surface generated by revolution round the axis of  $x$  is equal to the product of  $S$ , the length of the generating curve, into  $2\pi \bar{y}$ , the path described by the centre of gravity.

To prove the second proposition ; let  $A$  denote the area of the generating curve, and  $dA$  the element of area corresponding to any point  $x, y$ . Also let  $\bar{x}, \bar{y}$  be the co-ordinates of the centre of gravity of the area, then

$$\bar{y} = \frac{\Sigma y dA}{A} = \frac{\iint y \, dx \, dy}{A} \text{ (substituting } dx \, dy \text{ for } dA\text{)};$$

$$\therefore 2\pi \bar{y} A = 2\pi \iint y \, dx \, dy = \pi \int y^2 \, dx;$$

where the integral is supposed taken for every point round the perimeter of the curve : but, from Art. 171, the integral at the right-hand side represents the volume of the solid generated ; hence the proposition in question follows.

For example, the volume of the ring generated by the revolution of an ellipse around any exterior line situated in its plane is at once  $2\pi^2 abc$ , where  $a$  and  $b$  are the semiaxes

of the ellipse, and  $c$  is the distance of its centre from the axis of revolution.

It may be noted that these results still hold if we suppose the curve, instead of making a complete revolution, to turn round the axis through any angle. For, let  $\theta$  be the circular measure of the angle of rotation, and in the former case we have

$$\theta \bar{y}s = \theta \int y ds.$$

But  $\theta \bar{y}$  is the length of the path described by the centre of gravity, and  $\theta \int y ds$  is the area of the surface generated by the curve;  $\therefore$  &c.

In like manner the second proposition can be shown to hold.

Again, Guldin's theorems are still true if we suppose the rotation to take place around a number of different axes in succession; in which case the centre of gravity, instead of describing a single circle, would describe a number of arcs of circles consecutively; and the whole area of the surface generated will still be measured by the product of the length of the generating curve into the path of its centre of gravity; for this result holds for the part of the surface corresponding to each axis of revolution separately, and therefore holds for the sum.

Again, in the limit, when we suppose each separate rotation indefinitely small, we deduce the following theorem. If any plane curve move so that the path of its centre of gravity is at each instant perpendicular to the moving plane, then the surface generated by the curve is equal to the length of the curve into the path described by its centre of gravity.

The corresponding theorem holds for the volume of the surface generated.

These extensions of Guldin's theorems were given by Leibnitz (*Act. Erud. Lips.*, 1695).

**179. Expression for Volume of any Solid.**—The method given in Art. 171 of investigating the volume bounded by a surface of revolution can be readily extended to a solid bounded in any manner. For, if we suppose the volume divided into slices by a system of parallel planes, the entire volume may, as before, be regarded as the limit of the sum

of a number of infinitely thin cylindrical plates. Thus, if we suppose a system of rectangular co-ordinate axes taken, and the cutting planes drawn parallel to that of  $xy$ ; then, if  $A_z$  represent the area of the section made by a plane drawn at the distance  $z$  from the origin, the entire volume is denoted by

$$\int A_z dz,$$

taken between proper limits.

The area  $A_z$  is to be determined in each case as a function of  $z$  from the conditions of the bounding surface.

For example, to find the volume of the portion of a cone cut off by any plane; we take the origin at the vertex, and the axis of  $z$  perpendicular to the cutting plane; then, if  $B$  denote the area of the base, and  $h$  the height of the cone, it is easily seen that we have

$$A_z : B = z^2 : h^2, \text{ or } A_z = \frac{Bz^2}{h^2};$$

$$\therefore V = \frac{B}{h^2} \int_0^h z^2 dz = \frac{1}{3} B \times h; \text{ as in Art. 169.}$$

If the cutting planes be parallel to that of  $yz$ , the volume is denoted by  $\int A_x dx$ ; where  $A_x$  denotes the area of the section at the distance  $x$  from the origin.

**180. Volume of Elliptic Paraboloid.**—Let it be proposed to find the volume of the portion of the elliptic paraboloid

$$\frac{x^2}{p} + \frac{y^2}{q} = 2z,$$

cut off by a plane drawn perpendicular to the axis of the surface. Here, considering  $z$  as constant, the area of the ellipse

$$\frac{x^2}{p} + \frac{y^2}{q} = 2z, \text{ by Art. 128, is } 2\pi z \sqrt{pq}.$$

Hence, denoting by  $c$  the distance of the bounding plane from the vertex of the surface, we have

$$V = 2\pi \sqrt{pq} \int_0^c z dz = \pi c^2 \sqrt{pq}.$$

This result admits of being exhibited in another form ; for if  $B$  be the area of the elliptic section made by the bounding plane, we have

$$B = 2\pi c \sqrt{pq}.$$

Hence  $V = \frac{1}{3}$  circumscribing cylinder, as in paraboloid of revolution.

**181. The Ellipsoid.**—Next, to find the volume of the ellipsoid

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1.$$

The section of the surface at the distance  $z$  from the origin is the ellipse

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1 - \frac{z^2}{c^2} :$$

the area of this ellipse is

$$\pi \left( 1 - \frac{z^2}{c^2} \right) ab, \text{ i.e. } A_z = \pi \left( 1 - \frac{z^2}{c^2} \right) ab.$$

Hence, denoting the entire volume by  $V$ , we have

$$V = 2\pi ab \int_0^c \left( 1 - \frac{z^2}{c^2} \right) dz = \frac{4}{3} \pi abc.$$

**182. Case of Oblique Axes.**—It is sometimes more convenient to refer the surface to a system of oblique axes. In this case, if, as before, we take the cutting planes parallel to that of  $xy$ , and if  $\omega$  be the angle the axis of  $z$  makes with the plane of  $xy$ , the expression for the volume becomes

$$\sin \omega \int A_z dz,$$

taken between proper limits, where  $A_z$  represents the area of the section, as in the former case.

For example, let us seek the volume of the portion of an ellipsoid cut off by any plane.

Suppose  $DED'E'$  to represent the section made by the plane, and  $ABA'B'$  the parallel central section. Take  $OA$ ,  $OB$ , the axes of this section as axes of  $x$  and  $y$  respectively; and the conjugate diameter  $OC$  as axis of  $z$ .

Then the equation of the surface is

$$\frac{x^2}{a'^2} + \frac{y^2}{b'^2} + \frac{z^2}{c'^2} = 1;$$

where  $OA = a'$ ,  $OB = b'$ ,  $OC = c'$ .

It will now be convenient to transfer the origin to the point  $C'$ , without altering the directions of the axes, when the equation of the surface becomes

$$\frac{x^2}{a'^2} + \frac{y^2}{b'^2} = \frac{2z}{c'} - \frac{z^2}{c'^2}.$$

The area  $A_s$  of the section, by Art. 128, is

$$\pi a' b' \left( \frac{2z}{c'} - \frac{z^2}{c'^2} \right); \quad (3)$$

hence, denoting  $C'N$  by  $h$ , the volume cut off by the plane  $DED'$  is represented by

$$\pi a' b' \sin \omega \int_0^h \left( \frac{2z}{c'} - \frac{z^2}{c'^2} \right) dz,$$

or

$$\pi a' b' \sin \omega \left( \frac{h^2}{c'} - \frac{h^3}{3c'^2} \right).$$

But, by a well-known theorem,\* we have

$$a' b' c' \sin \omega = abc,$$

where  $a$ ,  $b$ ,  $c$ , are the principal semiaxes of the surface.

Hence the expression for the volume  $V$  in question becomes

$$V = \pi abc \left( \frac{h^2}{c'^2} - \frac{h^3}{3c'^3} \right); \quad (4)$$

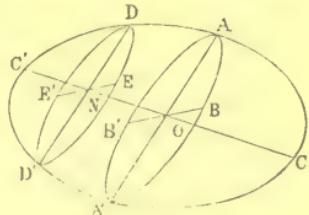


Fig. 44.

\* Salmon's *Geometry of Three Dimensions*, Art. 96.

or, denoting  $\frac{C'N}{C'O}$  by  $k$ ,

$$V = \pi abck^2 \left( 1 - \frac{k}{3} \right). \quad (5)$$

This result shows that the volume cut off is constant for all sections for which  $k$  has the same value. Again, since  $\frac{ON}{OC'} = 1 - k$ , the locus of  $N$  is a similar ellipsoid; and we infer that *if a plane cut a constant volume from an ellipsoid, the locus of the centre of the section is a similar and similarly situated ellipsoid.*

183. **Elliptic Paraboloid.**—The corresponding results for the elliptic paraboloid can be deduced from the preceding by adopting the usual method of such derivation: viz., by taking

$$a^2 = pc, \quad b^2 = qc,$$

and afterwards making  $c$  infinite; observing that in this case the ratio  $\frac{c}{c'}$  becomes unity.

Making these substitutions in (4), it becomes

$$V = \pi \sqrt{pq} h^2 \left( 1 - \frac{h}{3c'} \right), \text{ or } \pi h^2 \sqrt{pq}, \text{ since } c' = \infty.$$

Hence, if a constant length be measured on any diameter of an elliptic paraboloid and a conjugate plane drawn, then the volume\* of the segment cut from the paraboloid by the plane is constant.

Again, the area of an elliptic section by (3) is

$$\pi a' b' \left( \frac{2h}{c'} - \frac{h^2}{c'^2} \right), \text{ or } \frac{\pi abc}{c' \sin \omega} \left( \frac{2h}{c'} - \frac{h^2}{c'^2} \right).$$

\* For a more direct investigation the student is referred to a memoir "On some Properties of the Paraboloid," *Quarterly Journal of Mathematics*, June, 1874, by Professor Allman.

On making the same substitutions, this becomes for the paraboloid

$$\frac{2\pi\sqrt{pq}}{\sin\omega}h.$$

Now, if we suppose a cylinder to stand on this section, the volume of the portion cut off by the parallel tangent plane to the paraboloid is obtained by multiplying the area of the section by  $h \sin \omega$ ; and, consequently, is

$$2\pi\sqrt{pq}h^2,$$

i. e. is double the corresponding volume of the paraboloid.

This is an extension of the theorem of Art. 180.

#### EXAMPLES.

1. Prove that the volume of the segment cut from a paraboloid by any plane is  $\frac{1}{4}$ ths of that of the circumscribing cone standing on the section made by the plane as base.

2. A cylinder intersects the plane of  $xy$  in an ellipse of semiaxes  $OA = a$ ,  $OB = b$ , and the plane of  $xz$  in an ellipse of semiaxes  $OA = a$ ,  $OC = c$ ; the edges of the cylinder being parallel to  $BC$ ; find the volume of the portion of the cylinder bounded by the three co-ordinate planes. *Ans.*  $\frac{1}{3}abc$ .

3. The axes of two equal right cylinders intersect at right angles; find the volume common to both. *Ans.*  $\frac{16}{3}a^3$ , where  $a$  is the radius of either cylinder. This surface is called a *Groin*.

184. **Volume by Double Integration.**—In the application of the preceding method of finding volumes the area represented by  $A_x$ , instead of being immediately known, requires in general a previous integration; so that the determination of the volume of a surface involves two successive integrations, and consequently  $V$  is expressed by a *double integral*.

Thus, as the area  $A_x$  lies in a plane parallel to that of  $yz$ , its value, as in Art. 126, may generally be represented by  $\int z dy$ , taken between proper limits. Hence  $V$  may be represented by

$$\int [\int z dy] dx;$$

or, adopting the usual notation, by

$$\iint z dy dx,$$

taken between limits determined by the data of the question.

The value of  $z$  is supposed given by a relation  $z = f(x, y)$ , by means of the equation of the bounding surface; hence

$$\int z dy = \int f(x, y) dy.$$

In the determination of this integral we regard  $x$  as constant (since all the points in the area have the same value of  $x$ ), and integrate with respect to  $y$  between its proper limits.

Thus, if  $y_1$  and  $y_0$  denote the limiting values of  $y$ , the definite integral

$$\int_{y_0}^{y_1} f(x, y) dy$$

becomes a function of  $x$ : this function, when integrated with respect to  $x$  between the proper limits, determines the volume in question.

If  $x_1$  and  $x_0$  denote the limits of  $x$ ,  $V$  may be represented by the double integral

$$\int_{x_0}^{x_1} \int_{y_0}^{y_1} f(x, y) dy dx.$$

We shall exemplify this by a figure, in which we suppose the volume bounded by the plane of  $xy$ , by a cylinder perpendicular to that plane, and also by any surface.\* Let  $RPR'Q$  represent the section of the cylinder by the plane of  $xy$ ; and suppose  $PMNQ$  to be the section of the volume by a plane parallel to  $yz$  at the distance  $x$  from the origin. Let  $PL = y_1$ ,  $QL = y_0$ , then the area  $PMNQ$  is represented by the integral

$$\int_{y_0}^{y_1} z dy.$$

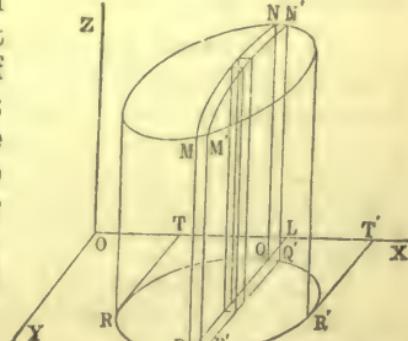


Fig. 45.

\* The determination of a volume of any form is virtually contained in this. For, if we suppose the surface circumscribed by a cylinder perpendicular to the plane of  $xy$ , the required volume will become the difference between two cylinders, bounded by the upper and lower portions of the surface, respectively. See Bertrand, *Calc. Int.* § 447.

The values\* of  $y_1$  and  $y_0$  in terms of  $x$  are obtained from the equation of the curve  $RPR'Q$ .

Again, suppose  $P'M'N'Q'$  to represent the parallel section at the infinitesimal distance  $dx$  from  $PMNQ$ , then the elementary volume between  $PMNQ$  and  $P'M'N'Q'$  is represented by

$$dx \int_{y_0}^{y_1} z dy.$$

Now, if  $RT$  and  $R'T'$  be tangents to the bounding curve, drawn perpendicular to the axis of  $x$ , and if  $OT' = x_1$ ,  $OT = x_0$ , the entire volume is represented by

$$\int_{x_0}^{x_1} \int_{y_0}^{y_1} z dy dx.$$

It should be observed that  $z dy dx$  represents the volume of the parallelepiped whose height is  $z$ , and whose base is the infinitesimal rectangle having  $dx$  and  $dy$  as sides; and consequently the volume may be regarded as the sum of all such parallelepipeds corresponding to every point within the area  $RPR'Q$ .

It is also plain that we shall arrive at the same result whether we integrate first with respect to  $x$ , and afterwards with respect to  $y$ , or *vice-versa*; i. e. whether we conceive the volume divided into slices parallel to the plane of  $xz$ , or to that of  $yz$ .

We shall illustrate the preceding by an example.†

Suppose  $RPR'Q$  to be the circle

$$(x - a)^2 + (y - b)^2 = R^2,$$

and the bounding surface the hyperbolic paraboloid

$$xy = cz;$$

\* In our investigation we have assumed that the parallels intersect the curve in but two points each; the general case is omitted, as the solution in such cases can be rarely obtained, and also as the investigation is unsuited for an elementary treatise.

† This and the next example are taken from Cauchy's *Applications Géométriques du Calcul Infinitésimal*, p. 109.

then we have

$$y_0 = b - \sqrt{R^2 - (x-a)^2}, \quad y_1 = b + \sqrt{R^2 - (x-a)^2},$$

and

$$\int_{y_0}^{y_1} z \, dy = \frac{1}{c} \int_{y_0}^{y_1} xy \, dy = \frac{x}{2c} (y_1^2 - y_0^2) = \frac{2bx}{c} \sqrt{R^2 - (x-a)^2}.$$

$$\text{Again,} \quad x_1 = a + R, \quad x_0 = a - R;$$

$$\therefore V = \frac{2b}{c} \int_{a-R}^{a+R} \sqrt{R^2 - (x-a)^2} x \, dx.$$

Now let  $x - a = R \sin \theta$ , and we get

$$V = \frac{2bR^2}{c} \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos^2 \theta (a + R \sin \theta) d\theta.$$

$$\text{But} \quad \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos^2 \theta d\theta = \frac{\pi}{2}, \quad \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos^2 \theta \sin \theta d\theta = 0,$$

$$\therefore V = \pi \frac{abR^2}{c}.$$

Again, if for the cylindrical surface which has for its base the circle we substitute a system of four planes  $x = x_0$ ,  $x = X$ ,  $y = y_0$ ,  $y = Y$ , we get

$$\begin{aligned} V &= \int_{x_0}^X \int_{y_0}^Y \frac{xy}{c} dy dx \\ &= \frac{1}{4c} (X^2 - x_0^2) (Y^2 - y_0^2) \\ &= (X - x_0) (Y - y_0) \frac{x_0 y_0 + x_0 Y + X y_0 + X Y}{4c} \\ &= (X - x_0) (Y - y_0) \frac{z_1 + z_2 + z_3 + z_4}{4}, \end{aligned}$$

in which  $z_1, z_2, z_3, z_4$ , are the ordinates of the four corner points of the portion of the surface in question.

Again, from the well-known properties of the surface, in order to construct the hyperbolic paraboloid it is sufficient to trace the gauche quadrilateral whose summits are the extremities of the ordinates  $z_1, z_2, z_3, z_4$ ; then a right line moving on a pair of opposite sides of this quadrilateral, and comprised in a plane parallel to the other pair, will generate the paraboloid in question.

Hence we arrive at the following proposition:—

Having traced a gauche quadrilateral on the four lateral faces of a right prism standing on a rectangular base, if a right line move on two opposite sides of this quadrilateral and be parallel to the planes of the faces which contain the other two sides, then the volume cut from the prism by the surface so generated is equal to the product of the area of the rectangular base of the prism by one-fourth of the sum of the edges of the prism between the vertices of the rectangle and those of the quadrilateral.

185. **Double Integration.**—From the preceding Article it is readily seen that the double integral

$$\iint f(x, y) dy dx$$

can be represented geometrically by a volume; and the determination of the double integral, when the limits are given, is the same as the finding the volume of a solid with corresponding limits.

For instance, the example in the preceding page is equivalent to finding the value of the double integral

$$\iint xy dx dy$$

taken for all values of  $x$  and  $y$  subject to the condition

$$(x - a)^2 + (y - b)^2 - R^2 < 0;$$

and similarly in other cases.

When the limits of  $x$  and  $y$  are constants, as in

$$\int_a^{a'} \int_b^{b'} f(x, y) dy dx,$$

the double integral represents the volume cut by the surface

$$z = f(x, y)$$

from the parallelepiped whose base is the rectangle formed by the lines

$$x = a, \quad x = a', \quad y = b, \quad y = b'.$$

It is plain that in this case the order of integration is indifferent, as already seen in Art. 115.

186. It is sometimes more convenient to refer the curve  $RPR'Q$  to polar co-ordinates, in which case we conceive the area divided into infinitesimal rectangles of the type  $r dr d\theta$ .

The corresponding parallelepiped is represented by  $z r dr d\theta$ , and the expression for  $V$  becomes

$$V = \iint z r dr d\theta,$$

taken between proper limits.

For instance, if the bounding surface be a sphere, whose centre is the origin, we have

$$z = \sqrt{a^2 - r^2},$$

and the equation becomes

$$V = \iint \sqrt{a^2 - r^2} r dr d\theta;$$

but  $\int \sqrt{a^2 - r^2} r dr = -\frac{1}{3} (a^2 - r^2)^{\frac{3}{2}}$ .

Hence, if  $V$  denote the volume included between the sphere and the *exterior* surface of the cylinder, we shall have

$$V = \frac{1}{3} \int (a^2 - r^2)^{\frac{3}{2}} d\theta,$$

where we suppose each radius of the sphere to cut the cylinder in but one point.

For example, let the base of the cylinder be the pedal of an ellipse whose major axis coincides with a diameter of the sphere; then

$$r^2 = a^2 \cos^2 \theta + b^2 \sin^2 \theta,$$

and  $V = \frac{1}{3} (a^2 - b^2)^{\frac{3}{2}} \int \sin^3 \theta d\theta.$

If this be integrated between the limits 0 and  $\frac{\pi}{2}$  we get the  $\frac{1}{8}$ th of the entire volume; hence the entire volume

$$V = \frac{16}{9} (a^2 - b^2)^{\frac{3}{2}}.$$

## EXAMPLES.

1. A sphere is cut by a right cylinder, the radius of whose base is half that of the sphere, and one of whose edges passes through the centre of the sphere; find the volume common to both surfaces.

*Ans.*  $\frac{2\pi a^3}{3} - \frac{8a^3}{9}$ ,  $a$  being the radius of the sphere.

2. If the base of the cylinder be the complete curve represented by the equation  $r = a \cos n\theta$ , where  $n$  is any integer, find the volume of the solid between the surface of the sphere and the external surface of the cylinder.

187. It is readily seen, as in Art. 141, that the volume included within the surface represented by the equation

$$F\left(\frac{x}{a}, \frac{y}{b}, \frac{z}{c}\right) = 0$$

is  $abc \times$  the volume of the surface

$$F(x, y, z) = 0.$$

For, let  $\frac{x}{a} = x'$ ,  $\frac{y}{b} = y'$ ,  $\frac{z}{c} = z'$ , and we shall have

$$z dx dy = abc z' dx' dy',$$

and

$$\therefore \iint z dx dy = abc \iint z' dx' dy';$$

which proves the theorem.

Hence, for example, the determination of the volume of an ellipsoid is reduced to that of a sphere.

Again, if the point  $(x, y, z)$  move along a plane, the corresponding point  $(x', y', z')$  will describe another plane. From this property the expression for the volume of an ellipsoidal cap (Art. 182) can be immediately deduced from that of a spherical cap (Art. 170).

In like manner the volume included between a cone enveloping an ellipsoid and the surface of the ellipsoid is reducible to the corresponding volume for a sphere.

188. **Quadrature on the Sphere.**—We next propose to give a brief discussion of quadrature on a sphere, and commence with the results on the subject usually given in treatises on Spherical Trigonometry. In the first place, since the area of a lune is to that of the entire sphere as the angle of the lune to four right angles, the area of a lune of angle  $A$  is represented by  $2R^2A$ ; where  $R$  is the radius of the sphere, and  $A$  is expressed in circular measure.

Again, the area of a spherical triangle  $ABC$  is expressed by  $R^2(A + B + C - \pi)$ ; for, the sum of the three lunes exceeds the hemisphere by twice the area of the triangle, as is easily seen from a figure.

Hence, it readily follows that the area  $\Sigma$  of a spherical polygon of  $n$  sides is represented by

$$\Sigma = R^2\{A + B + C + \&c. - (n - 2)\pi\};$$

$A, B, C, \&c.$ , being the angles of the polygon.

This result admits of being expressed in terms of the sides of the polar polygon; for, representing these sides by  $a', b', c', \&c.$ , we have

$$A = \pi - a', \quad B = \pi - b', \quad \&c.,$$

and consequently

$$\Sigma = R^2\{2\pi - (a' + b' + c' + \&c.)\}.$$

Or, denoting the perimeter of the polar figure by  $S$ ,

$$\Sigma + RS = 2\pi R^2. \quad (6)$$

This proof is perfectly general, and holds in the limit, when the polygon becomes any curve; and, accordingly, the area bounded by any closed spherical curve is connected with the perimeter of its polar curve by the relation (6).

Again, the spherical area bounded by a lesser circle (Art. 170) admits of a simple expression. If  $\rho$  denote the circular radius of the circle, or the arc from its pole to its circumference, the area in question is represented by

$$2\pi R^2(1 - \cos \rho);$$

for (see fig. Art. 170) we have

$$AN = AC - CN = R(1 - \cos \rho).$$

This result also follows immediately as a simple case of equation (6).

Again, the area bounded by the lesser circle and by two arcs drawn to its pole is plainly represented by

$$R^2 a (1 - \cos \rho),$$

where  $a$  is the circular measure of the angle between the arcs.

We can now find an expression for the area bounded by any closed curve on a sphere; for the position of any point  $P$  on the surface can be expressed by means of the arc  $OP$  drawn to a fixed point, and of the angle  $POX$  between this arc and a fixed arc through  $O$ . These are called the polar co-ordinates of the point, and are analogous to ordinary polar co-ordinates on a plane.

Now, let  $OP = \rho$ , and  $POX = \omega$ ; then any curve on the sphere may be supposed to be expressed by a relation between  $\rho$  and  $\omega$ .

Again, suppose  $OQ$  to represent an infinitely near vector, and draw  $PR$  perpendicular to  $OP$ ; then, neglecting in the limit the area  $PQR$ , the elementary area  $OPQ$  by the preceding is represented by

$$R^2 (1 - \cos \rho) d\omega.$$

Hence the area bounded by two vectors from  $O$  is expressed by the integral  $R^2 \int (1 - \cos \rho) d\omega$ , taken between suitable limits.

If the curve be closed, the entire superficial area becomes

$$R^2 \int_0^{2\pi} (1 - \cos \rho) d\omega.$$

The value of  $\cos \rho$  in terms of  $\omega$  is to be determined in each case by means of the equation of the bounding curve.

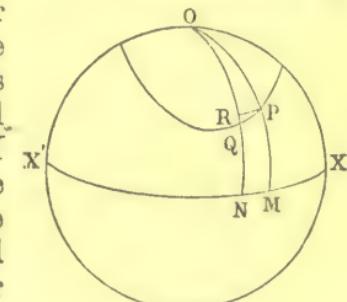


Fig. 46.

The integral  $R^2 \int_0^{2\pi} \cos \rho \, d\omega$  obviously represents the area included between the closed curve and the great circle which has  $O$  for its pole.

The length of the curve can also be represented by a definite integral; for, regarding  $PRQ$  as ultimately a right-angled triangle, we have in the limit,

$$PQ^2 = PR^2 + RQ^2 : \text{ also } PR = \sin \rho \, d\omega.$$

Hence  $ds^2 = dr^2 + \sin^2 \rho \, d\omega^2,$

or  $ds = d\omega \sqrt{\sin^2 \rho + \left(\frac{d\rho}{d\omega}\right)^2};$

$$\therefore s = \int d\omega \sqrt{\sin^2 \rho + \left(\frac{d\rho}{d\omega}\right)^2}.$$

Again, it is manifest from (6) that the determination of the length of any spherical curve is reducible to finding the area of its polar curve, and *vice versa*.

### EXAMPLES.

1. Find the area of the portion of the surface of a sphere which is intercepted by a right cylinder, one of whose edges passes through the centre of the sphere, and the radius of whose base is half that of the sphere.

Here, the equation of the base may be written in the form  $r = R \sin \omega$ ,  $R$  being the radius of the sphere, and  $\omega$  being measured from the tangent to the circular base.

Again, from the sphere we have  $r = R \sin \rho$ ;  $\therefore \rho = \omega$  is the equation of the curve of intersection of the sphere and the cylinder; hence the area in question is

$$2R^2 \int_0^{\frac{\pi}{2}} (1 - \cos \omega) d\omega = 2R^2 \left(\frac{\pi}{2} - 1\right).$$

This being doubled gives the whole intercepted area =  $2\pi R^2 - 4R^2$ .

This is the celebrated Florentine enigma, proposed by Vincent Viviani as a challenge to the Mathematicians of his time, in the following form:—"Inter venerabilia olim Græciæ monumenta extat adhuc, perpetuo quidem duraturum, Templum augustissimum ichnographia circulari Almae Geometriæ dicatum, quod Testudine intus perfecte hemisphærica operitur: sed in hac fenestrarum quatuor æquales areæ (circum ac supra basin hemisphæræ ipsius dispositarum) tali configuratione, amplitudine, tantaque industria, ac ingenii acumine sunt exstructæ,

ut his detractis, superstes curva Testudinis superficies, pretioso opere musivo ornata, Tetragnomis vere geometricis sit capax."—*Acta Eruditorum*, Leipsic, 1692. [See Montucla, *Histoire des Mathématiques*, tome ii., p. 94.]

In general, if  $r = f(\omega)$  be the equation of the base of a cylinder, it is easily seen that the equation of the curve of its intersection with the sphere may be written in the form  $R \sin \rho = f(\omega)$ .

For example, let the diameter of the right cylinder be less than half that of the sphere; then writing the equation of the base in the form  $r = a \sin \omega$ , where  $a$  is the diameter of the section, we get  $R \sin \rho = a \sin \omega$ , or  $\sin \rho = \kappa \sin \omega$  (where  $\kappa$  is  $< 1$ ), as the equation of the curve of intersection of the sphere and the cylinder.

Hence the intercepted area is denoted by

$$2R^2 \int_0^{\frac{\pi}{2}} (1 - \sqrt{1 - \kappa^2 \sin^2 \omega}) d\omega = \pi R^2 - 2R^2 \int_0^{\frac{\pi}{2}} \sqrt{1 - \kappa^2 \sin^2 \omega} d\omega.$$

Hence the area in question depends on the rectification of an ellipse.

2. Find the area of the portion of the surface of the cylinder intercepted by the sphere, in the preceding.

Here the area in question is easily seen to be represented by  $2 \int z ds$ , where  $ds$  denotes the element of the curve which forms the base, corresponding to the edge  $z$ .

Now (1), when the diameter of the base is equal to the radius of the sphere, we have

$$z = R \cos \omega, \text{ and } ds = R d\omega;$$

∴ area in question =  $2R^2 \int_0^{\frac{\pi}{2}} \cos \omega d\omega = 4R^2$ ; i.e. the square of the diameter of the sphere.

2. When the diameter is less than the radius of the sphere,

$$2 \int z ds = 2a \int \sqrt{R^2 - a^2 \sin^2 \omega} d\omega = 2aR \int \sqrt{1 - \kappa^2 \sin^2 \omega} d\omega; \therefore \&c.$$

189. **Quadrature of Surfaces.**—In seeking the area of a portion of any surface we regard it as the limit of a number of infinitely small elements, each of which is considered as a portion of a plane which is ultimately a tangent plane to the surface. Now let  $dS$  denote such an element of the superficial area, and  $d\sigma$  its projection on a fixed plane which makes the angle  $\theta$  with the plane of the element; then, from elementary geometry, we shall have

$$d\sigma = \cos \theta dS, \text{ or } dS = \sec \theta d\sigma.$$

Hence 
$$S = \int \sec \theta d\sigma,$$

taken between suitable limits.

The applications of this formula usually involve *double integration*, and are generally very complicated ; there is, however, one mode by which the determination of the area of a portion of a surface can be reduced to a single integration, and by whose aid its value can in some cases be found ; viz., by supposing the surface divided into zones by a system\* of curves along each of which the angle  $\theta$  between the tangent plane and a fixed plane is constant ; then, if  $dS$  denote the superficial area of the zone between the two infinitely near curves corresponding to the angles  $\theta$  and  $\theta + d\theta$  ; and, if  $dA$  be the projection of this area on the fixed plane, we shall have  $dS = \sec \theta dA$ .

If we suppose the surface referred to a rectangular system of axes, the fixed plane being that of  $xy$  ; and adopting the usual notation, if we take  $\lambda, \mu, \nu$  as the direction angles of the normal at any point on the surface, we get for  $dS$ , the area of the zone between the curves corresponding to  $\nu$  and  $\nu + d\nu$ , the equation

$$dS = \sec \nu dA,$$

where  $A$  denotes the area of the projection on the plane of  $xy$  of the closed curve defined by the equation  $\nu = \text{constant}$ .

Now whenever we can express the area  $A$  in terms of  $\nu$  and constants, then the area of a portion of the surface, bounded by two curves of the system in question, is reducible to a single integration.

The most important applications of this method are furnished by surfaces of the second degree, to which we proceed to apply it, commencing with the paraboloid.

**190. Quadrature of the Paraboloid.**—Writing the equation of the surface in the form

$$\frac{x^2}{p} + \frac{y^2}{q} = 2z,$$

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\* This method has been employed in a more or less modified form by M. Catalan, *Liouville*, tome iv., p. 323, by Mr. Jellett, *Camb. and Dub. Math. Journal*, vol. i., as also by other writers. The curves employed are called *parallel curves* by M. Lebesgue, *Liouville*, tome xi., p. 332, and *Curven isokliner Normalen*, by Dr. Schlömilch.

the equation of the tangent plane at the point  $(x, y, z)$  is

$$\frac{x}{p} X + \frac{y}{q} Y = z + Z,$$

where  $X, Y, Z$  are the co-ordinates of any point on the plane.  
Comparing this with the equation

$$X \cos \lambda + Y \cos \mu + Z \cos \nu = P,$$

we get  $\cos \lambda = -\frac{x}{p} \cos \nu, \cos \mu = -\frac{y}{q} \cos \nu$ :

substituting in the identical equation

$$\cos^2 \lambda + \cos^2 \mu + \cos^2 \nu = 1,$$

we get  $\frac{x^2}{p^2} + \frac{y^2}{q^2} = \tan^2 \nu.$  (7)

Consequently the curve along which the tangent plane makes the angle  $\nu$  with the tangent plane at the vertex is projected on that plane into the ellipse

$$\frac{x^2}{p^2} + \frac{y^2}{q^2} = \tan^2 \nu.$$

The area  $A$  of this ellipse is  $\pi p q \tan^2 \nu$ ; accordingly, we have

$$dA = \pi p q d(\tan^2 \nu);$$

$$\therefore dS = \pi p q \sec \nu d(\tan^2 \nu) = \pi p q \sec \nu d(\sec^2 \nu);$$

hence the area of the paraboloidal cap bounded by the curve  $\nu = a$  is

$$\pi p q \int^a \sec \nu d(\sec^2 \nu) = \frac{2}{3} \pi p q (\sec^3 a - 1).$$

Also the area of the belt\* between the curves

$$\nu = a \text{ and } \nu = a' \text{ is } \frac{2}{3} \pi p q (\sec^3 a' - \sec^3 a). \quad (8)$$

\* This form for the quadrature of a paraboloid is, I believe, due to Mr. Jellett: see *Camb. and Dub. Math. Journal*, vol. i. p. 65. The proof given above is in a great measure taken from Mr. Allman's paper in the *Quarterly Journal*, already referred to.

191. **Quadrature of the Ellipsoid.**—Proceeding in like manner to the ellipsoid

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1,$$

the equation of the tangent plane at the point  $(x, y, z)$  is

$$\frac{Xx}{a^2} + \frac{Yy}{b^2} + \frac{Zz}{c^2} = 1.$$

Hence, comparing with the equation

$$X \cos \lambda + Y \cos \mu + Z \cos \nu = P,$$

we get

$$\cos \lambda = \frac{c^2}{a^2} \frac{x}{z} \cos \nu, \quad \cos \mu = \frac{c^2}{b^2} \frac{y}{z} \cos \nu.$$

Hence, we have

$$\cos^2 \nu \frac{c^4}{z^2} \left( \frac{x^2}{a^4} + \frac{y^2}{b^4} \right) = \cos^2 \lambda + \cos^2 \mu = \sin^2 \nu;$$

or, substituting  $1 - \frac{x^2}{a^2} - \frac{y^2}{b^2}$  for  $\frac{z^2}{c^2}$ ,

$$\frac{x^2}{a^4} \left( a^2 \sin^2 \nu + c^2 \cos^2 \nu \right) + \frac{y^2}{b^4} \left( b^2 \sin^2 \nu + c^2 \cos^2 \nu \right) = \sin^2 \nu.$$

This shows that the projection on the plane of  $xy$  of a curve along which  $\nu = \text{constant}$  is an ellipse.

Again the area  $A$  of this ellipse is

$$\frac{\pi a^2 b^2 \sin^2 \nu}{(a^2 \sin^2 \nu + c^2 \cos^2 \nu)^{\frac{1}{2}} (b^2 \sin^2 \nu + c^2 \cos^2 \nu)^{\frac{1}{2}}}$$

and accordingly, the area  $dA$  of the elementary annulus between two consecutive ellipses is

$$\pi a^2 b^2 \frac{d}{d\nu} \left\{ \frac{\sin^2 \nu}{(a^2 \sin^2 \nu + c^2 \cos^2 \nu)^{\frac{1}{2}} (b^2 \sin^2 \nu + c^2 \cos^2 \nu)^{\frac{1}{2}}} \right\} d\nu.$$

The corresponding elementary ellipsoidal zone  $dS$  is represented by

$$\frac{\pi a^2 b^2}{\cos \nu} \frac{d}{d\nu} \left\{ \frac{\sin^2 \nu}{(a^2 \sin^2 \nu + c^2 \cos^2 \nu)^{\frac{1}{2}} (b^2 \sin^2 \nu + c^2 \cos^2 \nu)^{\frac{1}{2}}} \right\} d\nu.$$

Now, if  $S$  denote the superficial area\* between two curves corresponding to  $\nu = a$  and  $\nu = a'$ , after one or two reductions, it is easily seen that

$$S = \pi a^2 b^2 c^2 (I + I'), \quad (9)$$

where  $I = \int_a^{a'} \frac{\sin \nu d\nu}{(b^2 \sin^2 \nu + c^2 \cos^2 \nu)^{\frac{3}{2}} (a^2 \sin^2 \nu + c^2 \cos^2 \nu)^{\frac{1}{2}}}$

$$I' = \int_a^{a'} \frac{\sin \nu d\nu}{(a^2 \sin^2 \nu + c^2 \cos^2 \nu)^{\frac{3}{2}} (b^2 \sin^2 \nu + c^2 \cos^2 \nu)^{\frac{1}{2}}}.$$

It is easily shown that the former of these integrals is represented by an arc of an ellipse, and the latter by an arc of a hyperbola; it being assumed that  $a > b > c$ .

For, assuming  $a^2 - c^2 = a^2 e^2$ , and  $b^2 - c^2 = b^2 e'^2$ , and making  $\cos \nu = x$ , we get

$$I = \frac{1}{ab^3} \int_{\cos a}^{\cos a'} \frac{dx}{(1 - e'^2 x^2)^{\frac{3}{2}} (1 - e^2 x^2)^{\frac{1}{2}}},$$

$$I' = \frac{1}{a^3 b} \int_{\cos a'}^{\cos a} \frac{dx}{(1 - e^2 x^2)^{\frac{3}{2}} (1 - e'^2 x^2)^{\frac{1}{2}}}.$$

Again, let  $ex = \sin \theta$  in the former integral, and  $e'x = \sin \theta$  in the latter, and we get

$$I = \frac{e^2}{ab^3} \int \frac{d\theta}{(e^2 - e'^2 \sin^2 \theta)^{\frac{3}{2}}},$$

$$I' = \frac{e'^2}{a^3 b} \int \frac{d\theta}{(e'^2 - e^2 \sin^2 \theta)^{\frac{3}{2}}}.$$

Now, since  $e > e'$ , the former integral represents an arc of an ellipse, and the latter an arc of a hyperbola. (See Ex. 19, p. 249).

\* This form for the quadrature of an ellipsoid is given by Mr. Jellett in the memoir already referred to. He has also shown that the ellipse and the hyperbola in question are the focal conics of the reciprocal ellipsoid; a result which can be easily arrived at from the forms of  $I$  and  $I'$  given above.

For application to the hyperboloid, and further development of these results, the student is referred to Mr. Jellett's memoir.

192. **Integration over a Closed Surface.**—We shall conclude this Chapter with the consideration of some general formulæ in double integration relative to any closed surface. We commence by adopting the same notation as in Art. 189, where  $\lambda$ ,  $\mu$ ,  $\nu$  are taken as the angles which the exterior normal at the element  $dS$  makes with the positive directions of the axes of  $x$ ,  $y$ ,  $z$ , respectively.

Again, let each element of the surface be projected on the plane of  $xy$ , and suppose\* for simplicity that each  $z$  ordinate meets the surface in but two points: then, if the indefinitely small cylinder standing on any element  $dA$  in the plane of  $xy$  intersects the surface in the two elementary portions  $dS_1$  and  $dS_2$  (where  $dS_1$  is the upper, and  $dS_2$  the lower element), and if  $\nu_1$  and  $\nu_2$  be the corresponding values of  $\nu$ , it is plain that  $\nu_1$  is an acute, and  $\nu_2$  an obtuse angle, and we have

$$dA = \cos \nu_1 dS_1 = -\cos \nu_2 dS_2.$$

Hence, if we take into account all the elements of the surface, attending to the sign of  $\cos \nu$ , we shall have

$$\iint \cos \nu dS = 0.$$

In like manner we get

$$\iint \cos \lambda dS = 0, \text{ and } \iint \cos \mu dS = 0;$$

the integrals extending in each case over the whole of the closed curve

These formulæ are comprised in the equation

$$\iint (\alpha \cos \lambda + \beta \cos \mu + \gamma \cos \nu) dS = 0. \quad (10)$$

Again, if  $z_1$  and  $z_2$  be the values of  $z$  corresponding to the element  $dA$ , then, denoting by  $dV$  the element of volume standing on  $dA$  and intercepted by the surface, we plainly have

$$dV = (z_1 - z_2) dA = z_1 dS_1 \cos \nu_1 + z_2 dS_2 \cos \nu_2,$$

\* It is easily seen that this and the following demonstrations are perfectly general, inasmuch as each ordinate must meet a closed surface in an even number of points, which may be considered in pairs.

and the sum of all such elements, that is, the whole volume, is evidently represented by

$$\iint z \cos \nu dS.$$

Hence, denoting the whole volume by  $V$ , we have

$$V = \iint x \cos \lambda dS = \iint y \cos \mu dS = \iint z \cos \nu dS;$$

the integrals, as before, being extended over the entire surface.

Again, it is easily seen that we have

$$\iint x \cos \nu dS = 0, \quad \iint y \cos \nu dS = 0, \quad \iint x \cos \mu dS = 0,$$

$$\iint y \cos \lambda dS = 0, \quad \iint z \cos \lambda dS = 0, \quad \iint z \cos \mu dS = 0.$$

For, as in the first case, it readily appears that the elements are equal and opposite in pairs in each of these integrals.

These results are comprised in the equation

$$\begin{aligned} \iint (ax + \beta y + \gamma z) (a' \cos \lambda + \beta' \cos \mu + \gamma' \cos \nu) dS \\ = (aa' + \beta\beta' + \gamma\gamma') V. \quad (11) \end{aligned}$$

For a like reason, we have

$$\iint xy \cos \nu dS = 0, \quad \iint zx \cos \mu dS = 0, \quad \iint yz \cos \lambda dS = 0.$$

Also  $\iint x^2 \cos \nu dS = 0, \quad \iint x^2 \cos \mu dS = 0, \quad \&c.$

Next, let us consider the integral

$$\iint xz \cos \nu dS.$$

This integral is equivalent to  $\iint x dV$ ; consequently, if  $\bar{x}, \bar{y}, \bar{z}$ , be the co-ordinates of the centre of gravity of the enclosed volume  $V$ , we get  $\iint xz \cos \nu dS = \iint x dV = \bar{x}V$ ; in like manner  $\iint xz \cos \lambda dS = \bar{z}V$ .

Again, the integral

$$\iint z^2 \cos \nu dS$$

consists of elements of the form  $(z_1^2 - z_2^2) dA$ ; but

$$\begin{aligned} (z_1^2 - z_2^2) dA &= (z_1 + z_2)(z_1 - z_2) dA \\ &= (z_1 + z_2) dV. \end{aligned}$$

But the  $z$  ordinate of the centre of gravity of  $dV$  is plainly  $\frac{z_1 + z_2}{2}$ , and consequently

$$\iint z^2 \cos \nu dS = 2 \iint \frac{z_1 + z_2}{2} dV = 2\bar{z} V.$$

In like manner it can be shown that

$$\iint x^2 \cos \lambda dS = 2\bar{x} V, \quad \iint y^2 \cos \mu dS = 2\bar{y} V.$$

Accordingly we have

$$V\bar{x} = \frac{1}{3} \iint x^2 \cos \lambda dS = \iint xy \cos \mu dS = \iint xz \cos \nu dS,$$

$$V\bar{y} = \iint yx \cos \lambda dS = \frac{1}{3} \iint y^2 \cos \mu dS = \iint yz \cos \nu dS,$$

$$V\bar{z} = \iint zx \cos \lambda dS = \iint zy \cos \mu dS = \frac{1}{2} \iint z^2 \cos \nu dS.$$

### 193. Expression for Volume of a Closed Surface.

—Next, if we suppose a cone described with its vertex at the origin  $O$ , and standing on the elementary base  $dS$ , its volume is represented (Art. 169) by  $\frac{1}{3}pdS$ , where  $p$  is the length of the perpendicular drawn from  $O$  to the tangent plane at the point.

Also, if  $r$  be the distance of  $O$  from the point, and  $\gamma$  the angle which  $r$  makes with the *internal* normal, we have  $p = r \cos \gamma$ .

Hence the elementary volume is equal to  $\frac{1}{3}r \cos \gamma dS$ , and it is easily seen that if we integrate over the entire surface, the enclosed volume is represented by

$$\frac{1}{3} \iint r \cos \gamma dS.$$

194. Again, if we suppose a sphere of unit radius described with  $O$  as centre, and if  $d\omega$  represent the superficial portion of this sphere intercepted by the elementary cone standing on  $dS$ , then it is easily seen that  $\cos \gamma dS = r^2 d\omega$ ;

$$\therefore d\omega = \frac{\cos \gamma dS}{r^2}.$$

Now if  $O$  be inside the closed surface, and the integral be extended over the entire surface, it is plain that  $\iint d\omega = 4\pi$ , being the surface of the sphere of radius unity;

$$\therefore \iint \frac{\cos \gamma dS}{r^2} = 4\pi.$$

Again, if  $O$  be outside the surface, the cone will cut the surface in an even number of elements, for which the values of  $\cos \gamma$  will be alternately positive and negative, and, the corresponding elements of the integral being equal but with opposite signs, their sum is equal to zero, and we shall have

$$\iint \frac{\cos \gamma dS}{r^2} = 0.$$

If  $O$  be situated on the surface, it follows in like manner that

$$\iint \frac{\cos \gamma}{r^2} dS = 2\pi.$$

Hence, we conclude that

$$\iint \frac{\cos \gamma}{r^2} dS = 4\pi, 2\pi, \text{ or } 0, \quad (12)$$

according as the origin is inside, on, or outside the surface.

The multiple integrals introduced into this and the two preceding Articles are principally due to Gauss.

The student will find some important applications of this method in Bertrand's *Calc. Int.*, §§ 437, 455, 456, 476, &c.

## EXAMPLES.

1. A sphere of 15 feet radius is cut by two parallel planes at distances of 3 and 7 feet from its centre; find the superficial area of the portion of the surface included between the planes approximately. *Ans.* 376.9908 sq. feet.

2. Being given the slant height of a right cone, find the cosine of half its vertical angle when its volume is a maximum.

$$\text{Ans. } \frac{1}{\sqrt{3}}$$

3. Prove that the volume of a truncated cone of height  $h$  is represented by

$$\frac{\pi h}{3} (R^2 + Rr + r^2),$$

where  $R$  and  $r$  are the radii of its two bases.

4. A cone is circumscribed to a sphere of radius  $R$ , the vertex of the cone being at the distance  $D$  from the centre; find the ratio of the superficial area of the cone to that of the sphere.

$$\text{Ans. } \frac{D^2 - R^2}{4DR}.$$

5. Two spheres,  $A$  and  $B$ , have for radii 9 feet and 40 feet; the superficial area of a third sphere  $C$  is equal to the sum of the areas of  $A$  and  $B$ ; calculate the excess, in cubic feet, of the volume of  $C$  over the sum of the volumes of  $A$  and  $B$ .

$$\text{Ans. } 17558.$$

6. If any arc of a plane curve revolve successively round two parallel axes, show that the difference of the surfaces generated is equal to the product of the length of the arc into the circumference of the circle described by any point on either axis turning round the other.

If the axes of revolution lie at opposite sides of the curve, the sum of the surfaces must be taken instead of the difference.

7. Find, in terms of the sides, the volume of the solid generated by the complete revolution of a triangle round its side  $c$ .

$$\text{Ans. } \frac{4\pi s(s-a)(s-b)(s-c)}{3c}.$$

8. Apply Guldin's theorem to determine the distance, from the centre, of the centre of gravity, (1) of a semicircular area; (2) of a semicircular arc.

$$\text{Ans. (1) } \frac{4a}{3\pi}, \quad (2) \frac{2a}{\pi}.$$

9. If a triangle revolve round any external axis, lying in its plane, find an expression for the area of the surface generated in a complete revolution.

10. Prove that the volume cut from the surface

$$z^n = Ax^2 + By^2$$

by any plane parallel to that of  $xy$ , is  $\frac{1}{n+1}$  th part of the cylinder standing on the plane section, and terminated by the plane of  $xy$ .

11. A cone is circumscribed to a sphere of 23 feet radius, the vertex of the cone being 265 feet distant from the centre of the sphere; find the ratio of the superficial area of the cone to that of the sphere.

12. The axis of a right circular cylinder passes through the centre of a sphere; find the volume of the solid included between the concave surface of the sphere and the convex surface of the cylinder.

*Ans.*  $\frac{\pi c^3}{6}$ , where  $c$  is the length of the portion of any edge of the cylinder intercepted by the sphere.

This question is the same as that of finding the volume of the solid generated by the segment of a circle cut off by any chord, in a revolution round the diameter parallel to the chord.

13. Find the volume of the solid generated by the revolution of an arc of a circle round its chord.

$$\text{Ans. } 2\pi a \left\{ \frac{(2a^2 + c^2) \sin \alpha}{3} - ca \right\},$$

where  $a$  = radius,  $c$  = distance of chord from centre, and  $\cos \alpha = \frac{c}{a}$ .

In this we suppose the arc less than a semicircle: the modification when it is greater is easily seen.

14. If the ellipsoid of revolution,

$$x^2 + z^2 + \frac{a^2 y^2}{b^2} = a^2,$$

and the hyperboloid

$$x^2 + z^2 - \frac{a^2 - b^2}{b^2} y^2 = a^2,$$

be cut by two planes perpendicular to the axis of revolution, prove that the zones intercepted on the two surfaces are of equal area.

15. Find the entire volume bounded by the positive sides of the three co-ordinate planes, and

$$\left(\frac{x}{a}\right)^{\frac{1}{3}} + \left(\frac{y}{b}\right)^{\frac{1}{3}} + \left(\frac{z}{c}\right)^{\frac{1}{3}} = 1, \quad \text{Ans. } \frac{abc}{90}.$$

16. Find the volume of the surface generated by the revolution of an arc of a parabola round its chord; the chord being perpendicular to the axis of the curve.

*Ans.*  $\frac{8}{15} \pi b^2 c$ , where  $c$  is the length of the chord, and  $b$  the intercept made by it on the diameter of the parabola passing through the middle point of the chord.

17. A sphere of radius  $r$  is cut by a plane at distance  $d$  from the centre; find the difference of the volumes of the two cones having as a common base the circle in which the plane cuts the sphere, and whose vertices are the opposite ends of the diameter perpendicular to the cutting plane.

$$\text{Ans. } \frac{2}{3} \pi d (r^2 - d^2).$$

18. Find the area of a spherical triangle; and prove that if a curve traced on a sphere have for its equation  $\sin \lambda = f(l)$ ,  $\lambda$  denoting latitude, and  $l$  longitude, the area between the curve and the equator =  $\int f(l) dl$ .

19. Show that the volume contained between the surface of a hyperboloid of one sheet, its asymptotic cone, and two planes parallel to that of the real axes, is proportional to the distance between those planes.

20. Find the entire volume of the surface

$$\left(\frac{x}{a}\right)^{\frac{2}{3}} + \left(\frac{y}{b}\right)^{\frac{2}{3}} + \left(\frac{z}{c}\right)^{\frac{2}{3}} = 1. \quad \text{Ans. } \frac{4\pi abc}{5+7}.$$

21. The vertex of a cone of the second degree is in the surface of a sphere, and its internal axis is the diameter passing through its vertex; find the volume of the portion of the sphere intercepted within the cone.

22. Prove that the volume of the portion of a cylinder intercepted between any two planes is equal to the product of the area of a perpendicular section into the distance between the centres of gravity of the areas of the bounding sections.

23. If  $A$  be the area of the section of any surface made by the plane of  $xy$ , prove, as in Art. 192, that

$$A = \iint \cos \nu dS,$$

the integral being extended through the portion of the surface which lies above the plane of  $xy$ .

24. If a right cone stand on an ellipse, prove that its volume is represented by

$$\frac{\pi}{3} (OA \cdot OA')^{\frac{1}{2}} \sin^2 a \cos a;$$

where  $O$  is the vertex of the cone,  $A$  and  $A'$  the extremities of the major axis of the ellipse, and  $a$  is the semi-angle of the cone.

25. In the same case prove that the superficial area of the cone is

$$\frac{\pi}{2} (OA + OA') (OA \cdot OA')^{\frac{1}{2}} \sin a.$$

## CHAPTER X.

## INTEGRALS OF INERTIA.

195. **Integrals of Inertia.**—The following integrals are of such frequent occurrence in mechanical investigations, that it is proposed to give a brief discussion of them in this Chapter.

If each element of the mass of any solid body be supposed to be multiplied by the square of its distance from any fixed right line, and the sum extended throughout every element of the body, the quantity thus obtained is called the *moment of inertia of the body with respect to the fixed line or axis*.

Hence, denoting the element of mass by  $dm$ , its distance from the axis by  $p$ , and the moment of inertia by  $I$ , we have

$$I = \Sigma p^2 dm. \quad (1)$$

In like manner, if each element of mass of a body be multiplied by the square of its distance from a plane, the sum of such products is called the *moment of inertia of the body relative to the plane*.

If the system be referred to rectangular axes of co-ordinates, then the expression for the moment of inertia relative to the axis of  $z$  is obviously represented by

$$\Sigma (x^2 + y^2) dm.$$

Similarly, the moments of inertia relative to the axes of  $x$  and  $y$  are represented by  $\Sigma (y^2 + z^2) dm$  and  $\Sigma (x^2 + z^2) dm$ , respectively.

Again, the quantities  $\Sigma x^2 dm$ ,  $\Sigma y^2 dm$ ,  $\Sigma z^2 dm$ , are the moments of inertia of the body with respect to the planes of  $yz$ ,  $xz$ , and  $xy$ , respectively. Also the quantities  $\Sigma xy dm$ ,  $\Sigma zx dm$ ,  $\Sigma yz dm$ , are called the *products of inertia* relative to the same system of co-ordinate axes.

In like manner the *moment of inertia of the body with reference to a point* is  $\Sigma r^2 dm$ , where  $r$  denotes the distance of the element  $dm$  from the point. Thus the moment of inertia relative to the origin is  $\Sigma (x^2 + y^2 + z^2) dm$ .

**196. Moments of Inertia relative to Parallel Axes, or Planes.**—The following result is of fundamental importance:—*The moment of inertia of a body with respect to any axis exceeds its moment of inertia with respect to a parallel axis drawn through its centre of gravity, by the product of the mass of the body into the square of the distance between the parallel axes.*

For, let  $I$  be the moment of inertia relative to the axis through the centre of gravity,  $I'$  that for the parallel axis,  $M$  the mass of the body, and  $a$  the distance between the axes.

Then, taking the centre of gravity as origin, the fixed axis through it as the axis of  $z$ , and the plane through the parallel axes for that of  $zx$ , we shall have

$$I = \Sigma (x^2 + y^2) dm, \quad I' = \Sigma \{(x + a)^2 + y^2\} dm.$$

Hence  $I' - I = 2a \Sigma x dm + a^2 \Sigma dm = a^2 M,$

since  $\Sigma x dm = 0$  as the centre of gravity is at the origin;

$$\therefore I' = I + a^2 M. \quad (2)$$

Consequently, the moment of inertia of a body relative to any axis can be found when that for the parallel axis through its centre of gravity is known.

Also, the moments of inertia of a body are the same for all parallel axes situated at the same distance from its centre of gravity.

Again, it may be observed that of all parallel axes that which passes through the centre of gravity of a body has the least moment of inertia.

It is also apparent that the same theorem holds if the moments of inertia be taken with respect to parallel planes, instead of parallel axes.

A similar property also connects the moment of inertia relative to any point with that relative to the centre of gravity of the body.

In finding the moment of inertia of a body relative to any axis, we usually suppose the body divided into a system of indefinitely thin plates, or *laminæ*, by a system of planes perpendicular to the axis; then, when the moment of inertia is determined for a lamina, we seek by integration to find that of the entire body.

197. **Radius of Gyration.**—If  $k$  denote the distance from an axis at which the entire mass of a body should be concentrated that its moment of inertia relative to the axis may remain unaltered, we shall have

$$Mk^2 = I = \Sigma p^2 dm. \quad (3)$$

The length  $k$  is called the radius of gyration of the body with respect to the fixed axis.

In homogeneous bodies, which shall be here treated of principally, since the mass of any part varies directly as its volume, the preceding equation may be written in the form

$$k^2 V = \Sigma p^2 dV,$$

where  $dV$  denotes the element of volume, and  $V$  the entire volume of the body.

Hence, in homogeneous bodies, the value of  $k$  is independent of the density of the body, and depends only on its form.

We shall in our investigations represent the moment of inertia in the form

$$I = Mk^2;$$

and, it is plain that in its determination for homogeneous bodies we may take the element of volume for the element of mass, and the total volume of the body instead of its mass.

Also, in finding the moment of inertia of a lamina, since its radius of gyration is independent of the thickness of the lamina, we may take the element of area instead of the element of mass, and the total area of the lamina instead of its mass.

198. If  $A$  and  $B$  be the moments of inertia of an infinitely thin plate, or lamina, with respect to two rectangular axes  $OX$ ,  $OY$ , lying in its plane, and if  $C$  be the moment of inertia relative to  $OZ$  drawn perpendicular to the plane, we have

$$C = A + B. \quad (4)$$

For, we have in this case  $A = \Sigma y^2 dm$ ,  $B = \Sigma x^2 dm$ , and  $C = \Sigma (x^2 + y^2) dm$ .

Again, for every two rectangular axes in the plane of the lamina, at any point, we have

$$\Sigma x^2 dm + \Sigma y^2 dm = \text{const.}$$

Hence, if one be a maximum, the other is a minimum, and vice versa.

We shall, in all investigations concerning laminæ, take  $C$  for the moment of inertia relative to a line perpendicular to the lamina.

199. **Uniform Rod, Rectangular Lamina.**—We commence with the simple case of a rod, the axis being perpendicular to its length, and passing through either extremity.

Let  $x$  be the distance of any element  $dm$  of the rod from the extremity; then, since the rod is uniform,  $dm$  is proportional to  $dx$ , and we may assume  $dm = \mu dx$ : hence, the moment of inertia  $I$  is represented by  $\mu \Sigma x^2 dx$ , or by

$$\mu \int_0^l x^2 dx,$$

where  $l$  is the length of the rod.

Hence  $I = \frac{\mu l^3}{3} = M \frac{l^2}{3}$ .

If the axis be drawn through the middle point of the rod, perpendicular to its length, the moment of inertia is plainly the same for each half of the rod, and we shall have in this case

$$I = M \frac{l^2}{12}.$$

Next, let us take a rectangular lamina, and suppose the axis drawn through its centre, parallel to one of its sides

Here, it is evident that the lamina may be regarded as made up of an infinite number of parallel rods of equal length, perpendicular to the axis, each having the same radius of gyration, and consequently the radius of gyration of the lamina is the same as that of one of the rods.

Accordingly, we have, denoting the lengths of the sides of the rectangle by  $2a$  and  $2b$ , and the moments of inertia round axes through the centre parallel to the sides, by  $A$  and  $B$ , respectively,

$$A = \frac{1}{3} M b^2, \quad B = \frac{1}{3} M a^2. \quad (5)$$

Hence also, by (4), the moment of inertia round an axis through the centre of gravity and perpendicular to the plane of the lamina, is

$$\frac{1}{3} M (a^2 + b^2). \quad (6)$$

By applying the principle of Art. 196 we can now find its moments of inertia with respect to any right line either lying in, or perpendicular to, the plane of the lamina.

200. **Rectangular Parallelepiped.**—Since a parallelepiped may be conceived as consisting of an infinite number of laminæ, each of which has the same radius of gyration relative to an axis drawn perpendicular to their planes, it follows that the radius of gyration of the parallelepiped is the same as that of one of the laminæ.

Hence, if the length of the sides of the parallelepiped be  $2a$ ,  $2b$ , and  $2c$ , respectively; and, if  $A$ ,  $B$ ,  $C$  be respectively the moments of inertia relative to three axes drawn through the centre of gravity, parallel to the edges of the parallelepiped, we have, by the last,

$$A = \frac{1}{3} M(b^2 + c^2), \quad B = \frac{1}{3} M(c^2 + a^2), \quad C = \frac{1}{3} M(a^2 + b^2). \quad (7)$$

201. **Circular Plate, Cylinder.**—If the axis be drawn through its centre, perpendicular to the plane of a circular ring of infinitely small breadth, since each point of the ring may be regarded as at the same distance  $r$  from the axis, its moment of inertia is  $r^2 dm$ , where  $dm$  represents its mass.

Hence, considering each ring as an element of a circular plate, and observing that  $dm = \mu 2\pi r dr$ , we get for  $C$ , the moment of inertia of the circular plate of radius  $a$ ,

$$C = 2\pi\mu \int_0^a r^3 dr = \frac{\pi\mu a^4}{2} = M \frac{a^2}{2}.$$

Consequently, the moment of inertia of a ring whose outer and inner radii are  $a$  and  $b$ , respectively, with respect to the same axis, is

$$2\pi\mu \int_b^a r^3 dr = \pi\mu \frac{a^4 - b^4}{2} = M \frac{a^2 + b^2}{2}.$$

Again, by (4), the moment of inertia of a circular plate about any diameter is  $M \frac{a^2}{4}$ , since the moments of inertia are obviously the same respecting all diameters.

In like manner, the moment of inertia of a ring relative to any diameter is

$$M \frac{a^2 + b^2}{4}.$$

Also, the moment of inertia of a right cylinder about its axis of figure is

$$M \frac{a^2}{2},$$

$a$  being the radius of the section of the cylinder.

Again, the moment of inertia relative to any edge of the cylinder is  $\frac{3}{2} Ma^2$ .

202. **Right Cone.**—To find the moment of inertia of a right cone relative to its axis, we conceive it divided into an infinite number of circular plates, whose centres lie along the axis; and, denoting by  $x$  the distance of the centre of any section from the vertex of the cone, and by  $a$  the semi-angle of the cone, we have

$$I = \frac{\pi \mu \tan^4 a}{2} \int_0^h x^4 dx = \frac{\pi \mu b^4 h}{10},$$

where  $h$  is the height of the cone, and  $b$  the radius of its base.

Hence, since by Art. 169 the volume of the cone is  $\frac{\pi}{3} b^2 h$ , we have

$$I = \frac{3}{10} M b^2. \quad (8)$$

203. **Elliptic Plate.**—Next let us suppose the lamina an ellipse, of semi-axes  $a$  and  $b$ ; and let  $A$  and  $B$  be the moments of inertia relative to these axes, respectively.

Describe a circle with the axis minor for diameter, and suppose the lamina divided into rods by sections perpendicular to this axis. Let  $B'$  be the moment of inertia for the circle round its diameter.

Then, denoting by  $dB$  and  $dB'$  the moments of inertia of corresponding rods, we have

$$dB : dB' = (np)^3 : (np')^3 = (oa)^3 : (ob)^3 = a^3 : b^3;$$

$$\therefore B : B' = a^3 : b^3.$$

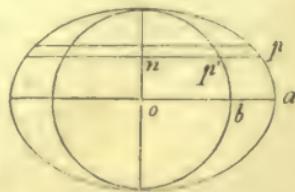


Fig. 47.

But  $B'$ , by Art. 201, is  $\frac{M' b^2}{4}$ ;

$$\therefore B = \frac{M' a^3}{4} \frac{b}{b} = \frac{M}{4} a^2.$$

Similarly,

$$A = \frac{M}{4} b^2.$$

Hence the moment  $C$  round a line through the centre of the ellipse, perpendicular to its plane, is

$$\frac{M}{4} (a^2 + b^2). \quad (9)$$

It is plain, as before, that the expression for the moment of inertia of an elliptical cylinder relative to its axis is of the same form.

**204. Sphere.**—If we suppose a sphere divided into an infinite number of concentric spherical shells, the moment of inertia of each shell is plainly the same for all diameters; and accordingly, representing the mass of any element of a shell by  $dm$ , and by  $x, y, z$  any point on it, we have

$$\Sigma x^2 dm = \Sigma y^2 dm = \Sigma z^2 dm.$$

$$\text{But} \quad \Sigma (x^2 + y^2 + z^2) dm = \Sigma r^2 dm;$$

$$\therefore \Sigma (x^2 + y^2) dm = \frac{2}{3} \Sigma r^2 dm.$$

Hence, (a) the moment of inertia of a shell whose radius is  $r$  with respect to any diameter is  $\frac{2}{3} mr^2$ , where  $m$  represents the mass of the shell.

Again, (b) for a solid sphere of radius  $R$ , since the volume of an indefinitely thin shell of radius  $r$  is  $4\pi r^2 dr$ , we get

$$\Sigma r^2 dv = 4\pi \int_0^R r^4 dr = \frac{4}{5} \pi R^5 = \frac{3}{5} VR^2.$$

When this is substituted, the moment of inertia of a solid homogeneous sphere relative to any diameter is found to be

$$\frac{2}{5} MR^2. \quad (10)$$

205. **Ellipsoid.**—Let the equation of an ellipsoid be

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1;$$

and suppose  $A, B, C$  to be the moments of inertia relative to the axes  $a, b, c$ , respectively; then

$$C = \mu \Sigma (x^2 + y^2) dV = \mu \iiint (x^2 + y^2) dx dy dz.$$

Now, let  $\frac{x}{a} = x', \frac{y}{b} = y', \frac{z}{c} = z'$ ,

and we get

$$C = \mu abc \iiint (a^2 x'^2 + b^2 y'^2) dx' dy' dz',$$

where the integrals are extended to all points within the sphere

$$x'^2 + y'^2 + z'^2 = 1.$$

But, by the last example we have

$$\iiint x'^2 dx' dy' dz' = \iiint y'^2 dx' dy' dz' = \frac{4}{15} \pi;$$

$$\therefore C = \frac{4}{15} \pi \mu abc (a^2 + b^2) = \frac{M}{5} (a^2 + b^2). \quad (11)$$

In like manner,

$$A = \frac{M}{5} (b^2 + c^2), \quad B = \frac{M}{5} (c^2 + a^2).$$

It should be remarked that the moments of inertia of the ellipsoid with respect to its three *principal planes* are

$$\frac{M}{5} a^2, \quad \frac{M}{5} b^2, \quad \frac{M}{5} c^2, \text{ respectively.}$$

206. **Moments of Inertia of a Lamina.**—Suppose that any plane lamina is referred to two rectangular axes drawn through any origin  $O$ , and that  $a$  is the angle which any right line through  $O$ , lying in the plane, makes with the axis of  $x$ ; then, if  $I$  be the moment of inertia of the lamina relative to this line, we have

$$\begin{aligned} I &= \Sigma p^2 dm = \Sigma (y \cos a - x \sin a)^2 dm \\ &= \cos^2 a \Sigma y^2 dm + \sin^2 a \Sigma x^2 dm - 2 \sin a \cos a \Sigma xy dm \\ &= a \cos^2 a + b \sin^2 a - 2h \sin a \cos a; \end{aligned} \quad (12)$$

where  $a$  and  $b$  represent the moments of inertia relative to the axes of  $x$  and  $y$ , respectively; and  $h$  is the product of inertia relative to the same axes.

Again, supposing  $X$  and  $Y$  to be the co-ordinates of a point taken on the same line at a distance  $R$  from the origin, we get  $\cos a = \frac{X}{R}$ ,  $\sin a = \frac{Y}{R}$ ; and, consequently,

$$IR^2 = aX^2 + bY^2 - 2hXY.$$

Accordingly, if an ellipse be constructed whose equation is

$$aX^2 + bY^2 - 2hXY = \text{const.}, \quad (13)$$

we have

$$IR^2 = \text{const.};$$

and, consequently, the moment of inertia relative to any line drawn through the origin varies inversely as the square of the corresponding radius vector of this ellipse.

The form and position of this ellipse are evidently independent of the particular axes assumed; but its equation is more simple if the axes, major and minor, of the ellipse had been assumed as the axes of co-ordinates. Again, since in this case the coefficient of  $XY$  disappears from the equation of the curve, we see that there exists at every point in a body one pair of rectangular axes for which the quantity  $h$  or  $\Sigma xy dm = 0$ .

This pair of axes is called the *principal axes* at the point; and the corresponding moments of inertia are called the *principal moments of inertia* of the lamina relative to the point.

Again, if  $A$  and  $B$  represent the principal moments of inertia, equation (12) becomes

$$I = A \cos^2 a + B \sin^2 a. \quad (14)$$

Hence, for a lamina, the moment of inertia relative to any axis through a point can be found when the principal moments relative to the point are determined.

The equation of the ellipse (13) becomes, when referred to the principal axes,

$$AX^2 + BY^2 = \text{const.}$$

**207. Momental Ellipse.**—Since the moments of inertia for all axes are determined when those relative to the centre of gravity are known, it is sufficient to consider the case where the origin is at the centre of gravity. With reference to this case, the ellipse

$$AX^2 + BY^2 = \text{const.} \quad (15)$$

is called the *momental ellipse* of the lamina.

Again, if two different distributions of matter in the same plane have a common centre of gravity, and have the same principal axes and principal moments of inertia, at that point, they have the same moments of inertia relative to all axes.

This is an immediate consequence of (14). Hence it is easily seen that the moments of inertia for any lamina are the same as for the system of four equal masses, each  $\frac{M}{4}$ , placed on the two central principal axes, at the four distances  $\pm a$  and  $\pm b$ , from the centre of gravity, where  $a$  and  $b$  are determined by the equations

$$A = \frac{1}{2} Mb^2, \quad B = \frac{1}{2} Ma^2.$$

Again, if two systems of the same total mass, in a plane, have a common centre of gravity, and have equal moments of inertia relative to any three axes, through their common centre of gravity, they have the same moments of inertia for all axes.

This follows immediately since an ellipse is determined when its centre and three points on its circumference are given.

Again, it may be observed that the boundary of an elliptical lamina may be regarded as the momental ellipse of the lamina.

For, if  $I$  be the moment of inertia relative to any diameter making the angle  $a$  with the axis major, we have

$$I = A \cos^2 a + B \sin^2 a.$$

But, by Art. 203,

$$A = \frac{M}{4} b^2, \quad B = \frac{M}{4} a^2;$$

$$\begin{aligned} \therefore I &= \frac{M}{4} (b^2 \cos^2 a + a^2 \sin^2 a) \\ &= \frac{M}{4} a^2 b^2 \left( \frac{\cos^2 a}{a^2} + \frac{\sin^2 a}{b^2} \right) \\ &= \frac{M}{4} \frac{a^2 b^2}{r^2}. \end{aligned}$$

Hence the moment of inertia varies inversely as the square of the semi-diameter  $r$ ; and, consequently, the ellipse may be regarded as its own momental ellipse.

**208. Products of Inertia of Lamina.**—Suppose the lamina referred to its principal axes at a point  $O$ ; and let  $p$  and  $q$  be the distances of any element  $dm$  from two axes, which make the angles  $a$  and  $\beta$  with the axis of  $x$ ; then we have

$$\begin{aligned} \Sigma pq dm &= \Sigma (y \cos a - x \sin a)(y \cos \beta - x \sin \beta) dm \\ &= \cos a \cos \beta \Sigma y^2 dm + \sin a \sin \beta \Sigma x^2 dm \\ &\quad - \sin(a + \beta) \Sigma xy dm \\ &= A \cos a \cos \beta + B \sin a \sin \beta, \end{aligned}$$

since  $A = \Sigma y^2 dm$ ,  $B = \Sigma x^2 dm$ , and  $\Sigma xy dm = 0$ .

Hence, if  $\Sigma pq dm = 0$ , we have

$$A \cos a \cos \beta + B \sin a \sin \beta = 0,$$

and accordingly the axes are a pair of conjugate diameters of the momental ellipse

$$AX^2 + BY^2 = \text{const.}$$

Hence, if two laminæ in the same plane have for any point two pairs of axes for which  $\Sigma pq dm = 0$  and  $\Sigma p'q' dm' = 0$ , they have the same principal axes at the point. This follows from the easily established property, that if two ellipses have two pairs of conjugate diameters in common, they must be similar and coaxal.

209. **Triangular Lamina and Prism.**—Suppose a triangular lamina, whose sides are  $a, b, c$ , to be divided into a system of rods parallel to a side  $a$ ; and let  $A$  represent the moment of inertia relative to a line parallel to the side  $a$ , and drawn through the opposite vertex; also let  $p$  be the perpendicular of the triangle on the side  $a$ , and  $x$  the distance of an elementary rod from the vertex; then we have, since the mass  $dm$  of the

elementary rod may be represented by  $\mu \frac{ax}{p} dx$ ,

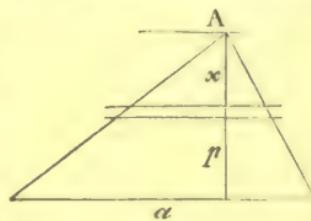


Fig. 48.

$$A = \Sigma x^2 dm = \mu \Sigma x^2 \frac{ax}{p} dx$$

$$= \mu \frac{a}{p} \int_0^p x^3 dx = \mu \frac{ap^3}{4} = \frac{M}{2} p^2.$$

In like manner, let  $B$  and  $C$  be the moments of inertia relative to lines drawn through the other vertices parallel to  $b$  and  $c$ ; and let  $q, r$  be the corresponding perpendiculæ of the triangle, and we have

$$B = \frac{M}{2} q^2, \quad C = \frac{M}{2} r^2.$$

Again, if  $A_0, B_0, C_0$ , represent the moments of inertia

relative to three parallels to the sides, drawn through the centre of gravity of the lamina, we have, by (2),

$$A_0 = \frac{I}{18} Mp^2, \quad B_0 = \frac{I}{18} Mq^2, \quad C_0 = \frac{I}{18} Mr^2. \quad (16)$$

Also, if  $A_1, B_1, C_1$ , be the moments of inertia relative to the sides  $a, b, c$ , respectively, it follows, in like manner, from (2), that

$$A_1 = \frac{I}{6} Mp^2, \quad B_1 = \frac{I}{6} Mq^2, \quad C_1 = \frac{I}{6} Mr^2. \quad (17)$$

Again, it is readily seen that the values of  $A, A_0, A_1, \&c.$ , are the same as if the whole mass  $M$  were divided into three equal masses, placed respectively at the middle points of the sides of the lamina.

Consequently, by Art. 207, the moments of inertia of the triangular lamina relative to all axes are the same as for three masses, each  $\frac{M}{3}$ , placed at the middle points of the sides of the triangle.

Hence, if  $I$  be the moment of inertia of a triangular lamina with respect to the perpendicular to its plane drawn through its centre of gravity, we have

$$I = \frac{I}{36} M(a^2 + b^2 + c^2). \quad (18)$$

This expression also holds for the moment of inertia of a right triangular prism with respect to its axis.\*

In like manner the moments of inertia of the triangular lamina relative to the three perpendiculars to its plane, drawn through its vertices, are

$$\frac{I}{4} M \left( b^2 + c^2 - \frac{a^2}{3} \right), \quad \frac{I}{4} M \left( c^2 + a^2 - \frac{b^2}{3} \right), \quad \frac{I}{4} M \left( a^2 + b^2 - \frac{c^2}{3} \right);$$

and the same expressions hold for a triangular prism relative to its edges.

\* By the axis of a prism is understood the right line drawn through its centre of gravity parallel to its edges.

**210. Momental Ellipse of a Triangle.**—It can be shown without difficulty that the ellipse which touches at the middle points of the sides may be taken for the momental ellipse of the triangle.

For, let  $x, y, z$  be the middle points of the sides, and it is easily seen that  $o$  is the centre of this ellipse; also, if  $I_1, I_2, I_3$  be the moments of inertia of the lamina relative to the lines  $ax, by, cz$ , respectively, it can be readily shown from (17), that we have

$$I_1 : I_2 : I_3 = \frac{I}{(ax)^2} : \frac{I}{(by)^2} : \frac{I}{(cz)^2}$$

$$= \frac{I}{(ox)^2} : \frac{I}{(oy)^2} : \frac{I}{(oz)^2}.$$

Accordingly, by Art. 207, the ellipse  $xyz$  may be taken for the momental ellipse of the lamina.

**211. Tetrahedron.**—If a solid tetrahedron be supposed divided into thin laminae parallel to one of its faces, and if  $A, B, C, D$  represent its moments of inertia with regard to the four planes drawn respectively through its vertices parallel to its faces; then, denoting the areas of the corresponding faces by  $a, b, c, d$ , and the corresponding perpendiculars of the tetrahedron by  $p, q, r, s$ , respectively, it is easily seen, as in Art. 209, that we shall have

$$\begin{aligned} A &= \Sigma x^2 dm = \mu \Sigma x^2 a \frac{x^2}{p^2} dx = \mu \frac{a}{p^2} \int_0^p x^4 dx \\ &= \mu \frac{ap^3}{5} = \frac{3}{5} Mp^2. \end{aligned}$$

In like manner we have

$$B = \frac{3}{5} Mq^2, \quad C = \frac{3}{5} Mr^2, \quad D = \frac{3}{5} Ms^2.$$

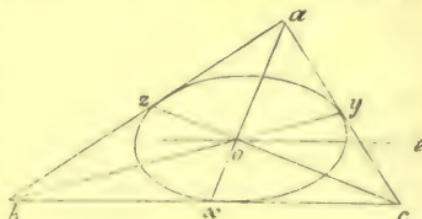


Fig. 49.

Again, if  $A_0, B_0, C_0, D_0$  be the corresponding moments of inertia relative to the parallel planes drawn through the centre of gravity of the tetrahedron, we have, by (2),

$$A_0 = \frac{3}{80} Mp^2, \quad B_0 = \frac{3}{80} Mq^2, \quad C_0 = \frac{3}{80} Mr^2, \quad D_0 = \frac{3}{80} Ms^2. \quad (19)$$

Also, if  $A_1, B_1, C_1, D_1$  be the moments of inertia relative to the four faces of the tetrahedron, we have

$$A_1 = \frac{1}{10} Mp^2, \quad B_1 = \frac{1}{10} Mq^2, \quad C_1 = \frac{1}{10} Mr^2, \quad D_1 = \frac{1}{10} Ms^2. \quad (20)$$

212. **Solid Ring.**\*—If a plane closed curve, which is symmetrical with respect to an axis  $AB$ , be made to revolve round a parallel axis, lying in its plane, but not intersecting the curve, to prove that the moment of inertia  $I$  of the generated solid, taken with respect to the axis of revolution, is represented by

$$M(h^2 + 3k^2),$$

where  $M$  is the mass of the solid,  $h$  the distance between the parallel axes, and  $k$  the radius of gyration of the generating area relative to its axis.

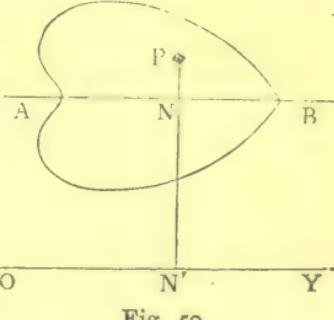


Fig. 50.

For, if the axis of revolution be taken as the axis of  $x$ , and, if  $y, Y$  be the distances of any point  $P$  within the generating area from  $AB$ , and from  $OX$ , respectively; and, if  $dA$  be the corresponding element of the area, then the volume of the elementary ring generated by  $dA$  is  $2\pi Y dA$ , and its mass  $2\pi \mu Y dA$ ; hence the moment of inertia of this elementary ring, relative to the axis of  $X$ , is  $2\pi \mu Y^3 dA$ . Accordingly, we have

$$\begin{aligned} I &= 2\pi \mu \Sigma Y^3 dA = 2\pi \mu \Sigma (h + y)^3 dA \\ &= 2\pi \mu \Sigma (h^3 + 3h^2y + 3hy^2 + y^3) dA. \end{aligned}$$

\* The theorems of this Article were given by Professor Townsend in the *Quarterly Journal of Mathematics*, 1869.

Moreover, since the curve is symmetrical with respect to the axis  $AB$ , it is easily seen that we have

$$\Sigma y dA = 0, \quad \Sigma y^2 dA = 0.$$

Also, by definition,  $\Sigma y^2 dA = Ak^2$ .

Hence  $I = 2\pi\mu hA(h^2 + 3k^2)$ .

Again, by Art. 177,  $M = 2\pi\mu hA$ ;

$$\therefore I = M(h^2 + 3k^2). \quad (21)$$

This leads immediately to some important cases.

Thus, for example, the moment of inertia of a circular ring, of radius  $a$ , round its axis is

$$M\left(h^2 + \frac{3}{4}a^2\right).$$

Again, if a square of side  $a$  revolve round any line in its plane, situated at the distance  $h$  from its centre, we have

$$I = M(h^2 + a^2).$$

There is no difficulty in adding other examples.

### 213. General Expression for Products of Inertia.

—We shall conclude this Chapter with a short discussion of the general case of the moments and products of inertia, for any body, or system.

Let us suppose the system referred to three rectangular planes, and let  $p, q, r$  represent the respective distances of any element  $dm$  from the three planes

$$\begin{aligned} x \cos \alpha + y \cos \beta + z \cos \gamma &= 0, \\ x \cos \alpha' + y \cos \beta' + z \cos \gamma' &= 0, \\ x \cos \alpha'' + y \cos \beta'' + z \cos \gamma'' &= 0. \end{aligned}$$

Then

$$\begin{aligned} \Sigma p q dm &= \Sigma (x \cos \alpha + y \cos \beta + z \cos \gamma)(x \cos \alpha' + y \cos \beta' + z \cos \gamma') dm \\ &= \cos \alpha \cos \alpha' \Sigma x^2 dm + \cos \beta \cos \beta' \Sigma y^2 dm + \cos \gamma \cos \gamma' \Sigma z^2 dm \\ &\quad + (\cos \alpha \cos \beta' + \cos \beta \cos \alpha') \Sigma xy dm \\ &\quad + (\cos \gamma \cos \alpha' + \cos \alpha \cos \gamma') \Sigma zx dm \\ &\quad + (\cos \beta \cos \gamma' + \cos \gamma \cos \beta') \Sigma yz dm; \end{aligned}$$

and we get similar expressions for  $\Sigma p r dm$  and  $\Sigma q r dm$ .

Now, suppose that we take

$$\begin{aligned}\Sigma x^2 dm &= a, & \Sigma y^2 dm &= b, & \Sigma z^2 dm &= c, \\ \Sigma yz dm &= f, & \Sigma xz dm &= g, & \Sigma xy dm &= h;\end{aligned}$$

then the preceding equation may be written

$$\begin{aligned}\Sigma pq dm &= \cos a (\alpha \cos a' + h \cos \beta' + g \cos \gamma') \\ &+ \cos \beta (h \cos a' + b \cos \beta' + f \cos \gamma') \\ &+ \cos \gamma (g \cos a' + f \cos \beta' + c \cos \gamma');\end{aligned}\quad (22)$$

along with similar expressions for  $\Sigma rp dm$  and  $\Sigma qr dm$ .

214. **Principal Axes.**—Next, let us suppose that the planes are so assumed as to satisfy the equations

$$\Sigma pq dm = 0, \quad \Sigma rp dm = 0, \quad \Sigma qr dm = 0;$$

then it is easily seen\* that these planes are a system of conjugate diametral planes in the ellipsoid represented by the equation

$$aX^2 + bY^2 + cZ^2 + 2fYZ + 2gZX + 2hXY = \text{const.} \quad (23)$$

Hence it follows that at any point there exists *one system of rectangular planes for which the corresponding products of inertia, for any body, vanish*: viz., *the principal planes of the preceding ellipsoid.*†

These three planes are called the *principal planes* of the body relative to the point, and the right lines in which they intersect are called the *principal axes* for the point.

Again, every two solids have for every point at least one common system of planes for which  $\Sigma pq dm = 0$ ,  $\Sigma rp dm = 0$ ,  $\Sigma qr dm = 0$ ,  $\Sigma p'q'dm' = 0$ ,  $\Sigma r'p'dm' = 0$ ,  $\Sigma q'r'dm' = 0$ ; where the unaccented letters refer to the elements of one solid, and the accented to those of the other.

This is obvious from the property that every two concentric ellipsoids have one common system of diametral planes.

\*. Salmon's *Geometry of Three Dimensions*, Art. 72.

† The exceptional cases when the ellipsoid is of revolution, or is a sphere, will be considered subsequently.

Again, if two solids have for any point more than one system of planes for which the foregoing six products of inertia vanish, they must have the same principal planes at the point. This follows since the two ellipsoids in that case must be similar and coaxal.

215. **Principal Moments of Inertia.**—Let us now suppose the co-ordinate planes to be the principal planes of the body for the origin, then the moment of inertia relative to the plane

$$x \cos \alpha + y \cos \beta + z \cos \gamma = 0$$

is

$$\begin{aligned}\Sigma p^2 dm &= \Sigma (x \cos \alpha + y \cos \beta + z \cos \gamma)^2 dm \\ &= \cos^2 \alpha \Sigma x^2 dm + \cos^2 \beta \Sigma y^2 dm + \cos^2 \gamma \Sigma z^2 dm,\end{aligned}\quad (24)$$

since in this case we have

$$\Sigma xy dm = 0, \quad \Sigma zx dm = 0, \quad \Sigma yz dm = 0.$$

Again, let  $I$  be the moment of inertia of the body relative to the line through the origin whose direction angles are  $\alpha, \beta, \gamma$ ; then we have

$$\begin{aligned}I + \Sigma p^2 dm &= \Sigma r^2 dm = \Sigma (x^2 + y^2 + z^2) dm; \\ \therefore I &= \cos^2 \alpha \Sigma (y^2 + z^2) dm + \cos^2 \beta \Sigma (z^2 + x^2) dm \\ &\quad + \cos^2 \gamma \Sigma (x^2 + y^2) dm;\end{aligned}$$

or

$$I = A \cos^2 \alpha + B \cos^2 \beta + C \cos^2 \gamma, \quad (25)$$

where  $A, B, C$  are the moments of inertia of the body relative to its three principal axes.

$A, B, C$  are called the *three principal moments of inertia* of the body relative to the origin.

If the centre of gravity be taken as the origin, the corresponding values of  $A, B, C$  are called the *principal moments of inertia of the body*.

We suppose, in general, that  $A$  is the greatest, and  $C$  the least of the three principal moments.

It follows from (25) that the moment of inertia of a body relative to any line passing through a given point is known, whenever the angles which the line makes with the principal axes are known, as also the moments of inertia relative to these axes.

216. **Ellipsoid of Gyration.**—Suppose, as before, the solid referred to its three principal axes at any point, and let  $a, b, c$  be the corresponding radii of gyration, i.e. let

$$A = Ma^2, \quad B = Mb^2, \quad C = Mc^2,$$

and  $I = Mk^2$ ; then equation (25) becomes

$$k^2 = a^2 \cos^2 \alpha + b^2 \cos^2 \beta + c^2 \cos^2 \gamma. \quad (26)$$

Now, if we suppose an ellipsoid described having the principal axes for the directions, and  $a, b, c$  for the lengths of its corresponding semi-axes; then (26) shows that the radius of gyration of the body, relative to the perpendicular from the origin on any tangent plane to this ellipsoid, is equal in length to this perpendicular. (Salmon's *Geometry of Three Dimensions*, Art. 89.)

The foregoing ellipsoid is called the *ellipsoid of gyration* relative to the point. It should, however, be observed that by the ellipsoid of gyration of a body is meant the ellipsoid in the particular case where the origin is at the centre of gravity of the body.

217. **Momental Ellipsoid.**—If  $X, Y, Z$  be the co-ordinates of a point  $R$  taken on the right line through the origin  $O$ , whose direction angles are  $\alpha, \beta, \gamma$ , we have

$$X = OR \cos \alpha, \quad Y = OR \cos \beta, \quad Z = OR \cos \gamma.$$

Substituting the values of  $\cos \alpha, \cos \beta, \cos \gamma$ , deduced from these equations, in (25), it becomes

$$I \cdot OR^2 = AX^2 + BY^2 + CZ^2.$$

Suppose, now, that the point  $R$  lies on the ellipsoid

$$AX^2 + BY^2 + CZ^2 = \text{const.}, \quad (27)$$

and we get  $I \cdot OR^2 = \lambda$ , denoting the constant by  $\lambda$ ;

$$\therefore I = \frac{\lambda}{OR^2}. \quad (28)$$

Hence the *moment of inertia relative to any axis, drawn through the origin, varies inversely as the square of the corresponding diameter of the ellipsoid* (27).

From this property the ellipsoid is called the *momental ellipsoid* at the point.

When the origin is taken at the centre of gravity of the body, this ellipsoid is called the *central ellipsoid* of the body.

If two of the principal moments of inertia relative to any point be equal, the momental ellipsoid becomes one of revolution, and in this case all diameters perpendicular to its axis of revolution are principal axes relative to the point.

If the three principal moments at any point be equal, the ellipsoid becomes a sphere, and the moments of inertia for all axes drawn through the point are equal. Every such axis is a principal axis at the point.

For example, it is plain that the three principal moments for the centre of a cube are equal, and, consequently, its moments of inertia for all axes, through its centre, are equal.

218. **Equimomental Cone.**—Again, since

$$\cos^2 \alpha + \cos^2 \beta + \cos^2 \gamma = 1,$$

equation (25) may be written in the form

$$(A - I) \cos^2 \alpha + (B - I) \cos^2 \beta + (C - I) \cos^2 \gamma = 0;$$

hence the equation

$$(A - I) X^2 + (B - I) Y^2 + (C - I) Z^2 = 0 \quad (29)$$

represents a cone such that the moment of inertia is the same for each of its edges. Such a cone is called an *equimomental cone* of the body.

Again, the three axes of any equimomental cone, for any solid, are the principal axes of the solid relative to the vertex of the cone.

When  $I = B$ , the cone breaks up into two planes; viz., the cyclic sections of the momental ellipsoid.

For a more complete discussion of the general theory of moments of inertia and principal axes, the student is referred to Routh's *Rigid Dynamics*, chapters I. and II.; as also to Professor Townsend's papers in the *Camb. and Dub. Math. Journal*, 1846, 1847.

## EXAMPLES.

Find the expressions for the moments of inertia in the following, the bodies being supposed homogeneous in all cases :—

1. A parallelogram, of sides  $a$ ,  $b$ , and angle  $\theta$ , with respect to its sides.

$$\text{Ans. } \frac{M}{3} b^2 \sin^2 \theta, \quad \frac{M}{3} a^2 \sin^2 \theta.$$

2. A rod, of length  $a$ , with respect to an axis perpendicular to the rod and at a distance  $d$  from its middle point.

$$\text{Ans. } M \left( \frac{a^2}{3} + d^2 \right).$$

3. An equilateral triangle, of side  $a$ , relative to a line in its plane at the distance  $d$  from its centre of gravity.

$$\text{Ans. } M \left( \frac{a^2}{24} + d^2 \right).$$

4. A right-angled triangle, of hypotenuse  $c$ , relative to a perpendicular to its plane passing through the right angle.

$$\text{Ans. } M \frac{c^2}{6}.$$

5. A hollow circular cylinder, relative to its axis.

$$\text{Ans. } M \frac{r^2 + r'^2}{2}, \text{ where } r \text{ and } r' \text{ are the radii of the bounding circles.}$$

6. A truncated cone with reference to its axis.

$$\text{Ans. } \frac{3M}{10} \frac{b^5 - b'^5}{b^3 - b'^3}, \text{ where } b \text{ and } b' \text{ are the radii of its bases.}$$

7. A right cone with respect to an axis drawn through its vertex perpendicular to its axis.

$$\text{Ans. } \frac{3M}{5} \left( h^2 + \frac{b^2}{4} \right), \text{ where } h \text{ denotes the altitude of the cone, and } b \text{ the radius of its base.}$$

8. An ellipsoid with respect to a diameter making angles  $\alpha$ ,  $\beta$ ,  $\gamma$  with its axes.

$$\text{Ans. } \frac{M}{5} \left( a^2 \sin^2 \alpha + b^2 \sin^2 \beta + c^2 \sin^2 \gamma \right).$$

9. Area bounded by two rectangles having a common centre, and whose sides are respectively parallel, with respect to an axis through their centre perpendicular to the plane.

$$\text{Ans. } \frac{M}{12} \frac{(a^2 + b^2)ab - (a'^2 + b'^2)a'b'}{ab - a'b'}.$$

10. A square, of side  $a$ , relative to any line in its plane, passing through its centre.

$$\text{Ans. } M \frac{a^2}{12}.$$

11. A regular polygon, or prism, with respect to its axis.

$\text{Ans. } \frac{M}{6} (R^2 + 2r^2)$ , where  $R$  and  $r$  are the radii of the circles circumscribed, and inscribed to the polygon.

12. Prove that a parallelogram and its maximum inscribed ellipse have the same principal axes at their common centre of figure.

13. Prove that the moments and products of inertia of any triangular lamina, of mass  $M$ , are the same as for three masses, each  $\frac{M}{12}$ , placed at the three vertices of the triangle, combined with a mass  $\frac{3}{4}M$  placed at its centre of gravity.

14. Prove that the moments and products of inertia of any tetrahedron are the same as for four masses, each  $\frac{M}{20}$ , placed at the vertices of the tetrahedron, combined with a mass  $\frac{4}{5}M$  placed at its centre of gravity.

15. If a system of equimomental axes, for any solid, all lie in a principal plane passing through its centre of gravity, prove that they envelop a conic, having that point for centre, and the principal axes in the plane for axes.

16. Prove also that the ellipses obtained by varying the magnitude of the moment of inertia form a confocal system.

17. Prove that the sum of the moments of inertia of a body relative to any three rectangular axes drawn through the same point is constant.

18. Prove that a principal axis belonging to the centre of gravity of a body is also a principal axis with respect to every point on its length.

19. Prove that the envelope of a plane for which the moment of inertia of a body is constant is an ellipsoid, confocal with the ellipsoid of gyration of the body.

20. If a system of equimomental planes pass through a point, prove that they envelop a cone of the second degree.

21. For different values of the constant moment the several enveloped cones are confocal?

22. The common axes of this system of cones are the three principal axes of the body for the point?

23. The three principal axes at any point are the normals to the three surfaces confocal to the ellipsoid of gyration, which pass through the point. (M. Binet, *Jour. de l'Ec. Poly.* 1813.)

## CHAPTER XI.

## MULTIPLE INTEGRALS.

219. **Double Integration.**—In the preceding Chapters we have considered several cases of double and triple integration in the determination of volumes and other problems connected with surfaces. We now proceed to a short treatment of the general problem of Multiple Integration, commencing with double integrals.

The general form of a double integral may be written

$$\int_{x_0}^X \int_{y_0}^Y f(x, y) dx dy,$$

in which we suppose the integration first taken with respect to  $y$ , regarding  $x$  as constant. In this case,  $Y, y_0$ , the limits of  $y$ , are, in general, functions of  $x$ ; and the limits of  $x$  are constants.

For example, let us take the integral

$$U = \int_0^a \int_x^{a^2} x^{l-1} y^{m-1} dx dy,$$

in which  $l$  is supposed greater than  $m$ .

$$\text{Here } \int_x^{a^2} y^{m-1} dy = \frac{1}{m} \left( \frac{a^{2m}}{x^m} - x^m \right);$$

$$\text{therefore } U = \frac{1}{m} \int_0^a x^{l-1} \left( \frac{a^{2m}}{x^m} - x^m \right) dx = \frac{2a^{l+m}}{l^2 - m^2}.$$

It should be observed that in many cases the variables are to be taken so as to include all values limited by a certain condition, which can be expressed by an inequality : for instance, to find

$$U = \iint x^{l-1} y^{m-1} dx dy,$$

extended to all *positive* values of  $x$  and  $y$  subject to the condition  $x + y < h$ .

Here the limits for  $y$  are 0 and  $h - x$ ; and the subsequent limits of  $x$  are 0 and  $h$ .

Hence 
$$U = \int_0^h \int_0^{h-x} x^{l-1} y^{m-1} dx dy$$

$$= \frac{1}{m} \int_0^h x^{l-1} (h-x)^m dx.$$

Let  $x = hu$ ; then

$$U = \frac{h^{l+m}}{m} \int_0^1 u^{l-1} (1-u)^m du = \frac{h^{l+m} \Gamma(l) \Gamma(m)}{\Gamma(l+m+1)}, \quad (1)$$

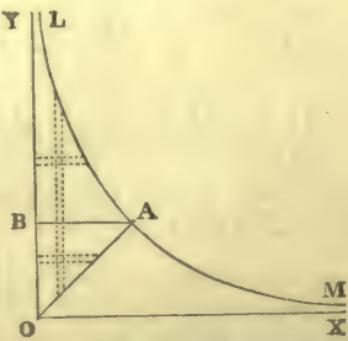
by Art. 121.

**220. Change of Order of Integration.**—We have seen (Art. 115) that when the limits of  $x$  and  $y$  are constants we may change the order of integration, the limits remaining unaltered. But when the limits of  $y$  are functions of  $x$ , if the order of integration be changed, it is necessary to find the new limits for  $x$  as functions of  $y$ . This is usually best obtained from geometrical considerations.

For example, in the integral

$$U = \int_0^a \int_x^{a^2} f(x, y) dx dy,$$

the limits for  $y$  are given by the right line  $y = x$  and the hyperbola  $xy = a^2$ ; and the integral extends to all points in the space bounded by the axis of  $y$ , the hyperbola  $AL$ , and the right line  $OA$ , where  $A$  is the vertex of the hyperbola. Draw  $AB$  perpendicular to the axis of  $y$ . Now when the order of integration is changed, we suppose the lines which divide the area into strips taken parallel to the axis of  $x$  instead of that of  $y$ . Thus the integral breaks up into two parts—one corresponding to



the triangle  $OAB$ , the other to the remaining area: hence

$$U = \int_0^a \int_0^y f(x, y) dy dx + \int_a^\infty \int_0^{\frac{a^2}{y}} f(x, y) dy dx.$$

As another example, let us interchange the variables in the integral

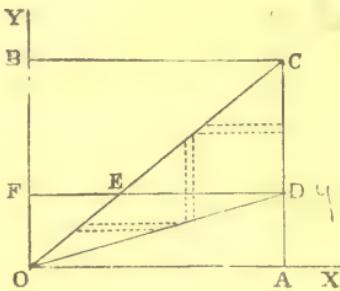
$$U = \int_0^a \int_{mx}^{lx} V dx dy.$$

Here, let  $OC$  and  $OD$  be the lines represented by  $y = lx$  and  $y = mx$ ; and let  $OA = a$ .

Then the integral is extended to all points within the triangle  $OCD$ .

Accordingly, changing the order, we get

$$U = \int_{ma}^{la} \int_{\frac{y}{l}}^a V dy dx + \int_0^{ma} \int_{\frac{y}{l}}^m V dy dx.$$



### EXAMPLES.

1. Find the value of the double integral

$$U = \int_0^a \int_0^x \frac{f'(y) dx dy}{\sqrt{(a-x)(x-y)}}.$$

Here, changing the order, the integral becomes

$$\int_0^a \int_y^a \frac{f'(y) dy dx}{\sqrt{(a-x)(x-y)}}.$$

But  $\int_y^a \frac{dx}{\sqrt{(a-x)(x-y)}} = \pi$ ; hence  $U = \pi \{ f(a) - f(0) \}$ .

2. Prove that

$$\int_a^{2a} \int_0^{\sqrt{2ax-x^2}} f(x, y) dx dy = \int_0^a \int_{a-\sqrt{a^2-y^2}}^{a+\sqrt{a^2-y^2}} f(x, y) dy dx.$$

3. Hence find the value of

$$\int_0^{2a} \int_0^{\sqrt{2ax-x^2}} \frac{\phi'(y)(x^2+y^2)x \, dx \, dy}{\sqrt{4a^2x^2-(x^2+y^2)^2}}.$$

$$Ans. \pi a^2 \{ \phi(a) - \phi(0) \}.$$

4. Change the order of integration in the double integral

$$U = \int_0^{2a} \int_{\sqrt{2ax-x^2}}^{\sqrt{2ax}} V \, dx \, dy.$$

The limits of  $y$  are represented by the circle  $x^2 + y^2 = 2ax$ , and the parabola  $y^2 = 2ax$ ; and we readily find that

$$U = \int_0^a \int_{\frac{y^2}{2a}}^{a-\sqrt{a^2-y^2}} V \, dy \, dx + \int_0^a \int_{a+\sqrt{a^2-y^2}}^{2a} V \, dy \, dx + \int_a^{2a} \int_{\frac{y^2}{2a}}^a V \, dy \, dx.$$

**221. Dirichlet's Theorem.** — The result given in equation (1) has been generalized by Dirichlet (Liouville's *Journal*, 1839), and extended to a large class of multiple integrals, as follows:

Commencing with three variables, let us consider the integral

$$U = \iiint x^{l-1} y^{m-1} z^{n-1} \, dx \, dy \, dz,$$

in which the variables are supposed always *positive*, and limited by the condition

$$x + y + z < 1.$$

In this case the limits of  $z$  are 0 and  $1 - x - y$ ; those of  $y$  are 0 and  $1 - x$ ; and those of  $x$  are 0 and 1.

Hence  $U = \int_0^1 \int_0^{1-x} \int_0^{1-x-y} x^{l-1} y^{m-1} z^{n-1} \, dx \, dy \, dz.$

It is easily seen, from (1), that

$$\int_0^{1-x} \int_0^{1-x-y} y^{m-1} z^{n-1} \, dy \, dz = (1-x)^{m+n} \frac{\Gamma(m) \Gamma(n)}{\Gamma(m+n+1)}.$$

Therefore

$$U = \frac{\Gamma(m) \Gamma(n)}{\Gamma(m+n+1)} \int_0^1 x^{l-1} (1-x)^{m+n} dx$$

$$= \frac{\Gamma(m) \Gamma(n)}{\Gamma(m+n+1)} \cdot \frac{\Gamma(l) \Gamma(m+n+1)}{\Gamma(l+m+n+1)} = \frac{\Gamma(l) \Gamma(m) \Gamma(n)}{\Gamma(l+m+n+1)}. \quad (2)$$

Again, in the same multiple integral, if  $x, y, z$ , being *still always positive*, are subject to the condition

$$x + y + z < h,$$

we get

$$U = h^{l+m+n} \frac{\Gamma(l) \Gamma(m) \Gamma(n)}{\Gamma(l+m+n+1)}. \quad (3)$$

This readily appears by substituting  $x = hx'$ ,  $y = hy'$ ,  $z = hz'$ , in the multiple integral.

There is no difficulty in extending these results to any number of variables. For we readily proceed from (3) to the case of four variables; and so by induction to any number.

Thus, the value of the multiple integral

$$U = \iiint \dots x^{l-1} y^{m-1} z^{n-1} \dots dx dy dz \dots,$$

extended to all *positive* values of  $x, y, z$ , &c., subject to the condition

$$x + y + z + \&c. < 1,$$

is

$$U = \frac{\Gamma(l) \Gamma(m) \Gamma(n) \dots}{\Gamma(1+l+m+n+\dots)}. \quad (4)$$

Again, in the integral

$$U = \iiint x^{l-1} y^{m-1} z^{n-1} dx dy dz,$$

suppose the variables to be still always positive, but limited by the condition

$$\left(\frac{x}{a}\right)^p + \left(\frac{y}{b}\right)^q + \left(\frac{z}{c}\right)^r < 1;$$

then making

$$\left(\frac{x}{a}\right)^p = u, \quad \left(\frac{y}{b}\right)^q = v, \quad \left(\frac{z}{c}\right)^r = w,$$

the integral transforms into

$$U = \frac{a^l b^m c^n}{pqr} \iiint u^{\frac{l}{p}-1} v^{\frac{m}{q}-1} w^{\frac{n}{r}-1} du dv dw,$$

where  $u + v + w < 1$ .

Accordingly,

$$U = \frac{a^l b^m c^n}{pqr} \frac{\Gamma\left(\frac{l}{p}\right) \Gamma\left(\frac{m}{q}\right) \Gamma\left(\frac{n}{r}\right)}{\Gamma\left(1 + \frac{l}{p} + \frac{m}{q} + \frac{n}{r}\right)}. \quad (5)$$

Again, from (3), the value of the triple integral

$$\iiint x^{l-1} y^{m-1} z^{n-1} dx dy dz,$$

extended to all positive values, subject to the condition

$$x + y + z > u \text{ and } < u + du,$$

is immediately found by differentiation to be

$$\frac{\Gamma(l) \Gamma(m) \Gamma(n)}{\Gamma(1 + l + m + n)} (l + m + n) u^{l+m+n-1} du, \text{ or } \frac{\Gamma(l) \Gamma(m) \Gamma(n)}{\Gamma(l + m + n)} u^{l+m+n-1} du.$$

Hence the multiple integral

$$\iiint F(x + y + z) x^{l-1} y^{m-1} z^{n-1} dx dy dz,$$

taken between the same limits, has for its value

$$\frac{\Gamma(l) \Gamma(m) \Gamma(n)}{\Gamma(l + m + n)} F(u) u^{l+m+n-1} du.$$

Accordingly, the value of the multiple integral

$$\iiint F(x + y + z) x^{l-1} y^{m-1} z^{n-1} dx dy dz,$$

extended to all *positive* values of the variables, subject to the condition

$$x + y + z < h,$$

is

$$\frac{\Gamma(l) \Gamma(m) \Gamma(n)}{\Gamma(l+m+n)} \int_0^h F(u) u^{l+m+n-1} du. \quad (6)$$

In like manner it is seen that if the multiple integral

$$U = \iiint F \left\{ \left(\frac{x}{a}\right)^p + \left(\frac{y}{b}\right)^q + \left(\frac{z}{c}\right)^r \right\} x^{l-1} y^{m-1} z^{n-1} dx dy dz$$

be extended to all positive values, subject to the condition

$$\left(\frac{x}{a}\right)^p + \left(\frac{y}{b}\right)^q + \left(\frac{z}{c}\right)^r < h,$$

we have

$$U = \frac{a^l b^m c^n}{pqr} \frac{\Gamma\left(\frac{l}{p}\right) \Gamma\left(\frac{m}{q}\right) \Gamma\left(\frac{n}{r}\right)}{\Gamma\left(\frac{l}{p} + \frac{m}{q} + \frac{n}{r}\right)} \int_0^h F(u) u^{\frac{l}{p} + \frac{m}{q} + \frac{n}{r} - 1} du. \quad (7)$$

These results can be readily extended to any number of variables.

### EXAMPLES.

1. Find the value of

$$\iint x^{l-1} y^{m-1} e^{x+y} dx dy,$$

extended to all positive values, subject to  $x + y < h$ .

$$Ans. \frac{\pi}{\sin l\pi} (e^h - 1).$$

2. More generally, prove that

$$\iint F'(x+y) x^{k-1} y^{-l} dx dy = \frac{\pi}{\sin \frac{k\pi}{l\pi}} \{ F(h) - F(0) \},$$

where

$$x+y < h.$$

3. Find the value of

$$\iiint \dots dx_1 dx_2 \dots dx_n,$$

extended to all positive values of the variables, subject to the condition

$$x_1^2 + x_2^2 + \dots + x_n^2 < R^2.$$

$$\text{Ans. } \left( \frac{R}{2} \right)^n \cdot \frac{\pi^{\frac{n}{2}}}{\Gamma \left( 1 + \frac{n}{2} \right)}.$$

4. Prove that

$$\iiint \frac{dx dy dz}{\sqrt{1 - x^2 - y^2 - z^2}} = \frac{\pi^3}{8},$$

the integral being extended to all positive values of the variables for which the expression is real.

5. Show in general that

$$\iiint \dots \frac{dx_1 dx_2 dx_3}{\sqrt{1 - x_1^2 - x_2^2 - \dots - x_n^2}} = \frac{\pi^{\frac{n+1}{2}}}{2^n \Gamma \left( \frac{n+1}{2} \right)},$$

under the same condition as in last.

**222. Transformation of Multiple Integrals.**—We now proceed to consider, in general, the transformation of a multiple integral to a new system of independent variables.

Suppose it be required to transform the integral

$$\iiint f(x, y, z) dx dy dz$$

to another system of variables,  $u, v, w$ ; being given  $x, y, z$  in terms of  $u, v, w$ .

This transformation implies in general three parts—  
(1) the expression of  $f(x, y, z)$  in terms of  $u, v, w$ ; (2) the determination of the new system or systems of limits; (3) the substitution for  $dx dy dz$ .

The solution of the first two questions is a purely algebraical

problem. We here accordingly limit ourselves to the consideration of the third question, and write the integral in the form

$$\int dx \int dy \int f(x, y, z) dz.$$

In the integration with respect to  $z$ ,  $x$  and  $y$  are regarded as constant; accordingly, in order to replace  $z$  by the new variable  $w$ , we suppose  $z$  expressed, by means of the given equations, in terms of  $x$ ,  $y$ ,  $w$ ; and then we replace  $dz$  by  $\frac{dz}{dw} dw$ . Again, to transform the integration from  $y$  to  $v$ , we suppose  $y$  expressed in terms of  $v$ ,  $w$ ,  $x$ , and then  $dy$  replaced by  $\frac{dy}{dv} dv$ : we next suppose  $x$  replaced by  $\frac{dx}{du} du$ ; and we finally replace

$$dx dy dz \text{ by } \frac{dz}{dw} \frac{dy}{dv} \frac{dx}{du} du dv dw.$$

It should be observed that in each of the latter transformations a change in the order of integration is supposed.

By this means the transformed expression is

$$\iiint \phi(u, v, w) \frac{dz}{dw} \frac{dy}{dv} \frac{dx}{du} du dv dw, \quad (8)$$

where  $\phi(u, v, w)$  is the transformation of  $f(x, y, z)$ .

The preceding transformation would present, in general, a problem of extreme difficulty, especially in the investigation of the new limits at each change in the order of integration. The one consideration in every case to be carefully observed is, that the transformed integral or integrals must include every element which enters into the original expression, and no more.

Again, it may be observed that in the foregoing transformation for  $dx dy dz$  the order of substitution may be interchanged in any manner.

Thus, if we commence by replacing  $x$  by  $u$ , we must suppose  $x$  expressed in terms of  $u$ ,  $y$ ,  $z$ ; and then replace  $dx$  by  $\frac{dx}{du} du$ , and so on.

As an illustration we shall consider the ordinary transformation from rectangular to polar coordinates, viz. :—

$$x = r \sin \theta \sin \phi, \quad y = r \sin \theta \cos \phi, \quad z = r \cos \theta.$$

Here we have

$$x^2 + y^2 + z^2 = r^2;$$

therefore

$$x^2 = r^2 - y^2 - z^2;$$

hence

$$\frac{dx}{dr} = \frac{r}{x} = \frac{1}{\sin \theta \sin \phi}.$$

Again,  $\frac{dz}{d\theta} = -r \sin \theta, \quad \frac{dy}{d\phi} = -r \sin \theta \sin \phi;$

therefore  $\frac{dx}{dr} \frac{dz}{d\theta} \frac{dy}{d\phi} = r^2 \sin \theta;$

and for the element of volume  $dx dy dz$  we substitute

$$r^2 \sin \theta dr d\theta d\phi,$$

a result which can be also readily shown from geometrical considerations.

Next, let us consider the more general transformation

$$x = r \sin \theta \sqrt{1 - m^2 \sin^2 \phi}, \quad y = r \sin \phi \sqrt{1 - n^2 \sin^2 \theta}, \quad z = r \cos \theta \cos \phi,$$

in which

$$m^2 + n^2 = 1.$$

Squaring, and adding the three equations, we get

$$x^2 + y^2 + z^2 = r^2.$$

In replacing  $x$  by  $r$ , we get, therefore,

$$\frac{dx}{dr} = \frac{r}{x} = \frac{1}{\sin \theta \sqrt{1 - m^2 \sin^2 \phi}}.$$

Next, to replace  $y$  by  $\phi$ , we must express  $y$  in terms of  $r$ ,  $\phi$ , and  $z$ : thus

$$y = r \sin \phi \sqrt{m^2 + n^2 \cos^2 \theta} = \sin \phi \sqrt{m^2 r^2 + \frac{n^2 z^2}{\cos^2 \phi}} \\ = \tan \phi \sqrt{m^2 r^2 \cos^2 \phi + n^2 z^2}.$$

Hence

$$\frac{dy}{d\phi} = \sec^2 \phi \sqrt{m^2 r^2 \cos^2 \phi + n^2 z^2} - \frac{m^2 r^2 \sin^2 \phi}{\sqrt{m^2 r^2 \cos^2 \phi + n^2 z^2}} \\ = \frac{m^2 r^2 \cos^2 \phi + n^2 z^2 \sec^2 \phi}{\sqrt{m^2 r^2 \cos^2 \phi + n^2 z^2}} = \frac{r(m^2 \cos^2 \phi + n^2 \cos^2 \theta)}{\cos \phi \sqrt{m^2 + n^2 \cos^2 \theta}};$$

and, finally,  $\frac{dz}{d\theta} = -r \sin \theta \cos \phi$ .

Hence for  $dx dy dz$  we substitute

$$\frac{r^2 (m^2 \cos^2 \phi + n^2 \sin^2 \phi)}{\sqrt{1 - m^2 \sin^2 \phi} \sqrt{1 - n^2 \sin^2 \theta}} dr d\theta d\phi. \quad (9)$$

In general (*Diff. Calc.*, Arts. 338, 342), the product

$$\frac{dz}{dw} \frac{dy}{dv} \frac{dx}{du}$$

is the Jacobian of the original system of variables,  $x, y, z$ , regarded as functions of the new system,  $u, v, w$ .

Accordingly, the general substitution for  $dx dy dz$  is

$$\left| \begin{array}{ccc} \frac{dx}{du} & \frac{dx}{dv} & \frac{dx}{dw} \\ \frac{dy}{du} & \frac{dy}{dv} & \frac{dy}{dw} \\ \frac{dz}{du} & \frac{dz}{dv} & \frac{dz}{dw} \end{array} \right| du dv dw. \quad (10)$$

**223. Transformation for Implicit Functions.**—If, instead of being given  $x, y, z$  explicitly as functions of  $u, v, w$ ,  
[21 a]

we are given equations of the form

$$F_1(x, y, z, u, v, w) = 0, \quad F_2(x, y, z, u, v, w) = 0, \quad F_3(x, y, z, u, v, w) = 0,$$

we have (*Diff. Calc.*, Art. 341), adopting the usual notation for Jacobians,

$$\frac{d(x, y, z)}{d(u, v, w)} = - \frac{\frac{d(F_1, F_2, F_3)}{d(u, v, w)}}{\frac{d(F_1, F_2, F_3)}{d(x, y, z)}}.$$

And for  $dx dy dz$  we must then substitute

$$\frac{J_1}{J_2} du dv dw, \quad (11)$$

where  $J_1$  is the Jacobian of the given system of equations with respect to the new variables, and  $J_2$  their Jacobian with respect to the original system.

**224. Transformation of Element of a Surface.**— If the equation of a surface be referred to a system of rectangular axes it is easily seen, from Art. 189, that the element of its superficial area, whose projection on the plane of  $xy$  is  $dx dy$ , is equal to

$$dx dy \sqrt{1 + \left(\frac{dz}{dx}\right)^2 + \left(\frac{dz}{dy}\right)^2}.$$

Accordingly the area of a surface may be represented by

$$\iint \sqrt{1 + \left(\frac{dz}{dx}\right)^2 + \left(\frac{dz}{dy}\right)^2} dx dy, \quad (12)$$

taken between proper limits. In this result  $z$  is regarded as a function of  $x$  and  $y$  by means of the equation of the surface.

To transform this expression to new variables  $u, v$ , we, by the preceding Article, substitute

$$\left(\frac{dx}{du} \frac{dy}{dv} - \frac{dy}{du} \frac{dx}{dv}\right) du dv \text{ instead of } dx dy.$$

Also

$$\frac{dz}{du} = \frac{dz}{dx} \frac{dx}{du} + \frac{dz}{dy} \frac{dy}{du},$$

$$\frac{dz}{dv} = \frac{dz}{dx} \frac{dx}{dv} + \frac{dz}{dy} \frac{dy}{dv};$$

therefore

$$\left. \begin{aligned} \frac{dz}{dx} &= \frac{\frac{dz}{dy} \frac{dy}{dv} - \frac{dy}{du} \frac{dz}{dv}}{\frac{dx}{dy} \frac{dy}{dv} - \frac{dy}{du} \frac{dx}{dv}} \\ \frac{dz}{dy} &= \frac{\frac{dz}{dx} \frac{dx}{dv} - \frac{dx}{du} \frac{dz}{dv}}{\frac{dx}{dy} \frac{dy}{dv} - \frac{dy}{du} \frac{dx}{dv}} \end{aligned} \right\}. \quad (13)$$

Substituting in (12), the expression for the superficial area becomes

$$\iint \sqrt{\left( \frac{dx}{du} \frac{dy}{dv} - \frac{dy}{du} \frac{dx}{dv} \right)^2 + \left( \frac{dx}{dv} \frac{dz}{du} - \frac{dz}{dv} \frac{dx}{du} \right)^2 + \left( \frac{dz}{dv} \frac{dy}{du} - \frac{dy}{dv} \frac{dz}{du} \right)^2} du dv.$$

**225. General Transformation for  $n$  Variables.**—The transformation of Art. 223 can be readily generalized. Thus, for the case of  $n$  variables, in the transformation of the multiple integral

$$\iiint \dots V dx_1 dx_2 dx_3 \dots dx_n$$

to a system of new variables,  $y_1, y_2, \dots, y_n$ , we substitute for  $dx_1 dx_2 \dots dx_n$  the Jacobian of the system  $x_1, x_2, \dots, x_n$  regarded as functions of  $y_1, y_2, y_3 \dots y_n$ ; hence

$$dx_1 dx_2 \dots dx_n = \frac{d(x_1, x_2, \dots, x_n)}{d(y_1, y_2, \dots, y_n)} dy_1 dy_2 \dots dy_n. \quad (14)$$

And in the case of implicit functions, we substitute

$$\frac{J_1}{J_2} dy_1 dy_2 \dots dy_n,$$

where  $J_1$  and  $J_2$  are respectively the Jacobians of the system of equations with respect to the new, and to the original system of variables (compare *Diff. Calc.*, Art. 341).

## EXAMPLES.

1. Transform the multiple integral

$$\iiint V dx dy dz dw$$

by the substitution

$$x = r \cos \theta \cos \phi, \quad y = r \cos \theta \sin \phi, \quad z = r \sin \theta \cos \psi, \quad w = r \sin \theta \sin \psi.$$

The transformed expression is

$$\iiint V_1 r^3 \sin \theta \cos \theta dr d\theta d\phi d\psi,$$

where  $V_1$  is the new value of  $V$ .

2. If

$$x_1 = \frac{u_2 u_3}{u_1}, \quad x_2 = \frac{u_3 u_1}{u_2}, \quad x_3 = \frac{u_1 u_2}{u_3},$$

prove that  $\iiint V dx_1 dx_2 dx_3$  transforms into  $4 \iiint V_1 du_1 du_2 du_3$ .

226. We shall next prove that

$$\iiint \left( \frac{du}{dx} + \frac{dv}{dy} + \frac{dw}{dz} \right) dx dy dz = \iint (u \cos \lambda + v \cos \mu + w \cos \nu) dS,$$

where the integrations, respectively, extend over a closed surface  $S$ , and through the volume contained by the surface:  $\lambda, \mu, \nu$  being the direction angles of the outward drawn normal at  $dS$ , and  $u, v, w$  being functions of  $x, y, z$ , which are supposed finite and continuous for all points within  $S$ .

Here, since  $S$  is a closed surface, any intersecting right line meets it in an even number of points; consequently

$$\iiint \frac{du}{dx} dx dy dz = \iint dy dz \Sigma (u_2 - u_1),$$

where  $u_1$  and  $u_2$  represent the values  $u$  for two corresponding points of intersection with  $S$ , made by an indefinitely thin

parallelepiped standing on  $dy dz$ ; and  $\Sigma$  denotes the summation extended to all such points of intersection. Now, as in Art. 192, let  $dS_1, dS_2, dS_3, \dots$ , represent the corresponding elementary portions of the surface; and  $\lambda_1, \lambda_2, \lambda_3, \dots$ , the angles that the *exterior* normals make with the positive direction of the axis of  $x$ ; we shall have

$$dy dz = -\cos \lambda_1 dS_1 = \cos \lambda_2 dS_2 = -\cos \lambda_3 dS_3 = \cos \lambda_4 dS_4 = \dots$$

Accordingly,

$$\iiint \frac{du}{dx} dx dy dz = \iint u \cos \lambda dS, \quad (15)$$

under the same restrictions as to limits as before. Hence it follows immediately that

$$\iiint \left( \frac{du}{dx} + \frac{dv}{dy} + \frac{dw}{dz} \right) dx dy dz = \iint (u \cos \lambda + v \cos \mu + w \cos \nu) dS. \quad (16)$$

This result obviously holds good when the triple integral is extended through any space which is bounded externally by one closed surface and internally by another, provided the double integral is extended over both the bounding surfaces.

Again, if for  $u$  we substitute  $uV$ , for  $v$ ,  $vV$ , and for  $w$ ,  $wV$ , we get immediately

$$\begin{aligned} & \iiint \left( u \frac{dV}{dx} + v \frac{dV}{dy} + w \frac{dV}{dz} \right) dx dy dz \\ &= \iint V (u \cos \lambda + v \cos \mu + w \cos \nu) dS - \iiint V \left( \frac{du}{dx} + \frac{dv}{dy} + \frac{dw}{dz} \right) dx dy dz \end{aligned} \quad (17)$$

under the same restrictions as above.

227. **Green's Theorem.**—We shall now give a brief notice of the very remarkable theorem given first by Green ("Essay on the application of Mathematics to Electricity and Magnetism," Nottingham, 1828, reprinted, 1871), as follows:—

If  $U$  and  $V$  be functions of  $x, y, z$ , the rectangular coordinates of a point; then, provided  $U$  and  $V$  are *finite and con-*

tinuous for all points within a given closed surface  $S$ , we have

$$\left. \begin{aligned} & \iiint \left( \frac{dU}{dx} \frac{dV}{dx} + \frac{dU}{dy} \frac{dV}{dy} + \frac{dU}{dz} \frac{dV}{dz} \right) dx dy dz \\ &= \iint U \frac{dV}{dn} dS - \iiint U \left( \frac{d^2 V}{dx^2} + \frac{d^2 V}{dy^2} + \frac{d^2 V}{dz^2} \right) dx dy dz \\ &= \iint V \frac{dU}{dn} dS - \iiint V \left( \frac{d^2 U}{dx^2} + \frac{d^2 U}{dy^2} + \frac{d^2 U}{dz^2} \right) dx dy dz \end{aligned} \right\},$$

where the triple integrals are extended to all points within the surface  $S$ , and the double integrals to all points on  $S$ ; and  $dn$  is the element of the normal to the surface at  $dS$ , measured *outwards*.

Here, since  $\frac{d}{dx} \left( U \frac{dV}{dx} \right) = \frac{dU}{dx} \frac{dV}{dx} + U \frac{d^2 V}{dx^2}$ ,

we have

$$\begin{aligned} \iiint \frac{d}{dx} \left( U \frac{dV}{dx} \right) dx dy dz &= \iiint \frac{dU}{dx} \frac{dV}{dx} dx dy dz \\ &+ \iiint U \frac{d^2 V}{dx^2} dx dy dz, \end{aligned}$$

the integrals being extended to all points within  $S$ .

Again, by (15), we have

$$\iiint \frac{d}{dx} \left( U \frac{dV}{dx} \right) dx dy dz = \iint U \frac{dV}{dx} \cos \lambda dS,$$

under the same restrictions as to limits as before.

Hence

$$\iiint \frac{dU}{dx} \frac{dV}{dx} dx dy dz = \iint U \frac{dV}{dx} \cos \lambda dS - \iiint U \frac{d^2 V}{dx^2} dx dy dz,$$

along with corresponding equations for  $y$  and  $z$ .

Accordingly,

$$\begin{aligned} & \iiint \left( \frac{dU}{dx} \frac{dV}{dx} + \frac{dU}{dy} \frac{dV}{dy} + \frac{dU}{dz} \frac{dV}{dz} \right) dx dy dz \\ &= \iint U \left( \frac{dV}{dx} \cos \lambda + \frac{dV}{dy} \cos \mu + \frac{dV}{dz} \cos \nu \right) dS \\ & - \iiint U \left( \frac{d^2 V}{dx^2} + \frac{d^2 V}{dy^2} + \frac{d^2 V}{dz^2} \right) dx dy dz. \end{aligned}$$

Again, we obviously have

$$\cos \lambda = \frac{dx}{dn}, \quad \cos \mu = \frac{dy}{dn}, \quad \cos \nu = \frac{dz}{dn};$$

$$\text{therefore } \frac{dV}{dx} \cos \lambda + \frac{dV}{dy} \cos \mu + \frac{dV}{dz} \cos \nu = \frac{dV}{dn}.$$

Hence

$$\left. \begin{aligned} & \iiint \left( \frac{dU}{dx} \frac{dV}{dx} + \frac{dU}{dy} \frac{dV}{dy} + \frac{dU}{dz} \frac{dV}{dz} \right) dx dy dz \\ &= \iint U \frac{dV}{dn} dS - \iiint U \left( \frac{d^2 V}{dx^2} + \frac{d^2 V}{dy^2} + \frac{d^2 V}{dz^2} \right) dx dy dz \\ &= \iint V \frac{dU}{dn} dS - \iiint V \left( \frac{d^2 U}{dx^2} + \frac{d^2 U}{dy^2} + \frac{d^2 U}{dz^2} \right) dx dy dz \end{aligned} \right\}. \quad (18)$$

The latter expression is obtained by the interchange of  $U$  and  $V$  in the preceding.

If  $U = V$ , we get

$$\begin{aligned} & \iiint \left\{ \left( \frac{dV}{dx} \right)^2 + \left( \frac{dV}{dy} \right)^2 + \left( \frac{dV}{dz} \right)^2 \right\} dx dy dz \\ &= \iint V \frac{dV}{dn} dS - \iiint V \left( \frac{d^2 V}{dx^2} + \frac{d^2 V}{dy^2} + \frac{d^2 V}{dz^2} \right) dx dy dz. \quad (19) \end{aligned}$$

If, as in *Diff. Calc.*, Art. 332, we denote

$$\frac{d^2 V}{dx^2} + \frac{d^2 V}{dy^2} + \frac{d^2 V}{dz^2} \text{ by } \nabla^2 V,$$

then equation (18) may be written in the following abridged form :—

$$\iint \left( U \frac{dV}{dn} - V \frac{dU}{dn} \right) dS = \iiint (U \nabla^2 V - V \nabla^2 U) dx dy dz. \quad (20)$$

228. **Case where  $U$  becomes Infinite.**—We shall now determine the modification to be made when one of the functions,  $U$  for example, becomes infinite within  $S$ . Suppose this to take place at one point  $P$  only: moreover, infinitely near this point let  $U$  be sensibly equal to  $\frac{1}{r}$  where  $r$  is the distance from  $P$ . If we suppose an indefinitely small sphere, of radius  $a$ , described with its centre at  $P$ , it is clear that (18) is applicable to all points exterior to the sphere; also, as

$$\left( \frac{d^2}{dx^2} + \frac{d^2}{dy^2} + \frac{d^2}{dz^2} \right) \frac{1}{r} = 0,$$

it is evident that the triple integrals may be supposed to extend through the entire enclosed space, since the part arising from points within the sphere is a small quantity of the same order as  $a^2$ . Moreover, the part of  $\iint U \frac{dV}{dn} dS$ , due to the surface of the sphere, is indefinitely small of the order of the radius  $a$ . It only remains to consider the part of  $\iint V \frac{dU}{dn} dS$  due to the spherical surface. Here, as  $V$  is supposed to vary continuously, we may take for its value that ( $V'$ ) at the point  $P$ : also

$$\frac{dU}{dn} = \frac{dU}{dr} = \frac{d\left(\frac{1}{r}\right)}{dr} = -\frac{1}{r^2} = -\frac{1}{a^2};$$

consequently the value of  $\iint V \frac{dU}{dn} dS$ , over the sphere, is  $-4\pi V'$ .

Thus (20) becomes in this case

$$\begin{aligned} & \iint U \frac{dV}{dn} dS - \iiint U \left( \frac{d^2 V}{dx^2} + \frac{d^2 V}{dy^2} + \frac{d^2 V}{dz^2} \right) dx dy dz \\ &= \iint V \frac{dU}{dn} dS - \iiint V \left( \frac{d^2 U}{dx^2} + \frac{d^2 U}{dy^2} + \frac{d^2 U}{dz^2} \right) dx dy dz + 4\pi V', \end{aligned} \quad (21)$$

where, as before, the integrals extend through the whole volume and over the whole exterior surface.

The same method will evidently apply however great may be the number of points, such as  $P$ , at which either  $U$  or  $V$  becomes infinite.

**229. Integration through External Space.**—Let us next suppose a surface  $S_2$  drawn inclosing another surface  $S_1$ , and let Green's theorem be applied to the space between these surfaces, we get

$$\begin{aligned} & \iint \left( \frac{dU}{dx} \frac{dV}{dx} + \frac{dU}{dy} \frac{dV}{dy} + \frac{dU}{dz} \frac{dV}{dz} \right) dx dy dz \\ &= \iint U \frac{dV}{dn} dS_2 - \iint U \frac{dV}{dn} dS_1 - \iiint U \nabla^2 V dx dy dz. \end{aligned}$$

Let us now suppose  $S_2$  to be a sphere of indefinitely great radius; then, provided the double integral

$$\iint U \frac{dV}{dn} dS_2$$

become evanescent, Green's equation can be applied to integration through the infinite space outside  $S_1$ , as well as through the finite space within it.

Moreover, since in this case

$$\iint U \frac{dV}{dn} dS_2 = \iint U \frac{dV}{dn} r^2 \sin \theta d\theta d\phi,$$

we see that the double integral vanishes whenever  $r^2 U \frac{dV}{dn}$  becomes evanescent when  $r$  is indefinitely increased; *i.e.* when-

ever  $UV$  is of lower degree than  $-1$  in the coordinates; a property which holds good in all physical applications of Green's theorem.

**230. Application to Spherical Harmonics.**—We shall conclude by establishing a few fundamental properties of spherical harmonic functions.

In Green's theorem let  $U = V_l$ ,  $V = V_m$ , where  $V_l$  is a solid harmonic (*Diff. Calc.*, Art. 333) of the degree  $l$ , and  $V_m$  another of the degree  $m$ . Now suppose a sphere of radius  $a$ , taken as the bounding surface  $S$ , then equation (21) becomes

$$\iint V_l \frac{dV_m}{dn} dS = \iint V_m \frac{dV_l}{dn} dS. \quad (22)$$

Next, let  $V_l = r^l Y_l$ ,  $V_m = r^m Y_m$ , so that  $Y_l$  and  $Y_m$  are surface harmonics (*Diff. Calc.* Art. 334); then

$$\frac{dV_l}{dn} = \frac{dV_l}{dr} = lr^{l-1} Y_l, \text{ and } \frac{dV_m}{dn} = mr^{m-1} Y_m.$$

Hence, since  $r = a$  over the surface  $S$ , equation (22) becomes

$$ma^{l+m-1} \iint Y_l Y_m dS = la^{l+m-1} \iint Y_m Y_l dS,$$

or  $(l - m) \iint Y_l Y_m dS = 0.$

Accordingly, so long as  $l$  and  $m$  are unequal, we have

$$\iint Y_l Y_m dS = 0, \quad (23)$$

where the integration is extended to all points on the surface of the sphere.

This may be written

$$\int_0^{2\pi} \int_{-1}^{+1} Y_l Y_m d\mu d\phi = 0, \quad (24)$$

adopting the usual notation (*Diff. Calc.*, Art. 336).

If we substitute  $P_l$  and  $P_m$  for  $Y_l$  and  $Y_m$ , we get, so long as  $l$  and  $m$  are unequal,

$$\int_0^{2\pi} \int_{-1}^{+1} P_l P_m d\mu d\phi = 0,$$

or  $\int_{-1}^{+1} P_l P_m d\mu = 0, \quad (25)$

since  $P_l$  and  $P_m$  are functions of  $\mu$  only.

Again, we have

$$\int_0^{2\pi} \int_{-1}^{+1} Y_l L_m d\mu d\phi = 0, \quad (26)$$

where  $L_m$  is Laplace's coefficient of the  $m^{\text{th}}$  order (*Diff. Calc.*, Art. 337).

231. We can now find the value of

$$\int_0^{2\pi} \int_{-1}^{+1} Y_m L_m d\mu d\phi.$$

For, let  $P$  be the point  $x, y, z$ , and  $P'$  the point  $x', y', z'$ , then, since  $\frac{1}{PP'}$  satisfies the equation  $\nabla^2 \left( \frac{1}{PP'} \right) = 0$ , we have from (21), assuming  $S$  to be a sphere of radius  $r$ ,

$$\iint \left\{ \frac{1}{PP'} \frac{d}{dr} V_m - V_m \frac{d}{dr} \left( \frac{1}{PP'} \right) \right\} dS = 4\pi V'_m, \quad (27)$$

in which we suppose  $P'$  situated inside the sphere  $S$ .

Again (*Diff. Calc.*, Art. 337),

$$\frac{1}{PP'} = \frac{1}{r} + \sum_{n=1}^{n=\infty} \frac{L_n r'^n}{r^{n+1}}; \quad (28)$$

hence  $\frac{d}{dr} \left( \frac{1}{PP'} \right) = -\frac{1}{r^2} - \sum_{n=1}^{n=\infty} \frac{(n+1) L_n r'^n}{r^{n+2}};$

also, since  $V_m = r^m Y_m$ , we have

$$\frac{dV_m}{dr} = mr^{m-1} Y_m.$$

Substituting in (27), and observing from (26) that

$$\iint Y_m L_n d\mu d\phi = 0$$

except when  $n = m$ , we get

$$(2m + 1) \iint L_m Y_m \frac{r'^m}{r^2} dS = 4\pi r'^m Y'_m,$$

or 
$$\int_0^{2\pi} \int_{-1}^{+1} L_m Y_m d\mu d\phi = \frac{4\pi}{2m + 1} Y'_m, \quad (29)$$

where  $Y'_m$  is the value that  $Y_m$  assumes at the point  $P'$ , *i.e.* when  $\mu = \mu'$ ,  $\phi = \phi'$ .

232. Next, let  $T_m^{(s)} = (\mu^2 - 1)^{\frac{s}{2}} \left( \frac{d}{d\mu} \right)^s P_m, \quad (30)$

in accordance with the usual notation; then (*Diff. Calc.*, Art. 336) the general value of the spherical harmonic  $Y_m$  may be written

$$Y_m = A_0 P_m + \Sigma (A_s \cos s\phi + B_s \sin s\phi) T_m^{(s)}. \quad (31)$$

If now we substitute  $P_m$  for  $Y_m$  in (29), it becomes

$$\int_0^{2\pi} \int_{-1}^{+1} L_m P_m d\mu d\phi = \frac{4\pi}{2m + 1} P'_m. \quad (32)$$

Again, if we substitute  $\cos s\phi T_m^{(s)}$  for  $Y_m$ , we get from (29),

$$\int_0^{2\pi} \int_{-1}^{+1} \cos s\phi L_m T_m^{(s)} d\mu d\phi = \frac{4\pi}{2m + 1} \cos s\phi' T'_m, \quad (33)$$

where  $T'_m$  denotes the value of  $T_m^{(s)}$  when we substitute  $\mu'$  instead of  $\mu$ .

Also, since  $L_m$  is a spherical harmonic, we may write

$$L_m = a_0 P_m + \Sigma (a_s \cos s\phi + b_s \sin s\phi) T_m^{(s)}, \quad (34)$$

in which the coefficients  $a_0, \dots, a_s, b_s, \dots$  are for the present undetermined.

If this value of  $L_m$  be substituted in (32), we readily get

$$a_0 \int_0^{2\pi} \int_{-1}^{+1} (P_m)^2 d\mu d\phi = \frac{4\pi}{2m+1} P'_m,$$

since all the other definite integrals vanish identically.

Hence, since  $a_0 = P'_m$  (*Diff. Calc.*, p. 428),

$$\int_{-1}^{+1} (P_m)^2 d\mu = \frac{2}{2m+1}. \quad (35)$$

Consequently, as  $P_m = \frac{1}{2^m m!} \left( \frac{d}{d\mu} \right)^m (\mu^2 - 1)^m$ ,

$$\text{we have } \int_{-1}^{+1} \left\{ \left( \frac{d}{d\mu} \right)^m (\mu^2 - 1)^m \right\}^2 d\mu = \frac{2^{2m+1} (m!)^2}{2m+1}. \quad (36)$$

Again, if we substitute for  $L_m$  in (33), we get in like manner

$$a_s \int_0^{2\pi} \int_{-1}^{+1} (\cos s\phi T_m^{(s)})^2 d\mu d\phi = \frac{4\pi}{2m+1} \cos s\phi' T'_m.$$

Hence

$$a_s \int_{-1}^{+1} (T_m^{(s)})^2 d\mu = \frac{4}{2m+1} \cos s\phi' T'_m. \quad (37)$$

233. In order to determine

$$\int_{-1}^{+1} (T_m^{(s)})^2 d\mu,$$

and consequently  $a_s$ , we shall commence by proving the following theorem in the *Differential Calculus*, viz.,

$$\begin{aligned} & (x-a)^n (x-b)^n D^{m+n} \{(x-a)^m (x-b)^m\} \\ &= \frac{m+n}{m-n} D^{m-n} \{(x-a)^m (x-b)^m\}, \end{aligned} \quad (38)$$

in which  $m$  and  $n$  are integers, and  $m > n$ ; also  $D$  represents  $\frac{d}{dx}$ .

Here, by Leibnitz' Theorem (*Diff. Calc.*, Art. 48), the general term in the development of

$$D^{m+n} \{(x-a)^m (x-b)^n\}$$

is of the form

$$\frac{(m+n)(m+n-1)\dots(m+n-r+1)}{r} D^{m+n-r} (x-a)^m \cdot D^r (x-b)^n.$$

Moreover, as this is evanescent so long as  $r$  is less than  $n$ , we can assume  $r = n + p$ , and the preceding may be written

$$\frac{\lfloor m+n \rfloor}{\lfloor n+p \lfloor m-p \rfloor} D^{m-p} (x-a)^m \cdot D^{n+p} (x-b)^n,$$

$$\text{or, } \frac{\lfloor m+n \rfloor}{\lfloor n+p \lfloor m-p \rfloor} \cdot \frac{\lfloor m \rfloor}{\lfloor p \rfloor} \cdot \frac{\lfloor m \rfloor}{\lfloor m-n-p \rfloor} (x-a)^p (x-b)^{m-n-p}.$$

Accordingly, the expression

$$(x-a)^n (x-b)^n D^{m+n} \{(x-a)^m (x-b)^n\} \\ = \sum_{p=0}^{p=m-n} \frac{\lfloor m+n \rfloor}{\lfloor n+p \lfloor m-p \rfloor} \frac{\lfloor m \rfloor}{\lfloor p \rfloor} \frac{\lfloor m \rfloor}{\lfloor m-n-p \rfloor} (x-a)^{n+p} (x-b)^{m-p}. \quad (39)$$

Again, the general term in

$$D^{m-n} \{(x-a)^m (x-b)^n\}$$

may be written

$$\frac{\lfloor m-n \rfloor}{\lfloor p \lfloor m-n-p \rfloor} \cdot D^{m-n-p} (x-a)^m \cdot D^p (x-b)^n \\ = \frac{\lfloor m-n \rfloor}{\lfloor p \lfloor m-n-p \rfloor} \frac{\lfloor m \rfloor}{\lfloor n+p \rfloor} \frac{\lfloor m \rfloor}{\lfloor m-p \rfloor} (x-a)^{n+p} (x-b)^{m-p}.$$

Comparing this with (39), the theorem in (37) follows immediately.

Again, if we substitute  $\mu$  for  $x$ ,  $s$  for  $n$ , and make  $b = 1$ ,  $a = -1$ , this result can be written in Rodrigues' form, viz.,

$$(\mu^2 - 1)^s D^{m+s} (\mu^2 - 1)^m = \frac{\underline{m+s}}{\underline{m-s}} D^{m-s} (\mu^2 - 1)^m. \quad (40)$$

Hence, since

$$T_m^{(s)} = \frac{(\mu^2 - 1)^{\frac{s}{2}} D^{m+s} (\mu^2 - 1)^m}{2^m \underline{m}},$$

we get

$$T_m^{(s)} = \frac{\underline{m+s}}{\underline{m-s}} \frac{(\mu^2 - 1)^{-\frac{s}{2}} D^{m-s} (\mu^2 - 1)^m}{2^m \underline{m}}.$$

Consequently, multiplying the two expressions,

$$(T_m^{(s)})^2 = \frac{\underline{m+s}}{\underline{m-s}} \frac{1}{(2^m \underline{m})^2} D^{m+s} (\mu^2 - 1)^m D^{m-s} (\mu^2 - 1)^m.$$

Therefore,

$$\int_{-1}^{+1} (T_m^{(s)})^2 d\mu = \frac{\underline{m+s}}{\underline{m-s}} \frac{1}{(2^m \underline{m})^2} \int_{-1}^{+1} D^{m+s} (\mu^2 - 1)^m D^{m-s} (\mu^2 - 1)^m d\mu.$$

Again, integrating by parts, and observing that the term outside the sign of integration vanishes for either limit, we get

$$\begin{aligned} & \int_{-1}^{+1} D^{m+s} (\mu^2 - 1)^m D^{m-s} (\mu^2 - 1)^m d\mu \\ &= - \int_{-1}^{+1} D^{m+s-1} (\mu^2 - 1)^m D^{m-s+1} (\mu^2 - 1)^m d\mu; \end{aligned}$$

hence, by successive integration by parts, we get finally

$$\begin{aligned} & \int_{-1}^{+1} D^{m+s} (\mu^2 - 1)^m D^{m-s} (\mu^2 - 1)^m d\mu \\ &= (-1)^s \int_{-1}^{+1} \{D^m (\mu^2 - 1)^m\}^2 d\mu. \end{aligned}$$

Consequently

$$\begin{aligned} \int_{-1}^1 (T_m^{(s)})^2 d\mu &= (-1)^s \underbrace{\frac{m+s}{m-s}}_{\frac{m+s}{m-s}} \int_{-1}^1 \left( \frac{D^m (\mu^2 - 1)^m}{2^m \sqrt{m}} \right)^2 d\mu \\ &= (-1)^s \underbrace{\frac{m+s}{m-s}}_{\frac{m+s}{m-s}} \int_{-1}^1 (P_m)^2 d\mu = (-1)^s \underbrace{\frac{m+s}{m-s}}_{\frac{m+s}{m-s}} \frac{1}{2m+1}. \end{aligned} \quad (41)$$

Hence, from (36),

$$a_s = (-1)^s \frac{2 \underbrace{\frac{m-s}{m+s}}_{\frac{m-s}{m+s}} \cos s\phi' T_m^{(s)}}{m+s}; \quad (42)$$

and the complete expression for  $L_m$  can be immediately written down. (Compare *Diff. Calc.*, p. 428.)

**234. Expansion of a Function in Spherical Harmonics.**—We next proceed to prove that any function  $f(\mu, \phi)$ , which is finite and continuous, can be expanded in a series of spherical harmonics, *i. e.* that

$$f(\mu, \phi) = Y_0 + Y_1 + Y_2 + \dots + Y_n + \text{&c.} \quad (43)$$

For if we assume this result, multiply both sides of the equation by  $L_n$ , and integrate, we get, from (26),

$$\begin{aligned} \int_0^{2\pi} \int_{-1}^{+1} f(\mu, \phi) L_n d\mu d\phi &= \int_0^{2\pi} \int_{-1}^{+1} Y_n L_n d\mu d\phi \\ &= \frac{4\pi}{2n+1} Y'_n, \text{ from (27),} \end{aligned}$$

Again, writing  $\mu', \phi'$  for  $\mu, \phi$  in (43), we have

$$f(\mu', \phi') = Y'_0 + Y'_1 + Y'_2 + \dots + Y'_n + \text{&c.}$$

$$= \frac{1}{4\pi} \sum_{n=1}^{n=\infty} (2n+1) \int_0^{2\pi} \int_{-1}^{+1} f(\mu, \phi) L_n d\mu d\phi. \quad (44)$$

We shall verify this result by proving that  $f(\mu', \phi')$  is the limit of the expression at the right hand side of (44) when  $n$  is increased indefinitely.

For, suppose  $h = \frac{r'}{r}$ ; then since, by hypothesis,  $r'$  is less than  $r$ , equation (28) may be written

$$\frac{1}{(1 - 2h\lambda + h^2)^{\frac{1}{2}}} = L_0 + hL_1 + h^2L_2 + \dots + h^nL_n + \dots, \quad (45)$$

where

$$\lambda = \cos PCP' = \mu\mu' + \sqrt{1 - \mu^2} \sqrt{1 - \mu'^2} \cos(\phi - \phi').$$

If we differentiate (45) with respect to  $h$ , and multiply by  $2h$ , we get

$$\frac{2h(\lambda - h)}{(1 - 2h\lambda + h^2)^{\frac{3}{2}}} = 2hL_1 + 4h^2L_2 + \dots + 2nh^nL_n + \dots$$

Adding to (45), we have

$$\frac{1 - h^2}{(1 - 2h\lambda + h^2)^{\frac{3}{2}}} = L_0 + 3hL_1 + 5h^2L_2 + \dots + (2n + 1)h^nL_n + \dots \quad (46)$$

Hence

$$\sum_{n=1}^{n=\infty} (2n + 1)h^n \iint f(\mu, \phi) L_n dS = \iint \frac{(1 - h^2)f(\mu, \phi) dS}{(1 - 2h\lambda + h^2)^{\frac{3}{2}}}, \quad (47)$$

where the integrals are supposed to be extended over the surface of a unit sphere, of which  $dS$  is an element.

Hence we infer that

$$\sum_{n=1}^{n=\infty} (2n + 1) \iint f(\mu, \phi) L_n d\mu d\phi$$

is the limiting value of

$$\iint \frac{(1 - h^2)f(\mu, \phi) dS}{(1 - 2h\lambda + h^2)^{\frac{3}{2}}} \text{ when } h = 1.$$

Again, when  $1 - h$  is indefinitely small, the coefficient of  
[22 a]

every element in the latter integral is indefinitely small except those for which  $(1 - 2h\lambda + h^2)^{\frac{1}{2}}$ , or  $PP'$ , is indefinitely small, *i.e.* for which the point  $P$  is taken indefinitely near to the point  $A$  on the sphere. Consequently the integral has ultimately the same value as if it were only taken over a very small portion of the surface around the point  $A$ ; but throughout this portion we may assume  $f(\mu, \phi) = f(\mu', \phi')$ , namely, its value at the point  $A$ . Hence the limiting value of

$$\iint \frac{(1 - h^2) f(\mu, \phi) dS}{(1 - 2h\lambda + h^2)^{\frac{3}{2}}} = f(\mu', \phi') \iint \frac{(1 - h^2) dS}{(1 - 2h\lambda + h^2)^{\frac{3}{2}}} \text{ when } h = 1.$$

Again, since  $\lambda = \cos ACP$ , we may write  $d\lambda d\phi_1$  for  $dS$ , where  $\phi_1$  is the angle the plane  $ACP$  makes with a fixed plane drawn through  $CA$ , and we have

$$\begin{aligned} \iint \frac{dS}{(1 - 2h\lambda + h^2)^{\frac{3}{2}}} &= \int_0^{2\pi} \int_{-1}^{+1} \frac{d\lambda d\phi_1}{(1 - 2h\lambda + h^2)^{\frac{3}{2}}} \\ &= 2\pi \int_{-1}^{+1} \frac{d\lambda}{(1 - 2h\lambda + h^2)^{\frac{3}{2}}} = \frac{4\pi}{1 - h^2}. \end{aligned}$$

Accordingly, for all values of  $h$ ,

$$\iint \frac{(1 - h^2) dS}{(1 - 2h\lambda + h^2)^{\frac{3}{2}}} = 4\pi,$$

when taken over the surface of a unit sphere; and we conclude that

$$\frac{1}{4\pi} \sum_{n=1}^{n=\infty} (2n+1) \int_0^{2\pi} \int_{-1}^{+1} f(\mu, \phi) L_n d\mu d\phi = f(\mu', \phi'), \quad (48)$$

thus verifying equation (44).

This is the well-known general formula of Laplace; from which we infer that every finite continuous function of  $\mu$  and  $\phi$

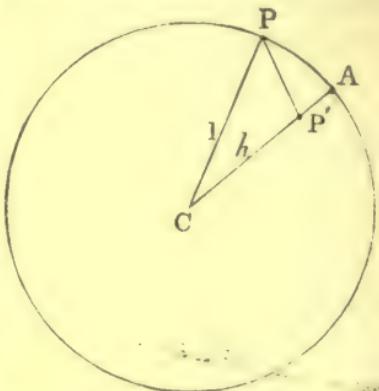


Fig. 53.

can be expressed in a series of Spherical Harmonics. There is no difficulty in showing that the series is unique: *i. e.* that a given function can only be expanded in one way in a series of Spherical Harmonics.

235. It may be observed that the determination of the value in spherical harmonics of a given function of  $\theta$  and  $\phi$  is usually best obtained by means of the corresponding solid harmonic functions. We shall illustrate this by an example.

To transform  $u = \cos \theta \sin^2 \theta \sin^2 \phi \cos \phi$ .

Here  $r^4 u = xyz^2$ ; and we readily see that we may suppose

$$u = Y_2 + Y_4. \quad (49)$$

This gives  $xyz^2 = r^2 V_2 + V_4$ , (50)

where  $V_2$  and  $V_4$  are solid harmonics.

Operating with  $\nabla^2$  on both sides, we get

$$2xy = \nabla^2(r^2 V_2) = 2.7 V_2;$$

hence  $V_2 = \frac{1}{7}xy$ , and therefore  $Y_2 = \frac{1}{7}\mu\sqrt{1-\mu^2} \cos \phi$ . Also from (50),

$$V_4 = xy \left( z^2 - \frac{r^2}{7} \right),$$

$$\therefore Y_4 = \mu\sqrt{1-\mu^2} \cos \phi \left\{ (1-\mu^2) \sin^2 \phi - \frac{1}{7} \right\}.$$

$$\text{Again, since } \cos \phi \sin^2 \phi = \frac{\cos \phi - \cos 3\phi}{4},$$

we readily get

$$Y_4 = \frac{\mu\sqrt{1-\mu^2}}{4} \left( \frac{3}{7} - \mu^2 \right) \cos \phi - \frac{\mu(1-\mu^2)^{\frac{3}{2}}}{4} \cos 3\phi.$$

$$\begin{aligned} \text{Hence } \cos \theta \sin^2 \theta \sin^2 \phi \cos \phi &= \frac{\mu\sqrt{1-\mu^2}}{7} \cos \phi \\ &+ \frac{\mu\sqrt{1-\mu^2}}{4} \left( \frac{3}{7} - \mu^2 \right) \cos \phi - \frac{\mu(1-\mu^2)^{\frac{3}{2}}}{4} \cos 3\phi. \end{aligned}$$

It is readily seen that a function cannot be exhibited in a finite series of spherical harmonics unless the corresponding expression in  $x$ ,  $y$ ,  $z$  is rational, or becomes rational when multiplied by  $r$ .

## EXAMPLES.

1. If

$$U = a \cos u + b \sin u \cos v + c \sin u \sin v,$$

prove that  $\int_0^{2\pi} \int_0^{2\pi} f(U) \sin u \, du \, dv = 2\pi \int_{-1}^{+1} f(Aw) \, dw,$

where

$$A = \sqrt{a^2 + b^2 + c^2}.$$

Let  $x = \cos u, \quad y = \sin u \cos v, \quad z = \sin u \sin v;$

then  $(x, y, z)$  are the coordinates of a point on a sphere of unit radius, with centre at the origin.

Also let  $a = Aw, \quad b = Aw, \quad c = Aw$ ; then  $a, b, c$  is also a point on the same sphere, and

$$a \cos u + b \sin u \cos v + c \sin u \sin v = A \cos \theta,$$

where  $\theta$  is the arc joining the point  $a, b, c$  to  $x, y, z$ . Again, the element of the surface of the sphere at the latter point may be represented by  $\sin u \, du \, dv$ , or by  $\sin \theta \, d\theta \, d\phi$ , indifferently. Consequently,

$$f(a \cos u + b \sin u \cos v + c \sin u \sin v) \sin u \, du \, dv = f(A \cos \theta) \sin \theta \, d\theta \, d\phi.$$

Integrating each of these over the entire surface, we get

$$\int_0^{\pi} \int_0^{2\pi} f(U) \sin u \, du \, dv = \int_0^{2\pi} \int_0^{\pi} f(A \cos \theta) \sin \theta \, d\theta \, d\phi = 2\pi \int_0^{\pi} f(A \cos \theta) \sin \theta \, d\theta.$$

2. Hence deduce the following :

$$\int_0^{\pi} \int_0^{2\pi} f(U) \sin u \cos u \, du \, dv = \frac{2\pi a}{A} \int_{-1}^{+1} f(Aw) \, dw,$$

$$\int_0^{\pi} \int_0^{2\pi} f(U) \sin^2 u \cos v \, du \, dv = \frac{2\pi c}{A} \int_{-1}^{+1} f(Aw) \, dw.$$

These are deduced from (1) by differentiation under the sign of integration.

3. Show that the integral

$$U = \iint f(x+y) x^{l-1} y^{m-1} \, dx \, dy,$$

supposed extended to all positive values subject to the condition  $x+y < k$ , can be reduced to a single definite integral, by the substitution

$$x = uv, \quad y = u(1-v).$$

Hence  $x+y=u$ , and  $dx \, dy$  becomes  $uv \, du \, dv$ ; also the limits for  $u$  are 0 and  $k$ , and those for  $v$  are 0 and 1; hence

$$U = \int_0^k \int_0^1 f(u) u^{l+m-1} v^{l-1} (1-v)^{m-1} \, du \, dv$$

$$= \frac{\Gamma(l) \Gamma(m)}{\Gamma(l+m)} \int_0^k f(u) u^{l+m-1} \, du. \quad (\text{Compare Art. 221}).$$

4. Show that the foregoing process can be extended to the integral

$$U = \iiint f(x + y + z) x^{l-1} y^{m-1} z^{n-1} dx dy dz,$$

when the variables are always positive and subject to the condition

$$x + y + z < a.$$

Substitute for  $x$  and  $y$  as in last; then, regarding  $z$  as constant, the limits for  $v$  are 0 and 1, and those for  $u$  are 0 and  $a - z$ ; hence

$$\begin{aligned} U &= \frac{\Gamma(l) \Gamma(m)}{\Gamma(l+m)} \int_0^a \int_0^{a-z} f(u+z) u^{l+m-1} z^{n-1} du dz \\ &= \frac{\Gamma(l) \Gamma(m) \Gamma(n)}{\Gamma(l+m+n)} \int_0^a f(u) u^{l+m+n-1} du. \end{aligned}$$

This process is readily extended to any number of variables.

5. Find the value of the definite integral

$$\int_0^1 \frac{v^{l-1} (1-v)^{m-1} dv}{\{b(1-v) + av\}^{l+m}}.$$

By Art. 120 we have

$$\int_0^\infty \int_0^\infty x^{l-1} y^{m-1} e^{-ax} by dx dy = \frac{\Gamma(l) \Gamma(m)}{a^l b^m}.$$

Transform by the substitution  $x = uv$ ,  $y = u(1-v)$ ; then, since the limits for  $v$  are 0 and 1, and those for  $u$  are 0 and  $\infty$ , we get

$$\begin{aligned} \frac{\Gamma(l) \Gamma(m)}{a^l b^m} &= \int_0^1 \int_0^\infty u^{l+m-1} (1-v)^{m-1} v^{l-1} e^{\{b(1-v) + av\}u} dv du \\ &= \Gamma(l+m) \int_0^1 \frac{v^{l-1} (1-v)^{m-1} dv}{\{b(1-v) + av\}^{l+m}}; \end{aligned}$$

therefore  $\int_0^\infty \frac{v^{l-1} (1-v)^{m-1} dv}{\{bv(1-v) + av\}^{l+m}} = \frac{\Gamma(l) \Gamma(m)}{\Gamma(l+m) a^l b^m}.$

6. Prove that

$$\int_{-\infty}^\infty \int_{-\infty}^\infty F(ax + by, a'x + b'y) dx dy = \frac{1}{k} \int_{-\infty}^\infty \int_{-\infty}^\infty F(x, y) dx dy,$$

where

$$k = \begin{vmatrix} a & b \\ a' & b' \end{vmatrix}.$$

7. Prove that

$$\int_0^{\frac{\pi}{2}} \int_0^{\frac{\pi}{2}} \frac{(m^2 \cos^2 \theta + n^2 \cos^2 \phi) d\theta d\phi}{\sqrt{(1 - m^2 \sin^2 \theta)(1 - n^2 \sin^2 \phi)}} = \frac{\pi}{2},$$

when

$$m^2 + n^2 = 1.$$

This is an immediate consequence of (9), Art. 222.

8. Show that Legendre's Theorem connecting complete elliptic integrals with complementary moduli follows immediately from the preceding example.

Let  $F(m) = \int_0^{\frac{\pi}{2}} \frac{d\theta}{\sqrt{1 - m^2 \sin^2 \theta}}, \quad E(m) = \int_0^{\frac{\pi}{2}} \sqrt{1 - m^2 \sin^2 \theta} d\theta,$

then the equation in Ex. 7 is immediately transformed into

$$F(m) E(n) + E(m) F(n) - F(n) F(m) = \frac{\pi}{2}.$$

9. Prove that the area of a surface in polar coordinates is represented by

$$\iint \sqrt{\sin^2 \theta \left( r^2 + \frac{dr^2}{d\theta^2} \right) + \frac{dr^2}{d\phi^2}} r d\theta d\phi,$$

taken between suitable limits.

10. Find the value of

$$\int_0^{2\pi} L_n d\phi. \quad \text{Ans. } 2\pi P_n P'_n.$$

11. Adopting the notation of Art. 232, prove the relation

$$D \{ u^{s+1} D^s P_m D^{s+1} P_m \} = (T_m^{(s+1)})^2 + (m-s)(m+s+1) (T_m^{(s)})^2,$$

where  $u = \mu^2 - 1$ .

Here  $D(u^{s+1} D^s P_m D^{s+1} P_m) = u^{s+1} (D^{s+1} P_m)^2 + u^s D^s P_m (u D^{s+2} P_m + 2\mu(s+1) D^{s+1} P_m).$

Also, Art. 335, *Diff. Calc.*, since  $P_m$  satisfies the equation

$$D(u D P_m) = m(m+1) P_m,$$

we have  $D^{s+1}(u D P_m) = m(m+1) D^s P_m;$

hence  $u D^{s+2} P_m + 2\mu(s+1) D^{s+1} P_m = (m-s)(m+s+1) D^s P_m.$

The result in question follows immediately.

12. Hence determine the value of the definite integral

$$\int_{-1}^{+1} (T_m(s))^2 d\mu.$$

Multiplying the result in Ex. 11 by  $d\mu$ , and integrating between the limits  $+1$  and  $-1$ , we get

$$\int_{-1}^{+1} (T_m(s+1))^2 d\mu = - (m+s+1)(m-s) \int_{-1}^{+1} (T_m(s))^2 d\mu.$$

Hence, substituting  $s = 1$  for  $s$ ,

$$\begin{aligned} \int_{-1}^{+1} (T_m(s))^2 d\mu &= - (m+s)(m+1-s) \int_{-1}^{+1} (T_m(s-1))^2 d\mu \\ &= (m+s)(m+s-1)(m+1-s)(m-s) \int_{-1}^{+1} (T_m(s-2))^2 d\mu \\ &= \&c. \end{aligned}$$

But when  $s = 0$ ,  $T_m(s)$  becomes  $P_m$ ; hence, by equation (35), Art. 232,

$$\int_{-1}^{+1} (T_m(s))^2 d\mu = (-1)^s \frac{1}{2m+1} \left[ \frac{m+s}{m-s} \right].$$

Compare Art. 233

13. Express  $\cos^2 \theta \sin^2 \theta \sin \phi \cos \phi$  in Surface Harmonics.

Proceeding as in Art. 235, we easily get

$$\begin{aligned} \cos^2 \theta \sin^2 \theta \sin \phi \cos \phi &= \frac{1}{4} (1 - \mu^2) \sin 2\phi \\ &\quad + \frac{1}{2} (1 - \mu^2) (\mu^2 - \frac{1}{2}) \sin 2\phi. \end{aligned}$$

## CHAPTER XII.

## ON MEAN VALUE AND PROBABILITY.

236. A very remarkable application of the Integral Calculus is that to the solution of questions on Mean or Average Values and Probability. In this Chapter we will consider a few of the less difficult questions on these subjects, which will serve to give at least some idea of the methods employed. We will suppose the student to be already acquainted with the general fundamental principles of the theory of Probability.

*Mean Values.*

237. By the *Mean Value* of  $n$  quantities is meant their arithmetical mean, i.e. the  $n^{\text{th}}$  part of their sum.

To estimate the mean value of a continuously varying magnitude, we take a series of  $n$  of its values, at very close intervals,  $n$  being a large number, and find the mean of these values. The larger  $n$  is taken, and consequently the smaller the intervals, the nearer is this to the required mean value.

This mean value, however, depends on the law according to which we suppose the  $n$  *representative* values to be selected, and will be different for different suppositions. Thus, for instance, if a body fall from rest till it attains the velocity  $v$ , and it be asked—What is its mean velocity during the fall? If we take the mean of the velocities at successive equal infinitesimal intervals of *time*, the answer will be  $\frac{1}{2}v$ ; but if we consider the velocities at equal intervals of *space*, it will be  $\frac{2}{3}v$ . The former is the most natural supposition in this case, because it is the answer to the question—What is the velocity with which the body would move, uniformly, over the same space in the same time?—a question which implies the former supposition. We might frame a similar question, of a less simple kind, to which the second value above would be the answer.

Again, if we wish to determine the mean value of the ordinate of a semicircle, we might take the mean of a series of ordinates equidistant from each other; or through equidistant points of the circumference; or such that the areas between each pair shall be equal: in each case the mean value will be different.

Thus we see that the Mean Value of any continuously varying magnitude is not a definite term, as might be supposed at first sight, but depends on the law assumed as to its successive values.

**238. Case of One Independent Variable.**—We will therefore suppose any variable magnitude  $y$  to be expressed as a function  $\phi(x)$  of some quantity  $x$  on which it depends, and its mean value taken as  $x$  proceeds by equal infinitesimal increments  $h$  from the value  $a$  to the value  $b$ . Let  $n$  be the number of values, then  $nh = b - a$ . The mean value is

$$\frac{1}{n} \left\{ \phi(a) + \phi(a+h) + \phi(a+2h) + \dots \right\}.$$

But (Art. 90),

$$h \left\{ \phi(a) + \phi(a+h) + \phi(a+2h) + \dots \right\} = \int_a^b \phi(x) dx.$$

Hence the mean value is

$$M = \frac{1}{b-a} \int_a^b \phi(x) dx. \quad (1)$$

#### EXAMPLES.

1. To find the mean value of the ordinate of a semicircle, supposing the series taken equidistant.

$$M = \frac{1}{2r} \int_{-r}^r \sqrt{r^2 - x^2} dx = \frac{1}{4} \pi r,$$

viz., the length of an arc of  $45^\circ$ .

2. In the same case, let us suppose the ordinates drawn through equidistant points on the circumference.

$$M = \frac{1}{\pi} \int_0^\pi r \sin \theta d\theta = \frac{2}{\pi} r; \text{ the ordinate of the centre of gravity of the arc.}$$

3. Determine the mean horizontal range of a projectile *in vacuo* for different angles of elevation from  $45^\circ - \theta$  to  $45^\circ + \theta$ ; given the initial velocity  $V$ .

If  $\alpha$  be the angle of elevation, the range is

$$R = \frac{V^2}{g} \sin 2\alpha.$$

Hence  $M = \frac{1}{2\theta} \int \frac{V^2}{g} \sin 2\alpha d\alpha$ , between the limits  $45^\circ \pm \theta$

therefore  $M = \frac{V^2 \sin 2\theta}{g - 2\theta}.$

The mean value for all elevations, from  $0^\circ$  to  $90^\circ$ , is  $\frac{2}{\pi} \frac{V^2}{g}.$

4. A number  $n$  is divided at random into two parts; to find the mean value of their product.

$$M = \frac{1}{n} \int_0^n x(n-x) dx = \frac{1}{6} n^2.$$

5. To find the mean distance of two points taken at random on the circumference of a circle.

Here we may evidently take one of the points,  $A$ , as fixed, and the other,  $B$ , to range over the whole circumference; since by altering the position of  $A$  we should only have the same series of values repeated: let  $\theta$  be the angle between  $AB$  and the diameter through  $A$ : as we need only consider *one* of the two semi-circles,

$$M = \frac{2}{\pi} \int_0^{\frac{\pi}{2}} 2r \cos \theta d\theta = \frac{4r}{\pi}.$$

6. To find the mean values of the reciprocals of all numbers from  $n$  to  $2n$ , when  $n$  is large; that is, to find the mean value of the quantities

$$\frac{1}{n}, \frac{1}{n} \frac{1}{1 + \frac{1}{n}}, \frac{1}{n} \frac{1}{1 + \frac{2}{n}}, \dots \dots \frac{1}{n} \frac{1}{1 + \frac{n}{n}};$$

that is, the mean value of the function  $\frac{1}{nx}$ , as  $x$  increases by equal increments from 1 to  $2$ ; therefore

$$M = \int_1^2 \frac{dx}{nx} = \frac{1}{n} \log 2.$$

7. To find the mean values of the two roots of the quadratic

$$x^2 - ax + b = 0,$$

the roots being known to be real, but  $b$  being unknown, except that it is positive.

In this case  $b$  is equally likely to have any value from 0 to  $\frac{a^2}{4}$ ; hence, for the greater root,  $a$ ,

$$M = \frac{1}{\frac{1}{4}a^2} \int_0^{\frac{a^2}{4}} a db$$

$$= \frac{4}{a^2} \int_{\frac{1}{2}\pi}^{\alpha} a(2a - a) da; \text{ since } b = a(a - a);$$

therefore  $M = \frac{5}{6}a.$

The mean value of the smaller root is  $\frac{1}{6}$ .

The mean squares of the two roots are  $\frac{17}{24}a^2$ ,  $\frac{1}{24}a^2$ . These might be deduced from the former results, since

$$M(x^2) - aM(x) + M(b) = 0.$$

8. Find the mean (positive) abscissa of all points included between the axis of  $x$  and the curve

$$y = ae^{-\frac{x^2}{c^2}}. \quad \text{Ans. } \frac{c}{\sqrt{\pi}}.$$

The mean square of the abscissa is  $\frac{1}{2}c^2$ .

239. If  $M$  be the mean of  $m$  quantities, and  $M'$  the mean of  $m'$  others of the same kind, and if  $\mu$  be the mean of the whole  $m + m'$  quantities, we have evidently

$$\mu = \frac{mM + m'M'}{m + m'}. \quad (2)$$

Thus if it be required to find the mean distance of one extremity of the diameter of a semicircle from a point taken at random anywhere on the whole periphery of the semicircle; since the mean value when it falls on the diameter is  $r$ , and the mean value when it falls on the arc is  $\frac{4r}{\pi}$ , we have

$$\mu = \frac{2r \cdot r + \pi r \frac{4r}{\pi}}{2r + \pi r} = \frac{6r}{2 + \pi}.$$

## 240. Case of Two or More Independent Variables.

—If  $z = \phi(x)$  be any function of two independent variables, and  $x, y$  be taken to vary by constant infinitesimal increments  $h, k$ , between given limits of any kind, the mean value of the function  $z$  will be

$$M = \frac{\iint z dx dy}{\iint dx dy}, \quad (3)$$

both integrals being taken between the given limits.

The easiest way of seeing this is to suppose  $x, y, z$  the coordinates of a point; and to conceive the boundary, representing the limits, traced on the plane of  $xy$ , and then ruled by lines parallel to  $x, y$  at intervals  $k, h$  apart. We have thus a reticulation of infinitesimal rectangles  $hk$ ; and if at each angle an ordinate  $z$  be drawn to the surface  $z = \phi(x, y)$ , as the number of ordinates will be the same as that of rectangles, we shall have

$$\text{volume } \iint z dx dy = \text{sum of ordinates} \times hk;$$

$$\text{also the plane area } \iint dx dy = \text{number of ordinates} \times hk;$$

so that dividing the sum of the ordinates by their number, the above expression results.

It may be shown, in like manner, that for three or more independent variables a similar expression holds.

It is evident that the above expression, viewed geometrically, gives the mean value of any function of the coordinates of a series of points uniformly distributed over a given plane area.

## EXAMPLES.

1. Suppose a straight line  $a$  divided at random at two points; to find the average value of the product of the three segments.

Let the distance of the two points  $X, Y$ , from one end of the line, be called  $x, y$ . Consider first the cases when  $x > y$ ; the sum of the products for these is half the whole sum; hence

$$M = \frac{2}{a^2} \int_0^a \int_0^x y(x-y)(a-x) dx dy = \frac{1}{60} a^3.$$

2. A number  $a$  is divided into three parts; to find the mean value of one part.

Let  $x, y, a - x - y$  be the parts;

$$M = \frac{\int_0^a \int_0^{a-x} x dx dy}{\int_0^a \int_0^{a-x} dy dx} = \frac{1}{3} a.$$

This value might be deduced, without performing the integrations, by considering that the expression is the abscissa of the centre of gravity of the triangle  $OAB$ ;  $OA, OB$  being lengths taken on two rectangular axes, each =  $a$ .

Of course the result in this case requires no calculation; as the sum of the mean values of the three parts must be =  $a$ ; and the three means must be equal.

The mean square of a part is  $\frac{1}{6} a^2$ .

3. A number  $a$  is divided at random into three parts: to find the mean value of the *least* of the three parts; also of the *greatest*, and of the *mean*.

Let  $x, y, a - x - y$ , be the greatest, mean, and least parts. The mean value of the greatest is  $M = \frac{\iint x dx dy}{\iint dx dy}$ : the limits of both integrations being given by

$$x > y > a - x - y > 0.$$

If  $x, y$  be the coordinates of a point, referred to the axes  $OA, OB$ , taking  $OA = OB = a$ , the above limits restrict the point to the triangle  $AVH$  ( $AM$  being drawn to bisect  $OB$ ); and the above value of  $M$  is the abscissa of the centre of gravity of

this triangle; i. e.  $\frac{1}{3}$  of the sum of the abscissas of its angles; hence

$$M = \frac{1}{3} \left( a + \frac{1}{2} a + \frac{1}{3} a \right) = \frac{11}{18} a.$$

The *ordinate* of the same centre of gravity, viz.,

$$\frac{1}{3} \left( \frac{1}{2} a + \frac{1}{3} a \right) = \frac{5}{18} a,$$

is the mean value of the mean part; hence the mean values of the three parts required are respectively

$$\frac{11}{18} a, \quad \frac{5}{18} a, \quad \frac{1}{9} a.$$

4. To find the mean square of the distance of a point within a given square (side =  $2a$ ), from the centre of the square.

$$M = \frac{1}{4a^2} \int_{-a}^a \int_{-a}^a (x^2 + y^2) dx dy = \frac{2}{3} a^2.$$

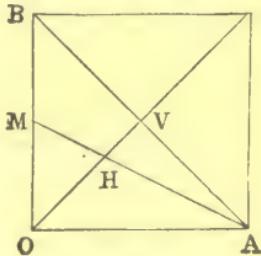


Fig. 54.

It is obvious that the mean square of the distance of all points on any plane area from any fixed point in the plane is the square of the *radius of gyration* of the area round that point.

5. To find the mean distance of a point on the circumference of a circle from all points inside the circle.

Taking the origin on the circumference, and the diameter for the axis, if  $dS$  be any element of the area, we have

$$M = \frac{\iint r dS}{\pi a^2} = \frac{1}{\pi a^2} \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \int_0^{2a \cos \theta} r^2 d\theta dr = \frac{32a}{9\pi}.$$

241. Many problems on Mean Values, as well as on Probability, may be solved by particular artifices, which, if attempted by direct calculation, lead to difficult multiple integrals which could hardly be dealt with.

### EXAMPLES.

1. To find the mean distance between two points within a given circle.

If  $M$  be the required mean, the sum of the whole number of cases is represented by

$$(\pi r^2)^2 M.$$

Now let us consider what is the differential of this, that is, the sum of the new cases introduced by giving  $r$  the increment  $dr$ . If  $M_0$  be the mean distance of a point on the circumference from a point within the circle, the new cases introduced, by taking one of the two points  $A$  on the infinitesimal annulus  $2\pi r dr$ , are

$$\pi r^2 M_0 \cdot 2\pi r dr;$$

doubling this, for the cases where the point  $B$  is taken in the annulus, we get

$$d \cdot \{(\pi r^2)^2 M\} = 4\pi^2 M_0 r^3 dr.$$

Now  $M_0 = \frac{32r}{9\pi}$  (Ex. 5, Art. 240);

therefore  $\pi^2 r^4 M = \frac{128}{9} \pi \int_0^r r^4 dr;$

therefore  $M = \frac{128}{45\pi}.$

2. To find the mean square of the distance between two points taken on any plane area  $\Omega$ .

Let  $dS, dS'$  be any two elements of the area,  $\Delta$  their mutual distance, and we have

$$M = \frac{1}{\Omega^2} \iiint \Delta^2 dS dS'.$$

Now, fixing the element  $dS$ , the integral of  $\Delta^2 dS'$  is the moment of inertia of the area  $\Omega$  round  $dS$ ; so that if  $K$  be the radius of gyration of the area round  $dS$ ,

$$M = \frac{I}{\Omega} \iint K^2 dS;$$

let  $r$  = distance of  $dS$  from the centre of gravity  $G$  of the area,  $k$  the radius of gyration round  $G$ ; then

$$K^2 = r^2 + k^2;$$

therefore

$$M = k^2 + \frac{I}{\Omega} \iint r^2 dS = 2k^2;$$

thus the mean square is twice the square of the radius of gyration of the area round its centre of gravity.

242. The mean distance of a point  $P$  within a given area from a fixed straight line (which does not meet the area) is evidently the distance of the centre of gravity  $G$  of the area from the line. Thus, if  $A, B$  are two fixed points on a line outside the area, the mean value of the area of the triangle  $APB$  is the triangle  $AGB$ .

From this it will follow, that if  $X, Y, Z$  are three points taken at random in three given spaces on a plane (such that they cannot all be cut by any one straight line), the mean value of the area of the triangle  $XYZ$  is the triangle  $GG'G''$ , determined by the three centres of gravity of the spaces.

#### EXAMPLE.

i. A point  $P$  is taken at random within a triangle  $ABC$ , and joined with the three angles. To find the mean value of the greatest of the three triangles into which the whole is divided.

Let  $G$  be the centre of gravity; then if the greatest triangle stands on  $AB$ ,  $P$  is restricted to the figure  $CHGK$ , and the mean value of  $APB$  is the same as if  $P$  were restricted to the triangle  $GCK$ ; hence we have to find the area of the triangle whose vertex is the centre of gravity of  $GCK$ , and base  $AB$ ;

$$\text{therefore } M = \frac{1}{3} (ACB + AKB + AGB) = \frac{1}{3} \left( 1 + \frac{1}{2} + \frac{1}{3} \right) ABC;$$

hence the mean value is  $\frac{11}{18}$  of the whole triangle.

The mean values of the least and mean triangles are respectively  $\frac{1}{9}$  and  $\frac{5}{18}$  of the whole.

This question can readily be shown to be reducible to Question 3, Art. 240.

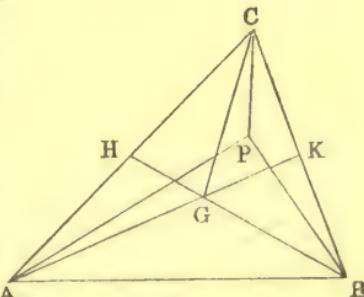


Fig. 55.

243. If  $M$  be the mean value of any quantity depending on the positions of two points (e.g. their distance) which are taken, one in a space  $A$ , the other in a space  $B$  (external to  $A$ ) ; and if  $M'$  be the mean value when both points are taken indiscriminately in the whole space  $A + B$  ;  $M_A$ ,  $M_B$ , the mean values when both points are taken in  $A$ , or both in  $B$ , respectively ; then

$$(A + B)^2 M' = 2ABM + A^2 M_A + B^2 M_B. \quad (4)$$

If the space  $A = B$ ,

$$4M' = 2M + M_A + M_B;$$

if, also,  $M_A = M_B$ ,

$$2M' = M + M_A;$$

thus if  $M$  be the mean distance of a point within a semi-circle from a point in the opposite semicircle,  $M_1$  that of two points in one semicircle, we have (Art. 241),

$$M + M_1 = \frac{256}{45\pi} r.$$

To determine  $M$  or  $M_1$  is rather difficult, though their sum is thus found. The value of  $M$  is  $\frac{147^2}{135\pi^2} r$ .

#### EXAMPLES.

1. Two points,  $X$ ,  $Y$  are taken at random within a triangle. What is the mean area  $M$  of the triangle  $XYC$ , formed by joining them with one of the angles of the triangle?

Bisect the triangle by the line  $CD$ ; let  $M_1$  be the mean value when both points fall in the triangle  $ACD$ ;  $M_2$  the value when one falls in  $ACD$  and the other in  $BCD$ ; then

$$2M = M_1 + M_2.$$

But  $M_1 = \frac{1}{2} M$ ; and  $M_2 = GG'C$ , where  $G$ ,  $G'$  are the centres of gravity of  $ACD$ ,  $BCD$ , this being a case of the theorem in Art. 242; hence

$$M_2 = \frac{2}{9} ABC, \quad \text{and} \quad M = \frac{4}{27} ABC.$$

2. To find the mean area of the triangle formed by joining an angle of a square with two points anywhere within it.

By a similar method this is found to be

$$\frac{13}{108} \text{ of the whole square.}$$

3. What is the mean area of the triangle formed by joining the same two points with the centre of the square?

We may take one of the points  $X$  always in the square  $OA$ ; take the whole square as unity; then if  $M$  be the mean, the sum of all the cases is

$$\frac{1}{4} M = \frac{1}{4^2} M_1 + 2 \frac{1}{4^2} M_2 + \frac{1}{4^2} M_3,$$

$M_1, M_2, M_3$  being the mean areas when the second point  $Y$  is taken respectively in  $OA$ ,  $OB$ , and  $OC$ . But  $M_3 = M_1$ , for to any point  $Y$  in  $OC$  there corresponds one  $Y'$  in  $OA$ , which gives the area  $OXY' = OXY$ ;

therefore  $M = \frac{1}{2} M_1 + \frac{1}{2} M_2.$

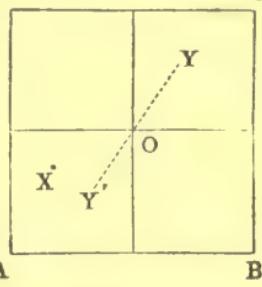


Fig. 56.

But  $M_1 = \frac{13}{108} \cdot \frac{1}{4}$ ,  $M_2 = \frac{1}{16}$ ; hence  $M = \frac{5}{108}$  of the whole square.\*

244. If two spaces  $A + C$ ,  $B + C$  have a common part  $C$ , and  $M$  be any mean value relating to two points, one in  $A + C$ , the other in  $B + C$ ; and if the whole space  $A + B + C = W$ , and  $M_w$  be the mean value when both points are taken indiscriminately in  $W$ ;  $M_A$  when taken in  $A$ , &c., then

$$2(A + C)(B + C)M = W^2 M_w + C^2 M - A^2 M_A - B^2 M_B, \quad (5)$$

as is easily seen by dividing the whole number  $W^2$  of cases into the different classes of cases which compose it.

\* In such questions as the above, relating to areas determined by points taken at random in a triangle or parallelogram, we may consider the triangle as equilateral, and the parallelogram as a square. This will appear from orthogonal projection; or by deforming the triangle into a second triangle on the same base and between the same parallels, when it is easy to see that to one or more random points in the former there correspond a like set in the latter, determining the same areas. This second triangle may be made to have a side equal to a side of an equilateral triangle of the same area; and then be deformed in like manner into the equilateral triangle itself. Likewise a parallelogram may be deformed into a square.

## EXAMPLE.

Two segments,  $AB$ ,  $CD$ , of a straight line have a common part  $CB$ ; to find the mean distance of two points taken, one in  $AB$ , the other in  $CD$ .

$$2AB \cdot CD \cdot M = AD^2 \cdot \frac{1}{3} AD + CB^2 \cdot \frac{1}{3} CB - AC^2 \cdot \frac{1}{3} AC - BD^2 \cdot \frac{1}{3} BD,$$

since the mean distance of two points in any line is  $\frac{1}{3}$  of the line;

therefore 
$$M = \frac{AD^3 + CB^3 - AC^3 - DB^3}{6AB \cdot CD}.$$

245. The consideration of probability may often be made to assist in determining mean values. Thus, if a given space  $S$  is included within a given space  $A$ , the chance of a point  $P$ , taken at random on  $A$ , falling on  $S$  is

$$p = \frac{S}{A}.$$

But if the space  $S$  be variable, and  $M(S)$  be its mean value,

$$p = \frac{M(S)}{A}. \quad (6)$$

For, if we suppose  $S$  to have  $n$  equally probable values  $S_1, S_2, S_3, \dots$ , the chance of any one  $S_1$  being taken, and of  $P$  falling on  $S_1$ , is

$$p_1 = \frac{1}{n} \frac{S_1}{A} :$$

now the whole probability  $p = p_1 + p_2 + p_3 + \dots$ ; which leads at once to the above expression.

The chance of *two* points falling on  $S$  is

$$p = \frac{M(S^2)}{A^2}. \quad (7)$$

In such a case, if the probability be known, the mean value follows, and *vive versa*. Thus, we might find the mean value of the distance of two points  $X, Y$ , taken at random in a line,

by the consideration that if a third point  $Z$  be taken at random in the line, the chance of it falling between  $X$  and  $Y$  is  $\frac{1}{3}$ ; as one of the three must be the middle one. Hence the mean distance is  $\frac{1}{3}$  of the whole line.

Again, the mean  $n^{\text{th}}$  power of the distance is  $\frac{2a^n}{(n+1)(n+2)}$ , where  $a$  = whole line. For if  $p$  is the probability that  $n$  more points taken at random shall fall between  $X$  and  $Y$ ,

$$M(XY)^n = a^n p.$$

Now, the chance that out of the  $n+2$  points  $X$  shall be one of the extreme points is  $\frac{2}{n+2}$ ; and if it is so, the chance that  $Y$  shall be the other extreme point is  $\frac{1}{n+1}$ .

### EXAMPLES.

1. From a point  $X$ , taken anywhere in a triangle, parallels are drawn to two of the sides. Find the mean value of the triangle  $UXV$ .

If a second point  $X'$  be taken at random within  $ABC$ , the chance of its falling in  $XUV$  is the same as the chance of  $X$  falling in the corresponding triangle  $X'U'V'$ ; that is, of  $X'$  falling in the parallelogram  $XC$ . Hence the mean value of  $UXV$  = mean value of  $XC$ . But the mean value of  $(UXV$

$+ XC)$  is  $\frac{1}{3} ABC$ ; as the whole triangle

can be divided into three such parts by drawing through  $X$  a parallel to  $AB$ .<sup>\*</sup> Thus

$$M(UXV) = \frac{1}{6} ABO.$$

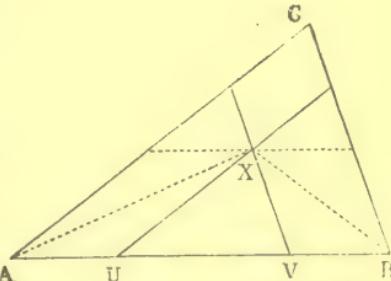


Fig. 57.

The mean value of  $UV$  is  $\frac{1}{3} AB$ . For  $UV$  is the same fraction of  $AB$  that the altitude of  $X$  is of that of  $C$ : see Art. 242.

\* The triangle may be considered equilateral: see note, Art. 243.

Cor. Hence, if  $p$  be the perpendicular from  $X$  on  $AB$ ,  $h$  the altitude of the triangle  $ABC$ , we get

$$M(p^2) = \frac{1}{6} h^2.$$

If the area  $ABC$  be taken as unity, we have, since  $UXV:AXB = AXB:ABC$ ,

$$(AXB)^2 = UXV.$$

Thus the mean square of the triangle  $AXB$  is  $\frac{1}{6}$ . If two other points  $Y, Z$  are taken at random in the triangle, the chance of both falling on  $AXB$  is thus the same as that of a single point falling on  $UXV$ ; i.e.  $\frac{1}{6}$ . Hence we may easily infer the following theorem:—

If three points  $X, Y, Z$  are taken at random in a triangle, it is an even chance that  $Y, Z$  both fall on one of the triangles  $AXB, AXC, BXC$ .

2. In a parallelogram  $ABCD$  a point  $X$  is taken at random in the triangle  $ABC$ , and another,  $Y$ , in  $ADC$ . Find the chance that  $X$  is higher than  $Y$ .

Draw  $XH$  horizontal: the chance is

$$\text{mean area of } AHK \div ADC.$$

But  $AHK = XUV$ , and the mean area of  $XUV$  is  $\frac{1}{6} ACB$  (Ex. 1); hence the chance is  $\frac{1}{6}$ .

3. If  $O$  be a point taken at random on a triangle, and lines be drawn through it from the angles, to find the mean value of the triangle  $DEF$ . (MR. MILLER.)

It will be sufficient to find the mean area of the triangle  $AEF$ , and subtract three times its value from  $ABC$ . If we put  $\alpha, \beta, \gamma$  for the triangles  $BOC, AOC, AOB$ , it is easy to prove that

$$AEF = \frac{\beta\gamma}{(\alpha + \beta)(\alpha + \gamma)} \cdot ABC.$$

If we put the whole area  $ABC = 1$ , and if  $dS$  be the element of the area at  $O$ ,

$$M(AEF) = \iint \frac{\beta\gamma dS}{(1 - \beta)(1 - \gamma)},$$

the integration extending over the whole triangle.

But if  $p, q$  are the perpendiculars from  $O$  on the sides  $b, c$ , it may be easily shown that the element of the area is

$$dS = \frac{dp dq}{\sin A} = \frac{4}{b \sin A} d\beta d\gamma = 2d\beta d\gamma.$$

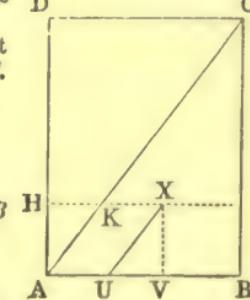


Fig. 58.

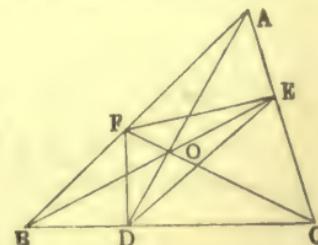


Fig. 59.

Thus the mean value of  $AEF$  becomes

$$M = \int_0^1 \int_0^{1-\beta} \frac{2\beta\gamma d\beta d\gamma}{(1-\beta)(1-\gamma)} = \int_0^1 (\beta - 1 - \log \beta) \frac{2\beta}{1-\beta} d\beta.$$

Again, by Art. 95, the definite integral

$$\int_0^1 \frac{\beta \log \beta}{1-\beta} d\beta = 1 - \frac{\pi^2}{6};$$

therefore  $M = -1 - 2 \left( 1 - \frac{\pi^2}{6} \right) = \frac{\pi^2}{3} - 3.$

Hence the mean value of the triangle  $DEF$  is

$$10 - \pi^2,$$

that of  $ABC$  being unity.

It is remarkable that the same value,  $10 - \pi^2$ , has been found by Col. Clarke to be the mean area of a triangle formed by the intersections of three lines, drawn from  $A, B, C$  to points taken at random in  $a, b, c$  respectively.

4. To find the average area of all triangles having a given perimeter ( $2s$ ). By this is meant that the given perimeter is divided at random in every possible way into three parts,  $a, b, c$ , and only those cases are taken in which  $a, b, c$  can form a triangle; then the mean value of

$$A = \sqrt{s(s-a)(s-b)(s-c)}$$

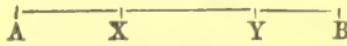


Fig. 60.

has to be found.

Take  $AB = 2s$ , let  $X, Y$  be the two points of division,  $AX = x, AY = y$ : these are subject to the conditions

$$x < s, \quad y > s, \quad y - x < s.$$

Now  $\frac{A}{\sqrt{s}} = \sqrt{(s-x)(y-s)(s-y+x)};$

$$\therefore \frac{1}{\sqrt{s}} M(A) = \frac{\int_s^{2s} \int_{y-s}^s \sqrt{(s-x)(y-s)(s-y+x)} \cdot dy dx}{\int_s^{2s} \int_{y-s}^s dy dx}.$$

Again, by Art. 132, we have

$$\int_{y-s}^s \sqrt{(s-x)(s-y+x)} dx = \frac{\pi}{8} (2s-y)^2;$$

$$\therefore \frac{1}{\sqrt{s}} M(A) = \frac{1}{\frac{1}{2}s^2} \cdot \frac{\pi}{8} \int_s^{2s} (2s-y)^2 \sqrt{y-s} \cdot dy = \frac{\pi}{4s^2} \int_0^s z^{\frac{1}{2}} (s-z)^2 dz = \frac{\pi}{4} \cdot \frac{16}{105} \cdot s^{\frac{3}{2}}.$$

Hence,

$$\text{Mean area} = \frac{\pi}{105} (2s)^2.$$

In the same case we should easily find

$$\text{Mean square of area} = \frac{\delta^4}{60}.$$

5. Three points are taken at random within a given triangle; prove that the mean area of the triangle formed by them is  $\frac{1}{12}$  of the given triangle.

Call the area of the given triangle  $\Delta$ , the required mean  $M$ : we will first prove that if  $M_0$  be the mean area when one of the three points is restricted to a side of the given triangle,

$$M = \frac{3}{4} M_0.$$

Let  $\Delta$  receive an increment of area  $d\Delta$ , by adding to it an infinitesimal band included between the base  $a$  and a line parallel to it; the increase produced in the sum of all the cases is found by considering one of the random points  $X$  taken in this band; the additional cases introduced will be represented by

$$\Delta^2 d\Delta \cdot M_0.$$

The whole increase is treble this, for we must consider also the cases when  $Y, Z$  fall in this band (the cases when *two* of the three fall in it may be neglected, their number being proportional to the square of  $d\Delta$ ). Now the sum of all the original cases is  $\Delta^2 M$ ; hence

$$d(\Delta^2 M) = 3\Delta^2 M_0 d\Delta.$$

Now  $\frac{M}{\Delta}$  is constant for all triangles (see note, Art. 243);

$$\text{hence } \frac{M}{\Delta} d \cdot \Delta^4 = 3\Delta^2 M_0 d\Delta; \quad \therefore M = \frac{3}{4} M_0.$$

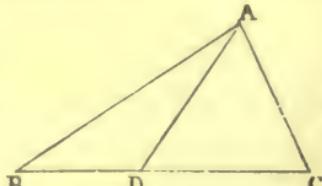


Fig. 61.

Again, to find  $M_0$ , consider the random point  $X$  fixed at a particular point  $D$  of the base  $a$ , the other two points,  $Y, Z$ , ranging all over the triangle. Let  $M'$  be the mean value of  $DIY$ ; the sum of all the cases, viz.,  $\Delta^2 M'$ , may be decomposed into three groups: (1) when  $Y, Z$  are in  $ABD$ ; (2) both in  $ACD$ ; (3) one in each triangle:

$$\therefore (ABC)^2 M' = (ABD)^2 \cdot \frac{4}{27} ABD + (ACD)^2 \cdot \frac{4}{27} ACD + 2ABD \cdot ACD \cdot \frac{ABC}{9},$$

by Ex. (1), Art. 243, and because in case (3) the mean value is the area of the triangle formed by joining  $D$  with the centres of gravity of  $ABD$  and  $ACD$  (Art. 242). Let  $BD = x$ , altitude of triangle =  $p$ , and we get

$$\Delta^2 M' = \frac{4}{27} \left(\frac{x}{2} p\right)^3 + \frac{4}{27} \left(\frac{a-x}{2} p\right)^3 + 2 \left(\frac{p}{2}\right)^3 x(a-x) \cdot \frac{1}{9} a.$$

Now when the point  $X$  falls on the element  $dx$ , the sum of all the cases is

$\Delta^2 M dx$ ; and hence, when  $X$  ranges from  $B$  to  $C$ , the whole sum of cases is represented by

$$a\Delta^2 M_0 = \int_0^a \Delta^2 M' dx = (\frac{1}{2}p)^3 \int_0^a \left\{ \frac{4}{27}x^3 + \frac{4}{27}(a-x)^3 + \frac{2}{9}ax(a-x) \right\} dx;$$

therefore

$$a\Delta^2 M_0 = (\frac{1}{2}p)^3 \frac{1}{9}a^4 = \frac{1}{9}a\Delta^3.$$

Hence  $M_0 = \frac{1}{9}\Delta$ ; and therefore  $M = \frac{3}{4}M_0 = \frac{1}{12}\Delta$ .

COR. Hence, if four points,  $A$ ,  $B$ ,  $C$ ,  $D$ , are taken at random within a triangle, the chance that they determine a re-entrant quadrilateral is  $\frac{1}{3}$ . For the chance that  $D$  falls in  $ABC$  is the mean value of  $ABC$  divided by the whole triangle, that is  $\frac{1}{12}$ ; and we have to add to this the chances that  $C$  falls

in  $ABD$ , &c. The chance that  $ABCD$  is convex is  $\frac{2}{3}$ .

6. The mean distance of the vertex of a triangle from all points in the area is equal to its distance from the centre of gravity, measured along a parabolic path, which leaves the vertex in the direction of one of its sides, and reaches the centre of gravity in a direction parallel to the other—the axis of the parabola being parallel to the base.

Let an indefinite line  $AP$  be conceived to revolve round  $A$ , from the direction  $AC$  to  $AB$ ; and as it revolves, suppose that all the mass of the triangle  $ABC$  which lies to the right of it is transferred continuously to the vertex  $A$ . The centre of gravity of the whole mass will thus describe a curve starting from  $G$ , and ending at  $A$ . When the line is at  $AP$  let the centre of gravity be at  $g$ ; and when it is in the consecutive position  $APP'$ , let the centre be at  $g'$ . As the mass of the triangle  $APP'$  has been transferred to  $A$ ,  $gg'$  is parallel to  $AP$ ; also

$$gg' = \frac{APP'}{ABC} \cdot \frac{2}{3}AP;$$

since  $\frac{2}{3}AP$  is the distance traversed by the centre of gravity of the transferred portion of the whole mass.\*

But as  $\frac{2}{3}AP$  is the mean distance of all points in  $APP'$  from  $A$ , the sum of

every element in  $APP'$  multiplied by its distance from  $A = APP' \times \frac{2}{3}AP$ .

Hence the sum of all the elements  $gg'$ , i.e. the whole arc  $GA$  = sum of every element of  $ABC$  into its distance from  $A$ , divided by the area  $ABC$ , i.e. the mean distance required.

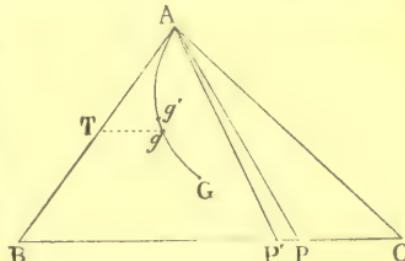


Fig. 62.

\* See Rankine, *Applied Mechanics*, p. 54.

It is easy to show that if  $gT$  is drawn parallel to  $BC$ , we have

$$\Delta T^2 = \frac{4}{3} \frac{c^2}{a} gT;$$

and that the curve is the parabola mentioned above. For  $A$  and  $g$  are in directum with the centre of gravity of  $ABP$ ; and hence, since  $g$  is the centre of gravity of  $ABP$  and of a mass at  $A$  equal to  $APC$ ,

$$\frac{\Delta T}{\frac{2}{3}c} = \frac{BP}{a}, \text{ and } \frac{BP}{2gT} = \frac{c}{\Delta T}.$$

### PROBABILITIES.

246. The calculation of Probabilities, when the number of favourable cases, as well as the whole number of cases, is finite, is not a subject for the Infinitesimal Calculus. It is when the number of cases depends on continuously varying magnitudes, and is therefore infinite, that recourse has to be made to the methods of the Integral Calculus.

The same remark applies here which we had occasion to make as to mean values (Art. 237). The value of the probability will depend on the law according to which we select the series of cases which we take as *representing* the total number—that is, it will depend on which variable (or variables) we suppose to be taken *at random*, that is, to proceed by constant infinitesimal increments;\* in other words, to be the *independent* variable (or variables). Thus, if we have to find the chance of the line, drawn from a fixed point to a given finite straight line, exceeding a given length, the results will be different if, first, we suppose a series of lines drawn to points taken at random on the given line, or, secondly, a series of lines drawn in *random directions* from the fixed point. In many cases, however, the problem has an obvious sense which precludes any such uncertainty.

247. Let us consider a simple question on chances. Two integers are chosen at random from 0 to 6 inclusive; to find

\* Of course a large number of values taken at random for a variable do not really form an equi-different series: but, as they must give a number of points (when measured along a straight line) of uniform *density*, they may be taken, for the purposes of calculation, as equi-different.

the chance that the greater of the two exceeds a given value, suppose 3. Here the whole number of cases, all equally probable, is easily seen to be

$$1 + 2 + 3 + 4 + 5 + 6,$$

and the number of favourable cases is

$$4 + 5 + 6,$$

so that the required chance is  $\frac{5}{7}$ .

If, however, the question is not confined to integers, but that the two numbers chosen may have any arbitrary values from 0 to  $a$ ; or as we may state the question:—Two quantities are taken at random from 0 to  $a$ ; find the chance that the greater of the two is less than a given value  $b$ :—

Let  $x$  be the greater; then for any assigned value of  $x$  the number of cases is measured by  $x$  (since the lesser may have any value from 0 to  $x$ ); hence the number of cases when the greater falls between  $x$  and  $x + dx$  is measured by  $x dx$ ; the whole number of cases is therefore  $\int_0^a x dx$ ; and the favourable

cases are  $\int_0^b x dx$ . The required chance is therefore  $p = \frac{b^2}{a^2}$ .

This instance will serve to show how the Integral Calculus may enter into the estimation of chances. It is true that it might easily be solved otherwise; for if the two numbers are considered as the distances from one end of the line of two points taken at random in a line of length  $a$ , and if we measure a distance  $b$  from that end, the problem is really to find the chance that *both* points fall within  $b$ ; which chance is evidently  $\frac{b^2}{a^2}$ .

248. We proceed to give a few easy questions on probabilities: general rules can hardly be given for their solution, the number and diversity of the questions which may be proposed being so great that no attempt seems to have been made to classify or connect them in a regular theory. We will give, in particular, several on Local or Geometrical Probability.

## EXAMPLES.

1. If an event  $B$  is known to have occurred in a certain century, the chance that it was not distant more than  $n$  years from the middle of the century is of course  $\frac{2n}{100}$ ; but if three events,  $A$ ,  $B$ ,  $C$ , are known to have occurred in the century, and that  $A$  preceded  $B$ , and  $B$  preceded  $C$ , let it be proposed to find how far this amount of knowledge alters the value of the chance for  $B$ .

Let  $x$  be the number of years from the beginning of the century to the event  $B$ ; then, for any assigned value of  $x$ , the number of triple cases is  $x(100-x)$ : hence the number of favourable cases divided by the whole number is

$$p = \frac{\int_{50-n}^{50+n} x(100-x) dx}{\int_0^{100} x(100-x) dx} = 3 \frac{n}{100} - 4 \left( \frac{n}{100} \right)^3.$$

2. Two numbers,  $x$ ,  $y$ , are chosen at random between 0 and  $a$ : find the chance that the product  $xy$  shall be less than  $\frac{a^2}{4}$  (its mean value).

Here

$$p = \frac{\iint dx dy}{a^2},$$

the integral being limited by  $a > x > 0$ ,  $a > y > 0$ , and  $xy < \frac{a^2}{4}$ . We have accordingly to integrate for  $y$  from 0 to  $a$ , when  $x$  is between 0 and  $\frac{a}{4}$ ; and from  $\frac{a^2}{4x}$  to 0, when  $x$  is between  $\frac{a}{4}$  and  $a$ ; thus

$$\iint dx dy = \int_0^{\frac{a}{4}} adx + \int_{\frac{a}{4}}^a \frac{a^2}{4x} dx = \frac{a^2}{4} + \frac{a^2}{4} \log 4.$$

Hence

$$p = \frac{1}{4} + \frac{1}{2} \log 2.$$

3. Two points are taken at random in a given line  $a$ ; to find the chance that their distance asunder shall exceed a given value  $c$ .

It is easy to see that the distances of two such points from one end of the line are the coordinates of a point taken at random in a square whose side is  $a$ . Thus to every case of partition of the line corresponds a point in the square—such points being uniformly distributed over its surface.

Thus, if in the above question  $x$ ,  $y$  stand for the distances of the two points, from one end of the line,  $y$  being greater than  $x$ , we have to find the chance of  $y - x$  exceeding  $c$ . The point  $P$  whose coordinates are  $x$ ,  $y$ , in the square  $OD$  (side =  $a$ ), may take all possible positions in the triangle  $OBD$ , if no condition is imposed on it. But if  $y - x > c$ , then if we measure  $OH = c$ , the favourable cases

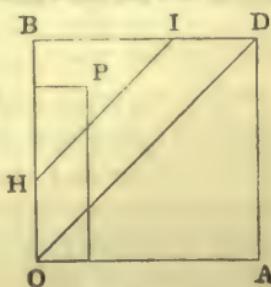


Fig. 63.

occur only when  $P$  is in the triangle  $BHI$ ; hence the probability required

$$p = \frac{BHI}{OBD} = \left(\frac{a-c}{a}\right)^2.$$

In fact this is only performing the integrations in the expression

$$p = \frac{\int_c^a \int_0^{y-c} dx dy}{\int_0^a \int_0^y dx dy}.$$

4. Two points being taken at random in a line  $a$ , to find the chance that no one of the three segments shall exceed a given length  $c$ .

The segments being as before,  $x$ ,  $y-x$ ,  $a-y$ ,  $PH=x$ ,  $PK=a-y$ ,  $PI=y-x$ . There will be two cases:—

(1). If  $c > \frac{1}{2}a$ ; take  $OU=BV=DZ=BN=c$ ;

then it is easy to see that the only favourable cases are when  $P$  falls in the hexagon  $UZNMJV$ ;

$$p_1 = \frac{OBD - 3 \cdot UBV}{OBD} = 1 - 3 \left(\frac{a-c}{a}\right)^2.$$

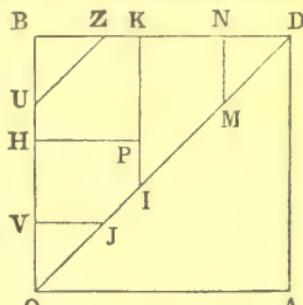


Fig. 64.

(2). If  $c < \frac{1}{2}a$ ; take  $OU=BV=c$ , as before; then the only favourable cases are when  $P$  falls in the triangle  $RST$ ;

$$\text{therefore } p_2 = \frac{RST}{OBD} = \left(\frac{3c-a}{a}\right)^2,$$

$$\text{since } RST = \frac{1}{2} RT^2, \text{ and } RT = VT + RH - VH \\ = 2c - (a-c).$$

Such cases of discontinuity in the functions expressing probabilities frequently present themselves. The functions are connected by very remarkable laws. Thus, in the present question, if  $p_1 = f(c)$ ,  $p_2 = F(c)$ , we have

$$f(c) - f(a-c) = F(a-c).$$

5. A floor is ruled with equidistant parallel lines; a rod, shorter than the distance between each pair, being thrown at random on the floor, to find the chance of its falling on one of the lines (*Buffon's problem*).

Let  $x$  be the distance of the centre of the rod from the nearest line,  $\theta$  the inclination of the rod to a perpendicular to the parallels,  $2a$  the common distance of the parallels,  $2c$  the length of rod; then as all values of  $x$  and  $\theta$  between their

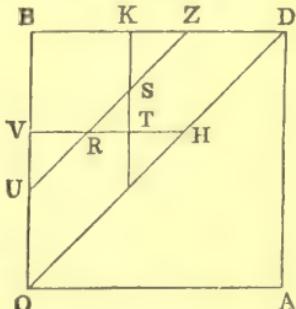


Fig. 65.

extreme limits are equally probable, the whole number of cases will be represented by

$$\int_0^a \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} dx d\theta = \pi a.$$

Now, if the rod crosses one of the lines, we must have  $c > \frac{x}{\cos \theta}$ ; so that the favourable cases will be measured by

$$\int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} d\theta \int_0^{c \cos \theta} dx = 2a.$$

Thus the probability required is  $= \frac{2a}{\pi a}$ .

This question is remarkable as having been the first proposed on the subject now called Local Probability. It has been proposed, as a matter of curiosity, to determine the value of  $\pi$  from this result, by making a large number of trials with a rod of length  $2a$ : the difficulty, however, here consists in ensuring that the rod shall fall really at random. The circumstances under which it is thrown may be more favourable to certain positions of the rod than others. Though we may be unable to take account *a priori* of the causes of such a tendency, it will be found to reveal itself through the medium of repeated trials.

249. Sometimes a result depends upon a variable (or variables) all the values of which are not equally probable, but are such that the probability of a certain value for a variable depends, according to some law, on the magnitude of that value itself (and also, perhaps, on the values of other variables). Thus a point may be taken in a straight line so that all positions are not equally probable, but the probability of the distance from one end having the value  $x$ , being proportional to  $x$  itself. This would be in fact supposing the series of points in question as ranged along the line with a *density* proportional to  $x$ ; as, e. g., if they were the projections, on the line, of points taken at random in the space between the line and another line drawn through one of its extremities. To give an example:—

Two points are taken in a line  $a$ , with probabilities varying as the distance from one end  $A$ ; to find the chance of their distance exceeding a length  $c$ .

Let  $x, y$ , be the distances from  $A$ , and suppose  $y > x$ .

Here the probability of a point falling between  $x$  and  $x + dx$  is not proportional to  $dx$ , but to  $x dx$ ; and the result will be

$$p = \frac{\int_c^a y dy \int_0^{y-c} x dx}{\int_c^a y dy \int_0^y x dx} = \left(1 + \frac{c}{3a}\right) \left(1 - \frac{c}{a}\right)^3.$$

The mean values of the three divisions of the line, in the same case, will be found to be

$$\frac{8}{15}a, \quad \frac{4}{15}a, \quad \frac{1}{5}a.$$

The above value of  $p$  is also the value of the chance, that the difference of the altitudes of two points within a triangle shall exceed a given fraction  $\frac{c}{a}$  of the altitude of the triangle.

### EXAMPLES.

I. Two points being taken on the sides  $OA$ ,  $OB$ , of a square  $a^2$ , the chance of their distance being less than a given value  $b$  is easily seen without calculation to be  $\frac{\pi b^2}{4a^2}$ , provided  $b < a$ ; as it is the chance of a point taken at random in the square falling within a quadrant of a given circle. Suppose now that two points are taken on  $OA$ , and two on  $OB$ , and that we take  $X$ ,  $Y$ , the two points furthest from  $O$  on each side, to find the chance that their distance  $XY$  is less than a given length  $b$ ; ( $b < a$ ).

Here the probability of  $X$  falling between  $x$  and  $x + dx$  is proportional to  $x dx$ ; likewise for  $y$ ; hence

$$p = \frac{\iint xy dx dy}{\int_0^a \int_0^a xy dx dy},$$

the upper integral being limited by  $x^2 + y^2 < b^2$ ; hence  $p = \frac{b^4}{2a^4}$ .

Thus it is an even chance that the point determined by the coordinates  $x$ ,  $y$  shall fall within the quadrant  $\frac{1}{2}\pi a^2$ .

2. In a circular target of area  $A$  the area of the bull's eye is  $a$ . If a shot is heard to strike the target, the chance of its having hit the bull's eye is of course  $\frac{a}{A}$ .\* If, however, two shots have been fired, to find the chance that the best of the two has hit the bull's eye.

This is easily solved by elementary considerations; as the chance of both missing the bull's eye is

$$p = \left( \frac{A-a}{A} \right)^2.$$

Hence the required chance of the best shot having hit it is

$$1-p = \frac{a}{A} \left( 2 - \frac{a}{A} \right).$$

3. Let it be proposed, however, to find the chance of the best of the two shots (i.e. that nearest the centre) having hit any given area  $a$ , traced out on the target.

The number of cases in which the worst shot falls on any element  $dS$ , at a distance  $r$  from the centre, is measured by  $\pi r^2 dS$ ; hence the chance of the worst shot striking the area  $a$  is

$$p = \frac{\iint r^2 dS \text{ (over } a)}{\iint r^2 dS \text{ (over } A)} = \frac{m}{M},$$

where  $M, m$  are the moments of inertia of  $A, a$  round the centre of the target. Now the probability of both shots missing  $a$  is

$$\left( \frac{A-a}{A} \right)^2;$$

hence that of  $a$  being hit (by one or both) is

$$1 - \left( \frac{A-a}{A} \right)^2;$$

and the chance of both hitting it is  $\frac{a^2}{A^2}$ . But the chance of  $a$  being hit is

chance of best + chance of worst - chance of both;

hence if  $p_1$  be the required chance, viz., of the best shot striking  $a$ ,

$$p_1 + \frac{m}{M} - \frac{a^2}{A^2} = 1 - \left( \frac{A-a}{A} \right)^2; \therefore p_1 = 2 \frac{a}{A} - \frac{m}{M},$$

where  $m, M$  are the moments of inertia above.

Or, we might have considered the number of cases in which the best shot fails on the element  $dS$ , viz.,  $\pi(R^2 - r^2)dS$ , where  $R$  = radius of target. This would have given the required probability

$$p_1 = \frac{R^2 a - m}{R^2 A - M};$$

which is easily shown to be identical with the above value.

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\* That is, disregarding the effect or the *aim* directing it with greater probability to the centre of the target. This would be practically correct in the case of a very bad marksman, who frequently misses the target altogether.

**250. Curve of Frequency.**—In questions relating to a variable, the probability of any value of which is a function of that value itself, it is often useful to consider what is called a *curve of frequency*. Thus, if the probability of a given value of  $x$  is proportional to  $\phi(x)$ , and we draw a curve  $y = C\phi(x)$ , then when a great number of values for  $x$  are taken, the number in any element  $dx$  is proportional to the area of the curve standing on that element; the ordinate at any point  $P$  representing the density or frequency of the points at  $P$ : the abscissas of all points taken at random in the area of the curve are equally probable.

Thus, if two points  $X, Y$  are taken at random in a straight line  $AB$ , and  $X$  means always that nearest to  $A$ , the curve of frequency for  $Y$  will be a straight line through  $A$ ; that for  $X$  a straight line through  $B$ . This will often simplify questions: e.g. suppose we have to find what is sometimes called the *most probable value* for  $AY$ , i.e. such a value  $AP$  that  $AY$  is equally likely to exceed or to fall short of it. Since the curve of frequency for  $Y$  is a line  $AC$ , we have only to find  $P$ , so that  $PD$  bisects the triangle  $ABC$ ; i.e.  $AP = \frac{AB}{\sqrt{2}}$  because as many values of  $AY$  exceed  $AP$  as fall short of it. The most probable value is not the mean value, viz.,  $\frac{2}{3} AB$ , being the horizontal distance of the centre of gravity of  $ABC$ , from  $A$ .

A point  $Y$  is taken at random in a line  $AB = a$ , and then a point  $X$  is taken at random in  $AY$  (or a rod may be supposed broken in two at random, and one of the pieces then broken in two), to find the chance of the length of  $AX$  falling within given limits.

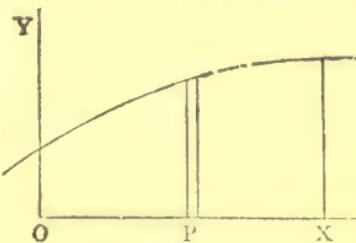


Fig. 66.

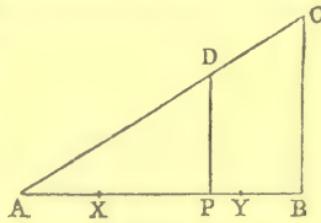


Fig. 67.

Let  $x, y$  be the distances from  $A$ ; for any assigned value of  $y$ , the chance of  $X$  falling between  $x$  and  $x + dx$  is  $\frac{dx}{y}$ ; hence the chance of  $X$  falling between  $x$  and  $x + dx$ , and of  $Y$  falling between  $y$  and  $y + dy$ , is measured by

$$\frac{dx dy}{ay};$$

hence the whole chance of  $X$  falling between  $x$  and  $x + dx$  is

$$\frac{dx}{a} \int_x^a \frac{dy}{y} = \frac{dx}{a} \log \frac{a}{x} = -dx \log x,$$

if for simplicity we put  $a = 1$ .

Thus the curve of frequency for  $X$  is a logarithmic curve  $BR$ , whose ordinate is

$$z = -\log x,$$

the frequency at  $A$  being infinitely great.

The area of this curve from 0 to  $x$  is

$$x \log \frac{e}{x};$$

and this is the probability of  $AX$  being between 0 and  $x$ ; the whole area, when  $x = 1$ , being 1, as it ought to be, since it is certain that  $X$  falls on  $AB$ . The chance of  $X$  falling between given limits  $x', x''$ , is of course

$$x' \log \frac{e}{x'} - x'' \log \frac{e}{x''}.$$

To find the *most probable* value of  $x$  we should have to solve the equation

$$x(1 - \log x) = \frac{1}{2}.$$

This gives  $x$  about one-fifth of the line  $AB$ .

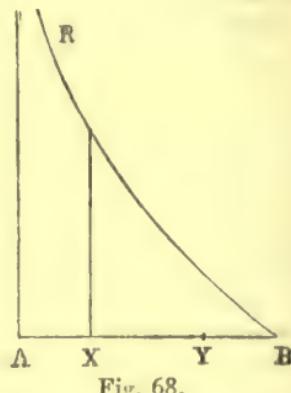


Fig. 68.

The *mean* value of  $x$  is

$$M = \frac{\int_0^1 xz \, dx}{\int_0^1 z \, dx} = \text{one-fourth of } AB.$$

This last result might have been foreseen ; because if we take a point at random in *each* of the segments  $AY$ ,  $YB$ , the line  $AB$  is divided into four parts, the mean values of which must be the same, as each of them goes through the same series of values as the others ; the sum of the mean values being  $AB$ .

#### EXAMPLES.

1. A line is divided at random, and one of the parts again divided at random as above, to find the chance that no one of the three parts shall exceed the sum of the other two (i.e. that a triangle might be formed by them.) (Cambridge *Math. Tripos*, 1854.)

The probability that  $X$ ,  $Y$  shall be taken in two assigned elements  $dx$ ,  $dy$  is (taking  $a = 1$ ),

$$\frac{dxdy}{y}.$$

This differential being integrated throughout any limits gives the sum of the probabilities of  $X$ ,  $Y$  being found in each pair of values for  $dx$  and  $dy$  which enter into the summation :—that is, the cases being mutually exclusive, the probability that  $X$ ,  $Y$  will be found in some one of those pairs.

In the present case the limits are equivalent to

$$x < \frac{1}{2} < y < 1, \quad x > y - \frac{1}{2}.$$

Hence 
$$p = \int_{\frac{1}{2}}^1 \int_{y-\frac{1}{2}}^{\frac{1}{2}} \frac{dy \, dx}{y} = \log 2 - \frac{1}{2}.$$

2. An urn contains a large number of black and white balls, the proportion of each being unknown : if on drawing  $m + n$  balls,  $m$  are found white and  $n$  black, to find the probability that the ratio of the numbers of each colour lies between given limits.

The question will not be altered if we suppose all the balls ranged in a line  $AB$ , the white ones on the left, the black on the right, the point  $X$  where they meet being unknown, and all positions for it in  $AB$  being *a priori* equally probable ; then  $m + n$  points being taken at random in  $AB$ ,  $m$  are found to fall on  $AX$ ,  $n$  on  $XB$ . That is, all we know of  $X$  is, that it is the  $(m + 1)^{\text{th}}$  in order,

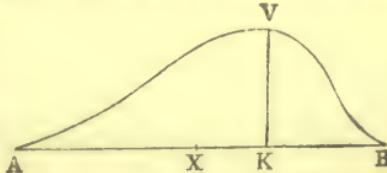


Fig. 69.

beginning from  $A$ , of  $m+n$  points falling at random on  $AB$ . If  $AX=x$ ,  $AB=1$ , the number of cases for  $X$  between  $x$  and  $x+dx$  is measured by

$$\left[ \frac{m+n}{m} \right] n x^m (1-x)^n dx. *$$

Hence the probability that the ratio of the white balls in the urn to the whole number lies between any two given limits  $\alpha, \beta$ —that is, that the distance from  $A$  of the point  $X$  lies between  $\alpha$  and  $\beta$ —is

$$p = \frac{\int_{\alpha}^{\beta} x^m (1-x)^n dx}{\int_0^1 x^m (1-x)^n dx}.$$

The *curve of frequency* for the point  $X$  will be one whose equation is

$$y = x^m (1-x)^n.$$

The maximum ordinate  $KI'$  occurs at a point  $K$  dividing  $AB$  in the ratio  $m:n$ . This is of course what we should expect: the ratio of the numbers of black and white balls is more likely to be that of the numbers drawn of each than any other. The value for  $p$  above is simply the area of the above curve between the values  $\alpha, \beta$ , of  $x$ , divided by the whole area.

Let us suppose, for instance, that 3 white and 2 black balls have been drawn; to find the chance that the proportion of white balls is between  $\frac{2}{5}$  and  $\frac{4}{5}$  of the whole—that is, that it differs by less than  $\pm \frac{1}{5}$  from  $\frac{3}{5}$ , its most natural value. Here

$$p = \frac{\int_{\frac{2}{5}}^{\frac{4}{5}} x^3 (1-x)^2 dx}{\int_0^1 x^2 (1-x)^2 dx} = \frac{2256}{5^5} = \frac{18}{25}, \text{ nearly.}$$

The above results will apply to any event that must turn out in one of two ways which are mutually exclusive, this being the whole of our *a priori* knowledge with regard to it—the ratio of the black or white balls to the whole number, meaning the real probability of either event, as would be manifested by an infinite number of trials. We will give one more example of the same kind.

3. An event has happened  $m$  times and failed  $n$  times in  $m+n$  trials. To find the probability that, on  $p+q$  further trials, it shall happen  $p$  times and fail  $q$  times.

\* For a specified set of  $m$  points, out of the  $m+n$ , falling on  $AX$ , the number is  $x^m (1-x)^n dx$ ; the number of such sets is  $\left[ \frac{m+n}{m} \right] n$ .

That is, that  $p + q$  more points being taken at random in  $AB$ ,  $p$  shall fall in  $AX$ , and  $q$  in  $BX$ . The whole number of cases is as before:

$$\frac{m+n}{m \lfloor n \rfloor} (AB)^{p+q} \int_0^1 x^m (1-x)^n dx = \frac{m+n}{m \lfloor n \rfloor} \int_0^1 x^m (1-x)^n dx.$$

When any particular set of  $p$  points, out of the  $p + q$  additional trials, falls in  $AX$ , the number of favourable cases is

$$\frac{m+n}{m \lfloor n \rfloor} \int_0^1 x^{m+p} (1-x)^{n+q} dx.$$

But the number of different sets of  $p$  points is  $\frac{1 \cdot 2 \cdot 3 \dots (p+q)}{1 \cdot 2 \cdot 3 \dots p \cdot 1 \cdot 2 \cdot 3 \dots q}$ .

Hence the probability is, putting as before  $\lfloor p \rfloor$  for  $1 \cdot 2 \cdot 3 \dots p$ ,

$$p_1 = \frac{\lfloor p+q \rfloor}{\lfloor p \rfloor \lfloor q \rfloor} \cdot \frac{\int_0^1 x^{m+p} (1-x)^{n+q} dx}{\int_0^1 x^m (1-x)^n dx}.$$

By means of the known values of these definite integrals (p. 117), we find

$$p_1 = \frac{\lfloor p+q \rfloor}{\lfloor p \rfloor \lfloor q \rfloor} \cdot \frac{\frac{m+p}{m \lfloor n \rfloor} \frac{n+q}{n \lfloor m \rfloor}}{\frac{m+n}{m \lfloor n \rfloor}} \cdot \frac{\frac{m+n+1}{m+n+p+q+1}}{\frac{m+n+p+q+1}{m+n+p+q+1}}.$$

For instance, the chance that in one further trial the event shall happen is  $\frac{m+1}{m+n+2}$ . This is easily verified, as the line  $AB$  has been divided into  $m+n+2$  sections by the  $m+n+1$  points in it, including  $X$ . Now, if one more trial is made, i.e. one more point taken at random, it is equally likely to fall in any section; and  $m+1$  sections out of the entire number are favourable.

4. Trace the curve of frequency of the ratio  $\frac{a}{b}$ ;  $a$  and  $b$  being numbers taken at random within the limits  $\pm 1$ .

If we measure the values of the ratio as abscissas along an axis  $OX$ , and make  $OA = 1$ ;  $OA' = -1$ ,  $AB = A'B' = 1$ ; then the line whose ordinates are proportional to the frequency will be, for values of  $\frac{a}{b}$  comprised between the limits  $\pm 1$ ,

the straight line  $BB'$ ; but, for values beyond these limits, will consist of the arcs  $BC$ ,  $B'C'$  of the curve  $x^2y = 1$ .

It is thus an even chance that the ratio  $\frac{a}{b}$  lies itself between the limits  $\pm 1$ : this would also appear by a construction such as that given in the next Article.

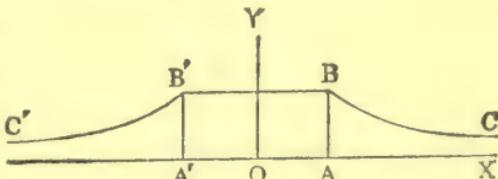


Fig. 70.

**251. Errors of Observation.**—One of the practically most important, as well as the most difficult, departments of the theory of Probability is that which treats of Errors of Observation. We will give here an example of the simplest description.

Two magnitudes  $A$  and  $B$  are measured ; each measurement being subject to an error, of excess or defect, which may amount to  $\pm a$ , all values between these limits being supposed equally probable.\* To determine the probability that the error in the sum,  $A + B$ , of the two magnitudes, shall lie within given limits ; also its mean value.

Thus the angular distance of two objects  $A$ ,  $C$  is sometimes found by measuring the angle between  $A$  and  $B$ , an intermediate object ; and afterwards that between  $B$  and  $C$ , and adding the two angles. If each measurement is liable to an error  $\pm 5'$ , all values being equally probable, to find the probability of the error of the result falling within assigned limits : its extreme limits being of course  $\pm 10'$ .

The question is more easily comprehended by means of a geometrical construction than by integration.

Take  $AB = 2a$  ; then all the values of the first error are the distances from  $O$  of points  $P$  taken at random in  $AB$  ; positive when in  $OB$  ; negative when in  $OA$ . Make also  $A'B' = 2a$  ; the values of the second error are given by points in  $A'B'$ . Take any values,  $OP = x$  for the first,  $OP' = x'$  for the second : these values taken as co-ordinates determine a point  $V$  corresponding to one case of the compound error  $x + x'$  ; and such points  $V$  will be uniformly distributed over the square  $HK$ . The value of the compound error  $\epsilon$  corresponding to the point  $V$  is

$$\epsilon = x + x' = OS,$$

if  $VS$  be drawn at  $45^\circ$  to the axes. Now all values of the

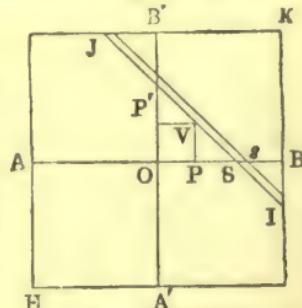


Fig. 71.

\* This supposition must not be taken to be practically correct. The Theory of Errors shows that the probability of an error of magnitude  $x$  is proportional to  $e^{-ax^2}$ .

errors  $x, x'$  which give  $x + x'$  the same value for  $\epsilon$ ; hence all points on the line  $JI$  correspond to compound errors of amount  $OS$ . Take  $Ss = d\epsilon$ ; the number of compound errors between  $\epsilon$  and  $\epsilon + d\epsilon$  is the number of points between  $JI$  and a parallel to it through  $s$ . Now the area of this infinitesimal strip is evidently

$$(2a - \epsilon) d\epsilon.$$

Hence the probability of the error being between  $\epsilon$  and  $\epsilon + d\epsilon$  is

$$p = \frac{(2a - \epsilon) d\epsilon}{4a^2}.$$

This holds for negative values of  $\epsilon$ , provided we only consider their arithmetical magnitude.

Thus the frequency of an error of magnitude  $\epsilon = OS$  is proportional to  $JI$ , the intercept of a line through  $S$  sloping at  $45^\circ$ . The probability of the error  $\epsilon$  falling between any two given limits  $OS, OS'$  is found by measuring these lengths (with their proper signs) from  $O$ , along  $AB$ , and dividing, by the area of the whole square, the area intercepted on the square by parallels through  $S$  and  $S'$ , sloping at  $45^\circ$ .

Thus the chance of the error falling between the limits  $\pm a$  (those of the two component errors) is  $\frac{3}{4}$ .

The mean value of the error, strictly speaking, is 0; but it is evident that for this purpose we ought to consider negative errors as positive; and consequently take the mean of the arithmetical values of all the errors, which is the same as the mean of the positive errors only; hence the mean error required is

$$M(\epsilon) = \pm \frac{2}{3} a.$$

The most probable value, such that it is an even chance that the error exceeds it (since the triangle  $JKI$  must be  $\frac{1}{4}$  of the whole square, for that value of  $OS$ ), is

$$\pm a(2 - \sqrt{2}) = \pm .586 a.$$

Let it be now proposed to find the probability of a given error in the sum of  $A$  and  $B$ , assuming, according to the modern theory of errors, that the probability of an error between  $x$  and  $x + dx$  in either is

$$p = \frac{1}{c \sqrt{\pi}} e^{-\frac{x^2}{c^2}} dx;$$

the coefficient  $\frac{1}{c \sqrt{\pi}}$  being determined by the necessary condition that the differential, being integrated from  $\infty$  to  $-\infty$ , must give unity, as the error must lie between these limits.\*

Referring to the above construction, the number of values of the first error between  $x$  and  $x + dx$  being proportional to

$$e^{-\frac{x^2}{c^2}} dx,$$

and the number of values of the second error between  $x'$  and  $x' + dx'$  being proportional to

$$e^{-\frac{x'^2}{c^2}} dx',$$

the corresponding number of values of the compound error is proportional to

$$e^{-\frac{x^2 + x'^2}{c^2}} dx dx'.$$

Hence the number of points, corresponding each to a case of the compound error, in any element  $dS$  of the plane at a distance  $r$  from the origin, is measured by

$$e^{-\frac{r^2}{c^2}} dS;$$

which shows that the points have the same density along any

\* It is of course absurd to consider infinite values for an error : but the

curve  $y = e^{-\frac{x^2}{c^2}}$  tends so rapidly to coincide with its asymptote, the axis of  $x$ , that the cases where  $x$  has any large values are so trifling in number, that it is indifferent whether we include them or not.

circle whose centre is  $O$ . Now the probability of this compound error being between  $\epsilon$  and  $\epsilon + d\epsilon$  is proportional to the number of points between  $JI$  and the consecutive line; making, as before,  $OS = \epsilon$ ,  $Ss = d\epsilon$ . But this number is the same as when the strip  $JI$  is turned round  $O$  through an angle of  $45^\circ$ , because the points lie in concentric circles of equal density. Hence the number is proportional to

$$e^{-\frac{\epsilon^2}{2c^2}} d\frac{\epsilon}{\sqrt{2}} \int_{-\infty}^{\infty} e^{-\frac{x^2}{c^2}} dx = \frac{c\sqrt{\pi}}{\sqrt{2}} e^{-\frac{\epsilon^2}{2c^2}} d\epsilon,$$

as the perpendicular from  $O$  on  $JI$  is  $\frac{\epsilon}{\sqrt{2}}$ .

Thus the probability of a compound error between  $\epsilon$  and  $\epsilon + d\epsilon$  is proportional to

$$e^{-\frac{\epsilon^2}{2c^2}} d\epsilon;$$

and as this, when integrated between the limits  $\pm \infty$ , must give the probability 1, the value of  $p$  is

$$p = \frac{1}{c\sqrt{2\pi}} e^{-\frac{\epsilon^2}{2c^2}} d\epsilon.$$

It thus follows the same law as the two component errors,  $c\sqrt{2}$  taking the place of  $c$ .

252. Various artifices have been employed for the solution of different interesting questions on Probability, which would be found extremely tedious, or impracticable, if attempted by direct integration. For example :

Two points are taken at random within a sphere of radius  $r$ ; to find the chance that their distance is less than a given value  $c$ .

Let  $F$  = number of favourable cases,  $W$  = whole number; then

$$p = \frac{F}{W}; \quad W = \left(\frac{4}{3} \pi r^3\right)^2.$$

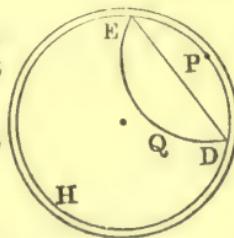


Fig. 72.

Let us consider the differential  $dF$ , or the additional favourable cases introduced by giving  $r$  the increment  $dr$ ,  $c$  remaining unchanged.

If one of the points  $A$  is taken anywhere (at  $P$ ) in the infinitesimal shell between the two spheres, then drawing a sphere with centre  $P$ , radius  $c$ , all positions of the second point,  $B$ , in the lens  $ED$  common to the two spheres, are favourable; let  $L$  = volume  $ED$ , then the number of favourable cases when  $A$  is in the shell is

$$4\pi r^2 dr \cdot L :$$

doubling this, for the cases when  $B$  is in the same shell,

$$dF = 8\pi r^3 L dr.$$

Now it may be easily proved, from the value for the volume of a segment of a sphere, that

$$L = \frac{2\pi}{3} c^3 - \frac{\pi}{4} \frac{c^4}{r};$$

hence 
$$F = 8\pi^2 \left( \frac{2}{9} c^3 r^3 - \frac{1}{8} c^4 r^2 + C \right);$$

$C$  being an unknown constant; i.e. involving  $c$ , but not  $r$ ;

therefore 
$$p = \frac{F}{\frac{16}{9} \pi^2 r^6} = \frac{c^3}{r^3} - \frac{9}{16} \cdot \frac{c^4}{r^4} + \frac{9}{2} \frac{C}{r^6}.$$

Now the probability = 1 if  $r = \frac{1}{2} c$ ;

therefore  $1 = 8 - 9 + \frac{9}{2} \times 64 \frac{C}{c^6}; \quad \therefore \frac{9}{2} C = \frac{2}{64} c^6;$

hence 
$$p = \frac{c^3}{r^3} - \frac{9}{16} \frac{c^4}{r^4} + \frac{1}{32} \frac{c^6}{r^6}.$$

If the two points be taken within a *circle*, instead of a sphere, it may be proved by a similar process that

$$p = \frac{c^2}{r^2} + \frac{2}{\pi} \left( 1 - \frac{c^2}{r^2} \right) \sin^{-1} \frac{c}{2r} - \frac{1}{4\pi} \cdot \frac{c}{r} \left( 2 + \frac{c^2}{r^2} \right) \sqrt{4 - \frac{c^2}{r^2}}.$$

It is a remarkable fact, pointed out by Mr. S. Roberts, that if we draw the chord  $ED$ , the probability in the case of the circle is.

$$p = \frac{2 \cdot \text{segment } EQD + \text{segment } EPD}{\text{area of circle } EHD};$$

and also, in the case of the sphere,

$$p = \frac{2 \cdot \text{volume } EQD + \text{volume } EPD}{\text{volume of sphere } EHD}.$$

These results evidently suggest that there must be some manner of viewing the question which would conduct to them in a direct way.

## EXAMPLES.

1. Three points being taken at random within a sphere, to find the chance that the triangle which they determine shall be acute-angled.

As the probability is independent of the radius of the sphere, it is easy to see that we may take the farthest from the centre of the three points as fixed on the surface of the sphere. For if  $p$  be the probability of an acute-angled triangle in this case,  $p$  will also be the probability of an acute-angled triangle for each position of the farthest point, as it travels over the whole volume of the sphere. Hence  $p$  will be the probability when no restriction is put on any of the points.

Take then  $A$ , one of the points on the surface of the sphere; two others,  $B, C$ , being taken at random within it, and let us find the chance of  $ABO$  being obtuse-angled: to do this, we will find separately the chance of the angles  $A, B, C$  being obtuse: the events being mutually exclusive, the probability required will be the sum of these three.

(1). To find the chance that  $A$  is obtuse, let us fix  $B$ ; then, drawing the plane  $AV$  perpendicular to  $AB$ , the chance required is

$$\frac{\text{volume of segment } AHV}{\text{volume of sphere}}.$$

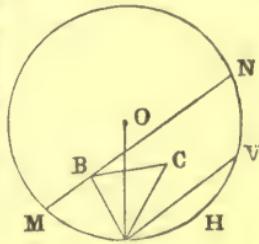


Fig. 73

Let  $r$  be the radius of sphere,  $\rho = AB$ ,  $\theta = \angle OAB$ ; then the volume of the segment  $AHV$  is

$$\frac{1}{3} \pi r^3 (1 - \cos \theta)^2 (2 + \cos \theta);$$

therefore when  $B$  is fixed the chance is

$$\frac{1}{4}(1 - \cos \theta)^2(2 + \cos \theta).$$

Now let  $B$  move over the whole volume of the sphere, and we have for  $P_A$ , the probability that  $A$  is obtuse,

$$P_A = \frac{1}{\text{sphere}} \int \int \int \frac{1}{4} (1 - \cos \theta)^3 (2 + \cos \theta) dV$$

$$= \frac{3}{8r^3} \int_0^{\frac{\pi}{2}} \int_0^{2r \cos \theta} (2 - 3 \cos \theta + \cos^3 \theta) \rho^2 \sin \theta d\theta d\rho.$$

Hence

$$P_A = \frac{3}{70}.$$

(2). To find the chance,  $P_B$ , that  $B$  is obtuse. Fix  $B$  as before; then the chance that  $B$  is acute is

$$\frac{\text{segment } MHN}{\text{sphere}}.$$

Now, volume  $MHN = \frac{1}{3}\pi r^3 \left( \frac{\rho}{r} + 1 - \cos \theta \right)^2 \left( 2 + \cos \theta - \frac{\rho}{r} \right)$ ; so that the chance is

$$\frac{1}{4} \left\{ 2 - 3 \cos \theta + \cos^3 \theta + 3 \frac{\rho}{r} (1 - \cos^2 \theta) + 3 \frac{\rho^2}{r^2} \cos \theta - \frac{\rho^3}{r^3} \right\}.$$

Hence the whole probability  $(1 - P_B)$  that  $B$  is acute is

$$\frac{3}{8r^3} \int_0^{\frac{\pi}{2}} \int_0^{2r \cos \theta} \left\{ 2 - 3 \cos \theta + \cos^3 \theta + 3 \frac{\rho}{r} (1 - \cos^2 \theta) + 3 \frac{\rho^2}{r^2} \cos \theta - \frac{\rho^3}{r^3} \right\} \rho^2 \sin \theta d\theta d\rho.$$

Performing the integrations, we find  $P_B = \frac{17}{70}$ .

The probability for  $C$  is, of course, the same as for  $B$ ; hence the whole probability of an obtuse-angled triangle is

$$P = P_A + P_B + P_C = \frac{3}{70} + \frac{17}{70} + \frac{17}{70} = \frac{37}{70}.$$

Hence, the chance of an acute-angled triangle is  $\frac{33}{70}$ .

For three points within a circle the chance of an acute-angled triangle is

$$\frac{4}{\pi^2} - \frac{1}{8}.$$

2. Two points,  $A, B$ , are taken at random in a triangle. If two other points,  $C, D$ , are also taken at random in the triangle, find the chance that they shall lie on opposite sides of the line  $AB$ .

The sides of the triangle  $ABC$  produced divide the whole triangle into seven spaces. Of these, the mean value of those marked ( $\alpha$ ) is the same, viz., the mean value of  $ABC$ ; or,  $\frac{1}{3}$  of the whole triangle, as we have shown in Art. 245; the mean value of those marked ( $\beta$ ) being  $\frac{2}{3}$  of the triangle.

This is easily seen: for instance, if the whole area = 1, the mean value of the space  $PBQ$  gives the chance that if the fourth point  $D$  be taken at random,  $B$  shall fall within the triangle  $ADC$ : now the mean value of  $ABC$  gives the chance that  $D$  shall fall within  $ABC$ ; but these two chances are equal.

Hence we see that if  $A, B, C$  be taken at random, the mean value of that portion of the whole triangle which lies on the same side of  $AB$  as  $C$  does is  $\frac{1}{8}$  of the whole; that of the opposite portion is  $\frac{7}{16}$ .

Hence the chance of  $C$  and  $D$  falling on opposite sides of  $AB$  is  $\frac{7}{12}$ .

**253. Random Straight Lines.**—If an infinite number of straight lines be drawn at random in a plane, there will be as many parallel to any one given direction as to any other, all directions being equally probable; also those having any given direction will be disposed with equal frequency all over the plane. Hence, if a line be determined by the *coordinates*,  $p, \omega$ , the perpendicular on it from a fixed origin  $O$ , and the inclination of that perpendicular to a fixed axis; and if  $p, \omega$  be made to vary by equal infinitesimal increments, the series of lines so given will represent the entire series of random straight lines. Thus the number of lines for which  $p$  falls between  $p$  and  $p + dp$ , and  $\omega$  between  $\omega$  and  $\omega + d\omega$ , will be measured by  $dpd\omega$ , and the integral

$$\iint dp d\omega,$$

between any limits, measures the number of lines within those limits.

It is easy to show from this that the number of random lines which meet any closed convex contour of length  $L$  is measured by  $L$ .

For, taking  $O$  inside the contour, and integrating first for  $p$ , from  $0$  to  $p$ , the perpendicular on the tangent to the contour, we have  $\int pd\omega$ : taking this through four right angles

for  $\omega$ , we have by Legendre's theorem (p. 232),  $N$  being the measure of the number of lines,

$$N = \int_0^2 pd\omega = L.$$

Thus if a random line meet a given contour, of length  $L$ , the chance of its also meeting another convex contour, of length  $l$ , internal to the former, is

$$p = \frac{l}{L}.$$

If the given contour be not convex, or not closed,  $N$  will evidently be the length of an endless string, drawn tight around the contour.

#### EXAMPLES.

1. If a random line meet a closed convex contour, of length  $L$ , the chance of it meeting another such contour, external to the former, is

$$p = \frac{X - Y}{L};$$

where  $X$  is the length of an endless band enveloping both contours, and crossing between them, and  $Y$  that of a band also enveloping both, but not crossing.

This may be shown by means of Legendre's integral above; or as follows:—

Call, for shortness,  $N(A)$  the number of lines meeting an area  $A$ ;  $N(A, A')$  the number which meet both  $A$  and  $A'$ ; then

$$N(SROQPH) + N(S'Q'OR'P'H') = N(SROQPH + S'Q'OR'P'H') \\ + N(SROQPH, S'Q'OR'P'H'),$$

since in the first member each line meeting *both* areas is counted twice. But the number of lines meeting the non-convex figure consisting of  $OQPHSR$  and  $OQ'S'H'P'R'$  is measured by the band  $Y$ , and the number meeting *both* these areas is identical with that of those meeting the given areas  $\Omega, \Omega'$ ; hence

$$X = Y + N(\Omega, \Omega').$$

Thus the number meeting both the given areas is measured by  $X - Y$ . Hence the theorem follows.

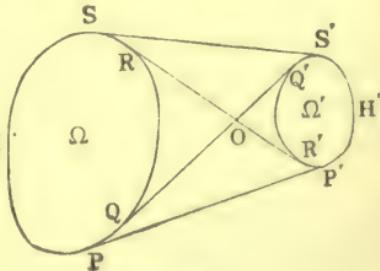


Fig. 75.

2. Two random chords cross a given convex boundary, of length  $L$  and area  $\Omega$ ; to find the chance that their intersection falls inside the boundary.

Consider the first chord in any position; let  $C$  be its length; considering it as a closed area, the chance of the second chord meeting it is

$$\frac{2C}{L};$$

and the whole chance of its co-ordinates falling in  $dp$ ,  $d\omega$ , and of the second chord meeting it in that position, is

$$\frac{2C}{L} \iint dp d\omega = \frac{2}{L^2} C dp d\omega.$$

But the whole chance is the sum of these chances for all its positions;

therefore  $\text{prob.} = \frac{2}{L^2} \int \int C dp d\omega.$

Now, for a given value of  $\omega$ , the value of  $\int C dp$  is evidently the area  $\Omega$ ; then taking  $\omega$  from  $\pi$  to 0,

$$\text{required probability} = \frac{2\pi\Omega}{L^2}.$$

The *mean value* of a chord drawn at random across the boundary is

$$M = \frac{\iint C dp d\omega}{\iint dp d\omega} = \frac{\pi\Omega}{L}.$$

3. A straight band of breadth  $c$  being traced on a floor, and a circle of radius  $r$  thrown on it at random, to find the mean area of the band which is covered by the circle. (The cases are omitted where the circle falls outside the band.)\*

If  $S$  be the space covered, the chance of a random point on the circle falling on the band is

$$p = \frac{M(S)}{\pi r^2}.$$

This is the same as if the circle were fixed, and the band thrown on it at random. Now let  $A$  be a position of the random point: the favourable cases are when  $HK$ , the *bisector of the band*, meets a circle, centre  $A$ , radius  $\frac{1}{2}c$ ; and the whole number are when  $HK$  meets a circle, centre  $O$ , radius  $r + \frac{1}{2}c$ ; hence (Art. 245) the probability is

$$p = \frac{2\pi \cdot \frac{1}{2}c}{2\pi(r + \frac{1}{2}c)} = \frac{c}{2r + c}.$$

This is constant for all positions of  $A$ ; hence, equating these two values of  $p$ , the

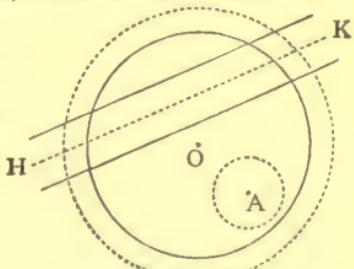


Fig. 76.

\* Or the floor may be supposed painted with parallel bands, at a distance asunder equal to the diameter; so that the circle must fall on one.

mean area required is

$$M(S) = \frac{c}{2r+c} \pi r^2.$$

The mean value of the part of the *circumference* which falls on the band is the same fraction  $\frac{c}{2r+c}$  of the whole circumference.

If any convex area  $\Omega$ , of perimeter  $L$ , be thrown on the band, instead of a circle, the mean area covered is

$$M(S) = \frac{\pi c}{L + \pi c} \Omega.$$

**254. Application to Evaluation of Definite Integrals.**—The consideration of probability sometimes may be applied to determine the values of Definite Integrals. For instance, if  $n+1$  points are taken at random in a line,  $l$ , and we consider the chance that one of them,  $X$ , shall be the last, beginning from the end  $A$  of the line, the number of favourable cases, when  $X$  is in the element  $dx$ , is, if  $AX = x$ , measured by

$$x^n dx.$$

Hence

$$p = \frac{\int_0^l x^n dx}{l^{n+1}};$$

but the chance must be  $\frac{1}{n+1}$ : we thus have an independent proof that

$$\int_0^l x^n dx = \frac{l^{n+1}}{n+1},$$

when  $n$  is an integer.

Again, if  $m+n+1$  points are taken, to find the chance that  $X$  shall be the  $(m+1)^{th}$  in order; the number of favourable cases when  $X$  falls in  $dx$  and a particular set of  $m$  points fall to the left of  $X$ , is

$$x^m (1-x)^n dx; \text{ taking } l = 1;$$

hence the whole number of favourable cases is

$$\left[ \frac{m+n}{m} \right]_0^1 x^m (1-x)^n dx;$$

this is the required probability, since  $l^{m+n+1} = 1$ . But the value is  $\frac{1}{m+n+1}$ , as every point is equally likely to fall in the  $(m+1)^{th}$  place: we thus deduce the definite integral

$$\int_0^1 x^m (1-x)^n dx = \frac{\lfloor m \rfloor \lfloor n \rfloor}{\lfloor m+n+1 \rfloor},$$

when  $m, n$  are integers. (See Art. 92.)

**255. Definite Integral deduced from Theory of Probability.**—To investigate the probability that the inclination of the line joining any two points in a given convex area  $\Omega$  shall lie within given limits.

We give here a method of reducing this question to calculation for the sake of an integral to which it leads, and which is not easily deduced otherwise.

First, let one of the points,  $A$ , be fixed; draw through it a chord  $PQ = C$ , at an inclination  $\theta$  to some fixed line; put  $AP = r$ ,  $AQ = r'$ ; then the number of cases for which the direction of the line joining  $A$  and a variable point  $B$  lies between  $\theta$  and  $\theta + d\theta$  is measured by

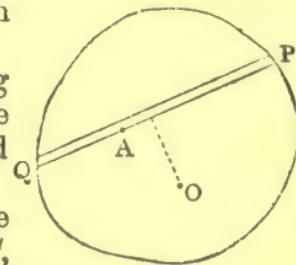
$$\frac{1}{2} (r^2 + r'^2) d\theta.$$

Next, let  $A$  range over the space between  $PQ$  and a parallel chord distant  $dp$  from it, the number of cases for which  $A$  lies in this space, and the direction of  $AB$  is between  $\theta$  and  $\theta + d\theta$ , is (first considering  $A$  to lie in the element  $drdp$ )

$$\frac{1}{2} dpd\theta \int_0^{\sigma} (r^2 + r'^2) dr = \frac{1}{3} C^3 dpd\theta.$$

Let  $p$  be the perpendicular on the chord  $C$  from any origin  $O$ , and let  $\omega$  be the inclination of  $p$  to the prime vector (we may put  $d\omega$  for  $d\theta$ ), then  $C$  will be a function of  $p, \omega$ ; and integrating first for  $\omega$  constant, the whole number of cases for which  $\omega$  falls between given limits  $\omega', \omega''$ , is

$$\frac{1}{3} \int_{\omega'}^{\omega''} d\omega \int C^3 dp;$$



the integral  $\int C^3 dp$  being taken for all positions of  $C$  between two tangents to the boundary parallel to  $PQ$ . The question is thus reduced to the evaluation of this integral; this, of course, is generally difficult enough; we may, however, deduce from it a remarkable result; for if the integral

$$\frac{1}{3} \iint C^3 dp d\omega$$

be extended to all possible positions of  $C$ , it gives the whole number of pairs of positions of the points  $A$ ,  $B$  which lie inside the area; but this number is  $\Omega^2$ ; hence

$$\iint C^3 dp d\omega = 3\Omega^2,$$

the integration extending to all possible positions of the chord  $C$ : its length being a given function of its co-ordinates  $p$ ,  $\omega$ .

Cor. Hence, if  $L$ ,  $\Omega$  be the perimeter and the area of any closed convex contour, the *mean value* of the cube of a chord drawn across it at random is  $\frac{3\Omega^2}{L}$ .

It follows that if a line cross such a contour at random, the chance that *three other lines*, also drawn at random, shall meet the first *inside the contour*, is  $24 \frac{\Omega^2}{L^4}$ .

Some other cases of definite integrals deduced from the theory of Probability are given in a paper in the *Philosophical Transactions* for 1868, pp. 181-199. See also *Proceedings of the London Math. Soc.*, vol. viii.

Several examples on Mean Values and Probability are annexed; some of them, as also some of the questions which have been explained in this chapter, are taken from the papers on the subject in the *Educational Times*, by the Editor, Mr. Miller, as also by Professor Sylvester, Mr. Woolhouse, Col. Clarke, Messrs. Watson, Savage, and others. Some few are rather difficult; but want of space has prevented our giving the solutions in the text.

We may refer to Mr. Todhunter's valuable *History of Probability* for an account of the more profound and difficult questions treated by the great writers on the theory of Probability.

## EXAMPLES.

1. A chord is drawn joining two points taken at random on a circle; find the mean area of the lesser of the two segments into which it divides the circle.

$$\text{Ans. } \frac{\pi r^2}{4} - \frac{r^2}{\pi}.$$

2. Find the mean latitude of all places north of the Equator.

$$\text{Ans. } 32^\circ.704.$$

3. Find the mean square of the velocity of a projectile *in vacuo*, taken at all instants of its flight till it regains the velocity of projection.

$$\text{Ans. } V^2 \cos^2 a + \frac{1}{2} V^2 \sin^2 a: \text{ where } V \text{ is the initial velocity, and } a \text{ is the angle of projection.}$$

4. If  $x$  and  $y$  are two variables, each of which may take independently any value between two given limits (different for each), show that the mean value of the product  $xy$  is equal to the product of the mean values of  $x$  and  $y$ .

5. If  $X, Y$  are points taken at random in a triangle  $ABC$ , what is the chance that the quadrilateral  $ABXY$  is convex?

$$\text{Ans. } \frac{1}{3}.$$

For, it is easy to see that of the three quadrilaterals  $ABXY, ACXY, BCXY$ , one must be convex, and two re-entrant.

6. Find the mean area of the quadrilateral formed by four points taken at random on the circumference of a circle.

$$\text{Ans. } \frac{3}{\pi^2} \text{ (area of circle).}$$

7. A class list at an examination is drawn up in alphabetical order; the number of names being  $n$ . If a name be selected at random, find the chance that the candidate shall not be more than  $m$  places from his place in the order of merit.

$$\text{Ans. } \frac{2m+1}{n} - \frac{m(m+1)}{n^2}. \quad (\text{N.B.---This is not, of course, the value of the chance } \text{after} \text{ the selection has been made: this may easily be found.})$$

8. A traveller starts from a point on a straight river and travels a certain distance in a random direction. Having quite lost his way, he starts again at random the next morning, and travels the same distance as before. Find the chance of his reaching the river again in the second day's journey.

$$\text{Ans. } \frac{1}{4}.$$

9. Two lengths,  $b, b'$ , are laid down at random in a line  $a$ , greater than either: find the chance that they shall not have a common part greater than  $c$ .

$$\text{Ans. } \frac{(a-b-b'+c)^2}{(a-b)(a-b')}.$$

10. A person in firing 10 shots at a mark has hit 5 times, and missed 5. Find the chance that in the next 10 shots he shall hit 5 times, and miss 5.

*Ans.*  $\frac{27 \cdot 4 \cdot 7}{19 \cdot 17 \cdot 13} = \frac{756}{4199}$ . If the first 10 shots had not been fired, so that nothing was known as to his skill, the chance would be  $\frac{1}{11}$ : if he had been found to hit the mark half the number of times out of a large number, the chance would be  $\frac{63}{256}$ .

11. If a line  $l$  be divided at random into 4 parts, the mean square of one of the parts is  $\frac{1}{16}l^2$ : but if the line be divided at random into 2 parts, and each part again divided into 2 parts, then the mean square of one of the 4 parts is  $\frac{1}{9}l^2$ .

12. Three points are taken at random in a line  $l$ . Find the mean distance of the intermediate point from the middle of the line.

$$\text{Ans. } \frac{3}{16}l.$$

13. A certain city is situated on a river. The probability that a specified inhabitant  $A$  lives on the right bank of the river is, of course,  $\frac{1}{2}$ , in the absence of any further information. But if we have found that an inhabitant  $B$  lives on the right bank, find the probability that  $A$  does so also.

*Ans.*  $\frac{2}{3}$ . (N.B.—It is here assumed that every possible partition of the number of inhabitants into 2 parts, by the river, is equally probable *a priori*.)

14.  $A, B, C, D$  are four given points *in directum*; if 2 points are taken at random in  $AD$ , and one is taken in  $BC$ , find the chance that it shall fall between the former two.

$$\text{Ans. } \frac{1}{AD^2} \left\{ \frac{1}{3} BC^2 + BC(AB + CD) + 2AB \cdot CD \right\}.$$

15. If  $z = x + y$ , where  $x$  may have any value from 0 to  $a$ , and  $y$  any value from 0 to  $b$ , find the probability that  $z$  is less than an assigned value  $c$ ; (suppose  $b < a$ ).

$$\text{Ans. (1) If } c < b, \quad p_1 = \frac{c^2}{2ab}.$$

$$(2) \text{ If } a > c > b, \quad p_2 = \frac{c - \frac{1}{2}b}{a}.$$

$$(3) \text{ If } c > a, \quad p_3 = 1 - \frac{(a + b - c)^2}{2ab}.$$

If we denote the functions expressing the probability in the three cases by  $f_1(a, b, c)$ ;  $f_2(a, b, c)$ ;  $f_3(a, b, c)$ , we shall find the relation

$$f_1(a, b, c) + f_3(a, b, c) = f_2(a, b, c) + f_2(b, a, c)$$

16. In the cubic equation

$$x^3 + px + q = 0,$$

$p$  and  $q$  may have any values between the limits  $\pm 1$ . Find the chance that the three roots are real.

$$\text{Ans. } \frac{2}{45} \sqrt{3}.$$

17. Two observations are taken of the same magnitude, and the mean of the results is taken as the true value. If the error of each observation is assumed to lie within the limits  $\pm a$ , and all its values to be equally probable, show that it is an even chance that the error in the result lies between the limits  $\pm 0.293 a$ .

18. A point is taken at random in each of two given plane areas; show that the mean square of the distance between the two points is

$$k^2 + k'^2 + \Delta^2,$$

where  $\Delta$  is the distance between the centres of gravity of the areas; and  $k, k'$ , are the radii of gyration of each area round its centre of gravity.

19. Show that the mean square of the area of the triangle formed by joining any three points taken in any given plane area is  $\frac{3}{2} h^2 k^2$ ; where  $h, k$  are the radii of gyration of the area round the two principal axes of rotation in its plane.

If one of the points is fixed at the centre of gravity, the value is  $\frac{1}{2} h^2 k^2$ . (WOOLHOUSE.)

20. A line is divided at random into 3 parts. Find the chance that they will form—(1) a triangle; (2) an acute-angled triangle.

$$\text{Ans. (1). } p_1 = \frac{1}{4}.$$

$$(2). \ p_2 = 3 \log 2 - 2.$$

21. A line is divided into  $n$  parts: find the chance that they cannot form a polygon.

$$\text{Ans. } \frac{2}{n^{n-1}}.$$

22. If two stars are taken at random in the northern hemisphere, find the chance that their distance exceeds  $90^\circ$ .

$$\text{Ans. } \frac{1}{\pi}.$$

23. The vertices of a spherical triangle are points taken at random on a sphere. Find the chance—(1) that all its angles are acute; (2) that all are obtuse.

$$\text{Ans. (1). } \frac{1}{2\pi} - \frac{1}{8}. \quad (2). \ \frac{3}{8} - \frac{1}{2\pi}.$$

24. Show that the mean value of  $\frac{1}{\rho}$ , where  $\rho$  is the distance of two points taken at random within a circle of radius  $r$ , is  $\frac{16}{3\pi r}$ .

25. Two equal lines of length  $a$  include an angle  $\theta$ : find the chance that if two points  $P, Q$  are taken at random, one on each line, their distance  $PQ$  shall be less than  $a$ .

$$Ans. (1). \text{ When } \frac{\pi}{2} > \theta > \frac{\pi}{3}; \quad p_1 = \frac{3\theta - \pi}{2 \sin \theta} + 2 \cos \theta.$$

$$(2). \text{ When } \theta > \frac{\pi}{2}; \quad p_2 = \frac{\pi - \theta}{2 \sin \theta}.$$

Here the functions are connected by the relation  $F(\theta) + F(\pi - \theta) = f(\theta) + f(\pi - \theta)$ .

26. The density of a city population varies inversely as the distance from a central point. Find the chance that two inhabitants chosen at random within a radius  $r$  from the centre shall not live further than a distance  $r$  from each other.

$$Ans. \quad p = \frac{1}{3} - \frac{1}{4} \log 3 + \frac{2}{\pi} \left( 1 - \frac{\sqrt{3}}{2} \right) + \frac{1}{2\pi} \int_0^{\frac{\pi}{2}} \frac{\theta d\theta}{\sin \theta} + \frac{3}{2\pi} \int_{\frac{\pi}{3}}^{\frac{\pi}{2}} \frac{\theta d\theta}{\sin \theta};$$

whence  $p = 0.771$ . This result is easily obtained by employing the values given in Question 25.

27. Four points are taken at random within a circle or an ellipse: show that the chance that they form a re-entrant quadrilateral is  $\frac{35}{12\pi^2}$ .

28. Find the mean distance of two points within a sphere.  $Ans. \frac{36}{35} r$ .

29. Three points  $A, B, C$  are taken within a circle whose centre is  $O$ . Find the chance that the quadrilateral  $ABCO$  is re-entrant.

$$Ans. \quad \frac{1}{4} + \frac{4}{3\pi^2}.$$

30. Find the chance that the distance of two points within a square shall not exceed a side of the square.

$$Ans. \quad p = \pi - \frac{13}{6}.$$

31. In the same case, find the chance that the distance shall not exceed an assigned value  $c$ ;  $a$  being the side of the square.

$$Ans. (1). \text{ When } c < a, \quad p = \frac{c^2}{a^4} \left( \pi a^2 - \frac{8}{3} ac + \frac{1}{2} c^2 \right).$$

$$(2). \text{ When } c > a, \quad p = 4 \frac{c^2}{a^2} \sin^{-1} \frac{a}{c} - \pi \frac{c^2}{a^2} + \frac{4}{3} \frac{2c^2 + a^2}{a^3} \sqrt{c^2 - a^2} - 2 \frac{c^2}{a^2} - \frac{c^4}{2a^4} + \frac{1}{3}.$$

32. Three points are taken at random on a sphere: show that the chance that in the spherical triangle some one angle shall exceed the sum of the other two is  $\frac{1}{2}$ . Also the chance that its area shall exceed that of a great circle is  $\frac{1}{6}$ .

33. If a line be divided at random into 4 parts, show that it is an even chance that one of the parts is greater than half the line.

34. Show that the mean distance of a point within a triangle from the vertex  $C$  is

$$\frac{1}{3} \left\{ \frac{a+b}{2} + \frac{(a-b)(a^2-b^2)}{2c^2} - \frac{h^2}{c} \log \frac{a+b+c}{a+b-c} \right\},$$

where  $h$  is the altitude of the triangle. (See Ex. 6, Art. 242.)

35. The mean value of the distance between any two points in an equilateral triangle is

$$M = \frac{3}{5} a \left( \frac{1}{3} + \frac{1}{4} \log 3 \right).$$

This question may be solved by proving that  $M = \frac{2}{3} M_0$ , where  $M_0$  is the mean distance of an angle of the triangle from any point within it. For, let  $M_0 = \mu \Delta^{\frac{1}{2}}$ , where  $\mu$  is constant, and  $\Delta$  = area of the triangle. Take now any element  $dS$  of the triangle, draw from it parallels to the sides to meet the base; let  $\delta$  be the area of the equilateral triangle so formed: the sum of the whole number of the cases will be equal to  $6 \iint \delta \mu \delta^{\frac{1}{2}} dS = M \Delta^2$ , if  $dS$  is made to range over the whole triangle: if we call the whole triangle unity, and put  $dS = 2dad\beta$  as in Ex. 3, Art. 245, then  $\delta = a^2$ , and the integral becomes  $\frac{2}{3} \mu = M$ . The result then follows from (34).

36. From a tower of height  $h$ , particles are projected in all directions in space, with a velocity due to a fall through a height  $h$ . Show that the mean value of the range is

$$M = 2h \int_0^1 \sqrt{1-x^4} dx. \quad (\text{Wolstenholme.})$$

37. If there be  $n$  quantities  $a, b, c, d \dots$ , each of which takes independently a given series of values  $a_1, a_2, a_3, \dots, b_1, b_2, b_3, \dots$  &c. (the number of values is different for each), if we put

$$\Sigma a = a + b + c + d + \dots,$$

and denote "the mean value of  $x$ " by  $Mx$ , prove that

$$M \Sigma a = Ma + Mb + Mc + \dots = \Sigma Ma,$$

$$M(\Sigma a)^2 = \Sigma (Ma)^2 - \Sigma (Ma)^2 + \Sigma M(a^2).$$

38. Two points are taken at random in a triangle: find the mean area of the triangular portion that the line joining them cuts off from the whole triangle.

$$\text{Ans. } \frac{4}{9} \text{ of the whole triangle.}$$

## CHAPTER XIII.

### ON FOURIER'S THEOREM.

256. **Expansion in Trigonometrical Series.**—In many physical investigations it is of importance to express a function  $f(x)$  in a series of sines and cosines of multiples of  $x$ . We propose to investigate the form of such expression, and the conditions under which it is possible.

Let us commence by assuming that  $f(x)$ , between the limits  $+\pi$  and  $-\pi$ , is capable of being represented by a series of the required form: thus suppose

$$f(x) = a_0 + a_1 \cos x + a_2 \cos 2x + \dots + a_n \cos nx + \dots + b_1 \sin x + b_2 \sin 2x + \dots + b_n \sin nx + \dots \quad (1)$$

Here, since this relation is supposed to hold for *all values* of  $x$  between  $\pm\pi$ , we get, as in Art. 33, on multiplying by  $\cos nx$  and integrating,

$$a_n = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \cos nx dx = \frac{1}{\pi} \int_{-\pi}^{\pi} f(v) \cos nv dv. \quad (2)$$

Also  $b_n = \frac{1}{\pi} \int_{-\pi}^{\pi} f(v) \sin nv dv,$

and  $a_0 = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(v) dv.$

Substituting in (1) it becomes

$$\begin{aligned} f(x) &= \frac{1}{2\pi} \int_{-\pi}^{\pi} f(v) dv + \frac{1}{\pi} \sum_{n=1}^{n=\infty} \cos nx \int_{-\pi}^{\pi} \cos nv f(v) dv \\ &\quad + \frac{1}{\pi} \sum_{n=1}^{n=\infty} \sin nx \int_{-\pi}^{\pi} \sin nv f(v) dv \\ &= \frac{1}{2\pi} \int_{-\pi}^{\pi} f(v) dv + \frac{1}{\pi} \sum_{n=1}^{n=\infty} \int_{-\pi}^{\pi} \cos n(v-x) f(v) dv. \quad (3) \end{aligned}$$

It should be noticed that when  $f(x)$  is an *even* function of  $x$  its development in general consists only of cosines; if  $\phi(x)$  be an *odd* function, its development contains sines only.

257. **Verification.**—We proceed to give an *a posteriori* verification of equation (3), and to examine the conditions under which it holds good.

The right-hand side of this equation may be written

$$\frac{1}{\pi} \int_{-\pi}^{\pi} f(v) dv \left( \frac{1}{2} + \cos \theta + \cos 2\theta + \dots + \cos n\theta + \&c. \right),$$

where

$$\theta = v - x.$$

But, by Trigonometry, we readily get

$$\frac{1}{2} + \cos \theta + \cos 2\theta + \dots + \cos n\theta = \frac{\sin (n + \frac{1}{2}) \theta}{2 \sin \frac{1}{2} \theta}.$$

Hence, to verify (3), it remains to prove that

$$\begin{aligned} f(x) &= \lim_{n \rightarrow \infty} \frac{1}{2\pi} \int_{-\pi}^{\pi} f(v) \frac{\sin (n + \frac{1}{2}) (v - x)}{\sin (v - x)} dv \\ &= \lim_{n \rightarrow \infty} \frac{1}{2\pi} \int_{-\frac{\pi+x}{2}}^{\frac{\pi-x}{2}} f(x + 2z) \frac{\sin (2n + 1) z}{\sin z} dz, \end{aligned} \quad (4)$$

where

$$z = \frac{1}{2} (v - x).$$

We now proceed to investigate the limiting value of the definite integral

$$\int_0^h \frac{\sin az}{\sin z} f(z) dz,$$

when  $a$  is *indefinitely great*.

First, we can see that

$$\lim_{n \rightarrow \infty} \int_g^h \sin az \phi(z) dz = 0,$$

where  $h$  and  $g$  are both positive, provided  $\phi(z)$  and  $\phi'(z)$  are

finite for all values of  $z$  between the limits of integration. For, integrating by parts, we have

$$\int \sin az \phi(z) dz = -\frac{\cos az}{a} \phi(z) + \int \phi'(z) \frac{\cos az}{a} dz.$$

Now, when  $a = \infty$ , and  $\phi(h)$ ,  $\phi(g)$  are finite, the term outside the sign of integration vanishes. Also, if  $\phi'(z)$  be finite for all values between the limits, the latter integral is also evanescent.

Consequently  $\lim_{a \rightarrow \infty} \int_g^h \sin az \phi(z) dz = 0.$  (5)

Hence  $\lim_{a \rightarrow \infty} \int_0^h \frac{\sin az}{\sin z} f(z) dz = \lim_{a \rightarrow \infty} \int_0^g \frac{\sin az}{\sin z} f(z) dz,$  (6)

provided  $h$  and  $g$  are each positive and less than  $\pi$ , and  $f(z)$  satisfies the above-mentioned conditions.

In the same case we see that

$$\int_g^h \frac{\sin az}{z} f(z) dz = 0. \quad (7)$$

Hence, with the same conditions, the values of

$$\int_0^h \frac{\sin az}{\sin z} f(z) dz \text{ and } \int_0^h \frac{\sin az}{z} f(z) dz$$

are known, if we can find their values for any one value of  $h$ , however small.

Now, when  $h$  is very small and  $f(z)$  continuous, we may assume, in general,  $f(h) = f(0),$

and therefore  $\int_0^h \frac{\sin az}{z} f(z) dz = f(0) \int_0^h \frac{\sin az}{z} dz.$

Also  $\lim_{a \rightarrow \infty} \int_0^h \frac{\sin az}{z} dz = \int_0^{ah} \frac{\sin z}{z} dz = \int_0^{\infty} \frac{\sin z}{z} dz = \frac{\pi}{2}.$

(Art. 116.)

Hence  $\lim_{a \rightarrow \infty} \int_0^h \frac{\sin az}{z} f(z) dz = \frac{\pi}{2} f(0).$  (8)

Accordingly

$$\lim_{a \rightarrow \infty} \int_0^h \frac{\sin az}{z} f(x+z) dz = \frac{\pi}{2} f(x). \quad (9)$$

Likewise,

$$\int_0^h \frac{\sin az}{\sin z} f(z) dz = \int_0^h \frac{\sin az}{z} \phi(z) dz,$$

where  $\phi(z) = \frac{z}{\sin z} f(z);$

hence, provided  $h$  is less than  $\pi$ , we have

$$\lim_{a \rightarrow \infty} \int_0^h \frac{\sin az}{\sin z} f(z) dz = \frac{\pi}{2} f(0),$$

If we change the sign of  $z$ , we have

$$\lim_{a \rightarrow \infty} \int_0^{-h} \frac{\sin az}{\sin z} f(-z) dz = -\frac{\pi}{2} f(0),$$

and we easily get

$$\lim_{a \rightarrow \infty} \int_{-b}^a \frac{\sin az}{\sin z} f(z) dz = \pi f(0), \quad (10)$$

for all positive values of  $a$  and  $b$ , less than  $\pi$ . From this it follows that

$$\lim_{n \rightarrow \infty} \int_{-\frac{\pi+x}{2}}^{\frac{\pi-x}{2}} f(x+2z) \frac{\sin(2n+1)z}{\sin z} dz = \pi f(x),$$

when  $x$  is less than  $\frac{\pi}{2}$ ; thus verifying equation (4).

258. **Poisson's Investigation.**—Another Investigation, which is a modification of that given by Poisson, is here added.

We readily see, by Trigonometry, that when  $h$  is less than unity, we have

$$\frac{1 - h^2}{1 - 2h \cos(\theta - \beta) + h^2} = 1 + 2h \cos(\theta - \beta) + 2h^2 \cos 2(\theta - \beta) + \dots + 2h^n \cos n(\theta - \beta) + \dots$$

Hence

$$\frac{1}{2} \int \frac{(1 - h^2)f(\theta) d\theta}{1 - 2h \cos(\theta - \beta) + h^2} = \frac{1}{2} \int f(\theta) d\theta + \sum_{n=1}^{\infty} \int_{\gamma}^{\delta} f(\theta) \cos n(\theta - \beta) d\theta. \quad (11)$$

$$\text{Consequently, } \frac{1}{2} \int_{\gamma}^{\delta} f(\theta) d\theta + \sum_{n=1}^{\infty} \int_{\gamma}^{\delta} f(\theta) \cos n(\theta - \beta) d\theta = \lim_{h \rightarrow 1} \frac{1}{2} \int_{\gamma}^{\delta} \frac{(1 - h^2)f(\theta) d\theta}{1 - 2h \cos(\theta - \beta) + h^2}. \quad (12)$$

But, as in Art. 234, when  $1 - h$  is indefinitely small and  $f(\theta)$  finite, the coefficient of  $d\theta$  in this integral is indefinitely small except when  $\theta - \beta$  is very small. Consequently, if  $\beta$  be outside the limits of integration, we have

$$\lim_{h \rightarrow 1} \int_{\gamma}^{\delta} \frac{(1 - h^2)f(\theta) d\theta}{1 - 2h \cos(\theta - \beta) + h^2} = 0. \quad (13)$$

Thus, when  $\beta$  is outside the limits,

$$\frac{1}{2} \int_{\gamma}^{\delta} f(\theta) d\theta + \sum_{n=1}^{\infty} \int_{\gamma}^{\delta} f(\theta) \cos n(\theta - \beta) d\theta = 0. \quad (14)$$

In particular we have

$$\frac{1}{2} \int_0^{2\pi} f(\theta) d\theta + \sum_{n=1}^{\infty} \int_0^{2\pi} f(\theta) \cos n(\theta + \beta) d\theta = 0, \quad (15)$$

where  $\beta$  is positive.

Again, if  $\beta$  lies between the limits of the integral in (12), we need only consider the portion of the integral arising from values of  $\theta$  which are indefinitely near to  $\beta$ . Accordingly, if  $f(\theta)$  be continuous,

$$\lim_{h \rightarrow 1} \int_0^{2\pi} \frac{(1 - h^2)f(\theta) d\theta}{1 - 2h \cos(\theta - \beta) + h^2} = f(\beta) \int_0^{2\pi} \frac{(1 - h^2) d\theta}{1 - 2h \cos(\theta - \beta) + h^2}$$

Again, whatever be the value of  $h$ ,

$$\begin{aligned} \int_0^{2\pi} \frac{(1-h^2) d\theta}{1-2h \cos(\theta+\beta)-h^2} &= \int_{-\beta}^{2\pi-\beta} \frac{(1-h^2) dz}{1-2h \cos z+h^2} \\ &= \int_0^{2\pi} \frac{(1-h^2) dz}{1-2h \cos z+h^2} = 2\pi. \quad (\text{Art. 18.}) \end{aligned}$$

Hence

$$\lim_{h \rightarrow 1} \int_0^{2\pi} \frac{(1-h^2) f(\theta) d\theta}{1-2h \cos(\theta-\beta)+h^2} = 2\pi f(\beta). \quad (16)$$

Consequently by (12),

$$\pi f(\beta) = \frac{1}{2} \int_0^{2\pi} f(\theta) d\theta + \sum_{n=1}^{\infty} \int_0^{2\pi} f(\theta) \cos n(\theta-\beta) d\theta. \quad (17)$$

This is usually called Fourier's theorem.

Also by aid of (15),

$$\frac{\pi}{2} f(\beta) = \sum_{n=1}^{\infty} \sin n\beta \int_0^{2\pi} f(\theta) \sin n\theta d\theta.$$

259. We shall next investigate the limit when  $a = \infty$  of the integral

$$\begin{aligned} & \int_0^a \int_a^b \phi(t) \cos ux \cos ut du dt \\ &= \frac{1}{2} \int_a^b \frac{\sin a(x-t)}{x-t} \phi(t) dt + \frac{1}{2} \int_a^b \frac{\sin a(x+t)}{x+t} \phi(t) dt \\ &= \frac{1}{2} \int_{a-x}^{b-x} \frac{\sin az}{z} \phi(z+x) dz + \frac{1}{2} \int_{a+x}^{b+x} \frac{\sin az}{z} \phi(z-x) dz. \end{aligned}$$

Now, by (7), the latter integral vanishes when  $a = \infty$  and  $x$  is positive; and by (10), when  $x$  lies between  $a$  and  $b$ , the former integral becomes  $\frac{\pi}{2} \phi(x)$ .

Also when  $x$  does not lie between  $a$  and  $b$ , the former integral vanishes, and we have

$$\int_0^{\infty} \int_a^b \phi(t) \cos ux \cos ut du dt = 0. \quad (18)$$

When  $x$  lies between  $a$  and  $b$ ,

$$\int_0^{\infty} \int_a^b \phi(t) \cos ux \cos ut du dt = \frac{\pi}{2} \phi(x). \quad (19)$$

Hence, if  $x$  be positive, we have

$$\int_0^{\infty} \int_0^{\infty} \phi(t) \cos ux \cos ut du dt = \frac{\pi}{2} \phi(x). \quad (20)$$

Likewise it is easily seen that

$$\int_0^{\infty} \int_0^{\infty} \phi(t) \sin ux \sin ut du dt = \frac{\pi}{2} \phi(x), \quad (21)$$

when  $x$  is positive.

We readily see that

$$\begin{aligned} & \int_0^{\infty} \int_{-\infty}^{\infty} \phi(t) \cos ux \cos ut du dt \\ &= \int_0^{\infty} \int_{-\infty}^{\infty} \phi(t) \sin ux \sin ut du dt = \pi \phi(x). \end{aligned} \quad (22)$$

$$\text{Also } 2\pi\phi(x) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \phi(t) \cos u(t-x) du dt, \quad (23)$$

the form in which the theorem was originally given by Fourier.

## EXAMPLES.

1. When  $x$  has any value between  $l$  and  $-l$ , prove that

$$\phi(x) = \frac{1}{2l} \int_{-l}^l \phi(v) dv + \frac{1}{l} \sum_{n=1}^{n=\infty} \int_{-l}^l \phi(v) \cos \frac{n\pi(v-x)}{l} dv.$$

2. For all values of  $x$  between 0 and  $l$ , prove that

$$\frac{1}{2} \int_0^l \phi(v) dv + \sum_{n=1}^{n=\infty} \int_0^l \phi(v) \cos \frac{n\pi(v+x)}{l} dv = 0.$$

3. For all values of  $x$  between 0 and  $l$ , prove that

$$\phi(x) = \frac{2}{l} \sum_{n=1}^{n=\infty} \sin \frac{n\pi x}{l} \int_0^l \phi(v) \sin \frac{n\pi v}{l} dv.$$

4. Prove that, for all values of  $x$  between  $+\pi$  and  $-\pi$ ,

$$\frac{1}{2}x = \sin x - \frac{1}{2} \sin 2x + \frac{1}{3} \sin 3x - \frac{1}{4} \sin 4x + \dots$$

5. For all values of  $x$  between  $\frac{\pi}{2}$  and  $-\frac{\pi}{2}$ , prove that

$$x = \frac{4}{\pi} \left( \sin x - \frac{\sin 3x}{9} + \frac{\sin 5x}{25} - \&c. \right).$$

6. Prove that

$$\frac{\pi}{2} \frac{e^{ax} - e^{-ax}}{e^{a\pi} - e^{-a\pi}} = \frac{\sin x}{a^2 + 1} - \frac{2 \sin 2x}{a^2 + 4} + \frac{3 \sin 3x}{a^2 + 9} - \&c.$$

Here (Art. 21),

$$\int_{-\pi}^{\pi} (e^{ax} - e^{-ax}) \sin nx dx = - (e^{a\pi} - e^{-a\pi}) \frac{m \cos m\pi}{a^2 + m^2}.$$

7. Find a function of  $x$  which has the value  $c$  when  $x$  lies between 0 and  $a$ , and the value zero when  $x$  lies between  $a$  and  $l$ .

$$\text{Ans. } \phi(x) = \frac{ca}{l} + \frac{2c}{\pi} \left( \sin \frac{\pi a}{l} \cos \frac{\pi x}{l} + \frac{1}{2} \sin \frac{2\pi a}{l} \cos \frac{2\pi x}{l} + \frac{1}{3} \sin \frac{3\pi a}{l} \cos \frac{3\pi x}{l} + \dots \right).$$

Here  $\int_0^l \cos \frac{n\pi v}{l} \phi(v) dv = c \int_0^a \cos \frac{n\pi v}{l} dv = \frac{cl}{n\pi} \sin \frac{n\pi a}{l}.$

8. Find a function of  $x$  which is equal to  $kx$  when  $x$  lies between 0 and  $\frac{l}{2}$ , and is  $k(l-x)$  when  $x$  lies between  $\frac{l}{2}$  and  $l$ .

$$Ans. \frac{kl}{4} - \frac{8kl}{\pi^2} \left( \frac{1}{2^2} \cos \frac{2\pi x}{l} + \frac{1}{6^2} \cos \frac{6\pi x}{l} + \frac{1}{10^2} \cos \frac{10\pi x}{l} + \dots \right).$$

Here

$$\int_0^l \phi(v) \cos \frac{n\pi v}{l} dv = \int_0^{\frac{l}{2}} kv \cos \frac{n\pi v}{l} dv + \int_{\frac{l}{2}}^l k(l-v) \cos \frac{n\pi v}{l} dv.$$

This  $= -\frac{4kl^2}{\pi^2 n^2}$  when  $n$  is of the form  $4m+2$ ; and is zero for other values of  $n$ .

9. If  $\phi(x) = \frac{1}{2}x$  when  $x$  lies between 0 and  $a$ , and  $\phi(x) = (\frac{1}{2}a)$  when  $x$  lies between  $a$  and  $\pi-a$ , and  $\phi(x) = \frac{1}{2}(\pi-x)$  when  $x$  varies from  $\pi-a$  to  $\pi$ , prove that

$$\phi(x) = \frac{1}{\pi} \left( \sin x \sin a + \frac{1}{9} \sin 3x \sin 3a + \frac{1}{25} \sin 5x \sin 5a + \dots \right).$$

10. When  $x$  lies between  $\pm \pi$ , prove the relations

$$\sin mx = \frac{2}{\pi} \sin m\pi \left( \frac{\sin x}{1-m^2} - \frac{2 \sin 2x}{2^2-m^2} + \frac{3 \sin 3x}{3^2-m^2} - \dots \right),$$

$$\cos mx = \frac{2}{\pi} \sin m\pi \left( \frac{1}{2m} + \frac{m \cos x}{1-m^2} - \frac{m \cos 2x}{2^2-m^2} + \frac{m \cos 3x}{3^2-m^2} - \dots \right).$$

11. Hence prove the relation

$$\cot u = \frac{1}{u} + \frac{2u}{u^2-\pi^2} + \frac{2u}{u^2-4\pi^2} + \dots$$

12. Find a function which shall be unity for all values of  $x$  between  $\pm 1$ , and zero for all other values of  $x$ .

$$Ans. F(x) = \frac{1}{\pi} \int_0^\infty d\mu \int_{-\infty}^{+\infty} F(\xi) \cos \mu \xi \cos \mu x d\xi = \frac{2}{\pi} \int_0^\infty d\mu \int_0^1 \cos \mu \xi \cos \mu x d\xi \\ = \frac{2}{\pi} \int_0^\infty \frac{\cos \mu x \sin \mu}{\mu} d\mu.$$

This result can be verified independently.

13. Find a function which shall be equal to  $\cos x$  for all values of  $x$  between 0 and  $\pi$ , and to  $-\cos x$  for values between  $-\pi$  and 0.

Here we easily find  $\int_{-\pi}^{\pi} f(x) \cos nx dx = 0$ ,

and we get

$$\cos x = \frac{4}{\pi} \left\{ \frac{2}{1 \cdot 3} \sin 2x + \frac{4}{3 \cdot 5} \sin 4x + \frac{6}{5 \cdot 7} \sin 6x + \dots \right\}.$$

## CHAPTER XIV.

## ON LINE AND SURFACE INTEGRALS.

260. We have already considered in Arts. 226 and 227 a general theorem, commonly called Green's theorem, that connects volume with surface integration. We now propose to consider the analogous theorem that connects integration taken over a portion of any surface with integration along the curve or curves that bound that portion of the surface—that is, which connect what are styled *surface integrals* with *line integrals*. All these relations can be shown to be based on the following elementary theorem concerning integration in a plane.

261. **Integration over a Plane Area.**—If we suppose  $P$  and  $Q$  to be real functions of  $x$  and  $y$ , that are finite and continuous for all points within a certain plane region, then we shall have

$$\iint \left( \frac{dQ}{dx} - \frac{dP}{dy} \right) dx dy = \int (P dx + Q dy), \quad (1)$$

where the double integral is taken for all points within the region, and the single integral is taken round the boundary of the region. This can be immediately deduced from the theorem given in Art. 226, by supposing the volume in question to be a portion of a cylinder intercepted between two planes drawn perpendicular to its edges, the edges being supposed parallel to the axis of  $z$ .

The theorem can be also proved independently, as follows:—

Taking the positive directions of the axes as in the accompanying figure, we define the positive direction along the boundary to be that for which the bounded surface is on the right hand; then, if we have to exclude any portion, e.g. a space without the outer boundary in the accompanying

figure, the positive direction of the boundary is that indicated by the arrows in the figure. In all the single integrals the integration must be effected in the positive direction thus defined.

First, to integrate  $\iint \frac{dQ}{dx} dx dy$  with respect to  $x$ , let us divide the region into elements by parallels to the axis of  $x$ . Select any one of these parallels, and, reading from left to right, denote the values of  $Q$ , where the line crosses the boundary at its entrances into the region, by  $Q_1, Q_2, \&c.$ , and at its exits by  $Q', Q'', \&c.$ ;

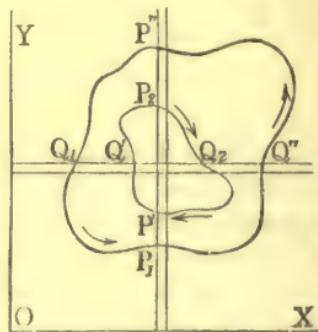


Fig. 78.

then  $\int \frac{dQ}{dx} dx = -Q_1 + Q' - Q_2 + Q'' \&c.$

and, accordingly,

$$\iint \frac{dQ}{dx} dx dy = - \int Q_1 dy + \int Q' dy - \int Q_2 dy + \int Q'' dy - \&c.$$

Now in each of these integrals  $y$  passes through all its values from the least to the greatest, therefore  $dy$  is always to be taken positively. Again, observing that in the figure the directions for the outer and inner boundaries must be taken as opposite, and denoting by  $dy_1, dy_2, \&c.$ , and by  $dy', dy'', \&c.$ , the projections on the axis of  $y$  of the arcs of the boundary cut off by the consecutive parallels as above, we have

$$dy = -dy_1 = -dy_2 = +dy' = +dy'' = \&c.;$$

thus

$$\iint \frac{dQ}{dx} dx dy = \int Q_1 dy_1 + \int Q' dy' + \int Q_2 dy_2 + \&c. = \int Q dy,$$

where the integral is taken along the entire boundary in the positive direction.

In like manner, dividing the region into elements parallel to the axis of  $y$ , and denoting the values of  $P$  at the

entrances, proceeding from below upwards, by  $P_1, P_2, \dots$ , and at the exits by  $P', P'', \dots$ , we have

$$\iint \frac{dP}{dy} dx dy = - \int P_1 dx + \int P' dx - \int P_2 dx + \dots,$$

where  $dx$  is positive. Hence, as before, taking account of the positive direction of the boundary, we have

$$dx = + dx_1 = + dx_2 = - dx' = - dx'', \dots,$$

and, consequently,

$$\iint \frac{dP}{dy} dx dy = - \int P_1 dx_1 - \int P' dx' - \int P_2 dx_2 - \dots = - \int P dx,$$

the integral being taken in the positive direction along the entire boundary. Accordingly, we have

$$\begin{aligned} \iint \left( \frac{dQ}{dx} - \frac{dP}{dy} \right) dx dy &= \int (P dx + Q dy) \\ &= \int \left( P \frac{dx}{ds} + Q \frac{dy}{ds} \right) ds, \end{aligned} \quad (2)$$

taken around the entire boundary.

We have assumed that there were no points within the region at which  $P$  or  $Q$  are discontinuous. If there were such, we should have to surround them with *closed curves*, as small as we please, and thus exclude them, by introducing these curves as parts of the boundary of the region.

**262. Stokes' Theorem.\***—Suppose  $u, v, w$  to be continuous functions of  $x, y, z$ , the coordinates of a point; and let  $dS$  be any element of a surface, and  $l, m, n$  the direction cosines of its outward drawn normal, then we shall have

$$\begin{aligned} I &= \iint dS \left\{ l \left( \frac{du}{dy} - \frac{dv}{dz} \right) + m \left( \frac{du}{dz} - \frac{dw}{dx} \right) + n \left( \frac{dv}{dx} - \frac{dw}{dy} \right) \right\} \\ &= \int (udx + vdy + wdz) = \int \left( u \frac{dx}{ds} + v \frac{dy}{ds} + w \frac{dz}{ds} \right) ds, \end{aligned} \quad (3)$$

\* This theorem was given by Professor Stokes at the Smith Prize Examination for 1854, and is of extensive application, both in the theory of "vortex motion," as also in electricity and magnetism.

the former, or *surface integral*, being taken over any portion of the surface  $S$ , and the latter, or *line-integral*, round the boundary or boundaries of the surface.

Here, from the equation of the surface, we may regard  $z$  as being a function of  $x$  and  $y$  at all points on the surface; hence, if  $p = \frac{dz}{dx}$ ,  $q = \frac{dz}{dy}$ , we have, by elementary geometry,

$$n = \frac{1}{\sqrt{1 + p^2 + q^2}}, \quad l = \frac{-p}{\sqrt{1 + p^2 + q^2}}, \quad m = \frac{-q}{\sqrt{1 + p^2 + q^2}}, \quad (4)$$

and  $dS = \sqrt{1 + p^2 + q^2} dx dy$ , (see Art. 224).

Hence we get

$$I = \iint \left( \frac{dv}{dx} - \frac{du}{dy} + p \frac{dv}{dz} - p \frac{dw}{dy} + q \frac{dw}{dx} - q \frac{du}{dz} \right) dx dy. \quad (5)$$

Again, if the *total differential* of  $v$  with respect to  $x$  be represented by  $\frac{d}{dx}(v)$ , we have

$$\frac{d}{dx}(v) = \frac{dv}{dx} + p \frac{dv}{dz}, \text{ and likewise } \frac{d}{dy}(u) = \frac{du}{dy} + q \frac{du}{dz};$$

also,

$$q \frac{dw}{dx} - p \frac{dw}{dy} = q \frac{d}{dx}(w) - p \frac{d}{dy}(w) = \frac{d}{dx}(wq) - \frac{d}{dy}(wp),$$

since

$$\frac{dp}{dy} = \frac{dq}{dx}.$$

Hence (5) becomes

$$I = \iint \left\{ \frac{d}{dx}(v + wq) - \frac{d}{dy}(u + wp) \right\} dx dy.$$

Accordingly, from (1), we get

$$\begin{aligned} I &= \iint \left\{ \frac{d}{dx}(v + wq) - \frac{d}{dy}(u + wp) \right\} dx dy \\ &= \int (udx + vdy + wdz), \end{aligned} \quad (6)$$

since  $dz = pdx + qdy$ .

This establishes the theorem in question.

263. **Example in Solid Harmonics.**—Let  $V$  be a solid harmonic (Art. 230), *i. e.* let it satisfy the equation

$$\frac{d^2 V}{dx^2} + \frac{d^2 V}{dy^2} + \frac{d^2 V}{dz^2} = 0; \quad (7)$$

then with the same notation we shall have

$$\iint \left( l \frac{d}{dx} + m \frac{d}{dy} + n \frac{d}{dz} \right) \frac{dV}{dz} dS = \int \left( \frac{dV}{dy} dx - \frac{dV}{dx} dy \right), \quad (8)$$

where the integrals, as before, are respectively taken over any portion of a surface, and along its boundary.

For, substituting

$$-\frac{d^2 V}{dx^2} - \frac{d^2 V}{dy^2} \text{ for } \frac{d^2 V}{dz^2},$$

the double integral becomes

$$\begin{aligned} & \iint \left( l \frac{d^2 V}{dzdx} + m \frac{d^2 V}{dzdy} - n \frac{d^2 V}{dx^2} - n \frac{d^2 V}{dy^2} \right) dS \\ &= - \iint \left( p \frac{d^2 V}{dzdx} + q \frac{d^2 V}{dzdy} + \frac{d^2 V}{dx^2} + \frac{d^2 V}{dy^2} \right) dx dy \\ &= - \iint \left\{ \frac{d}{dx} \left( \frac{dV}{dx} \right) + \frac{d}{dy} \left( \frac{dV}{dy} \right) \right\} dx dy \\ &= \int \left( \frac{dV}{dy} dx - \frac{dV}{dx} dy \right) = \int \left( \frac{dV}{dy} \frac{dx}{ds} - \frac{dV}{dx} \frac{dy}{ds} \right) ds. \end{aligned}$$

264. **Lemma on Solid Angles.**—If  $d\omega$  represents the elementary solid angle subtended at any external point  $P'$  by an element  $dS$  situated at a point  $P$  on a surface; then, as in Art. 193, we deduce immediately the expression

$$d\omega = \frac{\cos \gamma dS}{r^2},$$

where  $r = PP'$ , and  $\gamma$  is the angle made by  $r$  with the normal to the surface.

Again, it is obvious that the direction cosines of  $PP'$  are, respectively,

$$\frac{x-x'}{r}, \quad \frac{y-y'}{r}, \quad \frac{z-z'}{r},$$

and it follows that

$$\cos \gamma = \frac{l(x-x') + m(y-y') + n(z-z')}{r}.$$

Hence

$$d\omega = \frac{l(x-x') + m(y-y') + n(z-z')}{r^3} dS.$$

Again, since

$$r^2 = (x-x')^2 + (y-y')^2 + (z-z')^2,$$

we have

$$\frac{d}{dx} \left( \frac{1}{r} \right) = \frac{x'-x}{r^3}, \quad \frac{d}{dy} \left( \frac{1}{r} \right) = \frac{y'-y}{r^3}, \quad \frac{d}{dz} \left( \frac{1}{r} \right) = \frac{z'-z}{r^3}; \quad (9)$$

also

$$\frac{d}{dx'} \left( \frac{1}{r} \right) = -\frac{d}{dx} \left( \frac{1}{r} \right), \quad \frac{d}{dy'} \left( \frac{1}{r} \right) = -\frac{d}{dy} \left( \frac{1}{r} \right), \quad \frac{d}{dz'} \left( \frac{1}{r} \right) = -\frac{d}{dz} \left( \frac{1}{r} \right). \quad (10)$$

Hence we get

$$\begin{aligned} d\omega &= -dS \left( l \frac{d}{dx} + m \frac{d}{dy} + n \frac{d}{dz} \right) \left( \frac{1}{r} \right) \\ &= dS \left( l \frac{d}{dx'} + m \frac{d}{dy'} + n \frac{d}{dz'} \right) \left( \frac{1}{r} \right) \end{aligned} \quad (11)$$

Consequently, if  $\Omega$  be the solid angle subtended at  $P'$  by the boundary of any portion of a surface, we have

$$\begin{aligned} \Omega &= \int d\omega = - \iint dS \left( l \frac{d}{dx} + m \frac{d}{dy} + n \frac{d}{dz} \right) \left( \frac{1}{r} \right) \\ &= \iint dS \left( l \frac{d}{dx'} + m \frac{d}{dy'} + n \frac{d}{dz'} \right) \left( \frac{1}{r} \right) \end{aligned} \quad (12)$$

where the integral is taken for each element of the surface within the boundary.

265. **Differential Equations relative to Solid Angles.**—If we differentiate (12) with respect to  $z'$ , we get, since  $l, m, n$  are independent of the coordinates of  $P'$ ,

$$\begin{aligned}\frac{d\Omega}{dz'} &= \iint dS \left( l \frac{d}{dx'} + m \frac{d}{dy'} + n \frac{d}{dz'} \right) \frac{d}{dz'} \left( \frac{1}{r} \right) \\ &= \iint dS \left( l \frac{d}{dx} + m \frac{d}{dy} + n \frac{d}{dz} \right) \frac{d}{dz} \left( \frac{1}{r} \right) \\ &= \left( dx \frac{d}{dy} \left( \frac{1}{r} \right) - dy \frac{d}{dx} \left( \frac{1}{r} \right) \right),\end{aligned}\quad (13)$$

by (8), since  $\frac{1}{r}$  satisfies equation (7).

Again, by (10),

$$\int dy \frac{d}{dx} \left( \frac{1}{r} \right) = - \int dy \frac{d}{dx'} \left( \frac{1}{r} \right) = - \left( \frac{d}{dx'} \right) \int \frac{dy}{r},$$

and likewise

$$\int dx \frac{d}{dy} \left( \frac{1}{r} \right) = - \left( \frac{d}{dy'} \right) \int \frac{dx}{r},$$

and  $\int dz \frac{d}{dx} \left( \frac{1}{r} \right) = - \frac{d}{dx'} \int \frac{dz}{r},$

in which the integrals

$$\int \frac{dx}{r}, \quad \int \frac{dy}{r}, \quad \int \frac{dz}{r}$$

are supposed taken round the entire *circuit* that bounds the solid angle.

If we now put

$$F = \int \frac{dx}{r}, \quad G = \int \frac{dy}{r}, \quad H = \int \frac{dz}{r}, \quad (14)$$

and suppose  $F, G, H$  to denote *line-integrals* taken round the

circuit, or boundary, we get, from (13), and the analogous equations,

$$\left. \begin{aligned} \frac{d\Omega}{dx'} &= \frac{dH}{dy'} - \frac{dG}{dz'} \\ \frac{d\Omega}{dy'} &= \frac{dF}{dz'} - \frac{dH}{dx'} \\ \frac{d\Omega}{dz'} &= \frac{dG}{dx'} - \frac{dF}{dy'} \end{aligned} \right\}. \quad (15)$$

266. **Neumann's Theorem.**—If we suppose the point  $x'y'z'$  to be taken on any surface  $S'$ , and if  $dS'$  be the element of the surface at the point; also, if  $l'm'n'$  be the direction cosines of the normal at  $P'$ , we get

$$\begin{aligned} &\int \left( l' \frac{d\Omega}{dx'} + m' \frac{d\Omega}{dy'} + n' \frac{d\Omega}{dz'} \right) dS' \\ &= \int \left\{ l' \left( \frac{dH}{dy'} - \frac{dG}{dz'} \right) + m' \left( \frac{dF}{dz'} - \frac{dH}{dx'} \right) + n' \left( \frac{dG}{dx'} - \frac{dF}{dy'} \right) \right\} dS'. \end{aligned}$$

Hence, by (3), we have

$$\begin{aligned} &\int dS' \left( l' \frac{d}{dx'} + m' \frac{d}{dy'} + n' \frac{d}{dz'} \right) \Omega \\ &= \int \left( F \frac{dx'}{ds'} + G \frac{dy'}{ds'} + H \frac{dz'}{ds'} \right) ds', \quad (16) \end{aligned}$$

where the former integral is taken over any portion of  $S'$ , and the latter round the boundary.

If now we substitute for  $F$ ,  $G$ ,  $H$ , and  $\Omega$  their values as given in (12) and (14), the preceding equation becomes

$$\begin{aligned} &\iint dS dS' \left( l' \frac{d}{dx'} + m' \frac{d}{dy'} + n' \frac{d}{dz'} \right) \left( l \frac{d}{dx} + m \frac{d}{dy} + n \frac{d}{dz} \right) \left( \frac{1}{r} \right) \\ &= \iint \frac{1}{r} \left( \frac{dx}{ds} \frac{dx'}{ds'} + \frac{dy}{ds} \frac{dy'}{ds'} + \frac{dz}{ds} \frac{dz'}{ds'} \right) ds ds', \quad (17) \end{aligned}$$

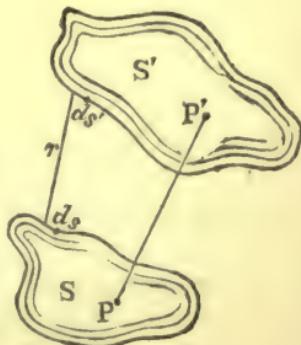


Fig. 79.

where the former integral is taken for all elements on both the surface regions, and the latter along the boundaries of the regions.

The latter integral may be written

$$\iint \frac{\cos \epsilon}{r} ds ds',$$

where  $\epsilon$  is the angle between the directions of the tangents to  $ds$  and  $ds'$ .

The foregoing, when interpreted in the theory of magnetism, leads to Neumann's theorem connecting the energy of electric currents with that of magnetic shells. See Clerk Maxwell's "Electricity and Magnetism," vol 2, § 637.

We shall conclude with the consideration of two or three surface integrals taken over a sphere, which are of great importance in the theory of attraction.

**267. Integrals over a Spherical Surface**—We commence with the determination of the single integral  $\int \frac{dS}{\rho}$ , where  $dS$  is an element

of a spherical surface at any point  $P$ , and  $\rho$  is the distance of  $P$  from any fixed point  $O$ .

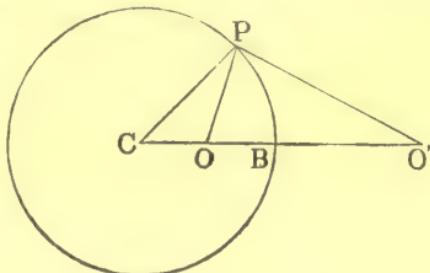


Fig. 80.

Let  $\angle PCO = \theta$ ,  $CP = a$ ,  $CO = f$ ;

then we have

$$\rho^2 = a^2 + f^2 - 2af \cos \theta;$$

therefore

$$\rho d\rho = af \sin \theta d\theta. \quad (18)$$

Again, as in Art. 230, we may write

$$dS = a^2 \sin \theta d\theta d\phi,$$

where  $\phi$  is the angle that the plane  $OCP$  makes with a fixed plane passing through  $OC$ .

Accordingly

$$\int \frac{dS}{\rho} = a^2 \iint \frac{\sin \theta d\theta d\phi}{\rho}.$$

Again, since  $\rho$  is independent of  $\phi$ ,

$$a^2 \iint \frac{\sin \theta d\theta d\phi}{\rho} = 2\pi a^2 \int \frac{\sin \theta d\theta}{\rho} = 2\pi \frac{a}{f} \int d\rho, \text{ by (17).}$$

Hence, (1°), when  $O$  is inside the sphere, since the limits for  $\rho$  are  $a - f$  and  $a + f$ , we have

$$\int \frac{dS}{\rho} = 4\pi a, \quad (19)$$

or the expression is constant in this case.

(2°) When the point is outside the sphere, we get

$$\int \frac{dS}{\rho} = \frac{4\pi a^2}{f} = \frac{\text{surface of sphere}}{CO}. \quad (20)$$

These show that a homogeneous sphere attracts an external mass as if the whole mass of the sphere was concentrated at its centre. Also, that a homogeneous spherical shell exerts no attraction at an internal point (Williamson and Tarleton's *Dynamics*, Art. 126).

In general we have

$$\int \frac{dS}{\rho^n} = 2\pi \frac{a}{f} \int \frac{d\rho}{\rho^{n-1}}.$$

Hence, when  $O$  is inside the surface,

$$\int \frac{dS}{\rho^n} = \frac{2\pi}{n-2} \frac{a}{f} \frac{1}{(a^2 - f^2)^{n-2}} \left\{ (a+f)^{n-2} - (a-f)^{n-2} \right\}, \quad (21)$$

and, when  $O$  is outside,

$$\int \frac{dS}{\rho^n} = \frac{2\pi}{n-2} \frac{a}{f} \frac{1}{(f^2 - a^2)^{n-2}} \left\{ (a+f)^{n-2} - (f-a)^{n-2} \right\}.$$

Also, if  $\phi(\rho)$  be any function of  $\rho$ , we have

$$\int dS \phi(\rho) = 2\pi \frac{a}{f} \int_{a-f}^{a+f} \rho \phi(\rho) d\rho. \quad (22)$$

It may be observed that we can take the point from which  $\rho$  is measured either inside or outside the surface according to pleasure; for, if  $O$  and  $O'$  are inverse points, *i.e.* if  $CO : CB = CB : CO'$ , the triangles  $C O' P$  and  $C P O$  are similar, and therefore  $PO : PO' = CO : CP$ . Consequently the ratio  $PO : PO'$  is the same for all points on the sphere.

268. **Theorem of Lord Kelvin.**—Again, to find the integral

$$V = \int \frac{dS}{OP_1^3 O_1 P_1}$$

taken over the surface of a sphere, where  $P_1$  is a point on the surface, and  $O$  and  $O_1$  are any two fixed points.

We may take one of these points inside, and the other outside the surface; since, as shown above, the ratio of the distances of two *inverse* points from any point on the surface of the sphere is constant.

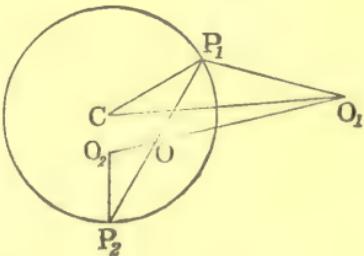
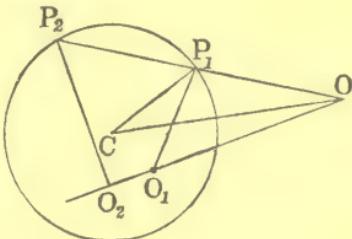
Produce  $OP_1$  to meet the surface again in  $P_2$ , and take  $O_2$  on  $OO_1$ , such that  $OO_1 \cdot OO_2 = OP_1 \cdot OP_2 = f^2 - a^2$ , where  $f = CO$ , as before.

Now, let  $OP_1 = r$ ,  $O_1 P_1 = \rho$ ,  $OP_2 = r_1$ ,  $P_2 O_2 = \rho_1$ ; and let  $dS'$  be the indefinitely small element at  $P_2$  intercepted by the cone whose vertex is at  $O$ , and which passes through the element  $dS$ ; then, it is immediately seen that we have

$$\frac{dS}{r^2} = \frac{dS'}{r_1^2}; \quad (23)$$

therefore

$$V = \int \frac{dS}{r^3 \rho} = \int \frac{dS'}{rr_1^2 \rho} = \frac{1}{f^2 - a^2} \int \frac{dS'}{r_1 \rho}.$$



Figs. 81 and 82.

Again, since the triangles  $P_2O_2O$ , and  $O_1P_1O$  are equiangular, we have

$$OP_2 : P_2O_2 = OO_1 : O_1P_1;$$

therefore

$$\rho r_1 = OO_1 \rho_1. \quad (24)$$

Accordingly,

$$V = \frac{1}{f^2 - a^2} \cdot \frac{1}{OO_1} \int \frac{dS'}{\rho_1}.$$

Hence, since  $O_2$  is inside the sphere, we see by (19), that

$$V = \frac{4\pi a}{f^2 - a^2} \cdot \frac{1}{OO_1}. \quad (25)$$

The preceding is a modification of Lord Kelvin's proof of his well-known theorem on the distribution of electricity on spherical conductors (*Cambridge and Dublin Mathematical Journal*, 1848; also Thomson and Tait's *Natural Philosophy*, vol. II., § 474).

More generally, if  $m + n = 4$ , we see by the preceding that, taking  $O$  inside,

$$\begin{aligned} V &= \int \frac{dS}{r^m \rho^n} = \int \frac{dS'}{r^{m-2} r_1^2 \rho^n} \\ &= \frac{(a^2 - f^2)^{n-2}}{(OO_1)^n} \int \frac{dS'}{\rho_1^n}. \end{aligned} \quad (26)$$

This can be immediately expressed by aid of (21).

## CHAPTER XV.

## ON THE SIGN OF SUBSTITUTION.

269. **Sign of Substitution.**—It is proposed in this chapter to give a short discussion on a symbol, called the sign of substitution, which was first introduced into analysis by Sarrus, in his *Recherches sur le Calcul des Variations*.\*

Let  $V$  represent any function of  $x$ , with or without other variables; then, if a particular value  $x_1$  be substituted for  $x$  in  $V$ , the result of the substitution is denoted by the symbol

$$\left| \begin{array}{c} x_1 \\ x_0 \end{array} \right| V.$$

Again, the difference between the values of  $V$ , when  $x = x_1$  and when  $x = x_0$  is denoted by  $\left| \begin{array}{c} x_1 \\ x_0 \end{array} \right| V$ .

That is  $\left| \begin{array}{c} x_1 \\ x_0 \end{array} \right| V - \left| \begin{array}{c} x_0 \\ x_0 \end{array} \right| V = \left| \begin{array}{c} x_1 \\ x_0 \end{array} \right| V.$  (1)

For instance, equation (31) in Art. 31, may be written in the following form:—

$$\int_{x_0}^{x_1} \frac{du}{dx} dx = \left| \begin{array}{c} x_1 \\ x_0 \end{array} \right| u. \quad (2)$$

Again, if  $V$  be a function of  $x$  and  $y$ , then the result of substituting  $x_1$  for  $x$ , and  $y_1$  for  $y$ , in  $V$  is denoted by

$$\left| \begin{array}{c} x_1 \\ y_1 \end{array} \right| V:$$

and so on for additional variables.

\* This memoir was awarded the prize offered in 1846 by the Academy of Science of Paris, for an essay on the treatment of maxima and minima values of Multiple Integrals. In the discussion here given, the form of the symbol as given in Moigno and Lindelhöf's *Calcul des Variations* has been adopted.

Also, the notation  $\begin{vmatrix} x_1 \\ x_0 \end{vmatrix} \begin{vmatrix} y_1 \\ y_0 \end{vmatrix} V$  signifies— $1^\circ$ , that  $y$  is re-

placed in  $V$  by the particular values  $y_1$  and  $y_0$ , respectively: then that the latter result is subtracted from the former;  $2^\circ$ , in the result thus obtained the values  $x_1$  and  $x_0$  are respectively substituted for  $x$ , and the results subtracted as before.

When written in full, this gives

$$\begin{vmatrix} x_1 \\ x_0 \end{vmatrix} \begin{vmatrix} y_1 \\ y_0 \end{vmatrix} V = \begin{vmatrix} x_1 \\ x_0 \end{vmatrix} \left( \begin{vmatrix} y_1 \\ y_0 \end{vmatrix} V - \begin{vmatrix} y_0 \\ y_0 \end{vmatrix} V \right) \\ = \begin{vmatrix} x_1 \\ x_1 \end{vmatrix} \begin{vmatrix} y_1 \\ y_0 \end{vmatrix} V - \begin{vmatrix} x_1 \\ y_0 \end{vmatrix} V - \begin{vmatrix} x_0 \\ y_1 \end{vmatrix} V + \begin{vmatrix} x_0 \\ y_0 \end{vmatrix} V. \quad (3)$$

This admits also of being written as the symbolic product

$$\begin{vmatrix} x_1 \\ x_0 \end{vmatrix} \begin{vmatrix} y_1 \\ y_0 \end{vmatrix} V = \left( \begin{vmatrix} x_1 \\ x_0 \end{vmatrix} - \begin{vmatrix} x_0 \\ x_0 \end{vmatrix} \right) \left( \begin{vmatrix} y_1 \\ y_0 \end{vmatrix} - \begin{vmatrix} y_0 \\ y_0 \end{vmatrix} \right) V. \quad (4)$$

These results can be easily extended to three or more variables.

**270. Differentiation under the Sign of Substitution.**—Again, suppose  $V$  to be a function of the variables  $x$  and  $a$ , represented by the equation

$$V = f(x, a);$$

then we have  $\begin{vmatrix} x_1 \\ x_0 \end{vmatrix} V = f(x_1, a).$

If now  $x_1$  be a function of  $a$ , we have

$$\begin{aligned} \frac{d}{da} \begin{vmatrix} x_1 \\ x_0 \end{vmatrix} V &= \frac{df(x_1, a)}{da} + \frac{df(x_1, a)}{dx_1} \frac{dx_1}{da} \\ &= \begin{vmatrix} x_1 \\ \frac{dV}{da} + \frac{dV}{dx} \frac{dx}{da} \end{vmatrix}; \end{aligned}$$

hence

$$\frac{d}{da} \begin{vmatrix} x_1 \\ x_0 \end{vmatrix} V = \begin{vmatrix} x_1 \\ x_0 \end{vmatrix} \left( \frac{dV}{da} + \frac{dV}{dx} \frac{dx}{da} \right). \quad (5)$$

Accordingly in such cases we differentiate under the sign of substitution as if  $x$  were a function of  $a$ .

For instance, if  $V$  be a function of  $x$  and  $y$ , and if  $y_0, y_1$  be both functions of  $x$ , we may write

$$\frac{d}{dx} \left|_{y_0}^{y_1} V \right. = \left|_{y_0}^{y_1} \left( \frac{dV}{dx} + \frac{dV}{dy} \frac{dy}{dx} \right) \right..$$

Hence

$$\frac{d}{dx} \left|_{y_0}^{y_1} V \frac{dy}{dx} \right. = \left|_{y_0}^{y_1} \left( V \frac{d^2y}{dx^2} + \frac{dy}{dx} \frac{dV}{dx} + \left( \frac{dy}{dx} \right)^2 \frac{dV}{dy} \right) \right.. \quad (6)$$

If now this equation be integrated between the limits  $x_1$  and  $x_0$ , we get

$$\left|_{x_0}^{x_1} \left|_{y_0}^{y_1} V \frac{dy}{dx} \right. \right. = \int_{x_0}^{x_1} \left|_{y_0}^{y_1} \left( V \frac{d^2y}{dx^2} + \frac{dy}{dx} \frac{dV}{dx} + \left( \frac{dy}{dx} \right)^2 \frac{dV}{dy} \right) dx \right.. \quad (7)$$

**271. Differentiation under the Sign of Integration.**—Let  $u = \int_{x_0}^{x_1} v dx$ , in which  $v, x_1$  and  $x_0$  are all functions of  $a$ : then, by (33) Art. 114, we have

$$\frac{du}{da} = \int_{x_0}^{x_1} \frac{dv}{da} dx + \left|_{x_0}^{x_1} v \frac{dx}{da} \right.. \quad (8)$$

For instance if  $u = \int_{y_0}^{y_1} v dy$ , where  $v, y_1$ , and  $y_0$  are functions of  $x$ , we have

$$\frac{du}{dx} = \int_{y_0}^{y_1} \frac{dv}{dx} dy + \left|_{y_0}^{y_1} v \frac{dy}{dx} \right..$$

Now if both sides of this equation be integrated with respect to  $x$  between the limits  $x_1$  and  $x_0$ , we get

$$\left|_{x_0}^{x_1} u \right. = \int_{x_0}^{x_1} \int_{y_0}^{y_1} \frac{dv}{dx} dx dy + \int_{x_0}^{x_1} \left|_{y_0}^{y_1} v \frac{dy}{dx} \right..$$

Hence, transposing and substituting for  $u$ ,

$$\int_{x_0}^{x_1} \int_{y_0}^{y_1} \frac{dv}{dx} dx dy = \left| \int_{x_0}^{x_1} \int_{y_0}^{y_1} v dy - \int_{x_0}^{x_1} \left| \int_{y_0}^{y_1} v \frac{dy}{dx} dx \right. \right|. \quad (9)$$

Also, since

$$\int_{y_0}^{y_1} \frac{du}{dy} dy = \left| \int_{y_0}^{y_1} u \right|,$$

we get

$$\int_{x_0}^{x_1} \int_{y_0}^{y_1} \frac{du}{dy} dx dy = \int_{x_0}^{x_1} \left| \int_{y_0}^{y_1} u dx \right|. \quad (10)$$

If (9) and (10) be added, we have

$$\int_{x_0}^{x_1} \int_{y_0}^{y_1} \left( \frac{dv}{dx} + \frac{du}{dy} \right) dx dy = \left| \int_{x_0}^{x_1} \int_{y_0}^{y_1} v dy + \int_{x_0}^{x_1} \left| \int_{y_0}^{y_1} \left( u - v \frac{dy}{dx} \right) dx \right. \right|. \quad (11)$$

**272. Differentiation for a Double Integral.—**  
Next, let

$$V = \int_{x_0}^{x_1} \int_{y_0}^{y_1} u dx dy,$$

where  $u$ ,  $y_1$ ,  $y_0$ ,  $x_1$ , and  $x_0$  are all functions of  $a$ , to find  $\frac{dV}{da}$ .

$$\text{Let } U = \int_{y_0}^{y_1} u dy, \quad \text{then } V = \int_{x_0}^{x_1} U dx.$$

Also, by (8),

$$\frac{dV}{da} = \int_{x_0}^{x_1} \frac{dU}{da} dx + \left| \int_{x_0}^{x_1} U \frac{dx}{da} \right|;$$

$$\text{but } \frac{dU}{da} = \int_{y_0}^{y_1} \frac{du}{da} dy + \left| \int_{y_0}^{y_1} u \frac{dy}{da} \right|,$$

hence, finally,

$$\frac{dV}{da} = \int_{x_0}^{x_1} \int_{y_0}^{y_1} \frac{du}{da} dx dy + \int_{x_0}^{x_1} \left| \int_{y_0}^{y_1} u \frac{dy}{da} dx \right| + \int_{x_0}^{x_1} \frac{dy}{da} \int_{y_0}^{y_1} u dy. \quad (12)$$

## EXAMPLES.

1. Find the value of  $\frac{d^2u}{da^2}$ , where  $u = \int_{x_0}^{x_1} v dx$ , where  $x_1$  and  $x_0$  are functions of  $a$ .

Here, by (6) and (8), we readily get

$$\frac{d^2}{da^2} \int_{x_0}^{x_1} v dx = \int_{x_0}^{x_1} \frac{d^2v}{da^2} dx + \left|_{x_0}^{x_1} \left\{ v \frac{d^2x}{da^2} + 2 \frac{dv}{da} \frac{dx}{da} + \frac{dv}{dx} \left( \frac{dx}{da} \right)^2 \right\} \right|.$$

2. Prove that

$$\frac{d}{da} \int_{x_0}^{x_1} \left|_{y_0}^{y_1} u dx \right. = \int_{x_0}^{x_1} \left|_{y_0}^{y_1} \left( \frac{du}{da} + \frac{du}{dy} \frac{dy}{da} \right) dx \right. + \left|_{x_0}^{x_1} \left|_{y_0}^{y_1} u \frac{dx}{da} \right. \right|,$$

where  $u$  is a function of  $x$ ,  $y$ , and  $a$ ; and  $y_1$ ,  $y_0$ ,  $x_1$  and  $x_0$  are functions of  $a$ .

3. Show that

$$\left|_{x_0}^{x_1} \int_{y_0}^{y_1} \left|_{z_0}^{z_1} V dy \right. \right. = \left|_{x_0}^{x_1} \int_{y_0}^{y_1} \left|_{z_0}^{z_1} \left|_{x_0}^{x_1} V dy \right. \right. \right|,$$

where  $V$  is a function of  $x$ ,  $y$ , and  $z$ ; and where  $z_1$ ,  $z_0$ ,  $y_1$  and  $y_0$  are functions of  $x$ .

273. **Geometrical Representation.**—The results given in Art. 271 admit of a simple geometrical representation.

For, if we suppose  $x$  and  $y$  to be the coordinates of a point referred to a system of axes  $OX$  and  $OY$ : then, since  $y_1$  and  $y_0$  are by hypothesis functions of  $x$ , the equation  $y = y_0$  may be represented by a curve  $AC$ , and  $y = y_1$  by a curve  $BD$ . Also, the equations  $x = x_0$ ,  $x = x_1$  are represented by two lines,  $AB$  and  $CD$ , parallel to the axis of  $y$ .

Consequently, the area  $ABDCA$  represents the space over which the double integral is extended.

It can now be readily seen that the right-hand side in equation (9) represents the value of the integral

$$-\int v dy,$$

taken around the entire boundary  $ABDCA$  in the direction indicated by the arrow-heads.

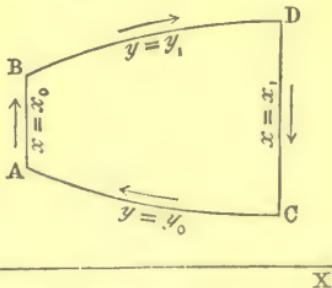


Fig. 83.

For, writing the expression in the expanded form

$$\left| \int_{y_0}^{y_1} v dy - \left| \int_{y_0}^{y_1} v dy - \int_{x_0}^{x_1} \left| v \frac{dy}{dx} dx + \int_{x_0}^{x_1} \left| v \frac{dy}{dx} dx, \right. \right. \right. \right.$$

and observing that

$$\left| \int_{y_0}^{y_1} v dy = \int_{y_0}^{y_1} \left| v dy, \right. \right.$$

we see that

$$\left| \int_{y_0}^{y_1} v dy = - \int v dy \right.$$

taken along  $DC$  from  $D$  to  $C$ . In like manner,

$$\left| \int_{y_0}^{y_1} v dy = - \int v dy \right.$$

taken along  $AB$ .

Again, we readily see that

$$\left. - \int_{x_0}^{x_1} \left| v \frac{dy}{dx} dx = - \int v dy \right. \right.$$

taken along  $BD$ , and also

$$\left. \int_{x_0}^{x_1} \left| v \frac{dy}{dx} dx = - \int v dy \right. \right.$$

taken along  $CA$ , from  $C$  to  $A$ .

This agrees with the result given in Art. 216, provided we observe that the integration round the boundary is here taken in the *opposite direction to that adopted* in the Article referred to.

In like manner, the right-hand side in equation (10) represents the value of  $\int u dx$  taken around the same boundary  $ABCDA$ . For

$$\left. \int_{x_0}^{x_1} \left| v \frac{dy}{dx} dx = \int u dx \right. \right.$$

taken along  $BD$ , from  $B$  to  $D$ , and

$$-\int_{x_0}^{x_1} \left| \begin{array}{c} y_0 \\ u \end{array} \right| u dx = \int u dx$$

taken along  $CA$ , from  $C$  to  $A$ . Hence the result follows, since  $x$  is constant along  $AB$  and  $DC$ .

Combining these results, we see, as in Art. 261, that

$$\iint \left( \frac{du}{dy} + \frac{dv}{dx} \right) dx dy = \int (u dx - v dy), \quad (13)$$

when taken round the entire boundary in the direction stated above.

**274. Case of a Closed Curvilinear Boundary.**—In many cases the double integral is taken for all points within a closed curvilinear boundary, represented by an equation of the form

$$y = \phi(x).$$

In such cases the lines  $AB$  and  $CD$  disappear, and consequently we have  $y_1 = y_0$  when  $x = x_1$ , and also when  $x = x_0$ : hence

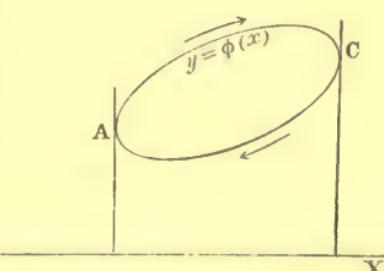


Fig. 84.

$$\left| \int_{y_0}^{y_1} v dy \right| = 0, \quad \text{and} \quad \left| \int_{x_0}^{x_1} \int_{y_0}^{y_1} v dy dx \right| = 0.$$

In this case, equation (9) becomes

$$\int_{x_0}^{x_1} \int_{y_0}^{y_1} \frac{dv}{dx} dx dy = - \int_{x_0}^{x_1} \left| \begin{array}{c} y_1 \\ v \end{array} \right| \frac{dy}{dx} dx = - \int_{x_0}^{x_1} v \frac{dy}{dx} dx, \quad (14)$$

where  $x_1$  and  $x_0$  are the extreme values for the boundary, and the value of  $\frac{dy}{dx}$  is obtained from its equation.

In this case equation (11) may be written

$$\iint \left( \frac{du}{dy} + \frac{dv}{dx} \right) dx dy = \int \left( u - v \frac{dy}{dx} \right) dx, \quad (15)$$

where the double integral is taken for all points in the area inclosed by the boundary, and the single integral is taken round the boundary in the direction indicated by the arrow-heads. The value of  $\frac{dy}{dx}$  is found, as stated before, from the equation of the bounding curve. Thus if this be denoted by  $y = \phi(x)$ , then  $\frac{dy}{dx} = \phi'(x)$ , for all points on the boundary.

It should be observed that the equation  $y = \phi(x)$  really represents a cylindrical surface, and that the actual bounding curve is *some curve traced on this cylinder*.

Likewise, in Art. 273, the boundary consists of two cylindrical surfaces,  $y = y_0$  and  $y = y_1$ , along with the planes,  $x = x_0$  and  $x = x_1$ ; and consequently the bounding curve is limited in like manner.

It may be observed that equations (15) and (13) may be written also in the form

$$\iint \left( \frac{du}{dy} + \frac{dv}{dx} \right) dx dy = \int \left( u \frac{dx}{ds} - y \frac{dy}{ds} \right) ds, \quad (16)$$

where  $ds$  is an element of the boundary, which may consist of a single or of several curves.

The modification to be made in the foregoing results, when the integral is taken between an inner and an outer boundary, is readily seen, as stated in Art. 261.

Again, if we substitute  $PQ$  for  $u$  in (10), we get

$$\int_{x_0}^{x_1} \int_{y_0}^{y_1} P \frac{dQ}{dy} dx dy = \int_{x_0}^{x_1} \left| \int_{y_0}^{y_1} PQ dx \right| - \int_{x_0}^{x_1} \int_{y_0}^{y_1} Q \frac{dP}{dy} dx dy. \quad (17)$$

If the same substitution be made in (9) we have

$$\int_{x_0}^{x_1} \int_{y_0}^{y_1} P \frac{dQ}{dx} dx dy = \left[ \int_{x_0}^{x_1} \int_{y_0}^{y_1} PQ dy - \int_{x_0}^{x_1} \left| \int_{y_0}^{y_1} PQ \frac{dy}{dx} \right. \right. dx \\ \left. \left. - \int_{x_0}^{x_1} \int_{y_0}^{y_1} Q \frac{dP}{dx} dx dy. \right. \right] \quad (18)$$

275. Again, since

$$\frac{d}{dx} \left( u \frac{dv}{dx} - v \frac{du}{dx} \right) = u \frac{d^2v}{dx^2} - v \frac{d^2u}{dx^2},$$

we get

$$\iint u \frac{d^2v}{dx^2} dx dy = \iint v \frac{d^2u}{dx^2} dx dy + \iint \frac{d}{dx} \left( u \frac{dv}{dx} - v \frac{du}{dx} \right) dx dy.$$

Hence by (9),

$$\int_{x_0}^{x_1} \int_{y_0}^{y_1} u \frac{d^2v}{dx^2} dx dy = \int_{x_0}^{x_1} \int_{y_0}^{y_1} v \frac{d^2u}{dx^2} dx dy \\ + \left| \int_{x_0}^{x_1} \int_{y_0}^{y_1} \left( u \frac{dv}{dx} - v \frac{du}{dx} \right) dy - \int_{x_0}^{x_1} \left| \int_{y_0}^{y_1} \left( u \frac{dv}{dx} - v \frac{du}{dx} \right) \frac{dy}{dx} \right. \right. dx. \quad (19)$$

If the boundary be represented by an equation of the form  $\phi(x, y) = 0$ , then, by Art. 274, we have

$$\iint u \frac{d^2v}{dx^2} dx dy = \iint v \frac{d^2u}{dx^2} dx dy - \int \left( u \frac{dv}{dx} - v \frac{du}{dx} \right) \frac{dy}{dx} dx, \quad (20)$$

where the double integrals are taken for all points within the boundary, and the single integral is taken around the boundary or boundaries.

### 276. Transformation of

$$\iiint \left( \frac{du}{dx} + \frac{dv}{dy} + \frac{dw}{dz} \right) dx dy dz.$$

As in Art. 226, we have

$$\iint \left( \frac{du}{dx} + \frac{dv}{dy} + \frac{dw}{dz} \right) dx dy dz = \iint (lu + mv + nw) dS,$$

where  $l, m, n$  are the direction cosines of the outward drawn normal at  $dS$  to the boundary of the space through which the triple integral is extended.

This theorem is perfectly general, and holds for any portion of space bounded in any manner, provided  $u, v, w$  are finite and continuous for all points within the field of integration.

Also, since over the bounding surface we have, in general,  $dz = pdx + qdy$ , we see, as in Art. 262, that

$$\begin{aligned} \iint (lu + mv + nw) dS &= \iint (w - pu - qv) dxdy \\ &= \iint \left( w - u \frac{dz}{dx} - v \frac{dz}{dy} \right) dxdy. \end{aligned} \quad (21)$$

where  $\frac{dz}{dx}$  and  $\frac{dz}{dy}$  are determined for any portion of the boundary when the equation of that portion is given. In general when the boundary is represented by one or more continuous surfaces, which taken together make up a closed boundary

$$\begin{aligned} \iiint \left( \frac{du}{dx} + \frac{dv}{dy} + \frac{dw}{dz} \right) dxdydz &= \Sigma \iint (lu + mv + nw) dS \\ &= \Sigma \iint \left( w - u \frac{dz}{dx} - v \frac{dz}{dy} \right) dxdy, \end{aligned} \quad (22)$$

where the symbol  $\Sigma$  means that the values of  $\frac{dz}{dx}, \frac{dz}{dy}$  are to be obtained for each surface separately, and the sum taken so as to embrace the entire boundary.

We shall next proceed to find the complete expression for the surface integral when the triple integral is given in the usual form

$$\int_{x_0}^{x_1} \int_{y_0}^{y_1} \int_{z_0}^{z_1} \left( \frac{du}{dx} + \frac{dv}{dy} + \frac{dw}{dz} \right) dxdydz,$$

in which  $z_1$  and  $z_0$  are given functions of  $x, y$ ; and  $y_1$  and  $y_0$  are functions of  $x$ ; and  $x_1, x_0$  are constants.

In this case the boundary consists of three parts:—

- (1) Two surfaces,  $z = z_0, z = z_1$ ;
- (2) Two cylinders,  $y = y_0, y = y_1$ ;
- (3) Two planes,  $x = x_0, x = x_1$ .

It remains to find the complete expression for

$$\iint (lu + mv + nw) dS,$$

when taken over (1), (2), (3), respectively.

1°. Over the surface,  $z = z_1$ , we have, by Art. 262,

$$\iint (lu + mv + nw) dS = \iint \left( w - u \frac{dz}{dx} - v \frac{dz}{dy} \right) dx dy, \quad (23)$$

and we may write the corresponding part of the expression in the form

$$\int_{x_0}^{x_1} \int_{y_0}^{y_1} \left| \begin{array}{c} z_1 \\ z_0 \end{array} \right. \left( w - u \frac{dz}{dx} - v \frac{dz}{dy} \right) dx dy.$$

2°. Over the cylinder  $y = y_1$ , we have  $n = 0$ , and  $mdS = dx dz$ ; consequently, the double integral becomes

$$\iint \left( \frac{l}{m} u + v \right) dx dz.$$

Also, by elementary geometry, we have, along the curve  $y = y_1$ ,

$$\frac{l}{m} = - \frac{dy}{dx};$$

and hence the double integral over this portion of the boundary is represented by

$$\int_{x_0}^{x_1} \int_{z_0}^{z_1} \left| \begin{array}{c} y \\ z_0 \end{array} \right. \left( v - u \frac{dy}{dx} \right) dx dz.$$

It readily follows that the portion of the double integral when taken over the two cylindrical boundaries is represented by

$$\int_{x_0}^{x_1} \int_{z_0}^{z_1} \left| \begin{array}{c} ? \\ z_0 \end{array} \right. \left( v - u \frac{dy}{dx} \right) dx dz.$$

3°. Along the plane  $x = x_1$ , we have  $l = 1$ ,  $m = 0$ ,  $n = 0$ ,  $dS = dydz$ ; therefore the corresponding integral becomes

$$\left| \int_{y_0}^{y_1} \int_{z_0}^{z_1} u dy dz. \right|$$

And over  $x = x_0$ , we have  $l = -1$ ,  $m = 0$ ,  $n = 0$ ; hence the part of the surface integral corresponding to both of these plane sections is represented by

$$\left| \int_{x_0}^{x_1} \int_{y_0}^{y_1} \int_{z_0}^{z_1} u dy dz. \right|$$

Combining these results we get

$$\begin{aligned} & \int_{x_0}^{x_1} \int_{y_0}^{y_1} \int_{z_0}^{z_1} \left( \frac{du}{dx} + \frac{dv}{dy} + \frac{dw}{dz} \right) dx dy dz \\ &= \int_{x_0}^{x_1} \int_{y_0}^{y_1} \left| \int_{z_0}^{z_1} \left( w - u \frac{dz}{dx} - v \frac{dz}{dy} \right) dx dy \right. \\ &+ \left. \int_{x_0}^{x_1} \int_{z_0}^{z_1} \left| \int_{y_0}^{y_1} \left( v - u \frac{dy}{dx} \right) dy dz \right. \right. + \left. \left. \int_{x_0}^{x_1} \int_{y_0}^{y_1} \int_{z_0}^{z_1} u dy dz. \right. \right. \end{aligned} \quad (24)$$

## CHAPTER XVI.

## CALCULUS OF VARIATIONS.

*Single Integrals.*

**277. Bernoulli's Problem.**—In this Chapter it is proposed to give a short account of the elementary principles of the Calculus of Variations, especially in connexion with the theory of maximum and minimum integrals.

The origin of the Calculus of Variations may be traced to John Bernoulli's celebrated problem, published in the *Acta Eruditorum* of Leipsic, in 1696, under the following form, *Datis in plano verticali duobus punctis A et B, assignare mobili M viam AMB per quam gravitate sua descendens, et moveri incipiens a punto A, brevissimo tempore perveniat ad punctum B.* This problem introduced considerations entirely different from those hitherto involved in the discussion of curves, for in its treatment it is necessary to conceive a curve as changing its form in a continuous manner, that is, as undergoing what is styled *deformation*. This change of form can be treated analytically as follows:—Suppose  $y = f(x)$  to represent the equation of a curve, and let us write

$$y = f(x) + a\psi(x), \quad (1)$$

where  $a$  is an infinitesimal quantity, and  $\psi(x)$  any function of  $x$ , subject only to the condition of being finite for all values of  $x$  within the limits of the problem. Then, equation (1) represents a new curve indefinitely close to the curve  $y = f(x)$ ; and by varying the form of  $\psi(x)$  we may regard (1) as representative of any curve indefinitely near to the original.

**278. Definition of Variation  $\delta y$ .**—Here,  $a\psi(x)$  is the difference between the  $y$  ordinates of the two curves for the same value of  $x$ . This indefinitely small difference is called the *variation* of  $y$ , and is denoted by  $\delta y$ .

If the ordinate of the second curve be denoted by  $y_1$ , we may write

$$\delta y = y_1 - y = a\psi(x). \quad (2)$$

Then  $\delta y$  may be regarded as the change in  $y$  arising solely from a change in the relation that connects  $y$  with  $x$  while  $x$  remains unaltered.

More generally, if  $u$  be any function of  $x$  and  $y$ , we may write

$$\delta u = u_1 - u, \quad (3)$$

where  $u_1$  is the value that  $u$  assumes when  $y$  becomes  $y + \delta y$ .

Again, when  $y$  becomes  $y + \delta y$ ,  $\frac{d^n y}{dx^n}$  becomes  $\frac{d^n y}{dx^n} + \frac{d^n \delta y}{dx^n}$ .

Hence we see that

$$\delta \frac{d^n y}{dx^n} = \frac{d^n}{dx^n} (\delta y). \quad (4)$$

This equation may also be written in the form

$$\delta D^n y = D^n \delta y, \quad (5)$$

where  $D$  stands for the symbol of differentiation  $\frac{d}{dx}$ .

Also, in general, we have

$$\delta Du = D\delta u, \text{ and } \delta D^n u = D^n \delta u.$$

More generally, if  $y$  be a function of any number of independent variables  $x_1, x_2, \dots, x_n$ , then  $\delta y$  represents any indefinitely small change in  $y$  arising solely from a change in the form of the function while  $x_1, x_2, \&c.$ , are unchanged. Thus the variable  $y$  may receive two essentially distinct kinds of increment—one arising from a change in one or more of the variables, the other arising solely from a change in the relation which connects  $y$  with these variables. The former increments are those contemplated and treated of in the ordinary calculus; the latter are those principally considered in the calculus of variations.

We shall follow Strauch, Jellett, Moigno, and the principal modern writers on the subject, by restricting, in general, the symbol  $\delta$  to the latter species of increment.

**279. Total Variations.**—In many cases, *more especially for the limiting values of the variables*, we have to take account of both kinds of increment.

Thus, if  $y = f(x_1, x_2, x_3)$ , and if  $\Delta y$  denote the total increment of  $y$ , we have

$$\Delta y = \delta y + \frac{dy}{dx_1} \Delta x_1 + \frac{dy}{dx_2} \Delta x_2 + \frac{dy}{dx_3} \Delta x_3, \quad (6)$$

where  $\Delta x_1, \Delta x_2, \Delta x_3$  denote indefinitely small increments in the variables  $x_1, x_2, x_3$ , respectively.

In the case of a single independent variable this gives

$$\Delta u = \delta u + \frac{du}{dx} \Delta x. \quad (7)$$

**280. Variation of a Function.**—We shall adopt Newton's notation, and write  $\dot{y}$  for  $\frac{dy}{dx}$ ,  $\ddot{y}$  for  $\frac{d^2y}{dx^2}$ ,  $\dots$   $y^{(n)}$  for  $\frac{d^ny}{dx^n}$ , and proceed to consider the variation of the general expression  $V = f(x, y, \dot{y}, \ddot{y}, \dots y^{(n)})$ , in which the form of the function  $f$  is given, while that of  $y$  in terms of  $x$  is indeterminate. Here, considering  $x$  as unchanged, we have

$$\delta V = \frac{dV}{dy} \delta y + \frac{dV}{d\dot{y}} \delta \dot{y} + \dots + \frac{dV}{dy^{(n)}} \delta y^{(n)}.$$

Now let

$$\frac{dV}{dy} = P, \quad \frac{dV}{d\dot{y}} = P_1, \quad \dots \quad \frac{dV}{dy^{(n)}} = P_n, \quad (8)$$

then we have

$$\delta V = P \delta y + P_1 D \delta y + P_2 D^2 \delta y + \dots + P_n D^n \delta y. \quad (9)$$

It may be observed that in all cases in finding the variation of a function we neglect terms of the second and higher degrees in the increments.

281. **Variation of a Definite Integral.**—We shall next consider the variation of the definite integral

$$U = \int_{x_0}^{x_1} V dx, \quad (10)$$

where  $V$  is of the form stated in the preceding Article, and does not contain either of the limits,  $x_0, x_1$ .

Here, when the limits are unchanged, we evidently have

$$\delta U = \int_{x_0}^{x_1} \delta V dx. \quad (11)$$

And, when the limits undergo variation,

$$\Delta U = \int_{x_0}^{x_1} \delta V dx + V_1 \Delta x_1 - V_0 \Delta x_0. \quad (12)$$

We may write the last equation, by Art. 269, in the form

$$\Delta U = \int_{x_0}^{x_1} \delta V dx + \left| \int_{x_0}^{x_1} V \Delta x \right|. \quad (13)$$

We shall suppose in general that  $y, \dot{y}, \ddot{y}, \&c.$ , are continuous and finite, and that  $\delta y, \delta \dot{y}, \&c.$ , are indefinitely small, for all values that lie between the limits of integration.

Again, as any relation between  $x$  and  $y$  can be represented by a curve, we can always give a geometrical meaning to the definite integral  $U$ , and we may speak of the limiting values of  $x$  and  $y$  as the coordinates of the *limiting points*.

282. **Case of  $V = f(x, y, \dot{y})$ .**—We now proceed to transform (13), commencing with the case in which  $V$  is a function of  $x, y$ , and  $\dot{y}$  solely.

Here,

$$\Delta U = \int_{x_0}^{x_1} \left( P \delta y + P_1 \frac{d}{dx} \delta y \right) dx + \left| \int_{x_0}^{x_1} V \Delta x \right|; \quad (14)$$

but

$$\int P_1 \frac{d}{dx} \delta y dx = P_1 \delta y - \int \delta y \frac{dP_1}{dx} dx;$$

therefore

$$\Delta U = \int_{x_0}^{x_1} \left( P - \frac{dP_1}{dx} \right) \delta y dx + \left| \int_{x_0}^{x_1} P \delta y + \int_{x_0}^{x_1} V \Delta x. \right.$$

Again, if  $\Delta y_1$  and  $\Delta y_0$  be the total variations of the limiting coordinates,  $y_1$  and  $y_0$ , we have, by (7),

$$\Delta y_1 = \delta y_1 + \dot{y}_1 \Delta x_1, \quad \Delta y_0 = \delta y_0 + \dot{y}_0 \Delta x_0. \quad (15)$$

Accordingly, substituting in the above, it becomes

$$\Delta U = \int_{x_0}^{x_1} \left( P - \frac{dP_1}{dx} \right) \delta y dx + \left| \int_{x_0}^{x_1} (V - P_1 \dot{y}) \Delta x + \int_{x_0}^{x_1} P_1 \Delta y. \right. \quad (16)$$

Next, if we suppose the limiting point  $(x_1, y_1)$  to be restricted to lie on a fixed curve ( $y = f_1(x)$  suppose); we shall have

$$\Delta y_1 = f_1'(x_1) \Delta x_1.$$

If the other limiting point be likewise restricted to lie on the curve  $y = f_0(x)$ , we shall have

$$\Delta y_0 = f_0'(x_0) \Delta x_0.$$

In such cases equation (16) becomes

$$\Delta U = \int_{x_0}^{x_1} \left( P - \frac{dP_1}{dx} \right) \delta y dx + \left| \int_{x_0}^{x_1} \left\{ V + P_1(f'(x) - \dot{y}) \right\} \Delta x. \right. \quad (17)$$

**283. Case of  $V = f(x, y, \dot{y}, \ddot{y})$ .**—If  $V$  be a function of  $x, y, \dot{y}, \ddot{y}$ , we have

$$\Delta U = \int_{x_0}^{x_1} (P \delta y + P_1 D \delta y + P_2 D^2 \delta y) dx + \left| \int_{x_0}^{x_1} V \Delta x.$$

Hence, since

$$P_2 D^2 \delta y - \delta y \frac{d^2 P_2}{dx^2} = \frac{d}{dx} \left( P_2 D \delta y - \delta y \frac{dP_2}{dx} \right),$$

we have

$$\int_{x_0}^{x_1} P_2 D^2 \delta y = \int_{x_0}^{x_1} \delta y \frac{d^2 P_2}{dx^2} dx + \left| \int_{x_0}^{x_1} P_2 D \delta y - \int_{x_0}^{x_1} \frac{dP_2}{dx} \delta y. \right.$$

Hence,

$$\begin{aligned}\Delta U = & \int_{x_0}^{x_1} \left( P - \frac{dP_1}{dx} + \frac{d^2P_2}{dx^2} \right) \delta y dx + \left|_{x_0}^{x_1} V \Delta x \right. \\ & \left. + \left|_{x_0}^{x_1} \delta y \left( P_1 - \frac{dP_2}{dx} \right) + \left|_{x_0}^{x_1} P_2 \delta \dot{y} \right. \right. \right). \quad (18)\end{aligned}$$

If we now suppose

$$P - \frac{dP_1}{dx} + \frac{d^2P_2}{dx^2} = (P), \quad P_1 - \frac{dP_2}{dx} = (P_1),$$

we may write our equation in the following simple form :—

$$\Delta U = \int_{x_0}^{x_1} (P) \delta y dx + \left|_{x_0}^{x_1} (V \Delta x + (P_1) \delta y + P_2 \delta \dot{y}) \right. \quad (19)$$

Again, as before, we have

$$\begin{aligned}\delta y_1 &= \Delta y_1 - \dot{y}_1 \Delta x_1, & \delta \dot{y}_1 &= \Delta \dot{y}_1 - \ddot{y}_1 \Delta x_1, \\ \delta y_0 &= \Delta y_0 - \dot{y}_0 \Delta x_0, & \delta \dot{y}_0 &= \Delta \dot{y}_0 - \ddot{y}_0 \Delta x_0.\end{aligned}$$

Substituting in (19), it becomes

$$\begin{aligned}\Delta U = & \int_{x_0}^{x_1} (P) \delta y dx + \left|_{x_0}^{x_1} (V - (P_1)\dot{y} - P_2\ddot{y}) \Delta x \right. \\ & \left. + \left|_{x_0}^{x_1} (P_1) \Delta y + \left|_{x_0}^{x_1} P_2 \Delta \dot{y} \right. \right. \right). \quad (20)\end{aligned}$$

It is often convenient to write this in the abbreviated form

$$\Delta U = L_1 - L_0 + \int_{x_0}^{x_1} M \delta y dx,$$

where

$$M = P - \frac{dP_1}{dx} + \frac{d^2P_2}{dx^2}, \quad (21)$$

and  $L_1$  and  $L_0$  represent the terms at the upper and lower limits, respectively.

**284. Maxima and Minima.**—The most important applications of the Calculus of Variations have reference to

the determination of the form of one or more unknown functions, contained in a definite integral, in such a manner that the integral shall have a maximum or minimum value. For instance, to determine the form of the function  $y$  which renders the integral  $U = \int_{x_0}^{x_1} V dx$  a maximum or a minimum.

Here, when we substitute  $y + a\psi$  instead of  $y$  in  $V$ , where  $a$  is an *infinitesimal*, and also vary the limits, we may suppose that  $U$  becomes

$$U + aU_1 + \frac{a^2}{1 \cdot 2} U_2 + \text{&c.}$$

Then, as in the *Differential Calculus*, if  $U$  be a maximum or a minimum, the expression

$$aU_1 + \frac{a^2}{1 \cdot 2} U_2 + \text{&c.}$$

must have the same sign for all variations that are consistent with the conditions of the problem.

Now, since  $\delta y$  or  $a\psi$  is, in general, restricted solely by the condition that it should be very small, we see that we can generally *change the sign of a* without violating the conditions of the problem. Hence, as in the *Differential Calculus*, Art. 138, we see that  $U$  cannot be either a maximum or a minimum unless

$$U_1 = 0.$$

Again, for a maximum  $U_2$  must be negative for all values of  $\delta y$  that are compatible with the conditions of the problem, and for a minimum  $U_2$  must be positive for all values of  $\delta y$  under similar conditions.

In many cases we can see from the nature of the problem that it necessarily admits of a maximum, or of a minimum, value; in such cases when we have obtained the solution by aid of equation  $U_1 = 0$ , we may dispense with the labour of investigating the second condition.

Again, it is easily seen that

$$\Delta U = a U_1,$$

and accordingly, for a maximum or a minimum value of  $U$ , we must have  $\Delta U = 0$ , or

$$L_1 - L_0 + \int_{x_0}^{x_1} M \delta y dx = 0. \quad (22)$$

Now, without restricting the value of  $\delta y$ , this equation cannot be satisfied unless we have

$$L_1 - L_0 = 0, \text{ and } \int_{x_0}^{x_1} M \delta y dx = 0.$$

For if  $L_1 - L_0$  be not zero, we must have

$$a \int_{x_0}^{x_1} \psi(x) M dx = \int_{x_0}^{x_1} M \delta y dx = L_0 - L_1.$$

This would require that the integral of an *arbitrary* function can be expressed in terms of the limiting values of the variables solely, but this is manifestly in general impossible; we must have therefore

$$L_1 - L_0 = 0, \text{ and } \int_{x_0}^{x_1} M \delta y dx = 0. \quad (23)$$

Again, since the value of any definite integral depends on the *form of the function* to be integrated, it is plainly impossible in general to determine the value of the definite integral in (23) without fixing the form of the function represented by  $\delta y$ .

Accordingly, since the form of  $\delta y$  is by hypothesis perfectly arbitrary, we infer that in general it is impossible to satisfy the equation

$$\int_{x_0}^{x_1} M \delta y dx = 0,$$

unless by making

$$M = 0 \quad (24)$$

for all values of  $x$  between the limits  $x_0$  and  $x_1$ .

In each particular case the form of  $y$  in terms of  $x$ , i. e. the equation of the curve, is determined by the integration of the differential equation  $M = 0$ : and also the arbitrary constants introduced in this integration are in general determined by aid of the equation  $L_1 - L_0 = 0$ . Again, this latter equation cannot be always zero unless the coefficient of each of the independent variations be separately zero.

It can be shown that the equations thus obtained are in general sufficient for the determination of the above-mentioned arbitrary constants; this will appear more fully when we come to discuss our applications.

Whenever the solution thus arrived at does not satisfy the criterion respecting the function  $U_2$ , such solution is not either a maximum or a minimum, and is called a *stationary solution*.

**285. Case of Geometrical Restrictions.**—We have here supposed that there is no restriction on  $\delta y$ , so that for any value of  $x$  the increments  $+\delta y$  and  $-\delta y$  are equally compatible with the conditions of the problem. The reasoning consequently will not apply if the conditions render this impossible. For instance, if a curve be restricted to lie *within a given boundary*, then for all points on the boundary the displacements must be inwards, and the opposite displacements are impossible. In this case it is easily seen that the curve satisfying a required maximum or minimum condition consists partly of portions of the boundary and partly of portions of a curve satisfying the equation  $M = 0$ .

We shall now show that the integration of the equation  $M = 0$  is much simplified for particular cases of the form of the function  $V$ .

**286.  $V$  a function of  $x$  and  $\dot{y}$  solely.**—In this case the equation  $M = 0$  becomes  $\frac{dP_1}{dx} = 0$ , and accordingly we have

$$P_1 = \text{const.} = c. \quad (25)$$

More particularly, if  $V$  be a function of  $\dot{y}$  solely, then  $P_1$  is a function of  $\dot{y}$  solely, and we get  $\dot{y} = \text{const.}$ , or  $y = cx + c'$ ; hence the line joining the limiting points is the solution of the problem in this case.

287. ***V* a Function of  $y$  and  $\dot{y}$  solely.**—In this case we have

$$P - \frac{dP_1}{dx} = 0.$$

Hence

$$\frac{d}{dx} V = \dot{y}P + \ddot{y}P_1 = \dot{y} \frac{dP_1}{dx} + \ddot{y}P_1 = \frac{d}{dx} (\dot{y}P_1),$$

accordingly we have in this case

$$V = c + \dot{y}P_1, \quad (26)$$

where  $c$  is a constant.

288. ***V* a Function of  $x$ ,  $\dot{y}$ , and  $\ddot{y}$  solely.**—Here the equation  $M = 0$  becomes

$$\frac{dP_1}{dx} - \frac{d^2P_2}{dx^2} = 0.$$

Hence we get

$$(P_1) = P_1 - \frac{dP_2}{dx} = \text{const.} \quad (27)$$

289. ***V* a Function of  $y$ ,  $\dot{y}$  and  $\ddot{y}$  solely.**—In this case we have

$$P - \frac{dP_1}{dx} + \frac{d^2P_2}{dx^2} = 0. \quad (28)$$

Also

$$\begin{aligned} \frac{d}{dx} V &= \dot{y}P + \ddot{y}P_1 + \ddot{y}P_2 \\ &= \dot{y} \frac{dP_1}{dx} - \dot{y} \frac{d^2P_2}{dx^2} + \ddot{y}P_1 + \ddot{y}P_2, \text{ by (28);} \end{aligned}$$

therefore

$$\frac{d}{dx} V = \frac{d}{dx} (\dot{y}P_1) - \dot{y} \frac{d^2P_2}{dx^2} + \ddot{y}P_2$$

Again

$$\frac{d}{dx} \left( \dot{y} \frac{dP_2}{dx} - \ddot{y}P_2 \right) = \dot{y} \frac{d^2P_2}{dx^2} - \ddot{y}P_2.$$

Consequently we get

$$\frac{d}{dx} V = \frac{d}{dx} (\dot{y} P_1) - \frac{d}{dx} \left( \dot{y} \frac{dP_2}{dx} - \ddot{y} P_2 \right);$$

therefore  $V = c + \dot{y} P_1 - \dot{y} \frac{dP_2}{dx} + \ddot{y} P_2;$

or  $V = c + \dot{y}(P_1) + \ddot{y}P_2. \quad (29)$

In particular if  $V$  be a function of  $\dot{y}$  and  $\ddot{y}$  solely, this becomes, by (27),

$$V = c + c' \dot{y} + \ddot{y} P_2. \quad (30)$$

290. **Case where  $V$  contains the Limits.**—In the equation

$$U = \int_{x_0}^{x_1} V dx,$$

if  $V$  contain explicitly the limiting values of one or more of the quantities  $x$ ,  $y$ ,  $\dot{y}$ , &c., the expression for  $\Delta U$ , whenever such limiting values are *not fixed*, contains terms additional to those given in Art. 283.

For instance, suppose

$$V = f(x, y, \dot{y} \dots x_1, y_1, \dot{y}_1),$$

then  $\delta V$  will contain additional terms arising from the changes in  $x_1$ ,  $y_1$ , and  $\dot{y}_1$ ; and we shall have

$$\frac{d}{dx_1} (V) = \frac{dV}{dx_1} + \dot{y}_1 \frac{dV}{dy_1} + \ddot{y}_1 \frac{dV}{d\dot{y}_1};$$

hence the additional terms in  $\Delta U$  are

$$\begin{aligned} \Delta x_1 \int_{x_0}^{x_1} \left( \frac{dV}{dx_1} + \dot{y}_1 \frac{dV}{dy_1} + \ddot{y}_1 \frac{dV}{d\dot{y}_1} \right) dx + \Delta y_1 \int_{x_0}^{x_1} \frac{dV}{dy_1} dx \\ + \Delta \dot{y}_1 \int_{x_0}^{x_1} \frac{dV}{d\dot{y}_1} dx. \end{aligned} \quad (31)$$

We shall illustrate the method of dealing with such additional terms subsequently.

291. **Case of Two Dependent Variables.**—It is easy to extend the preceding method to the discussion of

problems of maxima and minima when there are two or more dependent variables.

Thus let us consider the variation of the expression

$$U = \int_{x_0}^{x_1} V dx,$$

where  $V$  is a given function of  $x, y, z, \dot{y}, \dot{z}, \ddot{y}, \ddot{z}$ , and  $y, z$ , are both undetermined functions of  $x$ .

As before let

$$P = \frac{dV}{dy}, \quad P_1 = \frac{dV}{d\dot{y}}, \quad P_2 = \frac{dV}{d\ddot{y}},$$

and suppose

$$Q = \frac{dV}{dz}, \quad Q_1 = \frac{dV}{d\dot{z}}, \quad Q_2 = \frac{dV}{d\ddot{z}},$$

then

$$\begin{aligned} \Delta U = & \left| \int_{x_0}^{x_1} V \Delta x + \int_{x_0}^{x_1} (P \delta y + P_1 D \delta y + P_2 D^2 \delta y) dx \right. \\ & \left. + \int_{x_0}^{x_1} (Q \delta z + Q_1 D \delta z + Q_2 D^2 \delta z) dx. \right. \end{aligned}$$

Proceeding as in Art. 283, we readily find

$$\begin{aligned} \Delta U = & \int_{x_0}^{x_1} (P) \delta y dx + \int_{x_0}^{x_1} (Q) \delta z dx + \left| \int_{x_0}^{x_1} V \Delta x \right. \\ & \left. + \int_{x_0}^{x_1} \{(P_1) \delta y + P_2 \delta \dot{y} + (Q_1) \delta z + Q_2 \delta \dot{z}\} dx \right. \end{aligned}$$

where  $(P), (P_1)$  have the same meaning as in Art. 283, and  $(Q), (Q_1)$  are the corresponding expressions relative to the variable  $z$ .

Again, as in the case of a single variable, this expression readily admits of being transformed into

$$\begin{aligned} \Delta U = & \int_{x_0}^{x_1} (P) \delta y dx + \int_{x_0}^{x_1} (Q) \delta z dx \\ & + \left| \int_{x_0}^{x_1} \left( V - (P_1) \dot{y} - P_2 \ddot{y} - (Q_1) \dot{z} - Q_2 \ddot{z} \right) \Delta x \right. \\ & \left. + \int_{x_0}^{x_1} \{(P_1) \Delta y + P_2 \Delta \dot{y} + (Q_1) \Delta z + Q_2 \Delta \dot{z}\}. \right. \quad (32) \end{aligned}$$

This equation may be written for convenience in the form

$$\Delta U = \left| \begin{array}{l} x_1 \\ x_0 \end{array} \right| L + \int_{x_0}^{x_1} (M \delta y + N \delta z) dx. \quad (33)$$

**292. Application to Maxima and Minima.**—The determination of  $y$  and  $z$  when  $\int_{x_0}^{x_1} V dx$  is a maximum or a minimum leads, as in Art. 284, to the equations

$$M = 0, \quad N = 0, \quad (34)$$

along with the equation

$$\left| \begin{array}{l} x_1 \\ x_0 \end{array} \right| L = 0 \quad (35)$$

at the limits.

In the latter equation the coefficient of each *independent* limiting variation must be zero as before; and the equations thus obtained enable us, in general, to determine the arbitrary constants which appear in the solution of the equations

$$P - \frac{dP_1}{dx} + \frac{d^2 P_2}{dx^2} = 0, \quad Q - \frac{dQ_1}{dx} + \frac{d^2 Q_2}{dx^2} = 0. \quad (36)$$

When  $V$  is of particular forms it is easily seen that results similar to those given for a single variable still hold good.

For instance, when  $V$  does not contain  $x$  explicitly, we see by the method adopted in Art. 289 that we shall have

$$V = c + (P_1) \dot{y} + (Q_1) \dot{z} + P_2 \ddot{y} + Q_2 \ddot{z}. \quad (37)$$

Again, if  $V$  does not contain either  $x$ ,  $y$ , or  $z$  explicitly, this becomes, as in (30),

$$V = c + c' \dot{y} + c'' \dot{z} + P_2 \ddot{y} + Q_2 \ddot{z}. \quad (38)$$

The foregoing results can be readily extended to the case of three or more dependent variables.

**293. Relative Maxima and Minima. Isoperimetric Problems.**—In the discussion of the curve which possesses a maximum or a minimum property if we limit the investigation to all curves of a given length, or that satisfy

some other condition, we get a new class of problems, called problems of *relative maxima and minima*. These questions originated in the *isoperimetrical* problems of James Bernoulli.

For example, let it be proposed to determine the form of  $y$  that renders  $U = \int_{x_0}^{x_1} V dx$  a maximum or a minimum, and that also satisfies the relation  $U' = \int_{x_0}^{x_1} V' dx = \text{constant}$ , where  $V$  and  $V'$  are given functions of  $x, y, \dot{y}$ , &c.

Here it is obvious that if  $U$  be a maximum or a minimum, so also is  $U + aU'$ , where  $a$  is any arbitrary constant. Accordingly the problem reduces to the determination of the maximum or minimum value of

$$\int_{x_0}^{x_1} (V + aV') dx, \quad (39)$$

regarding  $a$  as a constant whose value is to be determined by aid of the given value of  $U'$ .

**294. Equations of Condition.**—Another class of problems closely allied with the preceding is that in which the variables  $x, y, \dot{y}, \ddot{y}$ , &c., are connected by a relation  $W = 0$ ; in this case we may plainly write

$$U = \int_{x_0}^{x_1} (V + \lambda W) dx, \quad (40)$$

where  $\lambda$  is any indeterminate function of  $x$ .

A very important case of this principle arises whenever we take the arc of the curve for the independent variable.

**295. Case of Arc being Independent Variable.**—For instance, in looking for the maximum or minimum solution of the integral

$$U = \int_{s_0}^{s_1} \mu ds,$$

let  $\frac{dx}{ds} = \dot{x}$ ,  $\frac{dy}{ds} = \dot{y}$ , and we have at each point of the curve the relation  $\dot{x}^2 + \dot{y}^2 - 1 = 0$ .

In this case we seek for the maximum or minimum solution of the expression

$$U = \int_{s_0}^{s_1} \left\{ \mu + \frac{1}{2} \lambda (\dot{x}^2 + \dot{y}^2 - 1) \right\} ds = \int_{s_0}^{s_1} V ds, \quad (41)$$

where  $V = \mu + \frac{1}{2}\lambda(\dot{x}^2 + \dot{y}^2 - 1)$  and  $\lambda$  is undetermined: the coefficient is written in the form  $\frac{1}{2}\lambda$  for convenience.

296. **Case where  $\mu$  does not contain  $s$  explicitly.**—For example, let  $\mu$  be a function of  $\dot{x}$  and  $\dot{y}$  solely; then, since

$$\frac{dV}{ds} = \frac{1}{2}(\dot{x}^2 + \dot{y}^2 - 1) \frac{d\lambda}{ds} = 0,$$

we get, by equation (37),

$$V = P_1\dot{x} + Q_1\dot{y} + c;$$

hence  $\mu = \lambda + c.$

This may be written  $\lambda = \mu + a,$

where  $a$  is an arbitrary constant, to be subsequently determined.

Again, the equation  $\left| \begin{array}{l} x_1 \\ x_0 \end{array} \right| L = 0$  at the limits becomes in this case

$$\left| \begin{array}{l} x_1 \\ x_0 \end{array} \right| \mu \Delta s + \left| \begin{array}{l} x_1 \\ x_0 \end{array} \right| \lambda (\dot{x} \delta x + \dot{y} \delta y) = 0,$$

or, since  $\delta x_1 = \Delta x_1 - \dot{x}_1 \Delta s_1$ , &c.,

$$\left| \begin{array}{l} x_1 \\ x_0 \end{array} \right| (\mu - \lambda) \Delta s + \left| \begin{array}{l} x_1 \\ x_0 \end{array} \right| \lambda (\dot{x} \Delta x + \dot{y} \Delta y) = 0;$$

therefore  $-a \Delta (s_1 - s_0) + \left| \begin{array}{l} x_1 \\ x_0 \end{array} \right| (\dot{x} \Delta x + \dot{y} \Delta y) = 0.$

Hence we obtain

$$a \Delta (s_1 - s_0) = 0, \text{ and } \left| \begin{array}{l} x_1 \\ x_0 \end{array} \right| \lambda (\dot{x} \Delta x + \dot{y} \Delta y) = 0. \quad (42)$$

Now, whenever the length of the curve is given, the former of these equations vanishes identically, but when the length is undetermined we must have  $a = 0$ .

Accordingly, in the latter case we have

$$\lambda = \mu, \quad (43)$$

while in *isoperimetrical* problems

$$\lambda = \mu + a, \quad (44)$$

in which the arbitrary constant is to be determined from the given length of the curve.

In the former case, substituting  $\mu$  for  $\lambda$  in (41), we see that whenever  $\mu$  does not contain  $s$  explicitly, we may write

$$U = \frac{1}{2} \int_{s_0}^{s_1} \mu (\dot{x}^2 + \dot{y}^2 + 1) ds. \quad (45)$$

Hence, if  $\mu$  be a function solely of one of the variables,  $y$  suppose, the maximum or minimum solution is given by aid of the equation

$$\mu \dot{x} = c. \quad (46)$$

Examples of this will be found further on.

297. In general, for a maximum or a minimum we have, from (45),

$$\frac{d\mu}{dx} = \frac{d}{ds} (\mu \dot{x}), \quad \frac{d\mu}{dy} = \frac{d}{ds} (\mu \dot{y}) \quad (47)$$

but

$$\frac{d\mu}{ds} = \dot{x} \frac{d\mu}{dx} + \dot{y} \frac{d\mu}{dy}.$$

Hence we get

$$\mu \ddot{x} = \dot{y} \left( \dot{y} \frac{d\mu}{dx} - \dot{x} \frac{d\mu}{dy} \right), \quad \mu \ddot{y} = \dot{x} \left( \dot{x} \frac{d\mu}{dy} - \dot{y} \frac{d\mu}{dx} \right). \quad (48)$$

Again, let  $\phi$  be the angle that  $ds$ , the element of the curve, makes with the positive direction of the axis of  $x$ , and we have

$$\dot{x} = \cos \phi, \quad \dot{y} = \sin \phi;$$

therefore

$$\ddot{x} = - \dot{y} \frac{d\phi}{ds}, \quad \ddot{y} = \dot{x} \frac{d\phi}{ds}.$$

Accordingly, either of the equations in (48) becomes

$$\frac{d\phi}{ds} = - \frac{1}{\mu} \left( \frac{d\mu}{dx} \sin \phi - \frac{d\mu}{dy} \cos \phi \right).$$

Hence, adopting the usual convention as to the sign of  $\rho$  the radius of curvature (*Differential Calculus*, Art. 226), we may write the last equation in the form

$$\frac{1}{\rho} = - \frac{1}{\mu} \left( \frac{d\mu}{dx} \sin \phi - \frac{d\mu}{dy} \cos \phi \right). \quad (49)$$

Further integration of this expression is impossible without having previously specified the form of  $\mu$ .

Again, at the limits we have

$$\left| \int_{x_0}^{x_1} \mu(\dot{x}\Delta x + \dot{y}\Delta y) \right| = 0.$$

This, when the limiting points are independent, leads to the equations

$$\left| \int_{x_0}^{x_1} (\dot{x}\Delta x + \dot{y}\Delta y) \right| = 0, \text{ and } \left| \int_{x_0}^{x_0} (\dot{x}\Delta x + \dot{y}\Delta y) \right| = 0, \quad (50)$$

provided  $\mu$  does not become zero at either limit.

When the limiting points are restricted to fixed curves, equations (50) show that the curve for which  $\int_{x_0}^{x_1} \mu ds$  is a maximum or a minimum must cut the limiting curves orthogonally.

It may be observed that if the proposed integral had been  $\int_{x_0}^{x_1} \frac{ds}{\mu}$ , equation (49) would become

$$\frac{1}{\rho} = \frac{1}{\mu} \left( \frac{d\mu}{dx} \sin \phi - \frac{d\mu}{dy} \cos \phi \right),$$

and consequently we see that the two curves contained under the equation  $\rho^2 = f\left(x, y, \frac{dy}{dx}\right)$  are such that if one renders  $\int \mu ds$  a maximum or a minimum, the other possesses the same property with regard to  $\int \frac{ds}{\mu}$ .

**298. Case where  $V = \mu + \mu_1 \dot{x} + \mu_2 \dot{y}$ .**—Next let us consider the case where  $V$  is of the form  $\mu + \mu_1 \dot{x} + \mu_2 \dot{y}$ , in which  $\mu$ ,  $\mu_1$ , and  $\mu_2$  are given functions of  $x$  and  $y$  solely.

Here, as before, we assume

$$U = \int_{s_0}^{s_1} \left\{ \mu + \mu_1 \dot{x} + \mu_2 \dot{y} + \frac{1}{2} \lambda (\dot{x}^2 + \dot{y}^2 - 1) \right\} ds. \quad (51)$$

Then, as in the previous case, we get

$$V = P_1 \dot{x} + Q_1 \dot{y} + c.$$

This leads immediately to the relation

$$\mu = \lambda + c.$$

Again, the equation  $\left|_{x_0}^{x_1} L = 0\right.$  at the limits reduces to

$$\left|_{x_0}^{x_1} (\mu + \mu_1 \dot{x} + \mu_2 \dot{y}) \Delta s + \left|_{x_0}^{x_1} \mu_1 \delta x + \mu_2 \delta y + \left|_{x_0}^{x_1} \lambda (\dot{x} \delta x + \dot{y} \delta y) = 0\right.\right.$$

Substituting, as before, for  $\delta x$  and  $\delta y$ , this expression immediately reduces to

$$c \Delta (s_1 - s_0) + \left|_{x_0}^{x_1} \mu_1 \Delta x + \mu_2 \Delta y + (\mu - c) \left|_{x_0}^{x_1} (\dot{x} \Delta x + \dot{y} \Delta y) = 0\right.\right.$$

Hence, as in the preceding case,  $c = 0$ , except for isoperimetric problems; also, we have

$$\left|_{x_0}^{x_1} \left\{ \mu_1 \Delta x + \mu_2 \Delta y + \mu (\dot{x} \Delta x + \dot{y} \Delta y) \right\} = 0. \quad (52)\right.$$

In this case we have  $\lambda = \mu$ , and equation (51) may be written

$$U = \int_s^{s_1} \left\{ \frac{1}{2} \mu (\dot{x}^2 + \dot{y}^2 + 1) + \mu_1 \dot{x} + \mu_2 \dot{y} \right\} ds. \quad (53)$$

If  $\mu$ ,  $\mu_1$ , and  $\mu_2$  be functions of one variable ( $y$  suppose solely), the differential equation for determining the curve assumes the simple form

$$\mu \dot{x} + \mu_1 = c. \quad (54)$$

299. In general we get the equations

$$\left. \begin{aligned} \frac{d\mu}{dx} + \dot{x} \frac{d\mu_1}{dx} + \dot{y} \frac{d\mu_2}{dx} &= \frac{d}{ds} (\mu \dot{x}) + \frac{d\mu_1}{ds} \\ \frac{d\mu}{dy} + \dot{x} \frac{d\mu_1}{dy} + \dot{y} \frac{d\mu_2}{dy} &= \frac{d}{ds} (\mu \dot{y}) + \frac{d\mu_2}{ds} \end{aligned} \right\}. \quad (55)$$

Hence, as in Art. 297, we readily have

$$\frac{1}{\rho} = - \frac{1}{\mu} \left\{ \frac{d\mu}{dx} \dot{y} - \frac{d\mu}{dy} \dot{x} + \frac{d\mu_1}{dy} - \frac{d\mu_2}{dx} \right\}. \quad (56)$$

We shall illustrate the results arrived at in the preceding articles by the consideration of a few elementary problems of maxima and minima.

300. **Lines of Shortest Length.**—In the case of plane curves the length of the curve between any two points is represented by

$$\int_{x_0}^{x_1} \sqrt{1 + \dot{y}^2} dx.$$

Hence, since  $V$  is a function of  $\dot{y}$  solely, we have, by Art. 286,  $\dot{y} = \text{const.}$ ; consequently, as is obvious geometrically, the curve of shortest length between two points is a straight line.

If the limiting point  $x_0, y_0$  be restricted to the curve  $y = f_0(x)$ , we have  $\Delta y_0 = f_0(x_0) \Delta x_0$ , and the limiting equation (17) gives

$$(1 + \dot{y}f_0(x_0)) \Delta x_0 = 0,$$

or

$$1 + \dot{y}f_0(x_0) = 0. \quad (57)$$

This shows that the right line cuts the boundary orthogonally.

Hence the problem reduces to the drawing a normal, or normals, from the point  $x_0, y_0$  to the bounding curve.

It is easily seen that if the point  $x_0, y_0$  is between the curve and the corresponding centre of curvature, the distance is a minimum, and leads to a real minimum solution. If the point lies *beyond* the centre of curvature, the normal in question furnishes a *stationary* solution, but not a minimum solution.

If each of the limiting points lies on a given curve, the solution is a line normal to both the curves.

Let us consider whether such a solution is a true minimum or only a stationary solution.

1°. Let the curves be convex to each other along the common normal  $P_1P_2$ : in this case  $P_1P_2$  is a minimum.

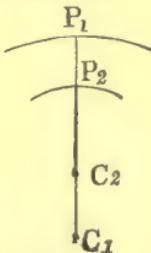


Fig. 85.

If the curves be concave relative to  $P_1P_2$ : the distance  $P_1P_2$  is not a true minimum, and consequently our solution is but a stationary solution.

If the curves lie as in the first part of the figure, then it is easily seen that  $P_1P_2$  is a true minimum only when  $C_1$ , the centre of curvature corresponding to  $P_1$ , lies beyond  $C_2$ , the centre of curvature corresponding to  $P_2$ .

More generally, we have for the length of any curve in space

$$U = \int_{x_0}^{x_1} \sqrt{1 + \dot{y}^2 + \dot{z}^2} dx.$$

Here, for a maximum or a minimum, we have, as in Art. 286,  $\dot{y} = \text{const.}$ ,  $\dot{z} = \text{const.}$ , and accordingly the curve is the right line that joins the limiting points.

If we suppose the limiting point  $x_0y_0z_0$  restricted to lie on the surface

$$u = f(x, y, z) = 0;$$

then we have

$$\left| \frac{x_1}{x_0} \left( \frac{du}{dx} \Delta x + \frac{du}{dy} \Delta y + \frac{du}{dz} \Delta z \right) \right| = 0. \quad (58)$$

Again, by (32), the term in  $\delta U$  that corresponds to this limit is

$$\frac{\Delta x_0}{\sqrt{1 + \dot{y}_0^2 + \dot{z}_0^2}} + \frac{\dot{y}_0 \Delta y_0 + \dot{z}_0 \Delta z_0}{\sqrt{1 + \dot{y}_0^2 + \dot{z}_0^2}}.$$

This gives

$$\Delta x_0 + \dot{y}_0 \Delta y_0 + \dot{z}_0 \Delta z_0 = 0;$$

hence, from (58) we see that we must have at the limiting point

$$\frac{du}{dx} = \frac{1}{\dot{y}} \frac{du}{dy} = \frac{1}{\dot{z}} \frac{du}{dz}. \quad (59)$$

This shows that the right line is normal to the surface  $u = 0$  at the limiting point  $x_0y_0z_0$ .

Hence when one of the limiting points is fixed, and the other lies on a given surface, the problem reduces to drawing normals to the surface from the given point.

It is easily seen from elementary geometry that for a true minimum solution the point must be nearer to the surface than either of the two corresponding principal centres of curvature.

301. **Brachystochrone.** — We shall next consider Bernoulli's problem (Art. 277) of the line of quickest descent under the action of gravity, which is commonly called the Brachystochrone.

Let us take the axis of  $x$  vertically *downwards*, and that of  $y$  horizontal. We shall suppose the particle to start from the fixed point  $x_0 y_0$ , with the velocity due to the height  $h$ ; then, if  $v$  be the velocity at any point, we have

$$v^2 = 2g(x + h - x_0),$$

also, if  $t$  be the time of motion,  $v = \frac{ds}{dt}$ ;

$$\therefore dt = \frac{ds}{v} = \frac{\sqrt{1 + \dot{y}^2} dx}{\sqrt{2g} \sqrt{x + h - x_0}} :$$

hence, neglecting the constant  $\sqrt{2g}$ , we may write

$$U = \int_{x_0}^{x_1} \frac{\sqrt{1 + \dot{y}^2} dx}{\sqrt{x + h - x_0}}. \quad (60)$$

Here, since  $V$  does not contain  $y$  explicitly, and  $x_0$  is constant, we have, by (25),

$$\frac{\dot{y}}{\sqrt{1 + \dot{y}^2}} \frac{1}{\sqrt{x + h - x_0}} = c. \quad (61)$$

Now, let  $\phi$  be the angle that the tangent to the curve at any point  $xy$  makes with the axis of  $x$ ; then

$$\dot{y} = \tan \phi; \quad \therefore \sqrt{x + h - x_0} = \frac{\sin \phi}{c},$$

$$\text{or} \quad x + h - x_0 = a \sin^2 \phi, \quad (62)$$

writing  $a$  instead of  $\frac{1}{c^2}$ ;

$$\text{hence} \quad dx = 2a \sin \phi \cos \phi d\phi,$$

$$\text{also} \quad dy = \tan \phi dx = 2a \sin^2 \phi d\phi,$$

therefore

$$y = 2a \int \sin^2 \phi d\phi = a\phi - \frac{a \sin 2\phi}{2} + \text{const.} \quad (63)$$

Hence (*Diff. Cal.*, Art. 272) we see that the curve of quickest descent is a cycloid.

The construction of the curve depends on the limiting conditions. Thus, if the particle starts from rest, we have  $h = 0$ ; and, taking the origin at the upper limiting point, we have  $x_0 = 0$ ,  $y_0 = 0$ ; and equations (62) and (63) become

$$x = a \sin^2 \phi, \quad y = a \left( \phi - \frac{\sin 2\phi}{2} \right).$$

These represent a cycloid having a cusp at the origin.

Again, if we suppose the lower point,  $x_1 y_1$ , to lie on the curve  $y = f(x)$ , the term outside the sign of integration corresponding to this limit gives

$$V + P_1 (f'(x) - \dot{y}) = 0. \quad (64)$$

But, by (61), we have

$$P_1 = c, \quad V = \frac{c(1 + \dot{y}^2)}{\dot{y}};$$

hence (64) becomes

$$1 + \tan \phi_1 f'(x_1) = 0.$$

This shows that the cycloid cuts the limiting curve at right angles.

**302. The Arc taken as Independent Variable.**—It will be instructive to illustrate the method of Art. 295 by applying it to the problem of the brachystochrone. Here we have

$$\mu = \frac{1}{\sqrt{x + h - x_0}};$$

and equation (45) gives, neglecting the constant multiplier,

$$U = \int_{s_0}^{s_1} \frac{(\dot{x}^2 + \dot{y}^2 + 1)}{\sqrt{x + h - x_0}} ds;$$

again, as this does not contain  $y$  explicitly, we have, as in equation (46),

$$\frac{\dot{y}^*}{\sqrt{x+h-x_0}} = \text{const.} = c, \quad \text{where } \dot{y} = \frac{dy}{ds}.$$

If  $\phi$  be the angle that the tangent at the point  $xy$  makes with the axis of  $x$ , we get as before,

$$x+h-x_0 = a \sin^2 \phi,$$

and also

$$\dot{x} = \cos \phi; \quad \therefore ds = \frac{dx}{\cos \phi} = 2a \sin \phi d\phi. \quad (65)$$

This gives  $s = -2a \cos \phi + \text{const.}$

Hence (*Diff. Cal.*, Art. 276), we see that the curve is a cycloid, as already shown.

Again, equation (50) gives at the limiting point  $x_1 y_1$

$$\dot{x} \Delta x + \dot{y} \Delta y = 0, \quad (66)$$

which shows that the cycloid intersects the limiting curve orthogonally.

Next, if we suppose the point  $x_0 y_0$  to be variable, we see, by Art. 290, that we must introduce in  $\Delta U$  the additional term

$$\frac{1}{2} \Delta x_0 \int_{s_0}^{s_1} \frac{ds}{(x+h-x_0)^{\frac{3}{2}}};$$

also, by (65),

$$\int_{s_0}^{s_1} \frac{ds}{(x+h-x_0)^{\frac{3}{2}}} = \frac{2}{\sqrt{a}} \int_{\phi_0}^{\phi_1} \frac{d\phi}{\sin^2 \phi} = \frac{2}{\sqrt{a}} (\cot \phi_0 - \cot \phi_1);$$

accordingly, the additional term introduced is

$$\frac{\Delta x_0}{\sqrt{a}} (\cot \phi_0 - \cot \phi_1). \quad (67)$$

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\* The student must be careful not to confound the symbol  $\dot{y}$  in this investigation with the same symbol in the previous article. In fact,  $\dot{y}$  in all cases represents the *fluxion of  $y$  relative to the independent variable*.

Also, the term

$$-\mu_0 \int_{x_0}^{x_1} (\dot{x} \Delta x + \dot{y} \Delta y),$$

in (42), becomes

$$-\frac{I}{\sqrt{h}} (\cos \phi_0 \Delta x_0 + \sin \phi_0 \Delta y_0),$$

or

$$-\frac{I}{\sqrt{a}} (\cot \phi_0 \Delta x_0 + \Delta y_0);$$

adding this to the term in (67), we get

$$-\frac{I}{\sqrt{a}} (\Delta x_0 \cot \phi_1 + \Delta y_0) = 0.$$

If we compare this with (66), we see that the tangents to the limiting curves at the upper and lower limiting points are parallel. [See Moigno, *Calcul des Variations*, § 113.]

For example, to find the curve of quickest descent between a given curve  $AB$  and a straight line  $CD$  situated in the same vertical plane, we draw to the given curve a tangent  $AT$  parallel to the line  $CD$ . Then, supposing the particle to start from rest, the cycloid satisfying the condition must start from a cusp at  $A$  and cut  $CD$  orthogonally.

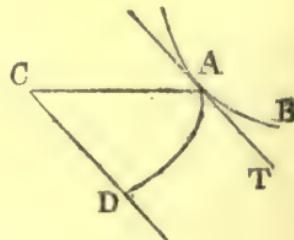


Fig. 86.

303. To find a curve of given length whose extremities lie on a given curve, and such that the area comprised between the two curves shall be a maximum.

Let  $y = f(x)$  be the equation of the given curve; then taking the arc as the independent variable, we may, as in Art. 298, write

$$U = \int \left\{ \frac{1}{2}c(\dot{x}^2 + \dot{y}^2 + 1) + (y - f(x))\dot{x} \right\} ds.$$

Hence, by (34), we get

$$\dot{x} = c\dot{y}; \quad \therefore c\dot{y} = x + a; \quad (68)$$

and it readily follows that the curve is a circle of radius  $c$ .

Again, since at the limits we have  $y = f(x)$ , the limiting equation becomes, by (50),

$$c \left| \begin{array}{l} x_1 \\ x_0 \end{array} \right. (\dot{x}\Delta x + \dot{y}\Delta y) = 0, \quad \text{or} \quad \left| \begin{array}{l} x_1 \\ x_0 \end{array} \right. (\dot{x} + \dot{y}f'(x)) = 0.$$

This shows that the curve cuts the given curve,  $y = f(x)$ , at right angles at each limiting point.

304. **Minimum Surface of Revolution.**—To find a curve such that the surface generated by its revolution around a given line shall be a minimum.

Here  $\int y\sqrt{1+y^2}dx$  is a minimum: hence, by (26), we must have

$$y\sqrt{1+y^2} = c + \frac{yy^2}{\sqrt{1+y^2}}, \quad \text{or} \quad y = c(1+y^2)^{\frac{1}{2}}.$$

Accordingly, we have

$$c \frac{dy}{dx} = \sqrt{y^2 - c^2};$$

$$\text{therefore } x = c \log \frac{y + \sqrt{y^2 - c^2}}{c} + \text{const.}$$

305. Otherwise: if we take the arc as the independent variable, and the given line as the axis of  $x$ , then the surface in question is represented by

$$U = 2\pi \int_{s_0}^{s_1} yds;$$

hence, neglecting a constant multiplier, we may write, as in Art. 295,

$$U = \int_{s_0}^{s_1} \{y + \frac{1}{2}\lambda(\dot{x}^2 + y^2 - 1)\} ds.$$

Again, by (45), this may be written in the form

$$U = \frac{1}{2} \int_{s_0}^{s_1} y(\dot{x} + \dot{y}^2 + 1) ds.$$

Consequently, as in (46), the curve is determined by the equation

$$y\dot{x} = a, \quad \text{or} \quad y = a \sec \phi. \quad (69)$$

From this we infer, by (3), Art. 131, that the curve is a catenary: a result which can also be readily seen, since (69) leads immediately to the equation

$$a \frac{dy}{dx} = \sqrt{y^2 - a^2};$$

or  $x = a \log (y + \sqrt{y^2 - a^2}) + \text{const.}$ , as before.

If now the origin be taken as in fig. 7, p. 184, we get

$$x = a \log \frac{y + \sqrt{y^2 - a^2}}{a};$$

and hence

$$y = \frac{a}{2} \left( e^{\frac{x}{a}} + e^{-\frac{x}{a}} \right) = a \cosh \frac{x}{a}. \quad (70)$$

Consequently, when the extreme points are given, the problem reduces to drawing a catenary passing through these points and having the given line for its axis. For a general investigation of the possibility of this construction the student is referred to Todhunter's *Researches on the Calculus of Variations*, § 62.

We limit the investigation here to the particular case where the limiting points,  $A$  and  $A'$ , are equidistant from the fixed line.

We shall first show that all catenaries, represented by the equation

$$y = \frac{a}{2} \left( e^{\frac{x}{a}} + e^{-\frac{x}{a}} \right),$$

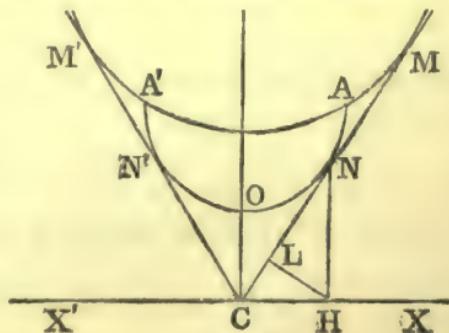


Fig. 87.

where  $a$  is variable, lie within two common tangents which pass through the origin  $C$ .

For, let  $CN$  be a tangent from the origin to the curve, and let

$$NCO = a, \quad CH = x, \quad NH = y;$$

then, as in Art. 131, we have

$$HL = a, \quad NL = \text{arc } ON = s;$$

also, from the figure,

$$\frac{y}{a} = \text{cosec } a, \quad \frac{x}{a} = \sec a;$$

hence, from equation (70) we get for the determination of  $a$ ,

$$2 \text{cosec } a = e^{\sec a} + e^{-\sec a}; \quad \therefore 2 \cot a = e^{\sec a} - e^{-\sec a};$$

hence

$$e^{\sec a} = \text{cosec } a + \cot a = \frac{1 + \cos a}{\sin a} = \sqrt{\frac{1 + \cos a}{1 - \cos a}}.$$

If we make  $\sec a = u$ , this gives

$$e^u = \sqrt{\frac{u + 1}{u - 1}}. \quad (71)$$

The value of  $u$  can readily be found approximately from this equation; for let  $u = 1 + z$ , then (71) transforms into

$$ze^2e^{2z} = 2 + z;$$

but  $e = 2.718 \dots$ ;  $\therefore e^2 = 7.4$ , approximately;

hence, approximately,

$$z \left( 1 + 2z + 2z^2 + \frac{4}{3}z^3 + \text{&c.} \right) = \frac{10}{37} + \frac{5z}{37}.$$

From this without difficulty we find

$$z = \frac{1}{5}, q \cdot p; \quad \therefore \sec a = \frac{6}{5}, q \cdot p.$$

Hence, by a table of natural sines, we find  $a = 33^\circ 30'$ , approximately.

The equation  $\tan a = \frac{x}{y}$  furnishes the *maximum* value of  $\frac{x}{y}$  for the catenary.

Accordingly, if  $y_0 = y_1$ , and if  $d$  be the distance between the limiting points, we may write  $2x_0 = d$ ; and we see that, whenever  $\frac{d}{2y_0} = \frac{x_0}{y_0} > \tan a$ , it is impossible to describe a catenary through the limiting points so as to have the fixed line for its axis.

When  $\frac{x_0}{y_0} < \tan a$ , it can be readily shown that two, and but two, catenaries can be so drawn; for let  $\frac{x_0}{y_0} = \tan \beta$ , and  $u = \frac{x_0}{a}$ , then equation (70) gives

$$2u \cot \beta = e^u + e^{-u} = 2 \left( 1 + \frac{u^2}{1 \cdot 2} + \frac{u^4}{1 \cdot 2 \cdot 3 \cdot 4} + \&c. \right). \quad (72)$$

This equation cannot have more than two real roots; and the preceding analysis shows that it has no real root when  $\beta > a$ .

Again, the roots are equal when  $\beta = a$ ; for the condition for equal roots gives  $2 \cot \beta = e^u - e^{-u}$ ; and we see that in that case  $u$  is given by equation (71), and we must have  $\beta = a$ .

Next, we have already seen in Ex. 4, p. 261, that if  $S$  be the surface generated by the revolution round its axis of any portion  $ON$ , measured from the vertex of a catenary, we have

$$S = \pi (ys + ax),$$

where  $x$  and  $y$  are the coordinates of  $N$ , and  $s = ON = NL$ .

Again, if  $\Sigma$  be the surface of the cone generated by  $PN$  in a complete revolution, we have

$$\Sigma = \pi (PN \cdot HN) = \pi y (NL + PL) = \pi ys + \pi y \cdot PL;$$

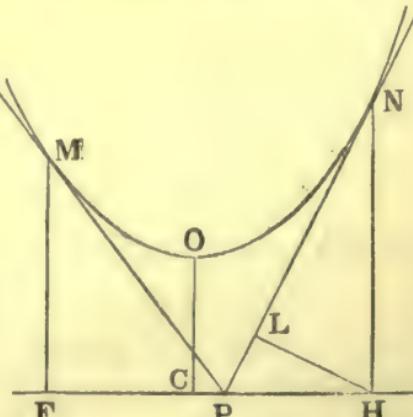


Fig. 88.

but by similar triangles, we have

$$NH \cdot PL = PH \cdot HL = a \cdot PH;$$

therefore

$$\Sigma = \pi (ys + a \cdot PH).$$

Accordingly

$$S - \Sigma = \pi a \cdot CP.$$

If  $PM$  be a second tangent drawn from  $P$  to the curve, we have, in like manner,

$$S' - \Sigma' = -\pi a CP,$$

where  $S'$  and  $\Sigma'$  are the surface-areas generated by  $OM$  and by  $PM$ , respectively; hence we see that

$$S + S' = \Sigma + \Sigma'. \quad (73)$$

Consequently, if from any point  $P$  on the axis of a catenary, tangents,  $PM$  and  $PN$ , be drawn to the curve, the surface generated by the arc  $MN$  in its revolution around the axis is equal to the surface generated by the broken line  $MPN$  in the same revolution.

More generally, if the tangent at  $M$  meets the axis in a point  $P'$ , we have, adopting a similar notation,

$$S' - \Sigma' = -\pi a CP';$$

and we get, in general,

$$S + S' - (\Sigma + \Sigma') = \pm \pi a PP'. \quad (74)$$

In this equation the upper or lower sign is taken according as the tangents intersect below or above the fixed axis.

From this it follows that, if tangents to the curve be drawn at any two points,  $M$  and  $N$ , on a catenary, the surface generated by the revolution of the curve  $MN$  round the axis is greater or less than the surface generated by the revolution of the broken line  $MP'PN$ , according as  $CP$  is greater or less than  $CP'$ .

In fig. 87 it can be shown without difficulty that the upper curve  $A'A$  gives a true minimum, while the lower curve corresponds only to a stationary solution. (Art. 284.)

306. To find the curve for which the area between the curve, its evolute, and the extreme radii of curvature shall be a minimum. Here we have

$$U = \int_{s_0}^{s_1} \rho ds = \int_{x_0}^{x_1} \frac{(1 + \dot{y}^2)^2}{\ddot{y}} dx.$$

Hence, since  $V$  does not contain either  $x$  or  $y$ , we have, by (30),

$$V = c + c' \dot{y} + P_2 \ddot{y};$$

but in this case

$$P_2 \ddot{y} = -V;$$

therefore we may write

$$V = c_1 + c_2 \dot{y}, \quad (75)$$

where  $c_1$  and  $c_2$  are arbitrary constants.

This equation may be written in the form

$$\begin{aligned} \rho &= \frac{c_1}{\sqrt{1 + \dot{y}^2}} + \frac{c_2 \dot{y}}{\sqrt{1 + \dot{y}^2}} \\ &= c_1 \cos \phi + c_2 \sin \phi, \end{aligned} \quad (76)$$

where  $\phi$ , as before, represents the angle that the tangent to the curve makes with the axis of  $x$ ; therefore

$$\frac{ds}{d\phi} = c_1 \cos \phi + c_2 \sin \phi.$$

This gives  $s = c_1 \sin \phi - c_2 \cos \phi + c_3$ ;

and accordingly the curve is a cycloid.

Again :

(1°). If the limiting points be fixed, but *not the tangents at these points*, equation  $\left| \begin{array}{l} x_1 \\ x_0 \end{array} \right. L = 0$  becomes

$$\left| \begin{array}{l} x_1 \\ x_0 \end{array} \right. P_2 \delta \dot{y} = 0.$$

This gives  $P_2 = 0$ , at each limit.

Hence  $\rho = 0$  at both limits, and consequently the *extreme points are cusps on the cycloid*; accordingly the curve in this case is a complete cycloid.

(2°). Suppose the extreme points lie on given curves. Here, the equation  $L = 0$  becomes, by (20),

$$\begin{cases} x_1 \\ x_0 \end{cases} (2c_1 \Delta x + 2c_2 \Delta y + P_2 \Delta \dot{y}) = 0.$$

Hence, since  $\Delta \dot{y}$  is arbitrary at the limits, we must have  $P_2 = 0$  at each limit, and therefore the extreme points are *cusps*, as in the former case.

Also we must have

$$c_1 \Delta x + c_2 \Delta y = 0$$

at each limit ; this shows that the curve touches each of the bounding curves ; and also that the line joining the limiting points is a maximum or a minimum distance between the limiting curves.

(3°). If either limiting point be completely indeterminate, we must have

$$c_1 = 0, \quad \text{and} \quad c_2 = 0,$$

and the equation reduces to  $\rho = 0$  at all points, an *impossible* equation, which shows that there is no solution in this case.

307. **Isoperimetrical Problem.**—Again, in the same problem, if the length of the curve be given, we may write

$$U = \int_{x_0}^{x_1} \left\{ \frac{(1 + \dot{y}^2)^2}{\dot{y}} + a \sqrt{1 + \dot{y}^2} \right\} dx.$$

Proceeding as before, we readily get

$$\rho = \frac{c_1}{\sqrt{1 + \dot{y}^2}} + \frac{c_2 \dot{y}}{\sqrt{1 + \dot{y}^2}} + b, \quad \text{where} \quad b = -\frac{1}{2}a;$$

therefore  $\frac{ds}{d\phi} = c_1 \cos \phi + c_2 \sin \phi + b;$

or  $s = c_1 \sin \phi - c_2 \cos \phi + b\phi + d. \quad (77)$

This is the intrinsic equation to the curve.

We see, as before, that the curve becomes a cycloid when  $b = 0$ , i.e. when the length of the curve is not given.

Again, the equations

$$\frac{dy}{ds} = \sin \phi, \quad \frac{dx}{ds} = \cos \phi,$$

give

$$\left. \begin{aligned} \frac{dy}{d\phi} &= \sin \phi (c_1 \cos \phi + c_2 \sin \phi + b) \\ \frac{dx}{d\phi} &= \cos \phi (c_1 \cos \phi + c_2 \sin \phi + b) \end{aligned} \right\}. \quad (78)$$

From these we can express  $x$  and  $y$  in terms of  $\phi$ , and thus determine the equation to the curve by elimination.

308. **General Transformation.**—In general if  $V$  be a function of  $x, y, \dot{y}, \ddot{y}, \dots, y^{(n)}$ , we have

$$\Delta U = \int_{x_0}^{x_1} (P \delta y + P_1 D \delta y + \dots + P_n D^n \delta y) dx + \left|_{x_0}^{x_1} V \Delta x.$$

Now, let  $D_1$  denote the symbol  $\frac{d}{dx}$  when operating on  $\delta y$  solely, and let  $D_2$  denote the symbol when operating on any of the functions  $P, P_1, \dots, P_n$ , then we may write

$$\begin{aligned} P_m D^m \delta y - (-1)^m \delta y D^m P_m &= (D_1^m - (-1)^m D_2^m) (P_m \delta y) \\ &= (D_1 + D_2) (D_1^{m-1} - D_1^{m-2} D_2 + \dots + (-1)^{m-1} D_2^{m-1}) (P_m \delta y) \\ &= \frac{d}{dx} \left( P_m D^{m-1} \delta y - \frac{dP_m}{dx} D^{m-2} \delta y + \dots + (-1)^{m-1} \frac{d^{m-1} P_m}{dx^{m-1}} \delta y \right). \end{aligned}$$

Hence we get

$$\begin{aligned} \int_{x_0}^{x_1} dx P_m D^m \delta y &= (-1)^m \int dx \delta y \frac{d^m P_m}{dx^m} \\ &+ \left|_{x_0}^{x_1} \left( P_m D^{m-1} \delta y - \frac{dP_m}{dx} D^{m-2} \delta y + \dots + (-1)^{m-1} \frac{d^{m-1} P_m}{dx^{m-1}} \delta y \right) \right|. \end{aligned}$$

Applying this to the different terms in the value of  $\Delta U$  given above, we get

$$\Delta U = \int_{x_0}^{x_1} (P) \delta y dx + \left| \begin{array}{l} x_1 \\ x_0 \end{array} \right. V \Delta x \\ + \left| \begin{array}{l} x_1 \\ x_0 \end{array} \right. \left\{ (P_1) \delta y + (P_2) \delta \dot{y} + \dots + P_n \delta y^{(n-1)} \right\}, \quad (79)$$

where

$$(P) = P - \frac{dP_1}{dx} + \frac{d^2P_2}{dx^2} - \dots + (-1)^n \frac{d^n P_n}{dx^n},$$

$$(P_1) = P_1 - \frac{dP_2}{dx} + \frac{d^2P_3}{dx^2} - \dots + (-1)^{n-1} \frac{d^{n-1} P_n}{dx^{n-1}},$$

and so on.

We may write this, as before, in the form

$$\Delta U = \int_{x_0}^{x_1} (P) \delta y dx + \left| \begin{array}{l} x_1 \\ x_0 \end{array} \right. L. \quad (80)$$

308a. **Maxima and Minima.**—It is plain, as in Art. 284, that for a maximum or minimum value of the definite integral, we must have

$$(P) = 0, \text{ and } \left| \begin{array}{l} x_1 \\ x_0 \end{array} \right. L = 0. \quad (81)$$

Also, as before, the coefficient of each independent variation in the equation at the limits

$$\left| \begin{array}{l} x_1 \\ x_0 \end{array} \right. L = 0$$

must be zero in this case.

309. **Case of Two Dependent Variables.**—More generally, let  $V$  be a function of  $x, y, z, \dot{y}, \dot{z}, \ddot{y}, \ddot{z}, \dots, y^{(n)}, z^{(m)}$ , where  $y$  and  $z$  are functions of  $x$ .

Then if

$$U = \int_{x_0}^{x_1} V dx,$$

we shall have

$$\begin{aligned}\Delta U = & \left| \int_{x_0}^{x_1} V \Delta x + \int_{x_0}^{x_1} (P \delta y + P_1 D \delta y + \dots + P_n D^n \delta y) dx \right. \\ & \left. + \int_{x_0}^{x_1} (Q \delta z + Q_1 D \delta z + \dots + Q_m D^m \delta z) dx, \right.\end{aligned}$$

adopting the notation given in Arts. 291 and 308.

Hence, proceeding as in the last Article, we readily see that  $\Delta U$  can be transformed into the following shape:—

$$\begin{aligned}\Delta U = & \left| \int_{x_0}^{x_1} \left\{ (P) \delta y + (Q) \delta z \right\} dx + \int_{x_0}^{x_1} V \Delta x \right. \\ & \left. + \int_{x_0}^{x_1} \left\{ (P_1) \delta y + (P_2) \delta \dot{y} + \dots + P_n \delta y^{(n-1)} \right\} \right. \\ & \left. + \int_{x_0}^{x_1} \left\{ (Q_1) \delta z + (Q_2) \delta \dot{z} + \dots + Q_m \delta z^{(m-1)} \right\} \right.\end{aligned}$$

where

$$(Q) = Q - \frac{dQ_1}{dx} + \frac{d^2Q_2}{dx^2} - \dots + (-1)^m \frac{d^m Q_m}{dx^m};$$

and so on.

This may be written, as before, in the form

$$\Delta U = \int_{x_0}^{x_1} (P) \delta y dx + \int_{x_0}^{x_1} (Q) \delta z dx + \int_{x_0}^{x_1} L dx. \quad (82)$$

Also, it is easily seen that for a maximum or minimum value of  $U$  we must have

$$(P) = 0, \quad (Q) = 0, \quad \text{and} \quad \int_{x_0}^{x_1} L = 0.$$

**310. Condition of Integrability.**—The result contained in equation (79) furnishes us at once with the condition that  $V dx$  should be an exact differential, independent of the particular form of the function  $y$ . For, in this case,

$$\int_{x_0}^{x_1} V dx$$

must be a function of the limiting values of  $x, y, \dot{y} \dots y^n$ , solely, and consequently when these limiting values are unaltered we must have  $\delta U = 0$ ; but by (79) we have in that case

$$\delta U = \int_{x_0}^{x_1} (P) \delta y \, dx.$$

Accordingly this integral must be zero for all values of  $\delta y$ ; and hence the equation

$$(P) = 0, \quad \text{or} \quad P - \frac{dP_1}{dx} + \frac{d^2P_2}{dx^2} - \dots \pm \frac{d^n P_n}{dx^n} = 0 \quad (83)$$

must vanish identically.

**311. Method of the Differential Calculus.**—This result can also be readily arrived at without any reference to the Calculus of Variations; for suppose that  $V dx$  is the exact differential of a function  $\phi$ , where  $\phi$  is of the order  $(n-1)$  in the differential coefficients  $\dot{y}, \ddot{y}, \dots$ , then we have

$$V = D \cdot \phi = \frac{d\phi}{dx} + \dot{y} \frac{d\phi}{dy} + \ddot{y} \frac{d\phi}{d\dot{y}} + \dots + y^{(n)} \frac{d\phi}{dy^{(n-1)}}. \quad (84)$$

This shows that  $V dx$  cannot be an exact differential unless it is linear in its highest differential coefficient,  $y^{(n)}$ .

We now proceed to determine the condition that any function  $V$  should satisfy equation (84).

In this case we have

$$P_n = \frac{dV}{dy^{(n)}} = \frac{d\phi}{dy^{(n-1)}}, \quad P_{n-1} = \frac{dV}{dy^{(n-1)}} = D \frac{d\phi}{dy^{(n-1)}} + \frac{d\phi}{dy^{(n-2)}},$$

these lead to

$$DP_n - P_{n-1} + \frac{d\phi}{dy^{(n-2)}} = 0;$$

$$\therefore D^2 P_n - DP_{n-1} + D \frac{d\phi}{dy^{(n-2)}} = 0.$$

Again,

$$P_{n-2} = D \frac{d\phi}{dy^{(n-2)}} + \frac{d\phi}{dy^{(n-3)}};$$

hence

$$D^2P_n - DP_{n-1} + P_{n-2} - \frac{d\phi}{dy^{(n-3)}} = 0.$$

It is readily seen, by continuing this process, that we must have

$$D^rP_n - D^{r-1}P_{n-1} + \dots \pm P_{n-r} \mp \frac{d\phi}{dy^{(n-r-1)}} = 0, \quad (85)$$

where the upper or lower signs are to be taken according as  $r$  is an even or an odd integer. If we make  $r = n - 1$ , this becomes

$$D^{n-1}P_n - D^{n-2}P_{n-1} + \dots \pm P_1 \mp \frac{d\phi}{dy} = 0.$$

Hence

$$D^nP_n - D^{n-1}P_{n-1} + \dots \pm DP_1 \mp P = 0,$$

observing that

$$P = \frac{dV}{dy} = D \frac{d\phi}{dy}.$$

This verifies the result arrived at by the Calculus of Variations.

312. **Converse Theorem.** — The Converse Theorem, viz. that when  $(P) = 0$ , identically,  $V$  is an exact differential coefficient, can also be proved as follows.

Here, we have

$$D^nP_n - D^{n-1}P_{n-1} + \dots \pm P = 0. \quad (86)$$

Again, we have the symbolic equation

$$DP_n = \left( \frac{d}{dx} + \dot{y} \frac{d}{dy} + \ddot{y} \frac{d}{d\dot{y}} + \dots + y^{(n+1)} \frac{d}{dy^n} \right) P_n;$$

$$\therefore D^nP_n = D^{n-1} \left( \frac{d}{dx} + \dot{y} \frac{d}{dy} + \dots + y^{(n+1)} \frac{d}{dy^{(n)}} \right) P_n;$$

and we see that the term of the *highest order* in (86) is

$$y^{(2n)} \frac{dP_n}{dy^{(n)}}.$$

Consequently we must have

$$\frac{dP_n}{dy^{(n)}} = 0, \quad \text{or} \quad \frac{d^2 V}{dy^{(n)2}} = 0.$$

Hence  $V$  must be *linear* in  $y^{(n)}$ ; and we may assume that  $V$  is of the form

$$V = f + y^{(n)} \psi, \quad (87)$$

where  $f$  and  $\psi$  are of the *order*  $n - 1$  at highest.

Also we can, in general, readily determine  $\phi_1$ , so as to satisfy the equation

$$\frac{d\phi_1}{dy^{(n-1)}} = \psi = \frac{dV}{dy^{(n)}}; \quad (88)$$

and accordingly we may write  $V$  in the form

$$V = f + y^{(n)} \frac{d\phi_1}{dy^{(n-1)}}. \quad (89)$$

Again, since

$$\frac{d}{dx} (\phi_1) = \left( \frac{d}{dx} + \dot{y} \frac{d}{dy} + \dots + y^{(n)} \frac{d}{dy^{(n-1)}} \right) \phi_1,$$

we may write (89) in the form

$$V = \chi_1 + \frac{d}{dx} (\phi_1),$$

where  $\chi_1$  is of the order  $n - 1$  at highest.

Since the latter term is an exact differential, our result will be proved if  $\chi_1$  can be shown to be an exact differential.

As before, since  $\chi_1$  must also satisfy the equation  $(P) = 0$ , it must be of the form

$$\chi_1 = f_1 + y^{(n-1)} \psi_1;$$

or

$$\chi_1 = \chi_2 + \frac{d}{dx} (\phi_2), \quad \text{where} \quad \frac{d\phi_2}{dy^{(n-2)}} = \psi_1, \quad (90)$$

and where  $\chi_2$  is of the order  $n - 2$  at highest.

In like manner, we must have

$$\chi_3 = \chi_s + \frac{d}{dx} (\phi_3), \text{ &c.,}$$

and hence it is easily seen that when  $(P) = 0$ , identically,  $V$  must be an exact differential.

**313. Integration of the Differential Equation.**—The determination of  $\phi$ , *i.e.* the integration of the differential equation  $V = 0$ , can be readily effected in this case; for we can find  $\phi_1$  from (88),  $\phi_2$  from (90), and so on.

For instance, to integrate the differential equation

$$x^3\ddot{y} + 2x^2\ddot{y} - 2x\dot{y} + y^2 + 2xy\dot{y} = 0,$$

which satisfies the criterion of integrability.

Here  $\frac{d\phi_1}{d\ddot{y}} = x^3; \therefore \phi_1 = x^3\ddot{y};$

hence  $\frac{d}{dx} (\phi_1) = 3x^2\ddot{y} + x^3\ddot{y};$

therefore  $\chi_1 = -x^2\ddot{y} - 2x\dot{y} + y^2 + 2xy\dot{y};$

hence  $\frac{d\phi_2}{d\dot{y}} = -x^2; \therefore \phi_2 = -x^2\dot{y},$

and  $\frac{d}{dx} (\phi_2) = -x^2\ddot{y} - 2x\dot{y}; \therefore \chi_2 = y^2 + 2xy\dot{y}.$

Accordingly the required integral is

$$x^3\ddot{y} - x^2\dot{y} + xy^2 = C_1.$$

**314. Condition of Integrability in case of two Dependent Variables.**—The preceding process can be easily extended to the case where  $V$  is a function of  $x, y, z, \dot{y}, \dot{z} \dots y^{(n)}, z^{(m)}$ ; and it can be readily seen that when  $V$  is an exact differential, we must have  $(P) = 0$ ,  $(Q) = 0$ , and *conversely*.

The proof is left to the student, and is seen to follow without difficulty from that given in the preceding Article.

**315. Criterion for Maxima and Minima.**—In Art. 284 we have seen that further conditions are requisite in order that the solution of any problem, obtained from the equation  $\Delta U = 0$ , should be a real maximum or minimum solution. These conditions were investigated by Legendre, Lagrange, and other eminent mathematicians, but the complete solution of the problem was first supplied by Jacobi.

It is easily seen, as in the extension of Taylor's theorem, that  $U_2$  is derived from  $U_1$  by the same process that  $U_1$  is derived from  $U$ .

Again, assuming that the limiting values of  $x, y, \dot{y}$ , &c., are fixed, we have, by (21),

$$\delta U = \int_{x_0}^{x_1} M \delta y dx,$$

and consequently

$$a^2 U_2 = \delta^2 U = \int_{x_0}^{x_1} \delta M \delta y dx, \quad (91)$$

where we also have  $M = 0$ .

Accordingly, as in Art. 284, the conditions for a real maximum or minimum in general depend on the value of the definite integral

$$\int_{x_0}^{x_1} \delta M \delta y dx.$$

**316. Application to  $V = f(x, y, \dot{y})$ .**—It would be beyond the limits proposed in this chapter to enter into a general discussion of the foregoing problem; we shall merely consider the case where  $V$  is a function of  $x, y$ , and  $\dot{y}$  solely.

In that case we have

$$M = P - \frac{dP_1}{dx}; \quad \therefore \delta M = \delta P - \frac{d}{dx} \delta P_1.$$

Now, observing that

$$\frac{dP_1}{dy} = \frac{dP}{d\dot{y}}, \quad \text{and writing } z \text{ for } dy,$$

$$\begin{aligned} \text{we have } \delta M &= \frac{dP}{d\dot{y}} z + \frac{dP_1}{dy} \dot{z} - \frac{d}{dx} \left( \frac{dP_1}{dy} z + \frac{dP_1}{d\dot{y}} \dot{z} \right) \\ &= z \left[ \frac{dP}{d\dot{y}} - \frac{d}{dx} \left( \frac{dP_1}{dy} \right) \right] - \frac{d}{dx} \left( \frac{dP_1}{d\dot{y}} \dot{z} \right). \end{aligned}$$

If we now suppose that  $u$  is any solution of the differential equation  $\delta M = 0$ , we have

$$u \left[ \frac{dP}{dy} - \frac{d}{dx} \left( \frac{dP_1}{dy} \right) \right] - \frac{d}{dx} \left( \frac{dP_1}{dy} \dot{u} \right) = 0;$$

hence, in general, we may write

$$\begin{aligned} \delta M &= \frac{1}{u} \left[ \dot{z} \frac{d}{dx} \left( \frac{dP_1}{dy} \dot{u} \right) - u \frac{d}{dx} \left( \frac{dP_1}{dy} \dot{z} \right) \right] \\ &= \frac{1}{u} \frac{d}{dx} \left[ \frac{dP_1}{dy} (\dot{u}z - u\dot{z}) \right] = - \frac{1}{u} \frac{d}{dx} \left[ u^2 Q_2 \frac{d}{dx} \left( \frac{z}{u} \right) \right], \end{aligned}$$

writing  $Q_2$  for  $\frac{dP_1}{dy}$ .

Consequently

$$\begin{aligned} \delta^2 U &= \int_{x_0}^{x_1} z \delta M dx \\ &= - \int_{x_0}^{x_1} \frac{z}{u} \frac{d}{dx} \left[ u^2 Q_2 \frac{d}{dx} \left( \frac{z}{u} \right) \right] dx \\ &= - \left[ \int_{x_0}^{x_1} z u Q_2 \frac{d}{dx} \left( \frac{z}{u} \right) + \int_{x_0}^{x_1} u^2 Q_2 \left[ \frac{d}{dx} \left( \frac{z}{u} \right) \right]^2 dx \right] \\ &= \int_{x_0}^{x_1} Q_2 \left[ u \frac{d}{dx} \left( \frac{z}{u} \right) \right]^2 dx = \int_{x_0}^{x_1} \frac{d^2 V}{dy^2} \left[ u \frac{d}{dx} \left( \frac{\delta y}{u} \right) \right]^2 dx, \quad (92) \end{aligned}$$

since  $\delta y$ , or  $z$ , vanishes at both limits, by hypothesis.

Hence we see that, provided the other factor does not vanish, the distinctive character of a maximum or a minimum depends on the function  $Q_2$  or  $\frac{d^2 V}{dy^2}$ .

If  $Q_2 dx$  is positive for all values between the limits of integration, then  $U$  has a minimum value; if  $Q_2 dx$  be negative,  $U$  has a maximum value. Again, if  $Q_2 dx$  changes its sign between the limits of integration there is neither a

maximum nor a minimum value for  $U$ ; for in that case we can dispose of the arbitrary function  $\delta y$  so that either the positive or the negative part of the integral shall be the greater, *at our pleasure*.

The application of this criterion to the examples previously considered is left for the student. For further investigations the student is referred to Jellett's *Calculus of Variations*, or to that of Moigno and Lindelöf. An original discussion of the criterion for the discrimination of maximum and minimum solutions has been given by Mr. Culverwell in the Royal Society Transactions (1887). See also Proc. Lond. Math. Soc., vol. xxiii.

### EXAMPLES.

1. Prove that the closed curve of given length that encloses a maximum area is a circle.

2. Prove that for any system of coplanar forces the curve of quickest descent is such that at each point the pressure on the curve due to the forces is equal to that due to the motion.

Here we have, by mechanical considerations,

$$\frac{1}{2}mv^2 = \int (Xdx + Ydy),$$

also

$$U = \int_{s_0}^{s_1} \frac{ds}{v}, \quad \text{a minimum,}$$

or, by (45),

$$U = \frac{1}{2} \int_{s_0}^{s_1} \frac{1}{v} (\dot{x}^2 + \dot{y}^2 + 1) ds;$$

hence, by (49),

$$\frac{mv^2}{\rho} = X \sin \phi - Y \cos \phi,$$

which proves the theorem in question.

3. Find the differential equation of the curve, such that the surface generated by its revolution round a given line shall be constant, and the contained volume shall be a maximum.

Here, by (53), Art. 298, we get

$$U = \int_{s_0}^{s_1} \{ y^2 \dot{x} + \frac{1}{2}ay(\dot{x}^2 + \dot{y}^2 + 1) \} ds;$$

hence the differential equation of the curve, by (54), is

$$ay\dot{x} + y^2 = \sigma.$$

[30]

4. Hence show that if the surface is closed the curve is a circle.  
It is readily seen that in this case we must have  $c = 0$ .

5. Show that, in general, the curve in Ex. 3 is the roulette described by the focus of an ellipse or hyperbola rolling on the given right line. [DELAUNAY, *Journal de Liouville*, tome VI.]

6. Find the differential equations of a curve of shortest length on a given surface.

Let  $u = 0$  be the equation of the surface; then we have  $\dot{x}^2 + \dot{y}^2 + \dot{z}^2 = 1$ , and  $\int ds$  a minimum; consequently we may write

$$U = \int_{s_1}^{s_2} \left\{ \frac{a}{2} (\dot{x}^2 + \dot{y}^2 + \dot{z}^2 + 1) + \mu u \right\} ds;$$

hence we get

$$\mu \frac{du}{dx} = a\dot{x}, \quad \mu \frac{du}{dy} = a\dot{y}, \quad \mu \frac{du}{dz} = a\dot{z};$$

and the differential equations of the curve are

$$\frac{\dot{x}}{\frac{du}{dx}} = \frac{\dot{y}}{\frac{du}{dy}} = \frac{\dot{z}}{\frac{du}{dz}}.$$

From these it follows that the osculating plane to the curve at each point passes through the normal at the point. Such curves are called *geodesics*.

7. Show that the differential equation of the plane curve which makes  $\int \phi(\rho) ds$  a maximum or a minimum,  $\rho$  being the radius of curvature, is given by the equation

$$\rho^2 \phi'(\rho) = ay.$$

Here

$$U = \int (\phi(\rho) + \lambda (\dot{x}^2 + \dot{y}^2 - 1)) ds;$$

also

$$\frac{1}{\rho^2} = \dot{x}^2 + \dot{y}^2.$$

Hence, as in (27), Art. 288, we have

$$(P_1) = a, \quad (Q_1) = b,$$

or

$$\lambda \dot{x} + \frac{d}{ds} (\rho^3 \phi'(\rho) \dot{x}) = a, \quad \lambda \dot{y} + \frac{d}{ds} (\rho^3 \phi'(\rho) \dot{y}) = b;$$

therefore

$$\dot{y} \frac{d}{ds} (\rho^3 \phi'(\rho) \dot{x}) - \dot{x} \frac{d}{ds} (\rho^3 \phi'(\rho) \dot{y}) = a\dot{y} - b\dot{x},$$

that is

$$\frac{d}{ds} \{ \rho^3 \phi'(\rho) (\dot{x}\dot{y} - \dot{y}\dot{x}) \} = a\dot{y} - b\dot{x};$$

hence

$$\rho^3 \phi'(\rho) = ay - bx + c.$$

If the limiting points be fixed, we have  $\Delta x = 0$ ,  $\Delta y = 0$ , at each limit; also by Art. 291, we must have  $P_2 \Delta \dot{x} + Q_2 \Delta \dot{y} = 0$  at each limit.

But we have in general  $\dot{x} \Delta \dot{x} + \dot{y} \Delta \dot{y} = 0$ ; hence, at each limit we get

$$\frac{\rho^2 \phi'(\rho)}{\dot{y}} \Delta \dot{x} = 0, \text{ that is } \rho^2 \phi'(\rho) = 0.$$

This shows that the line  $ay - bx + c = 0$  passes through the limiting points. If this line be taken for the axis of  $x$ , the general equation of the maximum or minimum curve may be written in the form

$$\rho^2 \phi'(\rho) = ay.$$

8. Prove that a sphere is the only closed surface of revolution which contains a maximum volume under a given surface.

9. Let it be required to draw between two points a curve for which  $\int \mu dr$  is a maximum or a minimum, where  $\mu$  is a function of  $x$  and  $y$  solely. Show that if it be possible to draw more than one curve satisfying the condition

$$\delta \int \mu ds = 0,$$

and if these curves be arranged according to the angles which their initial tangents make with a given line, then no two consecutive curves will give real maxima or minima.

## CHAPTER XVII.

## CALCULUS OF VARIATIONS.

*Multiple Integrals.*

317. **Variation of a Double Integral.**—We shall next proceed to the application of the Calculus of Variations to multiple integrals.

We shall first consider the case of the double integral

$$U = \iint V dx dy,$$

where  $V$  is a function of  $x, y, z, p, q$ : in which  $z$  is regarded as an indeterminate function of  $x, y$ , and

$$p = \frac{dz}{dx}, \quad q = \frac{dz}{dy},$$

in accordance with the ordinary notation.

A geometrical signification can always be given to the function  $U$ , by supposing  $x, y, z$  to be the coordinates of a point referred to rectangular axes: and, as in Art. 273, we may suppose the integral extended over any area contained within one or more closed boundaries.

Also, as in Art. 279, we shall suppose  $\delta z$  to represent any indefinitely small variation in  $z$  arising from a small change in the form of the function connecting  $z$  with  $x$  and  $y$ , while  $x$  and  $y$  remain unaltered.

Hence, as in Art. 281, we shall have

$$\delta V = \frac{dV}{dz} \delta z + \frac{dV}{dp} \delta p + \frac{dV}{dq} \delta q = N \delta z + P \delta p + Q \delta q, \quad (1)$$

where

$$N = \frac{dV}{dz}, \quad P = \frac{dV}{dp}, \quad Q = \frac{dV}{dq}.$$

Again, it is obvious that the variation of  $U$  consists in general of two parts—(1) that arising solely from the variation of  $V$ ; (2) that caused by a small variation of the boundary or boundaries.

318. **Case of a Fixed Boundary.**—If we suppose the whole boundary to remain unchanged, we shall have

$$\begin{aligned}\delta U &= \iint \delta V dx dy = \iint \left( N \delta z + P \frac{d \delta z}{dx} + Q \frac{d \delta z}{dy} \right) dx dy \\ &= \iint \left( N - \frac{dP}{dx} - \frac{dQ}{dy} \right) \delta z dx dy \\ &\quad + \iint \left( \frac{d(P \delta z)}{dx} + \frac{d(Q \delta z)}{dy} \right) dx dy. \quad (2)\end{aligned}$$

The reduction of the latter integral depends on the nature of the relations by which the boundary is defined.

If the boundary consists of one or more *fixed closed curves*, then, as in Art. 274, we have

$$\iint \left( \frac{d(P \delta z)}{dx} + \frac{d(Q \delta z)}{dy} \right) dx dy = \int \left( Q - P \frac{dy}{dx} \right) \delta z dx,$$

where the single integral is taken around the entire boundary.

Hence, in this case

$$\delta U = \iint \left( N - \frac{dP}{dx} - \frac{dQ}{dy} \right) \delta z dx dy + \int \left( Q - P \frac{dy}{dx} \right) \delta z dx. \quad (3)$$

It is to be observed that the value of  $\frac{dy}{dx}$  can be found for each part of the boundary when its equation is given.

It is often useful to take the boundary arc as the independent variable. In this case (3) becomes

$$\delta U = \iint \left( N - \frac{dP}{dx} - \frac{dQ}{dy} \right) \delta z dx dy + \int \left( Q \frac{dx}{ds} - P \frac{dy}{ds} \right) \delta z ds. \quad (4)$$

If the integral be written in the form

$$U = \int_{x_0}^{x_1} \int_{y_0}^{y_1} V dx dy,$$

we have, by (11), Art. 271,

$$\begin{aligned} \delta U = & \int_{x_0}^{x_1} \int_{y_0}^{y_1} \left( N - \frac{dP}{dx} - \frac{dQ}{dy} \right) dx dy \\ & + \int_{x_0}^{x_1} \left| \begin{array}{l} y_1 \\ y_0 \end{array} \right| \left( Q - P \frac{dy}{dx} \right) \delta z dx + \left| \int_{x_0}^{x_1} \int_{y_0}^{y_1} P \delta z dy \right|. \quad (5) \end{aligned}$$

This represents the *complete variation* of the double integral, whenever the bounding curves,  $y = y_0$ ,  $y = y_1$ , are *fixed*; and also  $x_1$  and  $x_0$ , the limiting values of  $x$ .

Moreover, if the value of  $z$  along the boundary be also unaltered, we must have  $\delta z = 0$  for the boundary, and the single integrals in this case vanish identically. This has place when the boundary consists of a *fixed curve*, or curves, *in space*.

**319. Terms arising from Variation of Boundary.**—Let us now consider the additional terms that arise from a *variation in the boundary relations*.

Here, if the complete variation of  $U$  be denoted by  $\Delta U$ , we readily see, from (12), Art. 272, that

$$\Delta U = \int_{x_0}^{x_1} \int_{y_0}^{y_1} \delta V dx dy + \int_{x_0}^{x_1} \left| \begin{array}{l} y_1 \\ y_0 \end{array} \right| V \Delta y dx + \left| \int_{x_0}^{x_1} \int_{y_0}^{y_1} V \Delta x dy \right|, \quad (6)$$

where  $\Delta x$  and  $\Delta y$  represent indefinitely small variations arising from any small alteration in the boundary relations.

**320. Geometrical Representation.**—The change in  $U$  arising from the variation of the boundary readily admits of geometrical representation.

For, let  $A_1B_1D_1C_1A_1$  represent any new boundary which is indefinitely near to the original boundary  $ABDCA$ : then, since the original integral is taken over the area  $ABDCA$ , while the new integral is taken over  $A_1B_1D_1C_1A_1$ , the difference between the two integrals (neglecting the variation in  $V$ ), when the proper algebraic signs are given to the portions that are *not common* to the two areas, is easily seen from the accompanying figure to be represented by the expression

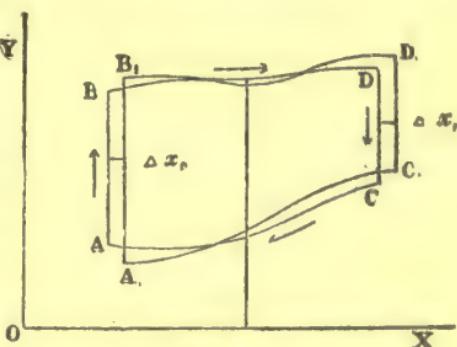


Fig. 89.

$$\Delta x_1 \int_{y_0}^{y_1} \left| \begin{array}{l} x_1 \\ y_1 \end{array} \right| V \cdot dy - \Delta x_0 \int_{y_0}^{y_1} \left| \begin{array}{l} x_0 \\ y_0 \end{array} \right| V \cdot dy + \int_{x_0}^{x_1} \left| \begin{array}{l} y_1 \\ x_1 \end{array} \right| V \Delta y \cdot dx \\ - \int_{x_0}^{x_1} \left| \begin{array}{l} y_0 \\ x_0 \end{array} \right| V \Delta y \cdot dx$$

This is readily identified with the expression in (5).

It is to be observed that the part of  $\Delta U$  that arises from a small change in  $V$  has been *neglected in the single integrals*, as it only introduces an indefinitely small quantity of the *second order* into the expression for  $\Delta U$ .

When the boundary consists of a single curve, as in Art. 274, the terms containing  $\Delta x_0$  and  $\Delta x_1$  disappear; and the variation arising from the alteration of the boundary is represented by

$$\int V \Delta y \cdot dx$$

taken, *with its proper sign*, round the entire boundary. The modification for the case of an inner and outer boundary is easily seen as before.

**321. Complete Variation of  $U$ .**—If we substitute in (6) the value given for

$$\iint \delta V dx dy$$

in (5), the complete variation of the double integral becomes

$$\begin{aligned} \Delta U = & \int_{x_0}^{x_1} \int_{y_0}^{y_1} \left( N - \frac{dP}{dx} - \frac{dQ}{dy} \right) \delta z dx dy \\ & + \int_{x_0}^{x_1} \left| \int_{y_0}^{y_1} \left( \left( Q - P \frac{dy}{dx} \right) \delta z + V \Delta y \right) dx \right. \\ & \quad \left. + \int_{x_0}^{x_1} \int_{y_0}^{y_1} \left( P \delta z + V \Delta x \right) dy \right. \quad (6) \end{aligned}$$

In the case of a closed curvilinear boundary, the latter single integral disappears, as in Art. 274 and Art. 317; and the result may be written

$$\begin{aligned} \Delta U = & \iint \left( N - \frac{dP}{dx} - \frac{dQ}{dy} \right) \delta z dx dy \\ & + \int \left\{ \left( Q - P \frac{dy}{dx} \right) \delta z + V \Delta y \right\} dx, \quad (7) \end{aligned}$$

where the double integral is taken for all points within the *whole field of integration*, and the single integral for all points on the boundary.

The further reduction of the single integrals in (6) and (7) depends on the boundary conditions.

**322. Maxima and Minima.**—The treatment of maximum or minimum problems in the case of double integrals proceeds on the same principles as those already considered in Art. 284 for the case of single integrals.

Thus, to determine the function  $z$  so as to render the double integral

$$U = \iint V dx dy$$

a maximum or a minimum, where  $V$  is a given function of  $x, y, z, p, q$ , we must have  $\Delta U = 0$ , for all small variations of  $z$ .

Hence, as in the case of a single integral, the form of the function of  $z$  is to be determined from the equation

$$\Omega = N - \frac{dP}{dx} - \frac{dQ}{dy} = 0. \quad (8)$$

Also, by (7), we must have

$$\left( Q - P \frac{dy}{dx} \right) \Delta z + V \Delta y = 0 \quad (9)$$

at all points on the boundary of the whole field of integration.

323. **Reduction of Boundary Relations.**—The further reduction of the expression in (9) depends on the conditions of the problem.

Thus—

(1). If the boundary be fixed, then  $\Delta y = 0$  at all points of the boundary ; and we see, from (9), that the equation

$$Qdx - Pdy = 0, \quad (10)$$

must hold at every point on the bounding curve or curves.

If only part of the boundary is fixed, then equation (10) must hold at every point of that part ; and the more general relation (9) will hold for the remainder.

(2). If the boundary be not fixed, and if there be no boundary relations connecting the coordinates  $x, y, z$ , then we must have

$$Qdx - Pdy = 0, \quad \text{and} \quad V = 0,$$

at each point on the boundary.

(3). Suppose the boundary is restricted to lie in a *fixed plane parallel to the plane of xy*.

In general at all points the complete variation  $\Delta z$  is, by Art. 279, given by the equation

$$\Delta z = \delta z + \frac{dz}{dy} \Delta y = \delta z + q \Delta y. \quad (11)$$

Hence, since  $\Delta z = 0$  for all points on the boundary, we must have

$$\delta z + q \Delta y = 0;$$

and we see, from (9), that we must have

$$V - \left( Q - P \frac{dy}{dx} \right) q = 0 \quad (12)$$

at all points on the boundary.

(4). Suppose the point  $x, y, z$ , for the boundary, in whole or in part, to be restricted to lie on a *fixed given surface*.

Let  $z = f_1(x, y)$  be the equation of this surface: and let

$$\frac{df_1}{dx} = p', \quad \frac{df_1}{dy} = q';$$

then along the boundary we have

$$\Delta z = q' \Delta y,$$

since we regard  $x$  as having no variation.

Also, by (11), we have

$$\Delta z = \delta z + q \Delta y;$$

therefore

$$\delta z = (q' - q) \Delta y \quad (13)$$

along the boundary; hence, from (9), we see that we have

$$V + \left( Q - P \frac{dy}{dx} \right) (q' - q) = 0 \quad (14)$$

at all points on the boundary.

Again, at all points on the fixed surface,  $z = f_1(x, y)$ , we have

$$dz = p'dx + q'dy;$$

but also, we have

$$dz = pdx + qdy;$$

hence, along the boundary we get

$$(p' - p) dx + (q' - q) dy = 0,$$

or

$$\frac{dy}{dx} = -\frac{p' - p}{q' - q}.$$

Accordingly, equation (14) becomes

$$V + P(p' - p) + Q(q' - q) = 0. \quad (15)$$

The modification in the case of two or more limiting surfaces is readily seen.

324. **Surface of Minimum Area.**—To investigate the surface of least superficial area between given limits.

Here we have

$$U = \iint \left( \sqrt{1 + p^2 + q^2} \right) dx dy,$$

and the equation  $\Omega = 0$  becomes

$$\frac{d}{dx} \left( \frac{p}{\sqrt{1 + p^2 + q^2}} \right) + \frac{d}{dy} \left( \frac{q}{\sqrt{1 + p^2 + q^2}} \right) = 0,$$

$$\text{or} \quad (1 + q^2) r - 2pqs + (1 + p^2) t = 0. \quad (16)$$

Hence (Salmon, *Geometry of Three Dimensions*, Art. 311), we get

$$\frac{1}{R} + \frac{1}{R'} = 0, \quad (17)$$

where  $R$  and  $R'$  are the principal radii of curvature at any point on the surface.

Accordingly, the *principal radii of curvature at each point on the surface are equal and of opposite signs.*

In the case of a fixed limiting surface or surfaces, equation (15) becomes

$$1 + pp' + qq' = 0. \quad (18)$$

This shows that the required surface cuts the limiting surfaces at right angles at each point of intersection.

325. More generally, to investigate the differential equation to the surface for which  $\iint \mu dS$  is a maximum or a minimum where  $\mu$  is a given function of the coordinates, and  $dS$  is an element of the surface.

Here we have

$$U = \iint \mu dS = \iint \mu \sqrt{1 + p^2 + q^2} dx dy;$$

$$\therefore V = \mu \sqrt{1 + p^2 + q^2}.$$

Hence

$$N = \frac{d\mu}{dz} \sqrt{1 + p^2 + q^2}, \quad P = \frac{\mu p}{\sqrt{1 + p^2 + q^2}}, \quad Q = \frac{\mu q}{\sqrt{1 + p^2 + q^2}};$$

$$\therefore \frac{dP}{dx} = \frac{p}{\sqrt{1 + p^2 + q^2}} \left( \frac{d\mu}{dx} + p \frac{d\mu}{dz} \right) + \mu \frac{d}{dx} \left( \frac{p}{\sqrt{1 + p^2 + q^2}} \right),$$

$$\frac{dQ}{dy} = \frac{q}{\sqrt{1 + p^2 + q^2}} \left( \frac{d\mu}{dy} + q \frac{d\mu}{dz} \right) + \mu \frac{d}{dy} \left( \frac{q}{\sqrt{1 + p^2 + q^2}} \right).$$

Consequently, the equation  $\Omega = 0$  gives

$$\begin{aligned} & \frac{1}{\mu \sqrt{1 + p^2 + q^2}} \left( \frac{d\mu}{dz} - p \frac{d\mu}{dx} - q \frac{d\mu}{dy} \right) \\ &= \frac{d}{dx} \left( \frac{p}{\sqrt{1 + p^2 + q^2}} \right) + \frac{d}{dy} \left( \frac{q}{\sqrt{1 + p^2 + q^2}} \right). \end{aligned}$$

If  $l, m, n$  be the direction-cosines of the normal to the

surface, this equation may be written in the following form:—

$$\frac{1}{R} + \frac{1}{R'} = \frac{1}{\mu} \left( l \frac{d\mu}{dx} + m \frac{d\mu}{dy} + n \frac{d\mu}{dz} \right). \quad (19)$$

(Compare Jellett, *Calculus of Variations*, Art. 121.)

Again, in the case of one or more *fixed* limiting surfaces, we get, by equation (15),

$$1 + pp' + qq' = 0. \quad (20)$$

This shows that the required surface must intersect each of the bounding surfaces orthogonally.

**326. Relative Maxima and Minima.**—The investigation of relative maxima and minima for double integrals is the same as that already considered in the case of single integrals. Thus to find the form of the function  $z$  for which  $\iint V dx dy$  shall be a maximum or a minimum, while  $\iint V' dx dy$  is a constant, the solution reduces to the investigation of the maximum or minimum value of

$$U = \iint (V + m V') dx dy, \quad (21)$$

as in the case of single integrals.

**327. Surface of Minimum Area and Maximum Volume.**—Here we may write

$$U = \iint (z + a \sqrt{1 + p^2 + q^2}) dx dy;$$

$$\therefore N = 1, \quad P = \frac{ap}{\sqrt{1 + p^2 + q^2}}, \quad Q = \frac{aq}{\sqrt{1 + p^2 + q^2}},$$

and accordingly, we must have

$$\frac{1}{R} + \frac{1}{R'} = \frac{1}{a}, \quad (22)$$

at each point on the required surface.

**328. Case where  $\Omega$  is reducible to the First Order.**—The equation

$$\Omega = N - \frac{dP}{dx} - \frac{dQ}{dy} = 0$$

is in general a differential equation of the second order; for it may be written in the form

$$\begin{aligned} \frac{dV}{dz} - \left( \frac{d}{dx} + p \frac{d}{dx} + r \frac{d}{dp} + s \frac{d}{dq} \right) \frac{dV}{dp} \\ - \left( \frac{d}{dy} + q \frac{d}{dz} + s \frac{d}{dp} + t \frac{d}{dq} \right) \frac{dV}{dq} = 0. \end{aligned} \quad (23)$$

Now, in order that this should only contain  $x, y, z, p, q$ , we must have

$$\frac{d^2V}{dp^2} = 0, \quad \frac{d^2V}{dpdq} = 0, \quad \frac{d^2V}{dq^2} = 0.$$

Accordingly, in this case  $V$  must be of the form

$$V = a + p\beta + q\gamma, \quad (24)$$

where  $a, \beta, \gamma$  are functions of  $x, y$ , and  $z$ , solely. Hence in this case the equation  $\Omega = 0$  reduces to

$$\frac{da}{dz} - \frac{d\beta}{dx} - \frac{d\gamma}{dy} = 0, \quad (25)$$

where the differentiations with respect to  $x$  and  $y$  are to be performed only so far as these variables appear explicitly.

**329.  $V$  a Partial Differential Expression of the Second Order.**—We now proceed to investigate the variation of the integral

$$U = \iint V dx dy,$$

when  $V$  is a given function of  $x, y, z, p, q, r, s, t$ ; where, in accordance with the usual notation,

$$r = \frac{d^2z}{dx^2}, \quad s = \frac{d^2z}{dxdy}, \quad t = \frac{d^2z}{dy^2}.$$

When the boundary is fixed, we have, as in Art. 318,

$$\begin{aligned} \delta U &= \iint \delta V dxdy \\ &= \iint (N\delta z + P\delta p + Q\delta q + R\delta r + S\delta s + T\delta t) dxdy, \end{aligned}$$

where

$$R = \frac{dV}{dr}, \quad S = \frac{dV}{ds}, \quad T = \frac{dV}{dt}.$$

This may also be written in the form

$$\delta U = \iint \left( N\delta z + P \frac{d\delta z}{dx} + Q \frac{d\delta z}{dy} + R \frac{d^2\delta z}{dx^2} + S \frac{d^2\delta z}{dxdy} + T \frac{d^2\delta z}{dy^2} \right) dxdy.$$

The transformation of the three first terms has been already given in Art. 318.

Again, we have

$$\iint R \frac{d^2\delta z}{dx^2} dxdy - \iint \frac{d^2R}{dx^2} \delta z dxdy = \iint \frac{d}{dx} \left( R \frac{d\delta z}{dx} - \frac{dR}{dx} \delta z \right) dxdy;$$

also, since

$$S \frac{d^2\delta z}{dxdy} - \frac{d^2S}{dxdy} \delta z = \frac{d}{dx} \left( S \frac{d\delta z}{dy} \right) - \frac{d}{dy} \left( \frac{dS}{dx} \delta z \right),$$

we have

$$\begin{aligned} \iint S \frac{d^2\delta z}{dxdy} dxdy &= \iint \frac{d^2S}{dxdy} \delta z dxdy + \iint \frac{d}{dx} \left( S \frac{d\delta z}{dy} \right) dxdy \\ &\quad - \iint \frac{d}{dy} \left( \frac{dS}{dx} \delta z \right) dxdy. \end{aligned}$$

Likewise

$$\iint T \frac{d^2 \delta z}{dy^2} dx dy = \iint \frac{d^2 T}{dy^2} \delta z dx dy + \iint \frac{d}{dy} \left( \frac{d \delta z}{dy} - \frac{dT}{dy} \delta z \right) dx dy,$$

where the integrals are taken over the whole field of integration.  
Hence

$$\begin{aligned} & \iint \left( R \frac{d^2 \delta z}{dx^2} + S \frac{d^2 \delta z}{dxdy} + T \frac{d^2 \delta z}{dy^2} \right) dx dy \\ &= \iint \left( \frac{d^2 R}{dx^2} + \frac{d^2 S}{dxdy} + \frac{d^2 T}{dy^2} \right) \delta z dx dy \\ &+ \iint \frac{d}{dx} \left( R \frac{d \delta z}{dx} + S \frac{d \delta z}{dy} - \frac{dR}{dx} \delta z \right) dx dy \\ &+ \iint \frac{d}{dy} \left( T \frac{d \delta z}{dy} - \frac{dT}{dy} \delta z - \frac{dS}{dx} \delta z \right) dx dy. \quad (26) \end{aligned}$$

Again, by Arts. 274 and 275, the two latter integrals are, in general, equivalent to the single integrals

$$\begin{aligned} & \int \left( T \frac{d \delta z}{dy} - \frac{dT}{dy} \delta z - \frac{dS}{dx} \delta z \right) dx \\ & - \int \left( R \frac{d \delta z}{dx} + S \frac{d \delta z}{dy} - \frac{dR}{dx} \delta z \right) \frac{dy}{dx} dx, \quad (27) \end{aligned}$$

taken around the entire boundary, the signs for each part of the boundary being determined on the principles given in Arts. 318 and 319.

Again, since over the boundary we regard  $y$  as a function of  $x$ , we have at each point on the boundary

$$\begin{aligned} \frac{d}{dx} (\delta z) &= \frac{d \delta z}{dx} + \frac{dy}{dx} \frac{d \delta z}{dy}, \\ \therefore R \frac{dy}{dx} \frac{d \delta z}{dx} &= R \frac{dy}{dx} \frac{d}{dx} (\delta z) - R \frac{dy^2}{dx^2} \frac{d \delta z}{dy} \\ &= \frac{d}{dx} \left( R \frac{dy}{dx} \delta z \right) - \delta z \left( \frac{dR}{dx} \frac{dy}{dx} + \frac{dR}{dy} \frac{dy^2}{dx^2} + R \frac{d^2 y}{dx^2} \right) - R \frac{dy^2}{dx^2} \frac{d \delta z}{dy}; \end{aligned}$$

hence

$$-\int \left( R \frac{d\delta z}{dx} - \frac{dR}{dx} \delta z \right) \frac{dy}{dx} dx = - \int \frac{d}{dx} \left( R \frac{dy}{dx} \delta z \right) dx \\ + \int \left( 2 \frac{dR}{dx} \frac{dy}{dx} + \frac{dR}{dy} \frac{dy^2}{dx^2} + R \frac{d^2y}{dx^2} \right) \delta z dx + \int R \frac{dy^2}{dx^2} \frac{d\delta z}{dy} dx.$$

Substituting in (27) it becomes

$$- \left|_{x_0}^{x_1} R \frac{dy}{dx} \delta z + \int \left( 2 \frac{dR}{dx} \frac{dy}{dx} + \frac{dR}{dy} \frac{dy^2}{dx^2} + R \frac{d^2y}{dx^2} - \frac{dS}{dx} - \frac{dT}{dy} \right) \delta z dx \right. \\ \left. + \int \left( R \frac{dy^2}{dx^2} - S \frac{dy}{dx} + T \right) \frac{d\delta z}{dy} dx \right).$$

Hence, when taken for all points within a fixed closed curvilinear boundary, we have

$$\iint \delta V dx dy = \iint \left( N - \frac{dP}{dx} - \frac{dQ}{dy} + \frac{d^2R}{dx^2} + \frac{d^2S}{dx dy} + \frac{d^2T}{dy^2} \right) \delta z dx dy \\ + \int \left( Q - P \frac{dy}{dx} + 2 \frac{dR}{dx} \frac{dy}{dx} + \frac{dR}{dy} \frac{dy^2}{dx^2} + R \frac{d^2y}{dx^2} - \frac{dS}{dx} - \frac{dT}{dy} \right) \delta z dx \\ + \int \left( R \frac{dy^2}{dx^2} - S \frac{dy}{dx} + T \right) \frac{d\delta z}{dy} dx. \quad (28)$$

330. When the double integral is given in the form

$$U = \int_{x_0}^{x_1} \int_{y_0}^{y_1} V dx dy,$$

we have, by (9), Art. 271,

$$\int_{x_0}^{x_1} \int_{y_0}^{y_1} \frac{d}{dx} \left( R \frac{d\delta z}{dx} + S \frac{d\delta z}{dy} - \frac{dR}{dx} \delta z \right) dx dy \\ = \int_{x_0}^{x_1} \int_{y_0}^{y_1} \left( R \frac{d\delta z}{dx} + S \frac{d\delta z}{dy} - \frac{dR}{dx} \delta z \right) dy dx \\ - \int_{x_0}^{x_1} \left|_{y_0}^{y_1} \left( R \frac{d\delta z}{dx} + S \frac{d\delta z}{dy} - \frac{dR}{dx} \delta z \right) \frac{dy}{dx} \right| dx. \quad (29)$$

And we readily see that, introducing the additional terms, we have

$$\begin{aligned}
 & \int_{x_0}^{x_1} \int_{y_0}^{y_1} \delta V dx dy \\
 &= \int_{x_0}^{x_1} \int_{y_0}^{y_1} \left( N - \frac{dP}{dx} - \frac{dQ}{dy} + \frac{d^2R}{dx^2} + \frac{d^2S}{dxdy} + \frac{d^2T}{dy^2} \right) \delta s dx dy \\
 &+ \int_{x_0}^{x_1} \left| \int_{y_0}^{y_1} \left( Q - P \frac{dy}{dx} + 2 \frac{dR}{dx} \frac{dy}{dx} + \frac{dR}{dy} \frac{dy^2}{dx^2} + R \frac{d^2y}{dx^2} - \frac{dS}{dx} - \frac{dT}{dy} \right) \delta z dx \right. \\
 &+ \int_{x_0}^{x_1} \left| \int_{y_0}^{y_1} \left( R \frac{dy^2}{dx^2} - S \frac{dy}{dx} + T \right) \frac{d\delta z}{dy} dx \right. \\
 &+ \left. \int_{x_0}^{x_1} \int_{y_0}^{y_1} \left( P - \frac{dR}{dx} \right) \delta z dy \right. + \left. \int_{x_0}^{x_1} \int_{y_0}^{y_1} R \frac{d\delta z}{dx} dy \right. \\
 &- \left. \int_{x_0}^{x_1} \int_{y_0}^{y_1} \frac{dS}{dy} \delta z dy \right. + \left. \int_{x_0}^{x_1} \left| \int_{y_0}^{y_1} \left( S - R \frac{dy}{dx} \right) \delta z \right. \right. \quad (30)
 \end{aligned}$$

When the boundary is varied, we get, as in (6), the additional terms

$$\int_{x_0}^{x_1} \left| \int_{y_0}^{y_1} V \Delta y dx \right. + \left. \int_{x_0}^{x_1} \int_{y_0}^{y_1} V \Delta x dy \right. \quad (31)$$

**331. Conditions for Maxima and Minima.**—As in Art. 322, in the case of a maximum or minimum solution we must have

$$\Omega = N - \frac{dP}{dx} - \frac{dQ}{dy} + \frac{d^2R}{dx^2} + \frac{d^2S}{dxdy} + \frac{d^2T}{dy^2} = 0, \quad (32)$$

the additional equations at the limits depending on the conditions of the problem in each case.

The function  $\Omega$  is, in general, a partial differential equation of the fourth order.

**332. Case where Terms of the Highest Order in  $\Omega$  disappear.**—We now proceed to consider the conditions in order that no term of the fourth order should appear in the expression for  $\Omega$ .

It is evident that the terms of the highest order in  $\frac{d}{dx}(R)$  are  $\frac{dR}{dr} \frac{dr}{dx} + \frac{dR}{ds} \frac{ds}{dx} + \frac{dR}{dt} \frac{dt}{dx}$ ;

accordingly, neglecting all terms except those of the highest order, we have

$$\frac{d^2}{dx^2}(R) = \frac{dR}{dr} \frac{d^2r}{dx^2} + \frac{dR}{ds} \frac{d^2s}{dx^2} + \frac{dR}{dt} \frac{d^2t}{dx^2},$$

$$\frac{d^2}{dxdy}(S) = \frac{dS}{dr} \frac{d^2r}{dxdy} + \frac{dS}{ds} \frac{d^2s}{dxdy} + \frac{dS}{dt} \frac{d^2t}{dxdy},$$

$$\frac{d^2}{dy^2}(T) = \frac{dT}{dr} \frac{d^2r}{dy^2} + \frac{dT}{ds} \frac{d^2s}{dxdy} + \frac{dT}{dt} \frac{d^2t}{dy^2}.$$

Hence, observing that

$$\frac{dr}{dy} = \frac{ds}{dx} \cdots \frac{dR}{ds} = \frac{dS}{dr} \cdots$$

we see that, when we retain only the terms of the highest order, we get

$$\begin{aligned} \frac{d^2R}{dx^2} + \frac{d^2S}{dxdy} + \frac{d^2T}{dy^2} &= \frac{dR}{dr} \frac{d^2r}{dx^2} + 2 \frac{dR}{ds} \frac{d^2s}{dx^2} \\ &+ \frac{d^2t}{dx^2} \left( \frac{dS}{ds} + 2 \frac{dR}{dt} \right) + 2 \frac{dS}{dt} \frac{d^2t}{dxdy} + \frac{dT}{dt} \frac{d^2t}{dy^2}. \end{aligned}$$

[31a]

Hence, if the terms of the fourth order disappear from  $\Omega$ , we must have

$$\frac{dR}{dr} = 0, \quad \frac{dR}{ds} = 0, \quad \frac{dS}{ds} + 2 \frac{dR}{dt} = 0, \quad \frac{dS}{dt} = 0, \quad \frac{dT}{dt} = 0,$$

or

$$\frac{d^2V}{dr^2} = 0, \quad \frac{d^2V}{drds} = 0, \quad \frac{d^2V}{ds^2} + 2 \frac{d^2V}{drdt} = 0, \quad \frac{d^2V}{dsdt} = 0, \quad \frac{d^2V}{dt^2} = 0.$$

Hence we readily see that  $V$  must be of the form

$$V = A(rt - s^2) + Br + 2Cs + Dt + E, \quad (33)$$

where  $A, B, C, D, E$  are functions of  $x, y, z, p$ , and  $q$  solely.

**333. The Terms of Third Order also disappear.**—It can now be readily shown that in this case the terms of the third order in  $\Omega$  also disappear.

For, from (33) we get

$$R = At + B, \quad S = -2As + 2C, \quad T = Ar + D.$$

Hence, writing  $\Omega$  in the form

$$\Omega = N + \frac{d}{dx}(\chi_1) + \frac{d}{dy}(\chi_2), \quad (34)$$

where

$$\chi_1 = \frac{dR}{dx} + \frac{1}{2} \frac{dS}{dy} - P, \quad \chi_2 = \frac{dT}{dy} + \frac{1}{2} \frac{dS}{dx} - Q,$$

neglecting all terms in which the differential coefficients are below the second order in  $\chi_1$  and  $\chi_2$ , and observing that

$$\frac{dt}{dx} = \frac{ds}{dy}, \quad \frac{dr}{dy} = \frac{ds}{dx}, \dots$$

we readily get

$$\begin{aligned}\chi_1 &= t \left( \frac{d}{dx} + p \frac{d}{dz} \right) A - s \left( \frac{d}{dy} + q \frac{d}{dz} \right) A + t \left( \frac{dC}{dq} - \frac{dD}{dp} \right) \\ &\quad - s \left( \frac{dC}{dp} - \frac{dB}{dq} \right), \\ \chi_2 &= r \left( \frac{d}{dy} + q \frac{d}{dz} \right) A - s \left( \frac{d}{dx} + p \frac{d}{dz} \right) A + r \left( \frac{dC}{dp} - \frac{dB}{dq} \right) \\ &\quad - s \left( \frac{dC}{dq} - \frac{dD}{dp} \right).\end{aligned}$$

Hence, introducing the additional terms, we may write

$$\chi_1 = Ht - Ks + F_1, \quad \chi_2 = Kr - Hs + F_2,$$

where

$$\begin{aligned}H &= \left( \frac{d}{dx} + p \frac{d}{dz} \right) A + \frac{dC}{dq} - \frac{dD}{dp} \Bigg\}, \\ K &= \left( \frac{d}{dy} + q \frac{d}{dz} \right) A + \frac{dC}{dp} - \frac{dB}{dq} \Bigg\},\end{aligned}\tag{35}$$

and  $F_1, F_2$  are of the first order only.

Again

$$\begin{aligned}\frac{d}{dx} (Ht - Ks) + \frac{d}{dy} (Kr - Hs) \\ = t \frac{dH}{dx} - s \left( \frac{dK}{dx} + \frac{dH}{dy} \right) + r \frac{dK}{dy},\end{aligned}\tag{36}$$

since

$$\frac{dt}{dx} = \frac{ds}{dy}, \quad \text{and} \quad \frac{ds}{dx} = \frac{dr}{dy}.$$

Consequently  $\Omega$  in this case contains no differential coefficients of an order higher than the second.

334. **General form of  $\Omega$  in this Case.**—It can now be seen without difficulty that  $\Omega$  becomes of the form

$$\Omega = A_1(rt - s^2) + B_1r + 2C_1s + D_1t + E_1\tag{37}$$

in this case.

For the terms in  $\Omega$ , in addition to those given in (36), are, by (34),

$$\frac{dV}{dz} + \frac{d}{dx} F_1 + \frac{d}{dy} F_2;$$

but

$$\frac{dV}{dz} = (rt - s^2) \frac{dA}{dz} + r \frac{dB}{dz} + 2s \frac{dC}{dz} + t \frac{dD}{dz} + \frac{dE}{dz},$$

which is of the required form.

Again

$$\frac{d}{dx} (F_1) = \left( \frac{d}{dx} + p \frac{d}{dz} + r \frac{d}{dp} + s \frac{d}{dq} \right) F_1,$$

$$\frac{d}{dy} (F_2) = \left( \frac{d}{dy} + q \frac{d}{dz} + s \frac{d}{dp} + t \frac{d}{dq} \right) F_2;$$

whence it follows that  $\Omega$  is of the form given in (37)

**335. Variation of a Triple Integral.**—We shall next consider the variation of the triple integral

$$U = \iiint V dx dy dz,$$

in which  $V$  is a given function of  $x, y, z, u, p, q, r$ , where  $u$  is a function of  $x, y$ , and  $z$ , and

$$p = \frac{du}{dx}, \quad q = \frac{du}{dy}, \quad r = \frac{du}{dz}.$$

Here, when the *field of integration is not altered*, we have

$$\delta U = \iiint \delta V dx dy dz,$$

also

$$\delta V = N \delta u + P \frac{d \delta u}{dx} + Q \frac{d \delta u}{dy} + R \frac{d \delta u}{dz},$$

where

$$N = \frac{dV}{du}, \quad P = \frac{dV}{dp}, \quad Q = \frac{dV}{dq}, \quad R = \frac{dV}{dr}.$$

Again

$$P \frac{d\delta u}{dx} = \frac{d}{dx} (P\delta u) - \frac{dP}{dx} \delta u, \text{ &c. ;}$$

hence

$$\begin{aligned} \delta U &= \iiint \left( N - \frac{dP}{dx} - \frac{dQ}{dy} - \frac{dR}{dz} \right) \delta u dx dy dz \\ &\quad + \iiint \left\{ \frac{d}{dx} (P\delta u) + \frac{d}{dy} (Q\delta u) + \frac{d}{dz} (R\delta u) \right\} dx dy dz \\ &= \iiint \left( N - \frac{dP}{dx} - \frac{dQ}{dy} - \frac{dR}{dz} \right) \delta u dx dy dz \\ &\quad + \iint \delta u (lP + mQ + nR) dS, \end{aligned} \quad (38)$$

where the double integral is a surface integral taken over the whole boundary of the field of integration. (See Arts. 226 and 276.)

Again since, as in Art. 262, we have at any point on the bounding surface  $dx dy = u dS$ , the double integral may, in general, be written

$$\iint \left( \frac{l}{n} P + \frac{m}{n} Q + R \right) dx dy.$$

**336. Variation of the Boundary.**—If the boundary be supposed to receive a small variation, the corresponding variation in  $U$  may, generally, be denoted, as in Art. 321, by

$$\iint V \Delta z dx dy.$$

Hence the complete variation may, in general, be denoted by

$$\begin{aligned} \Delta U &= \iiint \left( N - \frac{dP}{dx} - \frac{dQ}{dy} - \frac{dR}{dz} \right) \delta u dx dy dz \\ &\quad + \iint \left\{ V \Delta z + \left( \frac{l}{n} P + \frac{m}{n} Q + R \right) \delta u \right\} dx dy. \end{aligned} \quad (39)$$

337. **Maxima and Minima.**—From the preceding investigation we see that if the triple integral  $U$ , in Art. 335, be a maximum or a minimum, we must have

$$N - \frac{dP}{dx} - \frac{dQ}{dy} - \frac{dR}{dz} = 0, \quad (40)$$

and also

$$V\Delta z + \left( \frac{l}{n} P + \frac{m}{n} Q + R \right) \delta u = 0, \quad (41)$$

at *each point* on the boundary.

The further reduction of (41) depends on the conditions of the problem in each case. For instance, if the boundary is supposed not to vary, we must have, at each point on it,

$$lP + mQ + nR = 0. \quad (42)$$

Again, if the form of  $u$  as a function of  $x, y, z$  be given over the bounding surface, then, as in Art. 323, we have, over the boundary,

$$\delta u + r\Delta z = r'\Delta z, \quad \text{i.e.} \quad \delta u = (r' - r) \Delta z,$$

and (41) reduces to

$$V + \left( \frac{l}{n} P + \frac{m}{n} Q + R \right) (r' - r) = 0. \quad (43)$$

Also, we have, in general,

$$du = pdx + qdy + rdz,$$

and, over the boundary,

$$du = p'dx + q'dy + r'dz.$$

Therefore over the boundary we get the relation

$$(p - p') dx + (q - q') dy + (r - r') dz = 0;$$

hence it follows that the direction-cosines of the normal to the bounding surface are proportional to

$$p - p', \quad q - q', \quad \text{and} \quad r - r',$$

respectively, i.e.

$$l : m : n = p - p' : q - q' : r - r';$$

therefore

$$\frac{l}{n} = \frac{p' - p}{r' - r}, \quad \frac{m}{n} = \frac{q' - q}{r' - r},$$

and equation (43) becomes

$$V + P(p' - p) + Q(q' - q) + R(r' - r) = 0. \quad (44)$$

This furnishes the relation that must hold good over the bounding surface when  $U$  is a maximum or a minimum.

338. **Example.**—To find the maximum or minimum value of

$$\iiint \sqrt{1 + p^2 + q^2 + r^2} \, dx dy dz,$$

being given that

$$\iiint u \, dx dy dz$$

is constant.

Here, we have

$$V = au + \sqrt{1 + p^2 + q^2 + r^2},$$

and equation (40) becomes

$$\begin{aligned} \frac{d}{dx} \frac{p}{\sqrt{1 + p^2 + q^2 + r^2}} + \frac{d}{dy} \frac{q}{\sqrt{1 + p^2 + q^2 + r^2}} \\ + \frac{d}{dz} \frac{r}{\sqrt{1 + p^2 + q^2 + r^2}} = a. \end{aligned}$$

Also the boundary equation becomes

$$au + \frac{1 + pp' + qq' + rr'}{\sqrt{1 + p^2 + q^2 + r^2}} = 0.$$

**339. Condition of Integrability when  $V$  is of the First Order.**—The conditions that the double integral  $\iint V dx dy$  should be reducible to one or more single integrals, whatever function  $z$  may be of  $x$  and  $y$ , can be readily established. The proof is similar to that given in Art. 310 for the case of a single integral; and we readily see that in the case of a double integral the expression  $\Omega$  must vanish identically.

When  $V$  is a function of the *first order*, we see immediately, from Art. 328, that in the case supposed we must have

$$V = a + p\beta + q\gamma, \quad (45)$$

in which  $a$ ,  $\beta$ , and  $\gamma$  are functions of  $x$ ,  $y$ , and  $z$ , solely. Hence, in order that  $\Omega$  should vanish, we see at once that  $a$ ,  $\beta$ ,  $\gamma$  must be connected by the *identical* equation

$$\frac{da}{dz} = \frac{d\beta}{dx} + \frac{d\gamma}{dy}. \quad (46)$$

Moreover, it is readily seen that in this case  $V$  is reducible to the form

$$V = \frac{d}{dx}(\phi_1) + \frac{d}{dy}(\phi_2),$$

where  $\phi_1$  and  $\phi_2$  are functions of  $x$ ,  $y$ , and  $z$ , solely, for

$$\frac{d}{dx}(\phi_1) + \frac{d}{dy}(\phi_2) = \frac{d\phi_1}{dx} + \frac{d\phi_2}{dy} + p \frac{d\phi_1}{dz} + q \frac{d\phi_2}{dz}.$$

Hence, this will be identical with the value of  $V$  in (45), provided

$$a = \frac{d\phi_1}{dx} + \frac{d\phi_2}{dy}, \quad \beta = \frac{d\phi_1}{dz}, \quad \gamma = \frac{d\phi_2}{dz};$$

as it is readily seen that the equation

$$\frac{da}{dz} = \frac{d\beta}{dx} + \frac{d\gamma}{dy}$$

in this case is satisfied identically.

Again, since by Art. 274,

$$\iint \left( \frac{d\phi_1}{dx} + \frac{d\phi_2}{dy} \right) dx dy = \int (\phi_2 dx - \phi_1 dy),$$

we get at once the expressions for the single integrals.

It is to be observed that  $\phi_1$  and  $\phi_2$  can be determined from the equations

$$\frac{d\phi_1}{dz} = \beta, \quad \frac{d\phi_2}{dz} = \gamma, \quad \frac{d\phi_1}{dx} + \frac{d\phi_2}{dy} = a.$$

**340. Condition of Integrability when  $V$  is of Second Order.**—In this case in order that  $\iint V dx dy$  should be reducible to single integrals, we see, by Art. 332, that as a first condition  $V$  must be of the form

$$V = A(rt - s^2) + Br + 2Cs + Dt + E.$$

There is no difficulty in investigating the general relations in this case in order that  $\Omega$  should vanish identically.

We shall here only consider one or two special cases.

For instance, to find when

$$\iint (Br + 2Cs + Dt) dx dy$$

is reducible to single integrals, where  $B, C, D$  are functions of  $x$  and  $y$  solely.

Here  $P = 0, Q = 0, R = B, S = 2C, T = D;$

and the condition required reduces to

$$\frac{d^2B}{dx^2} + 2 \frac{d^2C}{dxdy} + \frac{d^2D}{dy^2} = 0. \quad (47)$$

More generally, let us consider

$$\iint (Br + 2Cs + Dt + E) dx dy,$$

where  $B$ ,  $C$ ,  $D$  are functions of  $x$  and  $y$ , solely, and  $E$  is a function of  $x$ ,  $y$ , and  $z$ ; here we must have

$$\Omega = \frac{dE}{dz} + \frac{d^2B}{dx^2} + 2 \frac{d^2C}{dxdy} + \frac{d^2D}{dy^2} = 0. \quad (48)$$

Hence, in order that the double integral should be reducible to single integrals,  $\frac{dE}{dz}$  must be independent of  $z$ , that is,

$E$  must be of the form  $z\phi_1 + \phi_2$ , where  $\phi_1$  and  $\phi_2$  are functions of  $x$  and  $y$  solely.

Accordingly, the condition in question may be written in the form

$$\phi_1 + \frac{d^2B}{dx^2} + 2 \frac{d^2C}{dxdy} + \frac{d^2D}{dy^2} = 0. \quad (49)$$

**341. General Transformation.**—If, by a well-known general method of transformation (see Boole's *Differential Equations*, Ch. xv., Art. 10), we make  $z = px + qy - u$ , we get  $du = xdp + ydq$ , since  $dz = pdx + qdy$ . If now we suppose  $p$  and  $q$  to be taken as independent variables, and  $u$  a function of them, we have

$$x = \frac{du}{dp}, \quad y = \frac{du}{dq}. \quad (50)$$

Hence  $x$  and  $y$  may be regarded as the partial differential coefficients of the first order of  $u$ , with respect to  $p$  and  $q$ .

If now we denote the differential coefficients of the second order by  $r'$ ,  $s'$ ,  $t'$ , we have

$$r' = \frac{d^2u}{dp^2} = \frac{dx}{dp}, \quad s' = \frac{d^2u}{dpdq} = \frac{dx}{dq} = \frac{dy}{dp}, \quad t' = \frac{d^2u}{dq^2} = \frac{dy}{dq}.$$

Hence we have

$$\left. \begin{aligned} dx &= \frac{dx}{dp} dp + \frac{dx}{dq} dq = r' dp + s' dq \\ dy &= \frac{dy}{dp} dp + \frac{dy}{dq} dq = s' dp + t' dq \end{aligned} \right\}. \quad (51)$$

But we have also

$$dp = rdx + sdy, \quad dq = sdx + tdy,$$

from which we get

$$(rt - s^2) dx = tdp - sdq,$$

$$(rt - s^2) dy = rdq - sdp;$$

hence, comparing the foregoing results, we obtain

$$r' = \frac{t}{rt - s^2}, \quad s' = \frac{-s}{rt - s^2}, \quad t' = \frac{r}{rt - s^2}. \quad (52)$$

By this means the expression

$$\iint V dx dy$$

can be transformed into another double integral of the form

$$\iint V' dp dq,$$

where  $(rt - s^2) dx dy$  transforms into  $dp dq$ .

342. For instance, if  $A$  be a function of  $x, y, z, p, q$ , the double integral

$$\iint A (rt - s^2) dx dy$$

transforms into

$$\iint A dp dq.$$

Also in order that this should be reducible to single integrals we must have, as in Art. 338,

$$A = \frac{d\phi_1}{dp} + \frac{d\phi_2}{dq}, \quad (53)$$

where  $\phi_1$  and  $\phi_2$  are functions of  $u, p$ , and  $q$ , solely.

Moreover

$$\begin{aligned} \iint \left( \frac{d\phi_1}{dp} + \frac{d\phi_2}{dq} \right) (rt - s^2) dx dy &= \int \left( \frac{d\phi_1}{dp} + \frac{d\phi_2}{dq} \right) dp dq \\ &= \int (\phi_1 dq - \phi_2 dp), \end{aligned}$$

taken over the boundary of the field of integration.

Again, from (52), it follows that

$$\iint (Br + 2Cs + Dt) dx dy$$

transforms into

$$\iint (Bt' - 2Cs' + Dr') dp dq. \quad (54)$$

Hence, by (47), if  $B, C, D$  are functions of  $p$  and  $q$  solely, the integral is reducible to single integrals if

$$\frac{d^2 B}{dq^2} + \frac{d^2 D}{dp^2} = 2 \frac{d^2 C}{dp dq}. \quad (55)$$

Again, the double integral

$$\iint \{A(rt - s^2) + Br + 2Cs + Dt\} dx dy$$

transforms into

$$\iint (A + Bt' - 2Cs' + Dr') dp dq; \quad (56)$$

and hence the condition for its reduction to single integrals becomes

$$\frac{dA}{du} + \frac{d^2 B}{d^2 q} - \frac{2d^2 C}{dp dq} + \frac{d^2 D}{dp^2} = 0, \quad (57)$$

in which  $A$  must be of the form  $u\phi_1 + \phi_2$ , and  $\phi_1, \phi_2, B, C$ , and  $D$ , are functions of  $p$  and  $q$  solely.

**343. Equation for Principal Radii of Curvature at any point on a Surface.**—If  $\rho$  be the radius of curvature of any normal section at a point on a surface, we easily get (Salmon, *Geometry of Three Dimensions*, Art. 313),

$$\rho = \sqrt{1 + p^2 + q^2} \cdot \frac{(1 + p^2) + 2pqm + (1 + q^2)m^2}{r + 2sm + tm^2}; \quad (58)$$

accordingly, if

$$v = \frac{(1 + p^2) + 2pqm + (1 + q^2)m^2}{r + 2sm + tm^2},$$

we see (by Art. 145, *Differential Calculus*) that the maximum and minimum values of  $v$  are given by the equation

$$v^2 (rt - s^2) - v \{(1 + q^2)r - 2pqm + (1 + p^2)t\} + 1 + p^2 + q^2 = 0$$

Consequently the maximum and minimum values of  $\rho$ , i. e. of  $R$  and  $R'$ , the principal radii of curvature, are the roots of the equation

$$\rho^2 (rt - s^2) - \rho \{ (1 + q^2) r - 2pqs + (1 + p^2) t \} \sqrt{1 + p^2 + q^2} + (1 + p^2 + q^2)^2 = 0. \quad (59)$$

We shall find this equation of importance in the discussion of the following examples:—

344. If a number of surfaces be described, touching along the same closed curve, the value of the double integral

$$\iint \left( \frac{1}{R} + \frac{1}{R'} \right) dx dy,$$

extended to the entire of that part of any one of the surfaces which is bounded by the curve of contact, will be the same for all such surfaces (Jellett, *Calculus of Variations*, Art. 156).

Here, by (59), we have

$$\frac{1}{R} + \frac{1}{R'} = - \frac{(1 + q^2) r - 2pqs + (1 + p^2) t}{(1 + p^2 + q^2)^{\frac{3}{2}}};$$

hence, transforming as in (54), we have

$$B = \frac{1 + q^2}{(1 + p^2 + q^2)^{\frac{3}{2}}}, \quad C = \frac{-pq}{(1 + p^2 + q^2)^{\frac{3}{2}}}, \quad D = \frac{1 + p^2}{(1 + p^2 + q^2)^{\frac{3}{2}}};$$

and we easily see that

$$\begin{aligned} \frac{dB}{dq} &= \frac{dC}{dp}, \quad \frac{dD}{dp} = \frac{dC}{dq}; \\ \therefore \frac{d^2 B}{dq^2} &= \frac{d^2 C}{dpdq}, \quad \frac{d^2 D}{dp^2} = \frac{d^2 C}{dpdq}. \end{aligned}$$

Consequently

$$\frac{d^2 B}{dq^2} + \frac{d^2 D}{dp^2} = 2 \frac{d^2 C}{dpdq},$$

which (by 55) proves the theorem.

345. If  $R, R'$  be the principal radii of curvature at any point on a closed surface,  $P$  the perpendicular on the tangent plane at the point, and  $d\omega$  the element of the spherical surface described by the unit of length measured on  $P$ , then

$$\iint (R + R') d\omega = \iint P d\omega,$$

the integrals being taken over the entire closed surface (Jellett, Calculus of Variations, Art. 158).

Here, it is easily shown that  $d\omega = \frac{dS}{RR'}$ , where  $dS$  is the corresponding element of the closed surface; hence

$$\begin{aligned} \iint (R + R') d\omega &= \iint \left( \frac{1}{R} + \frac{1}{R'} \right) dS = \iint \left( \frac{1}{R} + \frac{1}{R'} \right) \sqrt{1+p^2+q^2} dx dy \\ &= - \iint \frac{(1+q^2)r - 2pq s + (1+p^2)t}{1+p^2+q^2} dx dy, \text{ by (59).} \end{aligned}$$

Also, if  $l, m, n$  be the direction-cosines of the perpendicular, we have

$$P = lx + my + nz = \frac{z - px - qy}{\sqrt{1+p^2+q^2}};$$

hence,

$$\begin{aligned} 2 \iint P d\omega &= 2 \iint \frac{z - px - qy}{\sqrt{1+p^2+q^2}} \frac{dS}{RR'} \\ &= 2 \iint \frac{(z - px - qy)(rt - s^2)}{(1+p^2+q^2)^2} dx dy, \text{ by (59).} \end{aligned}$$

Accordingly, we see that the double integral

$$\iint \{2P - (R + R')\} d\omega$$

transforms into one of the form

$$\iint (A(rt - s^2) + Br + 2Cs + Dt) dx dy.$$

Now, adopting the general transformation of Art. 341, this becomes, by (56),

$$\iint \{A + Bt' - 2Cs' + Dr'\} dp dq, \quad (60)$$

where  $A = \frac{2u}{(1 + p^2 + q^2)^2}$ ,  $B = \frac{1 + q^2}{1 + p^2 + q^2} = 1 - \frac{p^2}{1 + p^2 + q^2}$ ,

$$C = \frac{-pq}{1 + p^2 + q^2}, \quad D = 1 - \frac{q^2}{1 + p^2 + q^2}.$$

Here  $\frac{dA}{du} = \frac{-2}{(1 + p^2 + q^2)^2}$ ,  $\frac{dB}{dq} = \frac{2p^2q}{(1 + p^2 + q^2)^2}$ ,

$$\frac{dC}{dp} = \frac{-q}{1 + p^2 + q^2} + \frac{2p^2q}{(1 + p^2 + q^2)^2} = \frac{-q(1 + q^2 - p^2)}{(1 + p^2 + q^2)^2},$$

$$\frac{dC}{dq} = \frac{-p(1 + p^2 - q^2)}{(1 + p^2 + q^2)^2}, \quad \frac{dD}{dp} = \frac{2q^2p}{(1 + p^2 + q^2)^2}.$$

Accordingly  $\frac{dB}{dq} - \frac{dC}{dp} = \frac{q}{1 + p^2 + q^2}$ ,

$$\frac{dD}{dp} - \frac{dC}{dq} = \frac{p}{1 + p^2 + q^2};$$

therefore  $\frac{d}{dq} \left( \frac{dB}{dq} - \frac{dC}{dp} \right) = \frac{1 + p^2 - q^2}{(1 + p^2 + q^2)^2}$ ,

$$\frac{d}{dp} \left( \frac{dD}{dp} - \frac{dC}{dq} \right) = \frac{1 + q^2 - p^2}{(1 + p^2 + q^2)^2}.$$

Hence we get

$$\frac{dA}{du} + \frac{d^2B}{dq^2} - 2 \frac{d^2C}{dpdq} + \frac{d^2D}{dp^2} = 0. \quad (61)$$

Accordingly, by (57), the variation of the double integral in the question vanishes in this case, and consequently the integral is reducible to single integrals taken along the boundary.

## EXAMPLES.

1. If  $z$  be a function of  $x$  and  $y$ , find the variation of

$$\int_{x_0}^{x_1} \int_{y_0}^{y_1} f(r, s, t) dx dy,$$

the limits of the integral being variable.

2. The equation furnished by the Calculus of Variations for the maximum or minimum values of

$$\iint V dx dy, \text{ where } V = f(x, y, z, p, q, r, s, t)$$

is, in general, of the fourth order. Prove that it is reduced to the second order if

$$V = A(rt - s^2) + Br + Cs + Dt + E,$$

$A, B, \&c.$  being functions of  $x, y, z, p, q$ .

3. If  $\mu$  be a homogeneous function, show that the result in Art. 325 admits of a geometrical interpretation.

4. Determine the variation of the integral

$$U = \int_{x_0}^{x_1} \int_{y_0}^{y_1} \int_{z_0}^{z_1} V dx dy dz$$

in its most reduced form, by signs of substitution, where

$$V = f \left( x, y, z, u \frac{du}{dx}, \frac{du}{dy}, \frac{du}{dz} \right),$$

and find the form of  $V$  in order that  $U$  should be reducible to single integrals.

5. Prove that the variation of the double integral

$$\iint V dx dy$$

vanishes when

$$V = 2 \frac{(z - px - qy)(rt - s^2)}{(1 + p^2 + q^2)^2} + \frac{(1 + q^2)r - 2pqs + (1 + p^2)t}{1 + p^2 + q^2}.$$

(a) What geometrical theorem can be derived from this result?

6. Determine the form of  $F$  when the integral

$$\iint F(x, y, z, p, q) (rt - s^2) dx dy$$

is reducible to single integrals.

Here, transforming by the method of Art. 341, the integral becomes

$$\iint F'(x, y, u, p, q) dp dq;$$

and, as in Art. 339, in order that this should be reducible to single integrals, the expression  $F'$  must, as in (45), be of the form

$$\phi_1 + x\phi_2 + y\phi_3$$

where

$$\phi_1, \phi_2, \text{ and } \phi_3$$

are functions of  $p, q$ , and  $u$  solely, and are connected by the equation

$$\frac{d\phi_1}{du} = \frac{d\phi_2}{dp} + \frac{d\phi_3}{dq}.$$

7. Determine the curve such that the following integral shall be a minimum, the extremities being fixed points:—

$$\int_{s_0}^{s_1} \frac{ds}{(\dot{x}^2 + \dot{y}^2)^{\frac{1}{2}}}.$$

8. Find the variation of the following integral

$$\int_{x_0}^{x_1} \int_{y_0}^{y_1} f(x, y, z, p, q, s, t) dx dy$$

in its most reduced form.

9. Prove that the plane curve which makes

$$\int \phi(\rho) ds,$$

taken between its points of intersection with two given curves, a maximum or a minimum, will intersect these curves in two points such that the rectilinear distance between them will be a maximum or a minimum.

10. Show that the curve of constant curvature, and of minimum length, between two fixed points, will be a circle, if the position of either of the extreme tangents is undetermined.

11. Determine the form  $z$  which renders the double integral

$$\iint (px + qy - z)^n dx dy$$

a maximum or minimum.

12. Investigate whether the area of a surface can be expressed as the integral of  $f(p, \theta, \phi) d\theta d\phi$ , where  $p, \theta, \phi$  are the polar coordinates of the foot of the perpendicular on the tangent plane.

13. In determining by the Calculus of Variations the surface of given superficial area which makes

$$\iint \left( \frac{1}{R} + \frac{1}{R'} \right) dS$$

a maximum or a minimum, show that the differential equation of the surface is

$$R + R' = \text{const.},$$

$R$  and  $R'$  being the principal radii of curvature.

## NOTE ON PAGE 240.

MR. RUSSELL has shown that Genocchi's expression for the rectification of a Cartesian Oval, as given in pp. 240-243, can be immediately arrived at as a case of a remarkable theorem on rectification which was proposed by him as a problem at the Moderatorship Examination in 1895.

Mr. Russell's problem is as follows:—

*A, B are any two fixed points, and C is a variable point on a plane curve: prove that, if the normal at C meets the circum-circle of ABC in D, then*

$$BC \cdot AD \cdot dA + CA \cdot BD \cdot dB$$

$$+ AB \cdot CD \cdot dC = \frac{AD^2 - BD^2}{AB} ds,$$

where  $ds$  is an element at C of the plane curve.

Let  $\angle ACD = \alpha$ ,  $\angle BCD = \beta$ ; then, by elementary geometry, we get

$$ds \cos \alpha = AC \cdot dA, \quad ds \cos \beta = - BC \cdot dB;$$

therefore

$$ds \sin(\beta - \alpha) = AC \sin \beta dA + BC \sin \alpha dB,$$

i.e.

$$ds \frac{\sin^2 \beta - \sin^2 \alpha}{\sin(\alpha + \beta)} = AC \sin \beta dA + BC \sin \alpha dB;$$

hence

$$ds \frac{BD^2 - AD^2}{AB} = AC \cdot BD \cdot dA + BC \cdot AD \cdot dB.$$

Again, we have

$$dA + dB + dC = 0,$$

and, by Ptolemy's theorem,

$$AB \cdot CD = AC \cdot BD + BC \cdot AD;$$

hence, we readily get,

$$ds \frac{AD^2 - BD^2}{AB} = BC \cdot AD \cdot dA - CA \cdot BD \cdot dB + AB \cdot CD \cdot dC. \quad (\alpha)$$

We shall apply this theorem to a Cartesian Oval, having A and B as foci.

Let, as in p. 239, the equation of the curve be  $mr + br' = nc$ , where  $AC = r$ ,  $BC = r'$ ,  $AB = c$ ; then we have already shown (p. 241) that

$$\frac{AD}{l} = \frac{BD}{m} = \frac{CD}{n} = u.$$

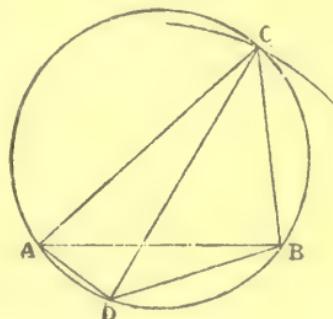


Fig. 90.

Accordingly equation (a) becomes in this case

$$\frac{l^2 - m^2}{c} ds = \frac{lBC}{u} dA + \frac{mCA}{u} dB + \frac{nAB}{u} dC;$$

but

$$\frac{BC}{u} = (m^2 + n^2 - 2mn \cos A)^{\frac{1}{2}},$$

$$\frac{CA}{u} = (l^2 + n^2 - 2ln \cos B)^{\frac{1}{2}},$$

$$\frac{AB}{u} = (l^2 + m^2 - 2lm \cos C)^{\frac{1}{2}}.$$

Hence we see, as in page 243, that the length of an arc of a Cartesian Oval is expressible in terms of three elliptic arcs.

## MISCELLANEOUS EXAMPLES.

1. Find the value of

$$\int \frac{dx}{x+c} \sqrt{\frac{x+a}{x+b}}$$

2. Find the area of the inverse of a hyperbola, the centre being the pole of inversion; and show that the area of the inverse of an ellipse, under the same circumstances, is an arithmetic mean between the areas of the circles described on its axes as diameters.

3. Find the integral of

$$\frac{dx}{x} \sqrt{\frac{a^2 - x^2}{x^2 - b^2}}.$$

$$Ans. \tan^{-1} \sqrt{\frac{a^2 - x^2}{x^2 - b^2}} + \frac{a}{b} \tan^{-1} \frac{b}{a} \sqrt{\frac{a^2 - x^2}{x^2 - b^2}}.$$

4. Prove that

$$\int_{x_0}^X f(x) dx = (\xi - a) f(\xi) \log \left( \frac{X - a}{x_0 - a} \right),$$

where  $\xi$  lies between  $X$  and  $x_0$ .

5. In a spiral of Archimedes, if  $P, Q$  and  $P', Q'$  be the points of section with any two branches of the curve made by a line passing through its pole, prove that the area bounded by the right line and by the two branches is half the area of the ellipse whose semiaxes are  $PP'$  and  $P'Q$ .

6. If  $a$  be the sagitta of a circular segment whose base is  $b$ , prove that the area of the segment is, approximately,

$$= \frac{2}{3} ab + \frac{8}{15} \frac{a^3}{b}.$$

7. If an ellipse roll upon a right line, show that the differential equation of the locus of its focus is

$$(y^2 + b^2) \frac{dy}{dx} = \sqrt{(2ay + y^2 + b^2)(2ay - y^2 - b^2)}.$$

8. A circle rolls from one end to the other of a curved line equal in length to the circumference of the circle, and then rolls back again on the other side of the curve: prove that, if the curvature of the curve be throughout less than that of the circle, the area contained within the closed curve traced out by the point of the circle which was first in contact with the fixed curve is six times the area of the circle. (*Camb. Math. Tripos*, 1871.)

9. In the same case show that the entire length of the path described is eight times the diameter of the circle.

10. Prove that the area of the locus formed by the points of intersection of normals to an ellipse, which cut at right angles, is  $\pi(a - b)^2$ .

11. Find the value of the definite integral

$$\int_2^1 \left( x^3 + 2 \log x + \sqrt{4 - x^2} + \frac{1}{\sqrt{9 + x^2}} + \sin^3 \frac{\pi x}{3} \right) dx.$$

12. Transform  $\int \frac{\sqrt{z-a}}{z-b} dz$  by the substitution  $z = a \sec^2 \theta - b \tan^2 \theta$ , and

hence find the value of  $\int \frac{\sqrt{z-a}}{z-b} dz$ .

13. Explain the following apparent difficulties :

$$(a) \int \frac{dx}{(a + cx^2)^{\frac{3}{2}}} = \frac{x}{a(a + cx^2)^{\frac{1}{2}}};$$

yet, when  $a$  becomes nearly zero, the denominator on the right-hand side becomes nearly zero, while that on the left-hand remains finite.

$$(b) \int \frac{dx}{\sqrt{(x-a)(x-b)}} = 2 \log (\sqrt{x-a} + \sqrt{x-b});$$

yet if  $a$  and  $b$  are positive, and  $x$  is less than either of them, the square root on the left-hand side is real, but those on the right-hand side are imaginary.

14. If  $\int \phi(x) dx + \int \phi(y) dy = \text{constant}$  leads to a relation connecting  $x$  and  $y$  of the form

$$Axy + B(x+y) + C = 0,$$

determine the form of  $\phi(x)$ .

15. If  $u$  and  $v$  be functions of  $x$  and  $y$ , prove that the elementary area included between the curves  $u = a$ ,  $v = b$ , and  $u = a + \delta a$ ,  $v = b + \delta b$  is represented by

$$\frac{\delta u \delta b}{\left| \begin{array}{cc} \frac{du}{dx}, & \frac{dv}{dx} \\ \frac{du}{dy}, & \frac{dv}{dy} \end{array} \right|}$$

where  $x$  and  $y$  are the coordinates of the point of intersection of the curves

$$u = a \quad \text{and} \quad v = b.$$

16. Find the area of a loop of the curve

$$r = \frac{ab \cos 2\theta}{b \cos \theta - a \sin \theta}.$$

17. Prove that the area between two focal radii of a parabola and the curve is half the area between the curve, the corresponding perpendiculars on the directrix, and the directrix.

18. Evaluate the following integrals:—

$$\int \frac{dx}{\sqrt{\tan x}}, \quad \int \sqrt{\sec x - 1} dx, \quad \int \frac{(1+x)^4 dx}{(1+x^2)(1+x^4)}$$

19. If  $R = (x^2 + ax)^2 + bx$ , and  $u = \log \frac{x^2 + ax + \sqrt{R}}{x^2 + ax - \sqrt{R}}$ , find the relation

between the integrals

$$\int \frac{dx}{\sqrt{R}}, \quad \int \frac{x dx}{\sqrt{R}}.$$

$$Ans. \int \frac{x dx}{\sqrt{R}} = \frac{a}{3} \int \frac{dx}{\sqrt{R}} + \frac{3}{u}.$$

20. If a curve be such that the area between any portion and a fixed right line is proportional to the corresponding length of the curve, show that it is a catenary.

21. Prove that the volume of a rectangular parallelepiped is to that of its circumscribed ellipsoid as  $2 : \pi \sqrt{3}$ .

$$22. \text{ Prove that } \int_0^\alpha \frac{d\theta}{\sqrt{1 - \kappa^2 \sin^2 \theta}} = \int_0^\beta \frac{d\theta}{\sqrt{\kappa^2 - \sin^2 \theta}},$$

where  $\sin \beta = \kappa \sin \alpha$ .

23. If any number of triangles be inscribed in one ellipse and circumscribed to another ellipse, concentric and similar, prove that these triangles have all the same area.

24. Show that the value of the integral  $\int_a^b \frac{dy}{\sqrt{y^m - 1}}$  may be exhibited by the following geometrical construction. Let the curve whose equation is

$$r^{\frac{m}{m+2}} \cos \frac{m}{m+2} \omega = 1$$

roll on the axis of  $x$ ; take the points  $(x_1, y_1), (x_2, y_2)$  on the roulette described by the pole, such that  $y_1 = a, y_2 = b$ ; then

$$\int_a^b \frac{dy}{\sqrt{y^m - 1}} = x_2 - x_1. \quad (\text{JELLETT.})$$

25. If  $s$  be the length of the arc of a spherical curve measured to any point  $P$ , and  $t$  be the intercept on the great circle touching at  $P$ , between the point of contact and the foot of the perpendicular from the pole, prove that

$$s - t = \int \sin p d\omega.$$

The proof is similar to that of the corresponding theorem *in plano*. See Art. 158.

26. Prove that the volume of a polyhedron, having for bases any two polygons situated in parallel planes, and for lateral faces trapezia, is expressed by the formula

$$\frac{H}{6} (B + B' + 4B''),$$

where  $H$  is the distance between the parallel planes,  $B$  and  $B'$  the areas of the polygonal bases, and  $B''$  the area of the section equidistant from the two bases.

27. If  $S$  be the length of a loop of the curve  $r^n = a^n \cos n\theta$ , and  $A$  the area of a loop of the curve  $r^{2n} = a^{2n} \cos 2n\theta$ , prove that

$$A \times S = \frac{\pi a^3}{2n}.$$

28. Find approximately the area, and also the length, of a loop of the curve  $r^{\frac{5}{3}} = a^{\frac{5}{3}} \cos \frac{5\theta}{3}$ . (See *Diff. Calc.*, Art. 268.)

$$Ans. \text{ area} = a^2 \times 0.56616; \text{ length} = a \times 2.72638.$$

29. Show from Art. 134 that, if a parabola roll on a right line, the locus of its focus is a catenary.

30. If  $A$  be the area of any oval,  $B$  that of its pedal with respect to any internal origin  $O$ , and  $C$  that of the locus of the point on the perpendicular whose distance from  $O$  is equal to the distance of the point of contact from  $O$ , prove that  $A, B, C$  are in arithmetical progression.

31. The arc of a curve is connected with the abscissa by the equation  $s^2 = kx$ : find the curve.

32. If the coordinates of a point on a curve be given by the equations

$$x = c \sin 2\theta (1 + \cos 2\theta), \quad y = c \cos 2\theta (1 - \cos 2\theta),$$

prove that the length of its arc, measured from its origin, is  $\frac{4}{3}c \sin 3\theta$ .

33. Show how to find the sum of every element of the periphery of an ellipse divided by any odd power  $(2r + 1)$  of the semi-diameter conjugate to that which passes through the element, and give the result in the case of the fifth power.

(W. ROBERTS.)

$$Ans. \frac{4}{(ab)^{r-1}} \int_0^{\frac{\pi}{2}} (a^2 \cos^2 \theta + b^2 \sin^2 \theta)^{r-1} d\theta.$$

This gives  $\frac{\pi(a^2 + b^2)}{a^3 b^3}$  when  $r = 2$ .

34. A sphere intersects a right cylinder: prove that the entire surface of the cylinder included within the sphere is equal to the product of the diameter of the cylinder into the perimeter of an ellipse whose axes are equal to the greatest and least intercepts made by the sphere on the edges of the cylinder.

35. Show that the equations of the involute of a circle are of the form

$$x = a \cos \phi + a\phi \sin \phi, \quad y = a \sin \phi - a\phi \cos \phi;$$

and prove that the length of the arc of this involute, measured from  $\phi = 0$ , is one-half of the arc of a circle which would be described by a radius equal to the arc of its evolute moving through the angle  $\phi$ .

36. Show that the area of the cassinoid

$$r^4 - 2a^2r^2 \cos 2\theta + a^4 = b^4$$

is expressed by aid of an elliptic arc when  $b > a$ , and by a hyperbolic arc when  $a > b$ .

37. A string  $AB$ , with its end  $A$  fixed, lies in contact with a plane convex curve; the string is unwound, and  $B$  is made to move about  $A$  till the string is again wound on the curve, the final position of  $B$  being  $B'$ : prove that for variations of the position of  $A$  the arc traced out by  $B$  will be a maximum or a minimum when the tangents at  $B$  and  $B'$  are equally inclined to the tangent at  $A$ , and will be the former or the latter according as the curvature at  $A$  is greater or less than half the sum of the curvatures at  $B$  and  $B'$ .—(*Camb. Math. Tripos*, 1871.)

38. Find the value of  $\int_0^\infty \frac{dx}{\sqrt{x}} e^{-\frac{a}{x} - \beta x}.$  *Ans.*  $\sqrt{\frac{\pi}{\beta}} e^{-2\sqrt{a\beta}}$

39. Find the length, and also the area, of the pedal of a cissoid, the vertex being origin.

$$\text{Ans. } \frac{8a}{\sqrt{3}} \log(2 + \sqrt{3}) - 4a; \quad \frac{\pi a^2}{24}.$$

40. Prove that the length of an arc of the lemniscate  $r^2 = a^2 \cos 2\theta$  is represented by the integral

$$\frac{a}{\sqrt{2}} \int \frac{d\phi}{\sqrt{1 - \frac{1}{2} \sin^2 \phi}}.$$

41. Integrate the equation

$$\cos \theta (\cos \theta - \sin \alpha \sin \phi) d\theta + \cos \phi (\cos \phi - \sin \alpha \sin \theta) d\phi = 0.$$

If the arbitrary constant be determined by the condition that the equation must be satisfied by the values  $(0, \alpha)$  of  $(\theta, \phi)$ , show that the equation is satisfied by putting  $\theta + \phi = \alpha$ .

42. Each element of the surface of an ellipsoid is divided by the area of the parallel central section of the surface: find the sum of all the elementary quotients extended through the entire ellipsoid. *Ans.* 4.

43. Hence, show that

$$\int_0^h \int_h^k \frac{(\mu^2 - v^2) d\mu dv}{\sqrt{\mu^2 - h^2} \sqrt{k^2 - \mu^2} \sqrt{h^2 - v^2} \sqrt{k^2 - v^2}} = \frac{\pi}{2}.$$

This depends on the expression for an element of the surface of an ellipsoid in terms of elliptic coordinates. See Salmon's *Geometry of Three Dimensions*, Art. 411. This proof is due to Chasles (*Liouville*, tome iii., p. 10).

44. Hence prove the relation

$$F(m) E(n) + F(n) E(m) - F(n) F(m) = \frac{\pi}{2},$$

where  $F(m) = \int_0^{\frac{\pi}{2}} \frac{d\theta}{\sqrt{1 - m^2 \sin^2 \theta}}$ ,  $E(m) = \int_0^{\frac{\pi}{2}} \sqrt{1 - m^2 \sin^2 \theta} d\theta$ ,  
and  $m^2 + n^2 = 1$ .

Let  $\nu = h \sin \theta$ , and  $\mu = \sqrt{h^2 \sin^2 \phi + k^2 \cos^2 \phi}$ , in the preceding example, and it becomes

$$\begin{aligned} & \int_0^{\frac{\pi}{2}} \int_0^{\frac{\pi}{2}} \frac{h^2 \sin^2 \phi + k^2 \cos^2 \phi - h^2 \sin^2 \theta}{\sqrt{h^2 \sin^2 \phi + k^2 \cos^2 \phi} \sqrt{h^2 - h^2 \sin^2 \theta}} d\theta d\phi \\ &= \int_0^{\frac{\pi}{2}} \int_0^{\frac{\pi}{2}} \frac{\sqrt{h^2 \sin^2 \phi + k^2 \cos^2 \phi}}{\sqrt{h^2 - h^2 \sin^2 \theta}} d\theta d\phi + \int_0^{\frac{\pi}{2}} \int_0^{\frac{\pi}{2}} \frac{\sqrt{k^2 - h^2 \sin^2 \theta}}{\sqrt{h^2 \sin^2 \phi + k^2 \cos^2 \phi}} d\theta d\phi \\ & \quad - \int_0^{\frac{\pi}{2}} \int_0^{\frac{\pi}{2}} \frac{k^2 d\theta d\phi}{\sqrt{h^2 \sin^2 \phi + k^2 \cos^2 \phi} \sqrt{k^2 - h^2 \sin^2 \theta}}. \end{aligned}$$

This furnishes the required result on making  $h = mk$ .

The preceding formula, which is due to Legendre, gives a general relation between complete elliptic functions of the first and second species, with complementary moduli.

45. If three curves be described on the surface of an ellipsoid, along the first of which the perpendicular to the tangent plane makes the constant angle  $\gamma$  with the axis of  $z$ , along the second  $\beta$  with the axis of  $y$ , and along the third  $\alpha$  with the axis of  $x$ , and if the angles be connected by the relations  $\frac{\tan \alpha}{a} = \frac{\tan \beta}{b} = \frac{\tan \gamma}{c}$ , then, if  $A_3$ ,  $A_2$ ,  $A_1$  be the included portions of the ellipsoid surface, prove that

$$\frac{A_3 - A_2}{a^2} + \frac{A_1 - A_2}{b^2} + \frac{A_2 - A_1}{c^2} = 0. \quad (\text{JELLETT.})$$

46. Show that the results given in Arts. 161 and 162 hold good for spherical conics, where the tangents are arcs of great circles on the sphere.

47. Prove that

$$\int_b^a \frac{dx}{\{(a-x)(b-x)(c-x)\}^{\frac{1}{2}}} = \int_{-\infty}^0 \frac{dx}{\{(a-x)(b-x)(c-x)\}^{\frac{1}{2}}}$$

where  $a$ ,  $b$ ,  $c$  are in the order of magnitude.

48. If  $\omega$  be an imaginary cube root of unity, show that, if

$$y = \frac{(\omega - \omega^2)x + \omega^2 x^3}{1 - \omega^2(\omega - \omega^2)x^2}, \text{ then } \frac{dy}{(1 - y^2)^{\frac{1}{2}}(1 + \omega y^2)^{\frac{1}{2}}} = \frac{(\omega - \omega^2)dx}{(1 - x^2)^{\frac{1}{2}}(1 + \omega x)^{\frac{1}{2}}}.$$

(CAYLEY.)

49. Prove that the value of

$$\int_0^\infty \frac{\cos bx \sin ax}{x} dx \text{ is } 0, \frac{\pi}{4}, \text{ or } \frac{\pi}{2},$$

according as  $b$  is  $>$ ,  $=$ , or  $<$   $a$ .

50. Prove that  $\int_0^\infty \frac{\sin bx \sin ax}{x^2} dx = \frac{\pi}{2}$  multiplied by the lesser of the numbers  $a$  and  $b$ .

51. If  $e$  be the eccentricity of an ellipse whose semiaxis major is unity, and  $E$  the length of its quadrant, prove that

$$\int_0^h \frac{Ee de}{(1 - e^2)\sqrt{(h^2 - e^2)}} = \frac{\pi h}{2\sqrt{1 - h^2}}. \quad (\text{W. ROBERTS.})$$

52. If  $S$  represent the length of a quadrant of the curve  $r^m = a^m \cos m\theta$ , and  $S_1$  the quadrant of its first pedal, prove that

$$S \cdot S_1 = \frac{m+1}{2m} \pi a^2.$$

Here (Ex. 3, Art. 156) we have

$$S = \frac{a\sqrt{\pi}}{2m} \frac{\Gamma\left(\frac{1}{2m}\right)}{\Gamma\left(\frac{m+1}{2m}\right)}.$$

Also since the first pedal (*Diff. Calc.*, Art. 268) is derived by substituting  $\frac{m}{m+2}$  instead of  $m$ ,

$$S_1 = \frac{(m+1)a\sqrt{\pi}}{2m} \frac{\Gamma\left(\frac{m+1}{2m}\right)}{\Gamma\left(1 + \frac{1}{2m}\right)};$$

$$\therefore SS_1 = \frac{(m+1)\pi a^2}{4m^2} \frac{\Gamma\left(\frac{1}{2m}\right)}{\Gamma\left(1 + \frac{1}{2m}\right)} = \frac{(m+1)\pi a^2}{2m}.$$

53. In general, if  $S_n$  be the quadrant of the  $n^{\text{th}}$  pedal of the curve in the last, prove that

$$S_{n-1} S_n = \frac{mn+1}{2m} \pi a^2.$$

Here it is readily seen that the  $n^{\text{th}}$  pedal is got by substituting  $\frac{m}{mn+1}$  instead of  $m$  in the equation of the proposed;  $\therefore$  &c.

(W. ROBERTS, *Liouville*, 1845, p. 177.)

54. If an endless string, longer than the circumference of an ellipse, be passed round the ellipse and kept stretched by a moving pencil, prove that the pencil will trace out a confocal ellipse.

55. If two confocal ellipses be such that a polygon can be described in one and circumscribed to the other, prove that an indefinite number of such polygons can be described, and that they all have the same perimeter.

(CHASLES, *Comp. Rend.* 1843.)

56. To two arcs of a hyperbola, whose difference is rectifiable, correspond equal arcs of the lemniscate which is the pedal of the hyperbola. (Ibid.)

57. Prove that the tangents drawn at the extremities of two arcs of a conic, whose difference is rectifiable, form a quadrilateral whose sides all touch the same circle. (Ibid.)

58. In the curve

$$x^{\frac{2}{3}} + y^{\frac{2}{3}} = a^{\frac{2}{3}},$$

prove that any tangent divides the portion of the curve between two cusps into arcs which are to each other as the segments of the portion of the tangent intercepted by the axes.

59. If two tangents to a cycloid cut at a constant angle, prove that their sum bears a constant ratio to the arc of the curve between them.

60. If  $AB, ab$ , be quadrants of two concentric circles, their radii coinciding, show that if an arc  $Ab$  of an involute of a circle be drawn to touch the circles at  $A, b$ , the arc  $Ab$  is an arithmetical mean between the arcs  $AB$  and  $ab$ .

61. If  $ds$  represent an infinitely small superficial element of area at a point outside any closed plane curve, and  $t, t'$  the lengths of the tangents from the point to the curve, and  $\theta$  the angle of intersection of these tangents, prove that the sum of the elements represented by  $\frac{\sin \theta ds}{t \times t'}$ , taken for all points exterior to the curve, is  $2\pi^2$ . (PROP. CROFTON, *Phil. Trans.*, 1868.)

62. Show that, for all systems of rectangular axes drawn through a given point in a given plane area,

$$\{ \iint (x^2 - y^2) dx dy \}^2 + 4 \{ \iint xy dx dy \}^2,$$

taken over the whole of the area, is constant; and that for a triangle, the point being its centre of gravity, this constant value is.

$$(1/8 \Delta)^2 (a^4 + b^4 + c^4 - b^2 c^2 - c^2 a^2 - a^2 b^2).$$

(J. J. WALKER.)

63. If  $ab = a'b'$ , prove that

$$\int_0^\infty \int_0^\infty \frac{\phi(ax+by) - \phi(a'x+b'y)}{xy} dx dy \\ = \log \left( \frac{a}{a'} \right) \log \left( \frac{a}{b'} \right) \{ \phi(\infty) - \phi(0) \},$$

provided the limits  $\phi(0)$  and  $\phi(\infty)$  are both definite.

(Mr. ELLIOTT, *Proceedings*, Lond. Math. Soc., 1876.)

64. If  $S$  denote the surface, and  $V$  the volume, of the cone standing on the focal ellipse of an ellipsoid, and having its vertex at an umbilic, prove that

$$S = \pi a (b^2 - c^2)^{\frac{1}{2}}, \quad V = \frac{1}{3} \pi c (b^2 - c^2),$$

where  $a, b, c$  are the principal semiaxes of the ellipsoid.

65. Prove that, if  $p$  be positive and less than unity,

$$\int_0^1 (xp + x^{-p}) \log(1+x) \frac{dx}{x} = \frac{\pi}{p \sin p\pi} - \frac{1}{p^2}, \quad (1)$$

and

$$\int_0^1 (xp + x^{-p}) \log(1-x) \frac{dx}{x} = \frac{\pi}{p} \cot p\pi - \frac{1}{p^2}, \quad (2)$$

where (1) may be deduced from (2) by putting  $x^2$  for  $x$ .

(WOLSTENHOLME.)

66. If  $\mu, \nu$  be the *elliptic coordinates* of a point in a plane, prove that the area of any portion of the plane is represented by

$$\iint \frac{(\mu^2 - \nu^2) d\mu d\nu}{\sqrt{(\mu^2 - c^2)(c^2 - \nu^2)}},$$

taken between proper limits.

67. Prove that the differential equation, in elliptic coordinates, of any tangent to the ellipse  $\mu = \mu_1$ , is

$$\frac{d\mu}{\sqrt{(\mu^2 - c^2)(\mu^2 - \mu_1^2)}} \pm \frac{d\nu}{\sqrt{(c^2 - \nu^2)(\mu_1^2 - \nu^2)}} = 0.$$

68. Hence show that the preceding differential equation in  $\mu$  and  $\nu$  admits of an algebraic integral.

69. Prove that the differential equation of the involute of the ellipse  $\mu = \mu_1$  is

$$\sqrt{\frac{\mu^2 - \mu_1^2}{\mu^2 - c^2}} d\mu \mp \sqrt{\frac{\mu_1^2 - \nu^2}{c^2 - \nu^2}} d\nu = 0.$$

70. Show that, for a homogeneous, solid parallelepiped of any form and dimensions, the three principal axes at the centre of gravity coincide in direction with those of the solid inscribed ellipsoid which touches at the six centres of gravity of its six faces; and that, for each of the three coincident axes, and therefore for every axis passing through their common centre of gravity, the moment of inertia of the parallelepiped is to that of the ellipsoid in the same constant ratio, viz. that of 10 to  $\pi$ . (TOWNSEND.)

71. Show that the volumes of any tetrahedron, and of the inscribed ellipsoid which touches at the centres of gravity of its four faces, have the same principal axes at their common centre of gravity; and that their moments of inertia for all planes through that point have the same constant ratio (viz.  $18\sqrt{3} : \pi$ ). (Ibid.)

72. A quantity  $M$  of matter is distributed over the surface of a sphere of radius  $a$ , so that the surface density varies inversely as the cube of the distance from a given internal point  $S$ , distant  $b$  from the centre: prove that the sum of the principal moments of inertia of  $M$  at  $S$  is equal to  $2M(a^2 - b^2)$ . (Camb. Math. Tripos, 1876.)

73. If  $(1 - 2ax + a^2)^{-\frac{1}{2}} = 1 + aX_1 + a^2X_2 \dots + a^nX_n + \dots$ , prove that

$$\int_{-1}^{+1} X_n X_m dx = 0, \quad \int_{-1}^{+1} X_n^2 dx = \frac{2}{2n+1}.$$

74. A closed central curve revolves round an arbitrary external axis in its plane. Prove that the moments of inertia  $I$  and  $J$ , with respect to the axis of revolution and to the perpendicular plane passing through the centre of inertia of the solid generated by the revolving area, are given respectively by the expressions

$$I = m(a^2 + 3h^2), \quad J = m\left(k^2 - \frac{l^4}{a^2}\right),$$

where  $m$  represents the mass of the solid,  $a$  the distance of the centre of the generating area from the axis of revolution,  $h$  and  $k$  the radii of gyration of the area with respect to the parallel and perpendicular axes through its centre, and  $l$  the arm length of its product of inertia with respect to the same axes.

(TOWNSEND, Quarterly Journal of Mathematics, 1879.)

75. If  $u = \int_0^x (x-z)^{n-1} f(z) dz$ , find the value of  $\frac{du}{dx^n}$ . Ans.  $f(x)$ .

76. Prove that the superficial area of an ellipsoid is represented by

$$2\pi c^2 + 2\pi ab \int_0^1 \frac{(1 - e^2 e'^2 x^2) dx}{\sqrt{(1 - e^2 x^2)(1 - e'^2 x^2)}},$$

where  $a^2 - b^2 = a^2 e^2$ ,  $b^2 - c^2 = e'^2 b^2$ .

(JELLETT, Hermathena, 1883.)

77. Find the mean distance of two points on opposite sides of a square whose side is unity.

$$\text{Ans. } \frac{2 - \sqrt{2}}{3} + \log(1 + \sqrt{2}).$$

78. A cube being cut at random by a plane, what is the chance that the section is a hexagon?  
 (COL. CLARKE.)

$$Ans. \frac{\sqrt{3} \cot^{-1} \sqrt{3} - \sqrt{2} \cot^{-1} \sqrt{2}}{\frac{1}{4}\pi} = .04646.$$

79. Three points are taken at random, one on each of three faces of a tetrahedron: what is the chance that the plane passing through them cuts the fourth face?  
 (Ibid.)

$$Ans. \frac{3}{4}$$

80. Two stars are taken at random from a catalogue: what is the chance that one or both shall always be visible to an observer in a given latitude,  $\lambda$ ?  
 (Ibid.)

$$Ans. \frac{1}{2} \operatorname{versin} \lambda + \frac{1}{4} \sin \lambda.$$

81. Find the chance that the centre of gravity of a triangle lies inside the triangle formed by three points taken at random within the triangle.

$$Ans. \frac{1}{27} \left( 2 + \frac{10}{3} \log 4 \right).$$

82. Two points are taken at random in a triangle, the line joining them dividing the triangle into two portions: find the mean value of that portion which contains the centre of gravity.

$$Ans. \frac{1}{3^6} \left( 470 + \frac{82}{3} \log 4 \right) = .6967, \text{ the triangle being unity.}$$

The mean value of the *greater* of the two portions is  $\frac{7}{12} + \frac{1}{6} \log 2 = .6987$ .

83. Show that the mean distance  $M$  of a point in a rectangle from one angle is given by

$$3M = d + \frac{b^2}{2a} \log \frac{a+d}{b} + \frac{a^2}{2b} \log \frac{b+d}{a},$$

$a$  and  $b$  being the sides,  $d$  the diagonal.

84. Show that the mean distance  $M$  of two points within a rectangle is given by

$$15M = \frac{a^3}{b^2} + \frac{b^3}{a^2} + d \left( 3 - \frac{a^2}{b^2} - \frac{b^2}{a^2} \right) + \frac{5}{2} \left( \frac{b^2}{a} \log \frac{a+d}{b} + \frac{a^2}{b} \log \frac{b+d}{a} \right).$$

This result may be deduced from the preceding; for if  $\mu$  = mean distance of a point within the rectangle whose sides are  $x, y$ , from one of its angles, it is easy to see that

$$a^2 b^2 M = 4 \int_b^a \int_0^b xy \mu dx dy; \quad \therefore \text{ &c.}$$

85. Show that if  $M$  be the mean distance of two points within any convex area  $\Omega$ , we have

$$M = \frac{1}{\Omega^2} \iint \Sigma \Sigma' dp d\omega,$$

where  $\Sigma$ ,  $\Sigma'$  are the segments into which the area is divided by a straight line crossing it, the coordinates of the line being  $p$ ,  $\omega$ , and the integration extending to all positions of the line.

This may be seen by considering that if a random line crosses the area, the chance of its passing between the two points is  $\frac{2M}{L}$ , where  $L$  is the length of the boundary. Again, for any portion of the line, the chance of the points lying on opposite sides of it is  $\frac{\Sigma \Sigma'}{2\Omega^2}$ ; therefore the whole chance is  $\frac{2}{\Omega^2} M(\Sigma \Sigma')$ , where  $M(\Sigma \Sigma')$  is the mean value of the product  $\Sigma \Sigma'$  for all positions of the line.

86. In the same case we also have

$$M = \frac{1}{6\Omega^2} \iint C^4 dp d\omega,$$

$C$  being the length of the intercepted chord. Hence we have the remarkable identity

$$\iint C^4 dp d\omega = 6 \iint \Sigma \Sigma' dp d\omega.$$

(CROFTON, *Proceedings, Lond. Math. Soc.*, vol. viii.)

87. Show that if  $\rho$  be the distance of two points taken at random in any area,

$$M \left( \frac{1}{\rho} \right) = \frac{1}{\Omega^2} \iint C^2 dp d\omega.$$

This may be applied to the circle. (See Ex. 24.)

88. Show that the mean area of the triangle determined by three points chosen at random within any convex area is

$$M = \Omega - \frac{1}{\Omega^3} \iint C^3 \Sigma^2 dp d\omega,$$

where  $\Sigma$  = either segment cut off by the chord  $C$ ; but throughout the integrations, as the direction of the chord alters,  $\Sigma$  means always the segment on the same side of the chord as at first.

89. A ship at  $A$  observes another at  $B$ , whose course is unknown. Supposing their speed the same, prove that the chance of their coming within a given distance  $d$  of each other is always  $\frac{2}{\pi} \sin^{-1} \frac{d}{a}$ , whatever the course taken by  $A$ ; provided its inclination to  $AB$  is not greater than  $\cos^{-1} \frac{d}{a}$ , where  $AB = a$ .

(Camb. Math. Tripos, 1871. PROF. MILLER.)

90. A random straight line crosses a circle: find the chance that two points taken at random in the circle shall lie on opposite sides of the line.

*Ans.*  $\frac{128}{45\pi^2}$ . This is deduced at once from the value of  $M$ , the mean distance of the two points, as the chance  $= \frac{2M}{2\pi r}$ . If two random lines are drawn, the chance that *both* lines shall pass between the points is  $\frac{I}{\pi^2}$ .

91. A point  $O$  is taken at random in a triangle. What is the probability that if three other points are taken at random, one shall lie in each of the triangles  $AOB$ ,  $BOC$ ,  $COA$ ?

*Ans.*  $\frac{1}{10}$ . This may easily be found to depend on the integral  $\iint \alpha \beta \gamma \cdot 2d\alpha d\beta$ , where  $\alpha$ ,  $\beta$ ,  $\gamma$  are the three triangles above.

92. A line crosses a circle at random: find the chance that a point taken at random in the circle shall be distant from the line by less than the radius of the circle.

*Ans.*  $1 - \frac{2}{3\pi}$ .

93. Two points are taken on the circumference of a semicircle. Find the chance that their ordinates fall on either side of a point taken at random on the diameter.

*Ans.*  $\frac{4}{\pi^2}$ .

94. In any convex area *which has a centre*  $O$ , let an indefinite straight line revolve round  $O$ , and the locus of the centre of gravity of either half into which it divides the area be traced. Show that the mean distance of  $O$  from all points in the area is equal to  $\frac{1}{4}$  the perimeter of this locus. Also,  $\frac{1}{4}$  of the area enclosed by this locus = mean area of the triangle  $OXY$ , where  $X$ ,  $Y$  are points taken at random in the given area. (CROFTON, *Proceedings*, Lond. Math. Soc., vol. viii.)

95. The probability that the distance of two points taken at random in a given convex area  $\Omega$  shall exceed a given limit  $(a)$  is

$$p = \frac{1}{3\Omega^2} \iint (C^3 - 3a^2C + 2a^3) dp d\omega,$$

where  $C$  is a chord of the area, whose coordinates are  $p$ ,  $\omega$ , the integration extending to all values of  $p$ ,  $\omega$ , which give a chord  $C > a$ .

96. Show, by means of Landen's transformation in elliptic functions or otherwise, that

$$\int_0^{\frac{1}{2}\pi} \frac{d\theta}{(a^2 \cos^2\theta + b^2 \sin^2\theta)^{\frac{1}{2}}} = \int_0^{\pi} \frac{d\phi}{(a_1^2 \cos^2\phi + b_1^2 \sin^2\phi)^{\frac{1}{2}}},$$

where  $a_1$  and  $b_1$  are respectively the arithmetic and the geometric means between  $a$  and  $b$ .

Point out the value of this result in the calculation of the numerical value of the definite integral. (Camb. Math. Tripos, part ii., 1889.)

416

## INDEX.



ALLMAN, on properties of paraboloid, 268, 281.  
 Amsler's planimeter, 214.  
 Annular solids, 261.  
 Approximate methods of finding areas, 211.  
 Archimedes, on solids, 254.  
     spiral of, 194.  
     area of, 194.  
     rectification of, 227.  
 Areas of plane curves, 176.  
 Ball, on Amsler's planimeter, 215.  
 Bernoulli's series, by integration by parts, 128.  
     on curve of quickest descent, 425.  
 Binet, on principal axes, 312.  
 Brachystochrone, 425, 445.  
 Buffon's problem, 365.

Calculus of Variations, 425.  
 Cardioid, area of, 192.  
     rectification of, 227, 238.  
 Cartesian oval, rectification of, 239, 586.  
 Catenary, equation to, 183.  
     rectification of, 223.  
     surface of revolution by, 260.  
     properties of, 456.  
 Cauchy, on exceptional cases in definite integrals, 128.  
     on principal and general values of a definite integral, 132.  
     on singular definite integrals, 134.  
     on hyperbolic paraboloid, 271.  
 Chasles, on rectification of ellipse, 234, 248.  
     on Legendre's formula, 508.  
 Clerk Maxwell, 409.

Condition of integrability for a single integral, 458, 462.  
 Condition of integrability for a double integral, 490, 491.  
 Cone, right, 256.  
 Criterion for Maxima and Minima, 463.  
 Crofton, on mean value and probability, 346-391.  
 Cycloid, 189.

Definite integrals, 30, 115.  
     exceptional cases, 128.  
     infinite limits, 131, 135.  
     principal and general values, 132.  
     singular, 134.  
     differentiation of, 143, 147.  
     deduced by differentiation, 144.  
     integration under the sign  $\int$ , 148.  
     double, 149, 313.  
 Definition of variation  $\delta y$ , 425.  
 Descartes, rectification of oval of, 239.  
 Differentiation under the sign of integration, 107, 415.  
     under the sign of substitution, 416.  
 Dirichlet's theorem, 316.

Elliott, extension of Holditch's theorem, 209.  
     on Frullani's theorem, 157.  
 Ellipse, arc of, 226.  
 Ellipsoid, 266.  
     quadrature of, 282, 508.  
     of gyration, 309, 312.  
     momental, 309.  
     central, 310.  
 Elliptic integrals, 29, 173, 226, 232, 235, 243, 279.  
     coordinates, 249.

Epitrochoid, rectification of, 237.  
 Equimomental cone, 310.  
 Errors of observation, 376.  
 Euler, 102,  
     theorem on parabolic sector, 198.  
 Eulerian integrals, 117, 124, 159.  
     definition of—  
          $\Gamma(n)$  and  $B(m, n)$ , 124, 160.  
          $B(m, n) = \frac{\Gamma(m) \Gamma(n)}{\Gamma(m+n)}$ , 161.  
          $\Gamma(n) \Gamma(1-n) = \frac{\pi}{\sin n\pi}$ , 162.  
 Eulerian integrals—  
     value of  $\Gamma\left(\frac{1}{n}\right) \Gamma\left(\frac{2}{n}\right) \dots \Gamma\left(\frac{n-1}{n}\right)$   
         164.  
     table of  $\log(\Gamma n)$ , 169.  
 Fagnani's theorem, 229.  
 Folium of Descartes, 192, 218.  
 Fourier's theorem, 392.  
 Frequency, curve of, 368.  
 Frullani, theorem of, 155, 511.  
 Gamma functions, 124, 159.  
 Gauss, on integration over a closed surface, 287.  
 General transformation in partial differential expressions, 492.  
 Genocchi, rectification of Cartesian oval, 240, 242.  
 Graves, on rectification of ellipse, 234.  
 Green's theorem, 327, 421.  
 Groir, 269.  
 Gudermann, 183.  
 Guldin's theorems, 262, 263, 288.  
 Gyration, radius of, 293.  
 Helix, rectification of, 244.  
 Hirst, on pedals, 202.  
 Holditch, theorem of, 206.  
 Hyperbola, rectification of, 233.  
     Landen's theorems on, 232.  
 Hyperbolic sines and cosines, 182.  
 Hypotrochoid : *see* Epitrochoid.  
 Inertia, integrals of, 291.  
     moments of, 291.  
     products of, 291, 306.  
     principal axes of, 307.  
     momental ellipsoid of, 309.  
 Integrals, definitions of, 1, 114.  
     elementary, 2.  
     double, 149, 313.  
     of inertia, 291.  
     transformation of multiple, 320.  
 Integration, different methods of, 20.  
     by parts, 20.  
     of  $\frac{x^m dx}{x^n - 1}$ , 58.  
     by successive reduction, 63.  
     by differentiation, 71, 144.  
     of binomial differentials, 75.  
     by rationalization, 92, 97.  
     by differentiation under sign  $\int$ , 109.  
     by infinite series, 110.  
 Integration, regarded as summation, 31, 114.  
     double, 269, 313.  
     change of order in, 314.  
     over a closed surface, 284.  
 Jacobians, 323, 326.  
 Jellett, on quadrature of ellipsoid, 288, 512.  
 Kelvin, theorem on attraction, 412.  
 Kempe, theorem on moving area, 210.  
 Lagrange's series, remainder in, 158.  
 Lambert, theorem on elliptic area, 196.  
 Landen, theorem on hyperbolic arc, 232.  
     on difference between asymptote and arc of hyperbola, 233.  
 Laplace's theorem on spherical harmonics, 338.  
 Legendre, on Eulerian integrals, 160.  
     formula on rectification, 228.  
     relation between complete elliptic functions, 508.  
 Leibnitz, on Guldin's theorems, 264.  
 Lemniscate, area of, 191.  
     rectification of, 507.  
 Leudesdorf, 157, 210, 220.  
 Limaçon, area of, 192.  
     rectification of, 237.  
 Limits of integration, 33, 115.  
 Line and surface integrals, 401.

Maxima and Minima for single integrals, 430.  
 for double integrals, 471, 482.  
 Mean value and probability, 346.  
 Mean value, definition of, 346.  
 for one independent variable, 347.  
 for two or more independent variables, 350.  
 Method of quadratures, 178.  
 Miller, 358.  
 Momental ellipse, 300.  
 of a triangle, 304.  
 Moments of inertia, 291.  
 relative to parallel axes, 292.  
 uniform rod, 294.  
 parallelepiped, cylinder, 295.  
 cone, 296.  
 sphere, 297.  
 ellipsoid, 298.  
 prism, 302.  
 tetrahedron, 304.  
 solid ring, 305.  
 M'Cullagh, on rectification of ellipse and hyperbola, 236.  
 Neil, on semi-cubical parabola, 224, 249.  
 Newton, method of finding areas, 177.  
 by approximation, 213.  
 on tractrix, 219.  
 Observation, errors of, 374.  
 Panton, on rectification of Cartesian oval, 240.  
 Paraboloid of revolution, 256.  
 elliptic, 265, 268.  
 Partial fractions, 42.  
 Pedal, area of, 199.  
 of ellipse, 190.  
 Steiner's theorem on area of, 201.  
 Raabe, on, 202.  
 Hirst, on, 202.  
 Roberts, on, 500.  
 Planimeter, Amsler's, 214.  
 Principal radii of curvature, 494.  
 Popoff, on remainder in Lagrange's series, 159.  
 Probability, used to find mean values, 356.  
 Probabilities, 349.  
 Products of inertia, 301, 306.  
 Quadrature, plane, 176.  
 on the sphere, 276.  
 of surfaces, 279.  
 paraboloid, 280.  
 ellipsoid, 282.  
 Raabe, theorem on pedal areas, 202.  
 Radius of gyration, 293.  
 Random straight lines, 381.  
 Rectification of plane curves, 222.  
 parabola, 223.  
 catenary, 233.  
 semi-cubical parabola, 224.  
 of evolutes, 224.  
 arc of ellipse, 226.  
 hyperbola, 231.  
 epitrochoid, 237.  
 roulettes, 238.  
 Cartesian oval, 239, 247, 501.  
 twisted curves, 243.  
 Recurring biquadratic under radical sign, 101.  
 Reduction, integration by, 63.  
 by differentiation, 71, 80.  
 Roberts, W., on Cartesian oval, 240.  
 on pedals, 510.  
 Roulette, quadrature of, 205.  
 rectification of, 238.  
 Russell, on rectification, 501.  
 Sarrus, on calculus of variations, 413.  
 Sign of substitution, 413.  
 Simpson's rules for areas, 213.  
 Sphere, surface and volume of, 252.  
 quadrature on, 276.  
 Spherical harmonics, 332.  
 Spheroid, surface of, 257, 258.  
 Spiral, hyperbolic, 191.  
 of Archimedes, 194, 227, 380.  
 logarithmic, 227.  
 Steiner, theorem on pedal areas, 201.  
 on areas of roulettes, 203.  
 on rectification of roulettes, 238.  
 Stokes' theorem on line integrals, 403.  
 Surface of solids, 250.  
 cone, 251.  
 sphere, 252.  
 revolution, 254.  
 spheroid, prolate, 257.  
 oblate, 258.  
 annular solid, 261.

Taylor's theorem, obtained by integration by parts, 126.  
 remainder as a definite integral, 127.

Total variations, 427.

Townsend on moments of inertia of a ring, 305.  
 on moments of inertia in general, 310.

Tractrix, area of, 219.  
 length of, 225.

Van Huraet, on rectification, 249.

Variation of a single integral, 428.  
 of a double integral, 467.  
 of a triple integral, 486.

Viviani, Florentine enigma, 278.

Volumes of solids, 250, 264, 286.

Wallis, value for  $\pi$ , 122.

Weddle, on areas by approximation 213.

Woolhouse, on Holditch's theorem 206.

Zolotareff, on remainder in Lagrange's series, 158.

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